Robot control technology and application items

Item	Representatives		DOI	Item	Representatives		DOI
$tc_{43}A_{6}$	s_{125}	cc_{120}	https://www.scopus.com/inward/record.uri?eid=2-s2.0-0016379227&partnerID=40&md5=70eb8ea58a10921531df9a9a493fd33f	$tc_{21}A_{22}$		cc_{75}	https://pdfs.semanticscholar.org/49be/2317c8681f6de026c379e2ce63b54096cadf.pdf
$tc_{220}A_{61}$	s_{9}	cc_{10}	https://doi.org/10.1016/0004-3702(74)90008-3	$tc_{40}A_{14}$	s_{127}	cc_{113}	http://en.cnki.com.cn/Article_en/CJFDTotal-NYJX201510048.htm
$tc_{172}A_{54}$	s_{11}	cc_{12}	https://doi.org/10.1109/tie.1983.356737	$tc_{61}A_{20}$	s_{39}	cc_{41}	https://doi.org/10.1016/j.autcon.2015.04.016
$tc_{181}A_{55}$		cc_{2}	https://www.scopus.com/inward/record.uri?eid=2-s2.0-0020922564&partnerID=40&md5=5d84c00add1d12f884f815bc3ca06411	$tc_{67}A_{21}$		cc_{101}	https://doi.org/10.1115/DSCC2015-9936
$tc_{172}A_{54}$	s_{11}	cc_{12}	https://www.scopus.com/inward/record.uri?eid=2-s2.0-0021628071&partnerID=40&md5=26833799f7208abfcafe5709ea14f1b3	$tc_{85}A_{25}$		cc_{53}	https://link.springer.com/chapter/10.1007/978-3-319-09858-6_48
$tc_{236}A_{54}$		cc_{8}	https://www.scopus.com/inward/record.uri?eid=2-s2.0-0022199557&partnerID=40&md5=586670f0b9a8e33d11d442d808b15b14	$tc_{108}A_{34}$	s_{54}	cc_{118}	https://doi.org/10.1016/j.autcon.2015.06.002
$tc_{171}A_{54}$		cc_{13}	https://www.scopus.com/inward/record.uri?eid=2-s2.0-0022951089&partnerID=40&md5=82f41cb94a7b45f9d6f63cc345427802	$tc_{111}A_{32}$	s_{143}	cc_{105}	https://doi.org/10.1109/icara.2015.7081130
$tc_{43}A_{14}$	s_{125}	cc_{120}	https://doi.org/10.1109/iros.1989.637898	$tc_{135}A_{54}$	s_{39}	cc_{20}	https://doi.org/10.1109/icit.2015.7125587
$tc_{7}A_{1}$	s_{65}	cc_{63}	10.1061/(ASCE)0733-947X(1990)116:3(261)	$tc_{158}A_{52}$	s_{67}	cc_{105}	https://doi.org/10.22260/isarc2015/0076
$tc_{97}A_{31}$		cc_{42}	https://doi.org/10.1061/(asce)0733-9364(1990)116:3(448)	$tc1_{99}A_{56}$	s_{39}	cc_{80}	https://doi.org/10.22260/isarc2015/0075
$tc_{11}A_{20}$	s_{34}	cc_{36}	https://doi.org/10.1109/icsmc.1991.169824	$tc_{202}A_{56}$	s_{136}	cc_{86}	https://doi.org/10.23919/ecc.1999.7099781
$tc_{19}A_{11}$	s_{33}	cc_{36}	https://doi.org/10.23919/acc.1991.4791519	$tc_{21}A_{22}$		cc_{75}	https://doi.org/10.1109/wsc.2016.7822361
$tc_{97}A_{31}$		cc_{42}	https://doi.org/10.1061/(ASCE)0887-3801(1991)5:4(444)	$tc_{28}A_{12}$	s_{96}	cc_{99}	https://www.icevirtuallibrary.com/doi/pdf/10.1680/tfitsi.61279.277
$tc_{115}A_{4}$	s_{76}	cc_{95}	https://doi.org/10.1016/0926-5805(92)90036-J	$tc_{45}A_{18}$	s_{39}	cc_{44}	https://dr.ntu.edu.sg//handle/10356/84427
$tc_{64}A_{20}$	s_{6}	cc_{38}	https://doi.org/10.1061/(ASCE)0893-1321(1993)6:2(167)	$tc_{76}A_{34}$		cc_{73}	https://doi.org/10.1017/cbo9781139872027
