

# Evolutionary Computation for Dynamic Optimization Problems: Case Studies & Advanced Topics

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# Recall: EC for DOPs

- EC for DOPs: Important and young research area
- Approaches to enhance EC for DOPs:
  - Memory: store and reuse useful information
  - Diversity: handle convergence directly
  - Multi-population: co-operate sub-populations
  - Adaptive: adapt generators and parameters
  - Prediction: predict changes and take actions in advance
  - Hybrid methods

- M. Mavrovouniotis, C. Li, and S. Yang. A survey of swarm intelligence for dynamic optimization: Algorithms and applications. *Swarm and Evolutionary Computation*, 33: 1-17, April 2017
- T. T. Nguyen, S. Yang, and J. Branke. Evolutionary dynamic optimization: A survey of the state of the art. *Swarm and Evolutionary Computation*, 6: 1-24, October 2012

# Outline of the Lecture

- Part II: Case studies
  - Population-Based Incremental Learning (PBIL) for binary DOPs
  - Particle swarm optimization (PSO) for continuous DOPs
  - EC for combinatorial DOPs
    - Genetic algorithms (GAs) for dynamic routing in MANETs
    - Ant colony optimization (ACO) for combinatorial DOPs
- Part III: Advanced Topics
- Summary

# Case Study: Population-Based Incremental Learning

- PBIL: proposed by Baluja in 1994

Initialize the probability vector  $\vec{P}^0 := 0.5$

**repeat**

    Generate a population of samples by  $\vec{P}^t$

    Evaluate and denote the best sample by  $\vec{B}^t$

    Learn  $\vec{P}^t$  toward  $\vec{B}^t$  by Eq. (1)

**until** *terminated* = **true**

- Learning rule:

$$P_i^{t+1} := (1 - \alpha) * P_i^t + \alpha * B_i^t, \quad i = \{1, \dots, l\} \quad (1)$$

where  $\alpha$  is the learning rate

- Sampling a solution  $\vec{S}$  by  $\vec{P}^t$ :

For each locus  $i$ , if  $\text{rand}(0, 1) < P_i^t$ ,  $S_i = 1$ ; otherwise,  $S_i = 0$

S. Baluja, "Population-based incremental learning: A method for integrating genetic search based function optimization and competitive learning," Carnegie Mellon Univ., Tech. Rep. CMU-CS-94-163, 1994.

# Case Study: PBIL with Associative Memory for DOPs

Idea: Uses a memory to store  $\langle \vec{P}, S \rangle$  pairs

- Updated in a dynamic time pattern

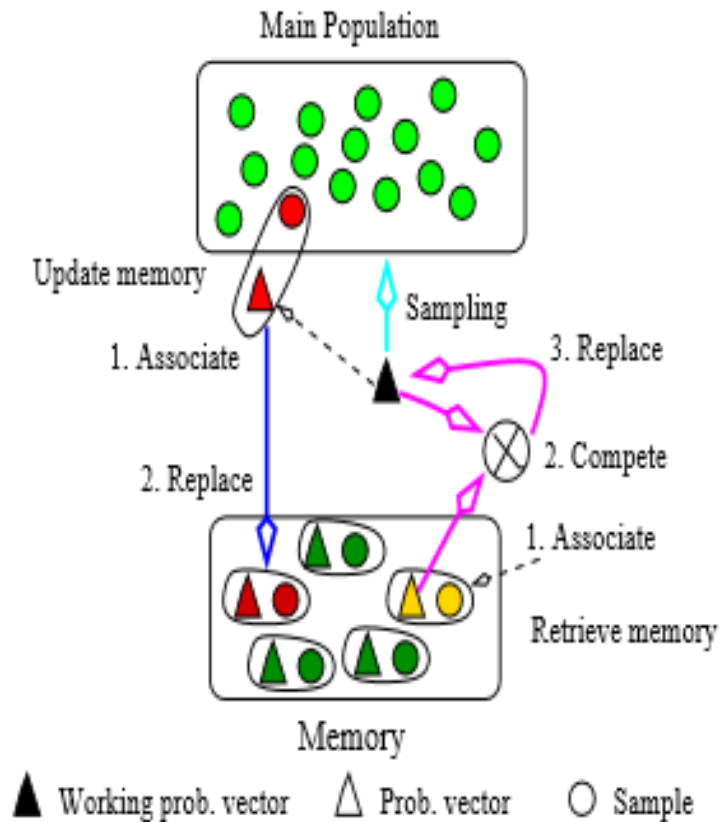
$$t_M = t + \text{rand}(5, 10)$$

- Using the most similar strategy

- Find memory sample closest to best pop sample
- If the best pop sample is fitter, swap them and associated  $\vec{P}$ 's

