

CS 115 Functional Programming

Lecture 20:

State Monads (part 2)





Previously

- State monads
- The State datatype
- (State s) as a monad
- The runState function





Today

- More on state monads
- The MonadState type class
 - the get and put methods to retrieve/change values in the state being passed around
- Examples using state monads





- State monads are a way to encapsulate a "statepassing" mode of computation
- Can use state monads to simulate either local or global variables in an imperative-style computation
- Unlike the IO monad, can easily exit from a state monad computation using the runState function



 State-passing computations can be written like this (for a given state type s):

$$(a, s) -> (b, s)$$

Or with the first argument curried:

$$a -> s -> (b, s)$$

The State datatype wraps the s -> (b, s) part into a constructor:

```
data State s a = State (s -> (a, s))
```





- Using the State datatype, state-passing computations are represented as:
- a -> State s b
- For a given state type s, State s is a monad





 The Monad instance definition for (State s) is as follows:

```
instance Monad (State s) where
 return x = State (\st -> (x, st))
 mv >>= g =
    State (\st ->
      let (State ff) = f x
          (y, st') = ff st
          (State gg) = g y
      in gg st')
```





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```





- Even though the Monad instance for (State s) definition looks complex
 - the definition of return is equivalent to the state-passing identity function id_state (x, st) = (x, st) translated to use the State datatype
 - the definition of >>= is equivalent to composing two state-passing functions (translated to use the State datatype) to create a third



 So the Monad instance is completely natural and can be derived without even using the monad laws





Example

- Big deal... what does this buy us in practice?
- We'll use state monads to write a function which is structurally equivalent to imperative C code, but without using the IO monad
- Previously we saw how to write the gcd function using IORefs
- Now we'll see how to do the same thing (more simply!) using a state monad



Disclaimer

- Much like the previous gcd example, this isn't something you would use state monads for in real world code
- However, any time you have a number of functions that
 - share state
 - need to sometimes read from or change that state
 - don't need to read/write state all the time then state monads can be an effective tool





Example

Recall the C version of gcd:

```
int gcd(int i, int j) {
  while (i != j) {
    if (i > j) {
      i = i - j;
    } else {
      j = j - i;
  return i;
```





Example

- We will translate the C gcd function into the equivalent state monad version in Haskell
- To do this, we will need a way to put values into the state and withdraw them from the state
- We will show how to do this in general, then introduce the MonadState type class, which will do it for us



Retrieving the state

- In a state monad, we are combining state transformers which have the type s -> (a, s) for some state type s (wrapped in a State constructor)
- Each state transformer specifies the way it changes the state as well as a "return value"
- If the value we want to return is the state itself, what will the type of the state transformer be?
- Answer: s -> (s, s)





Retrieving the state

 Let's write such a state transformer and call it getState:

```
getState :: State s s
getState = State (\st -> (st, st))
```

 In a state monad computation, we would use it like this:

```
do ...
st <- getState
... -- (computations involving st)</pre>
```





Changing the state

- Changing the state requires that we have a state transformer that can change the existing state
- Written in the purely-functional style, this would look like this:

```
putState' :: (s, s) -> ((), s)
putState' (st', st) = ((), st')
```

Writing this with the State datatype, it becomes:

```
putState :: s -> State s ()
putState st' = State (\st -> ((), st'))
-- substitute new state st' for old state st
```





Changing the state (2)

- getState and putState are the only essential functions needed to interact directly with the state in a state monad
- However, another useful function is called modifyState
- It takes a function and applies it to the state, yielding a new state

```
modifyState :: (s -> s) -> State s ()
modifyState f = State (\st -> ((), f st))
```





- With these functions, we can write our first version of the GCD function using state monads
- We will define a GCD state transformer called gcdState
- The GCD computation requires what state variables?





- With these functions, we can write our first version of the GCD function using state monads
- We will define a GCD state transformer called gcdState
- The GCD computation requires what state variables?
 - two integers, which we'll call i and j
- Therefore, the type signature of gcdState is:

```
gcdState :: State (Integer, Integer) Integer
```





gcdState :: State (Integer, Integer) Integer

- Note that the "return" type of the state transformer is Integer
- Meaning: when the computation is done, the result will be an integer
- Before we discuss how to write this state transformer, let's see how to use it!
- We will use the runState function to define the gcd function itself





- runState takes the initial state and the state transformer and returns the final state, plus the return value
- We assume the return value will be the GCD itself
- Therefore, we have:

```
gcd :: Integer -> Integer -> Integer
gcd i j = fst $ runState gcdState (i, j)
```

- runState gcdState (i, j) returns a (value, state) pair
- Take the value part, which is the GCD



evalState and execState

- Most state monad computations either want just the return value or the final state (not both)
- Therefore, in the Control.Monad.State module (where all the state monad stuff is defined) are two useful helper functions:

```
-- result is the final returned value only:

evalState :: State s a -> s -> a

evalState trans init_st = fst $ runState trans init_st

-- result is the final state only:

execState :: State s a -> s -> s

execState trans init_st = snd $ runState trans init_st
```



evalState and execState

 We can simplify our gcd function a tad using evalState:

```
gcd :: Integer -> Integer -> Integer
gcd i j = evalState gcdState (i, j)
```

Now we merely have to define gcdState!