$tc_{80}A_{24}$	s_{10}	cc_{64}	https://doi.org/10.1016/0926-5805(93)90007-K	$tc_{122}A_{54}$		cc_{21}	10.16183/j.cnki.jsjtu.2016.S.010
$tc_{82}A_{24}$		cc_{33}	https://doi.org/10.1016/0926-5805(93)90044-X	$tc_{177}A_{55}$	s_{6}	cc_{3}	https://doi.org/10.1051/matecconf/20167504001
$tc_{97}A_{7}$		cc_{42}	https://doi.org/10.1016/0926-5805(93)90041-U	$tc_{180}A_{55}$		cc_{3}	https://doi.org/10.1109/oceans.2016.7761072
$tc_{106}A_{32}$	s_{39}	cc_{52}	https://doi.org/10.1016/0926-5805(93)90005-I	$tc_{195}A_{56}$	s_{22}	cc_{78}	https://doi.org/10.20965/jrm.2016.p0149
$tc_{13}A_{14}$		cc_{115}	10.1299/kikaic.60.4222	$tc_{203}A_{56}$	s_{39}	cc_{86}	https://doi.org/10.1109/sii.2015.7405135
$tc_{75}A_{22}$	s_{74}	cc_{73}	https://doi.org/10.1016/0926-5805(94)90033-7	$tc_{218}A_{61}$		cc_{9}	https://doi.org/10.22260/isarc2016/0062
$tc_{87}A_{50}$	s_{8}	cc_{5}	https://doi.org/10.1299/jsmec1993.37.678	$tc_{16}A_{6}$		cc_{32}	https://www.scopus.com/inward/record.uri?eid=2-s2.0-85027992343&partnerID=40&md5=821c3439f403f7e0f87c6a9e6476988b

$tc_{97}A_{48}$		cc_{42}	https://onlinelibrary.wiley.com/doi/pdf/10.1111/j.1467-8667.1994.tb00363.x	$tc_{16}A_{58}$		cc_{32}	https://doi.org/10.1109/ftc.2016.7821707
$tc_{137}A_{45}$	s_{50}	cc_{79}	https://doi.org/10.1061/(ASCE)0893-1321(1994)7:1(33)	$tc_{21}A_{3}$		cc_{75}	https://doi.org/10.1007/978-3-319-49058-8_61
$tc_{51}A_{50}$	s_{22}	cc_{10}	https://doi.org/10.1016/0926-5805(94)00036-M	$tc_{27}A_{34}$		cc_{90}	https://doi.org/10.1016/j.autcon.2016.11.003
$tc_{84}A_{24}$		cc_{103}	https://doi.org/10.1016/0926-5805(94)00033-J	$tc_{44}A_{16}$		cc_{44}	https://doi.org/10.1109/urai.2017.7992753
$tc_{13}A_{14}$		cc_{115}	10.1299/kikaic.62.209	$tc_{44}A_{16}$		cc_{44}	https://doi.org/10.1016/j.autcon.2017.08.018
$tc_{27}A_{11}$		cc_{90}	https://doi.org/10.1016/0926-5805(95)00014-3	$tc_{44}A_{16}$		cc_{44}	https://doi.org/10.23919/sice.2017.8105732
$tc_{164}A_{50}$		cc_{114}	https://doi.org/10.1016/0926-5805(95)00020-8	$tc_{44}A_{16}$		cc_{44}	https://doi.org/10.22260/ISARC2017/0037
$tc_{78}A_{22}$	s_{1}	cc_{71}	https://doi.org/10.1016/0926-5805(95)00015-1	$tc_{73}A_{8}$	s_{14}	cc_{75}	http://www.iaarc.org/publications/fulltext/ISARC2017-Paper089.pdf
$tc_{79}A_{22}$	s_{21}	cc_{70}	https://doi.org/10.1016/0926-5805(95)00020-8	$tc_{77}A_{22}$		cc_{72}	https://doi.org/10.1016/j.ifacol.2017.08.1114
$tc_{116}A_{58}$		cc_{70}	https://doi.org/10.1016/0926-5805(95)00017-8	$tc_{83}A_{24}$	s_{39}	cc_{105}	https://link.springer.com/article/10.1007/s10514-016-9609-6