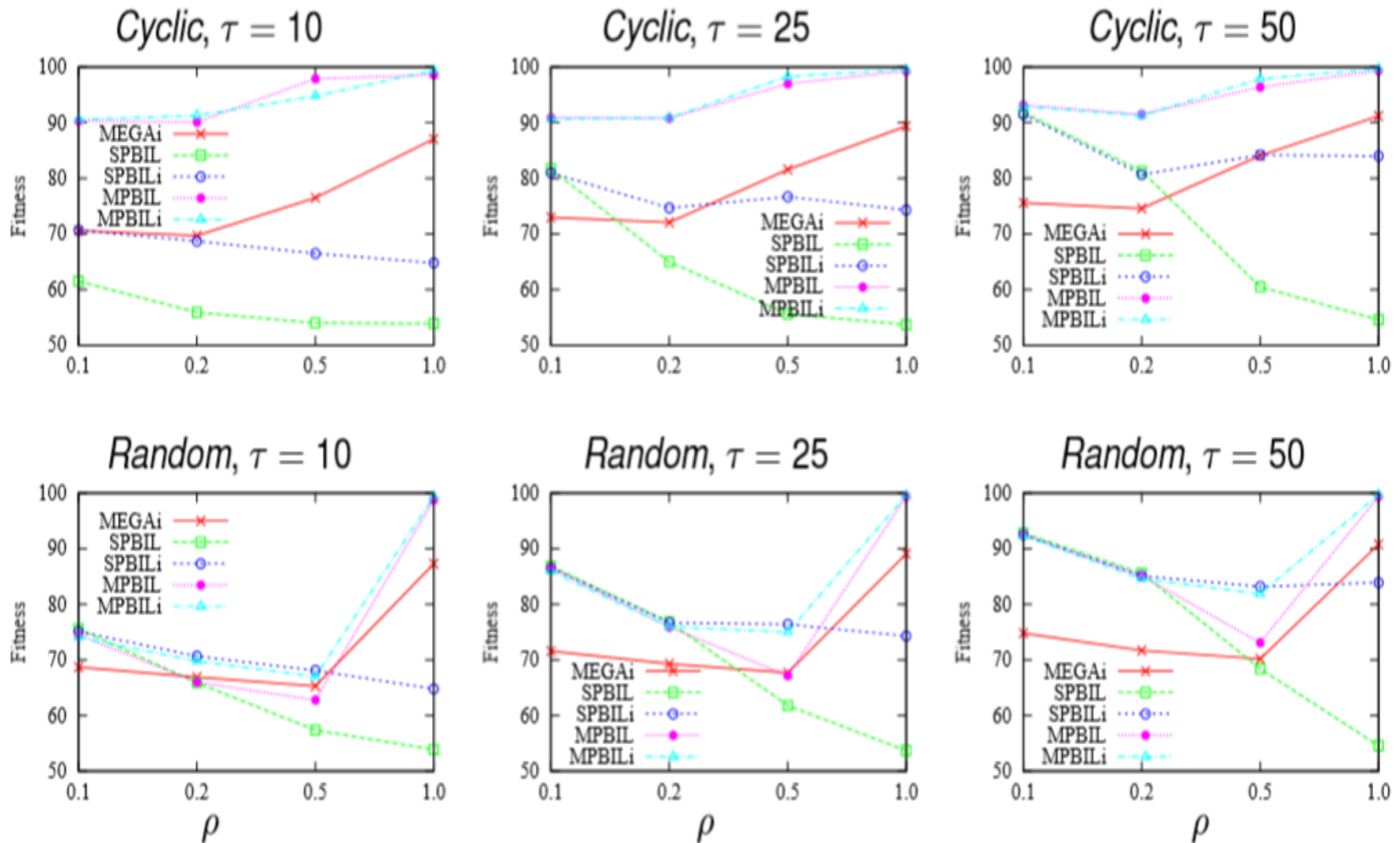
- Re-evaluated every iteration

- If change detected, best memory  $\vec{P}_M$  competes with working  $\vec{P}$



S. Yang. Population-based incremental learning with memory scheme for changing environments. Proceedings of the 2005 Genetic and Evolutionary Computation Conference, Vol. 1, pp. 711-718, 2005

# PBIL with Associative Memory for DOPs: Results



- Associative memory efficiently improves PBIL's performance

# Case Study: PSO for Continuous DOPs

- Developed by Kennedy and Eberhart (1995)
- A population based optimization technique inspired by social behaviour of bird flocking or fish schooling
- Swarm members can profit from their own discovery and previous experience of all other members of the school



Kennedy, J. and Eberhart, R.: Particle Swarm Optimization. Proceedings of the Fourth IEEE International Conference on Neural Networks, Perth, Australia. IEEE Service Center 1942-1948, 1995.