Here is our first version of gcdState:

```
gcdState :: State (Integer, Integer) Integer
gcdState = do
  (i, j) <- getState</pre>
  if i > j
                          new i new j
     then do putState (i - j, j)
              gcdState
     else if i < j
              then do putState (i, j - i)
                       gcdState
              else -- i == j
                return i
```





- The nested if statements are gross, so let's use the compare function instead
- compare outputs a value of the Ordering type:

```
data Ordering = LT | EQ | GT
```

 This will allow us to clean up the code without changing anything significant





```
gcdState :: State (Integer, Integer) Integer
gcdState = do
  (i, j) <- getState</pre>
  case compare i j of
    GT -> do putState (i - j, j)
             gcdState
    LT -> do putState (i, j - i)
             gcdState
    EQ -> return i
```





Notice this code:

```
do putState (i - j, j)
  gcdState
```

- This combines two state transformers to get one bigger state transformer
- The new state transformer changes the state, then runs the gcdState transformer again



- We will improve this code still more, but first let's introduce a very useful type class called MonadState
- MonadState has this definition:

```
class Monad m => MonadState s m | m -> s where
  get :: m s
  put :: s -> m ()
  state :: (s -> (a, s)) -> m a
```



- What MonadState does is to generalize the getState and putState functions to arbitrary state-like monads
- The definition for the (State s) monad is as follows:

```
instance MonadState s (State s) where
get = State (\st -> (st, st))
put st' = State (\st -> ((), st'))
state = State -- won't be using this
```

Look familiar?





- Why does MonadState need to be a type class?
- Why not define get and put to just be getState and putState?





- Answer: It's more general!
- Monads other than (State s) can have get and put methods
- One class of these are aggregate monads built on top of (State s) using what are called monad transformers (advanced topic! coming soon!)



Also notice the line:

```
class Monad m => MonadState s m | m -> s where
```

- Note the functional dependency | m -> s
- This means: any given monad m which is an instance of MonadState uniquely determines the state type s for the instance
- In our case, m is (State s) and s is s, so the connection is pretty obvious





 We can use MonadState's methods to shrink our getState code a tiny bit:





 We can also define a function called modify which generalizes modifyState:

```
modify :: MonadState s m => (s -> s) -> m ()
modify f = do s <- get
    put (f s)</pre>
```

 This allows us to modify the state for any monad m that is an instance of MonadState (and thus has get and put methods)





runState again

- We have seen how to use runState to "run" a computation in a state monad and get a result
- A different use for runState is to extract the state transformer function out of a State value



runState again

Recall the definition of runState:

```
runState :: State s a -> s -> (a, s)
runState (State f) init_st = f init_st
• Leaving off the final init_st, we have:
runState (State f) = f -- extract f
```





 We will use the MonadState methods, modify and runState to define whileState, a while loop that operates in a state monad



Here is the definition:

Let's walk through this step-by-step





Look at the type declaration:

```
whileState :: (s -> Bool) -> State s () -> State s ()
whileState test body = ...
```

- The first argument is a test function
 - It takes the existing state, examines it to see if the computation has completed, and returns a boolean value
- The second argument is the body of the while loop
 - It is a state transformer that changes the state and returns nothing
- The return value is also a state transformer that returns nothing





```
whileState :: (s -> Bool) -> State s () -> State s ()
whileState test body = do
    s0 <- get
    when (test s0)
        (do modify (snd . runState body)
        whileState test body)</pre>
```

First, we get the state and bind it to s0



```
whileState :: (s -> Bool) -> State s () -> State s ()
whileState test body = do
    s0 <- get
    when (test s0)
        (do modify (snd . runState body)
        whileState test body)</pre>
```

- when is a monadic if statement with no else
- Definition:

```
when :: (Monad m) => Bool -> m () -> m () when b s = if b then s else return ()
```





```
whileState :: (s -> Bool) -> State s () -> State s ()
whileState test body = do
    s0 <- get
    when (test s0)
        (do modify (snd . runState body)
        whileState test body)</pre>
```