$tc_{175}A34$		cc_{103}	https://www.scopus.com/inward/record.uri?eid=2-s2.0-0029723178&partnerID=40&md5=db8e8bec5317e99ec4bf4f4bd18d5b83	$tc_{87}A_{55}$	s_{8}	cc_{5}	https://link.springer.com/chapter/10.1007/978-3-319-50904-4_72
$tc_{29}A_{12}$	s_{39}	cc_{96}	https://doi.org/10.1061/(ASCE)0887-3801(1997)11:2(113)	$tc_{98}A_{32}$	s_{82}	cc_{96}	https://doi.org/10.1061/(ASCE)CP.1943-5487.0000166
$tc_{33}A_{12}$		cc_{49}	https://doi.org/10.1061/(ASCE)0887-3801(1997)11:3(175)	$tc_{110}A_{32}$	s_{14}	cc_{110}	https://doi.org/10.1109/icarcv.2016.7838683
$tc_{42}A_{53}$	s_{54}	cc_{90}	https://onlinelibrary.wiley.com/doi/pdf/10.1111/0885-9507.00071	$tc_{120}A_{34}$	s_{127}	cc_{82}	https://doi.org/10.1016/j.autcon.2017.06.022
$tc_{60}A_{53}$	s_{14}	cc_{46}	https://doi.org/10.1109/mwscas.1997.666180	$tc1_{36}A_{14}$	s_{126}	cc_{108}	https://doi.org/10.1260/1369-4332.15.6.943
$tc_{117}A_{34}$	s_{70}	cc_{26}	https://doi.org/10.1109/robot.1997.620014	$tc_{176}A_{55}$	s_{6}	cc_{6}	https://doi.org/10.1109/ut.2017.7890284
$tc_{121}A_{26}$	s_{154}	cc_{90}	https://doi.org/10.1016/S0926-5805(96)00161-6	$tc_{179}A_{55}$	s_{6}	cc_{4}	https://doi.org/10.20965/jdr.2017.p0432
$tc_{140}A_{46}$	s_{1}	cc121	https://doi.org/10.1016/S0926-5805(97)00030-7	$tc_{204}A_{56}$	s_{137}	cc_{86}	https://doi.org/10.1177/1687814017709701
$tc_{170}A_{54}$	s_{14}	cc_{14}	https://doi.org/10.1111/0885-9507.00043	$tc_{217}A_{60}$		cc_{57}	https://doi.org/10.22260/isarc2017/0064
$tc_{189}A_{56}$		cc_{26}	https://doi.org/10.1016/S0926-5805(96)00168-9	$tc_{221}A_{62}$	s_{39}	cc_{94}	https://doi.org/10.1016/j.autcon.2017.06.009
$tc_{189}A_{32}$		cc_{26}	https://doi.org/10.1016/S0926-5805(96)00185-9	$tc_{234}A_{52}$	s_{6}	cc_{114}	https://doi.org/10.1109/iros.2017.8206298
$tc_{205}A_{20}$		cc_{92}	https://doi.org/10.1016/S0926-5805(96)00162-8	$tc_{12}A_{43}$	s_{129}	cc_{82}	https://doi.org/10.1061/9780784481264.001
$tc_{4}A_{1}$	s_{6}	cc_{73}	https://doi.org/10.1016/S1474-6670(17)44137-1	$tc_{12}A_{43}$	s_{129}	cc_{82}	https://doi.org/10.22260/isarc2018/0035
$tc_{5}A_{1}$	s_{67}	cc_{65}	https://doi.org/10.1016/S0926-5805(98)00060-0	$tc_{17}A_{11}$	s_{28}	cc_{31}	https://doi.org/10.22260/isarc2016/0118
$tc_{6}A_{1}$	s_{66}	cc_{64}	https://doi.org/10.1016/S0926-5805(98)00084-3	$tc_{21}A_{63}$		cc_{75}	https://doi.org/10.1016/j.autcon.2018.01.006
$tc_{31}A_{12}$	s_{94}	cc_{96}	https://tsapps.nist.gov/publication/get_pdf.cfm?pub_id=860118	$tc_{21}A_{9}$		cc_{75}	https://doi.org/10.22260/isarc2018/0112
$tc_{86}A_{56}$		cc_{86}	https://doi.org/10.1109/ramech.2008.4681331	$tc_{21}A_{14}$		cc_{75}	https://doi.org/10.1088/1742-6596/1069/1/012142
$tc_{70}A_{38}$		cc_{89}	10.1299/kikaic.65.2398	$tc_{21}A_{37}$		cc_{75}	https://doi.org/10.1061/9780784482438.048

$tc_{200}A_{56}$		cc_{81}	https://www.researchgate.net/publication/228412020_Teleoperation_Control_of_ETS-7_Robot_Arm_for_On-Orbit_Truss_Construction	$tc_{32}A_{59}$	s_{39}	cc_{73}	https://doi.org/10.1016/j.procir.2018.01.021
$tc_{57}A_{2}$	s_{39}	cc_{61}	https://doi.org/10.1016/S0926-5805(99)00044-8	$tc_{32}A_{51}$	s_{39}	cc_{73}	https://doi.org/10.22260/isarc2018/0120
$tc_{118}A_{34}$	s_{138}	cc_{26}	https://doi.org/10.1016/S0926-5805(00)00059-5	$tc_{34}A_{29}$	s_{39}	cc_{112}	https://doi.org/10.1061/(asce)cp.1943-5487.0000304
$tc_{226}A_{7}$	s_{44}	cc_{43}	https://doi.org/10.1016/S0926-5805(00)00056-X	$tc_{37}A_{13}$	s_{29}	cc_{75}	https://doi.org/10.1109/ictc.2018.8539444
$tc_{169}A_{12}$		cc_{15}	https://doi.org/10.1163/156855301300235797	$tc_{38}A_{13}$	s_{39}	cc_{118}	https://doi.org/10.22260/isarc2018/0063
$tc_{41}A_{14}$	s_{39}	cc_{56}	https://doi.org/10.1016/S0926-5805(02)00004-3	$tc_{38}A_{32}$	s_{39}	cc_{118}	https://doi.org/10.1016/j.autcon.2018.10.009
$tc_{224}A_{7}$	s_{45}	cc_{89}	https://doi.org/10.1108/eb021227	$tc_{45}A_{18}$	s_{39}	cc_{44}	https://doi.org/10.1016/j.autcon.2018.08.004
$tc_{87}A_{26}$	s_{8}	cc_{5}	https://doi.org/10.1109/iros.2003.1249679	$tc_{50}A_{18}$	s_{54}	cc_{44}	https://doi.org/10.1109/iros.2018.8593815
$tc_{95}A_{30}$	s_{6}	cc_{100}	https://doi.org/10.1109/iros.2003.1248950	$tc_{59}A_{34}$		cc_{60}	https://www.researchgate.net/publication/328094405_FOAM_Custom_Single_Task_Construction_Robot
$tc_{124}A_{38}$	s_{14}	cc_{115}	https://doi.org/10.20965/jrm.1997.p0293	$tc_{69}A_{22}$		cc_{38}	https://doi.org/10.1016/j.autcon.2018.09.008
$tc_{144}A_{5}$	s_{86}	cc_{87}	https://doi.org/10.1061/(asce)0887-3801(2003)17:2(97)	$tc_{73}A_{22}$	s_{14}	cc_{75}	https://link.springer.com/chapter/10.1007/978-3-319-61431-1_31
$tc_{33}A_{12}$		cc_{49}	https://doi.org/10.1016/j.autcon.2004.05.002	$tc_{76}A_{36}$		cc_{73}	https://doi.org/10.22260/isarc2018/0003
$tc_{56}A_{2}$	s_{54}	cc_{62}	https://doi.org/10.1016/j.autcon.2004.05.004	$tc_{76}A_{36}$		cc_{73}	https://doi.org/10.1051/matecconf/201825103060
$tc_{76}A_{24}$		cc_{73}	https://doi.org/10.1111/j.1467-8667.2004.00351.x	$tc_{81}A_{24}$		cc_{7}	https://doi.org/10.22260/isarc2018/0169
$tc_{138}A_{45}$	s_{33}	cc_{43}	https://doi.org/10.1111/j.1467-8667.2004.00368.x	$tc_{99}A_{32}$	s_{109}	cc_{75}	https://doi.org/10.22260/isarc2018/0012
$tc_{182}A_{55}$	s_{1}	cc_{1}	https://doi.org/10.1109/ut.2004.1405573	$tc_{102}A_{32}$	s_{39}	cc_{66}	https://doi.org/10.1061/9780784482438.042
$tc_{187}A_{56}$		cc_{31}	https://doi.org/10.1109/cca.2004.1387531	$tc_{103}A_{32}$	s_{109}	cc_{73}	https://doi.org/10.1109/lars-sbr-wre48964.2019.00079