- When the test (test s0) returns True,
 - execute the line modify (snd . runState body)
 - then run whileState all over again
- Otherwise, you're done!





```
modify (snd . runState body)
```

- body is the body of the while loop, as a state transformer of type State s ()
- runState body is a state transforming function,
 of type s -> ((), s)
- (snd . runState body) is a function of type
 (s -> s); it takes in a state s, runs
 runState body on it to get a value of type
 ((), s), and takes the second part of the tuple
 (of type s)





```
modify (snd . runState body)
```

- (snd . runState body) is thus a function that uses the state transformer body to modify the state
- modify takes the function
 (snd . runState body) and actually modifies
 the state
- then whileState is repeated again, until it's done
- Now we can use whileState to simplify our gcdState state transformer





- One small tweak...
- (snd . runState body) is equivalent to (execState body)
- Rewriting, we have:

```
whileState :: (s -> Bool) -> State s () -> State s ()
whileState test body = do
    s0 <- get
    when (test s0)
        (do modify (execState body)
        whileState test body)</pre>
```





- But wait!!!
- We will show that

```
modify (execState body)
```

• is the same as just:

body

 which will allow us to simplify this definition even more!





```
body :: State s ()
body = State (s \rightarrow ((), f s)) -- for some f
runState body :: s -> ((), s)
runState body = \slashs -> ((), f s)
execState body :: s -> s
execState body s = snd (runState body s)
                  = snd ((), f s)
                  = f s
```





So:

```
execState body = \s -> f s = f

modify :: (s -> s) -> State s () -- in state monads
modify f = State (\s -> ((), f s))

modify (execState body)
    = modify f
    = State (\s -> ((), f s))
    = body
```





Rewriting again, we have:

```
whileState :: (s -> Bool) -> State s () -> State s ()
whileState test body = do
   s0 <- get
   when (test s0)
        (do body
        whileState test body)</pre>
```

which is pretty intuitive





Or:

```
whileState :: (s -> Bool) -> State s () -> State s ()
whileState test body = do
    s0 <- get
    when (test s0)
        (body >> whileState test body)
```

(if you're into the whole brevity thing)



New version of gcdState:

```
gcdState :: State (Integer, Integer) Integer
gcdState = do
  whileState (\(i, j) -> i /= j)
    (do (i, j) <- get
        if i > j
           then put (i - j, j)
           else put (i, j - i))
  (i, _) <- get
  return i
```





• Or:

```
gcdState :: State (Integer, Integer) Integer
gcdState = do
  whileState (uncurry (/=)) []
    (do (i, j) <- get
        if i > j
           then put (i - j, j)
           else put (i, j - i))
  (i, _) <- get
  return i
```





Compare with C version:

- Very similar!
- But we can do even better...





```
gcdState :: State (Integer, Integer) Integer
gcdState = do
  whileState (\(i, j) -> i /= j)
    (do (i, j) <- get
        if i > j
           then put (i - j, j) icky
           else | put (i, j - i) |)
  (i, _) <- get
  return i
```





. . .

```
then put (i - j, j)
else put (i, j - i)
```

• •

- The put lines are icky because you only need to modify either i or j, not both
- Let's define two functions putI and putJ that will only modify i or j



Here you go:

```
putI :: Integer -> State (Integer, Integer) ()
putI i = modify (\( (\_, j) -> (i, j) )

putJ :: Integer -> State (Integer, Integer) ()
putJ j = modify (\( (i, _) -> (i, j) )
```



Now gcdState becomes:

```
gcdState :: State (Integer, Integer) Integer
gcdState = do
  whileState (\(i, j) -> i /= j)
    (do (i, j) <- get
        if i > j
           then putI (i - j)
           else putJ (j - i))
  (i, _) <- get
  return i
```





Compare with C version now:

- Almost identical!
- Downside: had to define trivial helper functions putI and putJ





Caveats

- Some of the presentation here has been simplified
- Actual ghc library code can be quite complex (hyper-general versions of everything)
- Modules also often import other modules and reexport the same functions
- Sometimes modules restrict access to constructors
 - Example: the State constructor is not exported; need to use the state function which does the exact same thing
- When in doubt, consult Hoogle and read the source code!





ghci

 To import Control.Monad.State in ghci, first need to enable the mtl (Monad Transformer Library) package with this syntax:

```
ghci> :set -package mtl
ghci> import Control.Monad.State
...
```





Conclusion

- State monads allow us to simulate stateful code that uses local or global variables
- Advantages:
 - can easily get into/out of monad
 - purely functional, often simpler than using IORefs
- Disadvantages:
 - can't do I/O (unless you use a monad transformer)
 - may be slower than using IO monad
- State monads are a useful tool in many kinds of programming





Coming up

- Parsing with parser combinators
- Monad transformers