$tc_{187}A_{56}$		cc_{31}	https://doi.org/10.1109/iros.2004.1389442	$tc_{107}A_{32}$	s_{29}	cc_{118}	https://doi.org/10.1007/978-3-319-91635-4_14
$tc_{222}A_{7}$	s_{47}	cc_{47}	https://doi.org/10.1111/j.1467-8667.2004.00335.x	$tc_{127}A_{39}$	s_{158}	cc_{73}	https://doi.org/10.1109/lra.2017.2719763
$tc_{223}A_{7}$	s_{43}	cc_{73}	https://doi.org/10.1109/tase.2016.2582213	$tc_{141}A_{46}$		cc_{118}	https://doi.org/10.22260/isarc2018/0006
$tc_{3}A_{1}$	s_{54}	cc_{67}	http://www.iaarc.org/publications/fulltext/isarc2005-29hong.pdf	$tc_{142}A_{46}$	s_{14}	cc_{110}	https://doi.org/10.1016/j.autcon.2017.11.007
$tc_{23}A_{11}$	s_{23}	cc_{26}	https://doi.org/10.1061/40754(183)38	$tc_{150}A_{50}$	s_{146}	cc_{73}	https://doi.org/10.1016/j.autcon.2017.11.005
$tc_{26}A_{11}$	s_{22}	cc_{25}	https://www.researchgate.net/publication/290269665_A_heavy_climbing_robotic_platform_for_geotechnical_applications	$tc_{173}A_{55}$	s_{6}	cc_{9}	https://onepetro.org/conference-paper/ISOPE-P-18-117
$tc_{93}A_{3}$	s_{39}	cc_{36}	https://doi.org/10.1108/01439910510582309	$tc_{174}A_{55}$	s_{6}	cc_{8}	https://doi.org/10.1016/j.apor.2017.12.005
$tc_{216}A_{6}$		cc_{102}	https://doi.org/10.1109/coase.2005.1506764	$tc_{175}A_{33}$		cc_{103}	https://doi.org/10.1061/9780784481288.003
$tc_{1}A_{1}$	s_{69}	cc_{69}	https://doi.org/10.1061/40830(188)92	$tc_{178}A_{55}$	s_{6}	cc_{5}	https://www.onepetro.org/conference-paper/ISOPE-P-18-118
$tc_{2}A_{1}$	s_{68}	cc_{68}	https://doi.org/10.1016/j.autcon.2005.07.009	$tc_{198}A_{55}$	s_{6}	cc_{79}	https://doi.org/10.1142/S0217979218400386
$tc_{22}A_{11}$	s_{24}	cc_{27}	https://doi.org/10.1177/105971230601400104	$tc_{203}A_{56}$	s_{39}	cc_{86}	https://doi.org/10.20965/jrm.2018.p0406
$tc_{27}A_{8}$		cc_{90}	https://doi.org/10.22260/ISARC2006/0079	$tc_{210}A_{6}$	s_{39}	cc_{32}	https://doi.org/10.1016/j.autcon.2018.03.028
$tc_{55}A_{19}$	s_{38}	cc_{114}	https://doi.org/10.1007/s10514-006-5943-4	$tc_{225}A_{7}$	s_{48}	cc_{31}	https://doi.org/10.1016/j.autcon.2018.02.007
$tc_{105}A_{32}$	s_{142}	cc_{31}	https://doi.org/10.22260/isarc2006/0093	$tc_{233}A_{52}$	s_{6}	cc_{17}	https://doi.org/10.1109/ccta.2018.8511324
$tc_{132}A_{42}$	s_{14}	cc_{109}	https://doi.org/10.22260/isarc2006/0049	$tc_{8}A_{10}$	s_{6}	cc_{89}	https://doi.org/10.1016/j.autcon.2019.01.006
$tc_{145}A_{5}$	s_{87}	cc_{65}	https://doi.org/10.1061/(asce)0887-3801(2006)20:4(302)	$tc_{9}A_{11}$	s_{29}	cc_{32}	https://doi.org/10.1109/tim.2018.2878427

$tc_{154}A_{50}$		cc_{46}	https://doi.org/10.22260/isarc2006/0156	$tc_{14}A_{11}$	s_{31}	cc_{34}	https://doi.org/10.1109/cyber46603.2019.9066688
$tc_{197}A_{56}$	s_{81}	cc_{79}	https://doi.org/10.1109/cesa.2006.313626	$tc_{32}A_{15}$	s_{39}	cc_{73}	https://doi.org/10.1016/j.autcon.2019.01.022
$tc_{232}A_{51}$	s_{39}	cc_{74}	https://doi.org/10.22260/isarc2006/0033	$tc_{32}A_{32}$	s_{39}	cc_{73}	https://doi.org/10.1061/9780784482438.041
$tc_{33}A_{45}$		cc_{49}	https://doi.org/10.22260/isarc2007/0037	$tc_{32}A_{32}$	s_{39}	cc_{73}	https://doi.org/10.3390/data4010040
$tc_{76}A_{52}$		cc_{73}	https://www.scopus.com/inward/record.uri?eid=2-s2.0-34147208423&partnerID=40&md5=119f6c021daa94e82e43ad1c00f48c01	$tc_{32}A_{51}$	s_{39}	cc_{73}	https://doi.org/10.1016/j.autcon.2019.04.004
$tc_{93}A_{56}$	s_{39}	cc_{36}	https://doi.org/10.1016/j.autcon.2005.12.002	$tc_{32}A_{33}$	s_{39}	cc_{73}	https://doi.org/10.22260/isarc2019/0147
$tc_{199}A_{56}$	s_{39}	cc_{80}	https://doi.org/10.1109/iccas.2007.4406515	$tc_{44}A_{16}$		cc_{44}	https://doi.org/10.1061/(asce)me.1943-5479.0000706
$tc_{215}A_{6}$	s_{14}	cc_{103}	https://doi.org/10.22260/isarc2007/0041	$tc_{44}A_{18}$		cc_{44}	https://doi.org/10.1016/j.autcon.2019.102933
$tc_{229}A_{8}$		cc_{91}	https://doi.org/10.1109/iccas.2007.4406517	$tc_{60}A_{2}$	s_{14}	cc_{46}	https://doi.org/10.22260/isarc2019/0096
$tc_{21}A_{15}$		cc_{75}	https://doi.org/10.1061/9780784481264.033	$tc_{73}A_{11}$	s_{14}	cc_{75}	https://doi.org/10.1016/j.addma.2019.04.002
$tc_{54}A_{19}$	s_{118}	cc_{115}	https://doi.org/10.1016/s0926-5805(02)00003-1	$tc_{73}A_{29}$	s_{14}	cc_{75}	https://doi.org/10.1109/icarm.2018.8610860
$tc_{89}A_{29}$	s_{114}	cc_{36}	https://doi.org/10.1109/iccas.2008.4694682	$tc_{76}A_{22}$		cc_{73}	https://doi.org/10.5151/proceedings-ecaadesigradi2019_605
$tc_{119}A_{34}$		cc_{79}	https://doi.org/10.1109/tase.2007.909631	$tc_{76}A_{33}$		cc_{73}	https://doi.org/10.1061/9780784482438.034
$tc_{149}A_{5}$	s_{89}	cc_{90}	https://doi.org/10.1016/j.autcon.2007.11.002	$tc_{76}A_{36}$		cc_{73}	https://doi.org/10.22260/isarc2019/0094
$tc_{168}A_{54}$		cc_{16}	https://www.researchgate.net/publication/290345447_Construction_of_welding_robot_network_control_system	$tc_{88}A_{28}$		cc_{55}	https://doi.org/10.22260/isarc2019/0175
$tc_{198}A_{56}$	s_{6}	cc_{79}	http://en.cnki.com.cn/Article_en/CJFDTotal-JLGY200803017.htm	$tc_{90}A_{29}$	s_{14}	cc_{58}	https://doi.org/10.1007/978-981-13-8410-3_25
$tc_{71}A_{22}$	s_{18}	cc_{105}	https://doi.org/10.1016/j.autcon.2008.12.008	$tc_{92}A_{38}$	s_{54}	cc_{75}	https://doi.org/10.1109/tase.2019.2897135
$tc_{91}A_{29}$	s_{113}	cc_{111}	https://doi.org/10.1016/j.autcon.2009.03.011	$tc_{92}A_{30}$	s_{54}	cc_{75}	https://www.researchgate.net/publication/336778488_Robotic_Construction_Prototyping_of_a_3D-Printed_Mars_Surface_Habitat
$tc_{104}A_{32}$	s_{14}	cc_{51}	https://pdfs.semanticscholar.org/366c/d1e40b6b4ff31f51cb60fe67f685782becfd.pdf	$tc_{108}A_{32}$	s_{54}	cc_{118}	https://doi.org/10.1016/j.autcon.2019.04.011
$tc_{128}A_{41}$	s_{81}	cc_{59}	https://doi.org/10.22260/isarc2009/0073	$tc_{123}A_{37}$	s_{62}	cc_{118}	https://doi.org/10.22260/isarc2019/0164
$tc_{167}A_{54}$	s_{14}	cc_{32}	https://mechanika.ktu.lt/index.php/Mech/article/view/15204	$tc_{131}A_{42}$	s_{39}	cc_{110}	https://doi.org/10.1016/j.autcon.2018.11.024
$tc_{186}A_{56}$	s_{133}	cc_{36}	https://doi.org/10.3182/20090909-4-JP-2010.00108	$tc_{133}A_{43}$		cc_{82}	https://doi.org/10.1061/9780784482438.043
$tc_{192}A_{56}$	s_{134}	cc_{113}	https://doi.org/10.1109/icma.2009.5246470	$tc_{134}A_{43}$	s_{54}	cc_{82}	https://doi.org/10.1016/j.autcon.2018.12.020
$tc_{209}A_{6}$	s_{104}	cc_{73}	https://doi.org/10.1016/j.autcon.2009.04.003	$tc_{139}A_{54}$	s_{19}	cc_{22}	https://doi.org/10.1016/j.autcon.2019.04.020
$tc_{86}A_{56}$		cc_{86}	https://doi.org/10.4028/www.scientific.net/amm.29-32.2170	$tc_{146}A_{5}$	s_{84}	cc_{85}	https://doi.org/10.1016/j.autcon.2019.102934
$tc_{160}A_{50}$		cc_{45}	https://doi.org/10.4028/www.scientific.net/ssp.166-167.83	$tc_{147}A_{5}$	s_{83}	cc_{92}	https://doi.org/10.22260/isarc2019/0134
$tc_{162}A_{50}$	s_{57}	cc_{79}	https://doi.org/10.1007/978-90-481-3522-6_49	$tc_{148}A_{5}$	s_{85}	cc_{73}	https://doi.org/10.1109/med.2016.7535925
$tc_{190}A_{56}$	s_{135}	cc_{26}	https://doi.org/10.1109/icma.2010.5588360	$tc_{151}A_{50}$	s_{147}	cc_{73}	https://doi.org/10.1016/j.autcon.2018.11.022
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tc62A20	s37	cc40	https://doi.org/10.22260/isarc2013/0165	tc143A48	s17	cc75	https://link.springer.com/chapter/10.1007/978-3-030-48989-2_27
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tc87A37	s8	cc5	https://www.researchgate.net/publication/273060859_Potentials_of_Robotic_Fabrication_in_Wood_Construction_Elastic	tc161A50	s145	cc50	https://doi.org/10.1088/1757-899x/832/1/012009

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$tc_{66}A_{21}$	S_{39}	cc_{62}	https://doi.org/10.1109/iros.2014.6942993	$tc_{63}A_{20}$		cc_{39}	https://doi.org/10.1016/j.autcon.2020.103415
$tc_{113}A_{34}$	s_{49}	cc_{98}	http://idm-lab.org/bib/abstracts/papers/icaps14c.pdf	$tc_{228}A_{8}$	s_{92}	cc_{92}	https://doi.org/10.1061/(ASCE)AE.1943-5568.0000134
$tc_{156}A_{50}$	s_{39}	cc_{26}	https://doi.org/10.22260/ISARC2014/0111	$tc_{185}A_{56}$	s_{136}	cc_{62}	https://doi.org/10.20965/jrm.2014.p0110
$tc_{160}A_{50}$		cc_{45}	https://www.researchgate.net/publication/320388911_Modified_Discrete_Event_Simulation_Algorithm_for_Control_of_Automated_Construction_Operations				
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