# Particle Swarm Optimization (PSO)

- PSO consists of a **swarm** of **particles**
- Each particle resides at a **position** in the search space and flies over the search space with a certain **velocity**
- The **velocity** of each particle is influenced by
  - **Momentum**: maintaining previous velocity it has travelled so far
  - **Cognitive component**: returning to the best position visited so far
  - **Social component**: moving to the best position found by neighbors so far

$$\vec{v}_i \leftarrow \vec{v}_i + \vec{U}(0, \varphi_1) \otimes (\vec{p}_i - \vec{x}_i) + \vec{U}(0, \varphi_2) \otimes (\vec{g}_i - \vec{x}_i)$$
$$\vec{x}_i \leftarrow \vec{x}_i + \vec{v}_i$$

- Eventually the swarm will converge to optimal positions



# PSO for Continuous DOPs: Issues

- Recently, PSO has been applied for continuous DOPs
- Two aspects to consider:
  - Outdated memory. Two solutions:
    - Simply set *pbest* to the current position
    - Reevaluate *pbest* and reset it to current position if it is worse than the current position
  - Diversity loss. Three solutions:
    - Introduce diversity after a change
    - Maintain diversity during the run
    - Use multi-swarms

# Multi-swarm PSO for DOPs

- Aim: To maintain multiple swarms on different peaks
- Key questions:
  - How to guide particles to different promising sub-regions?
  - How to determine the proper number of sub-swarms?
  - How to calculate the search area of each sub-swarm?
  - How to create sub-swarms?
- Algorithms:
  - Kennedy's k-means clustering algorithm
  - Brits's nbest PSO algorithm and niching PSO (NichePSO)
  - Parrott and Li's speciation based PSO (SPSO)
  - Blackwell and Branke's charged PSO (mCPSO) and quantum swarm optimization (mQSO)

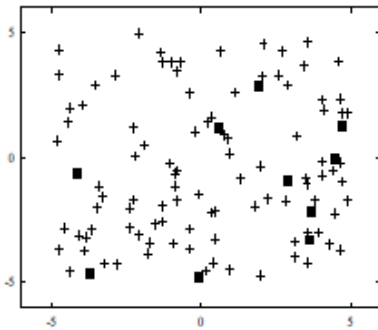
- T. Blackwell and J. Branke. Multiswarms, exclusion, and anti-convergence in dynamic environments. IEEE Trans Evol Comput, 10(4): 459-472, Aug. 2006.
- D. Parrott and X. Li. Locating and tracking multiple dynamic optima by a particle swarm model using speciation. IEEE Trans. Evol. Comput., 10(4): 440-458, Aug. 2006.

# Multi-swarm PSO for DOPs

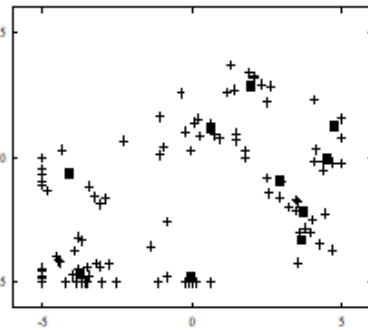
- Limitations of the above algorithms:
  - The number of sub-swarms is predefined ( $k$ -means PSO, mCPSO, and mQSO)
  - The search radius of each sub-swarm must be given by experimental experience (SPSO, mCPSO, and mQSO)
  - Simply create sub-swarms without analysing the population distribution (NichePSO and SPSO)
- Problems might be caused by the above algorithms:
  - There may be improper number of sub-swarms
  - One sub-swarm might cover more than one peak
  - One peak might be surrounded by more than one sub-swarm

# Clustering PSO (CPSO) for DOPs

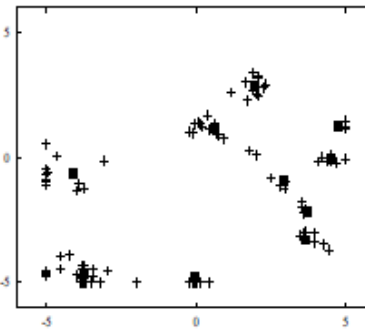
- Training: Move particles toward different regions



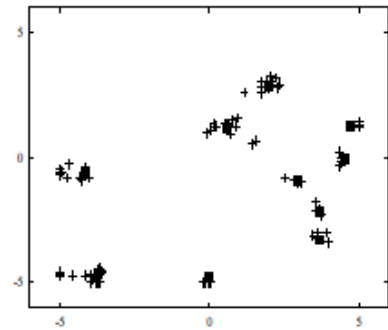
(a) initial stage



(b) iteration 3



(c) iteration 6



(d) iteration 9

- Clustering sub-swarms: Single linkage hierarchical clustering
- Local search: Each sub-swarm searches one peak quickly
- Overlapping and convergence check strategy
- Strategies to response to changes

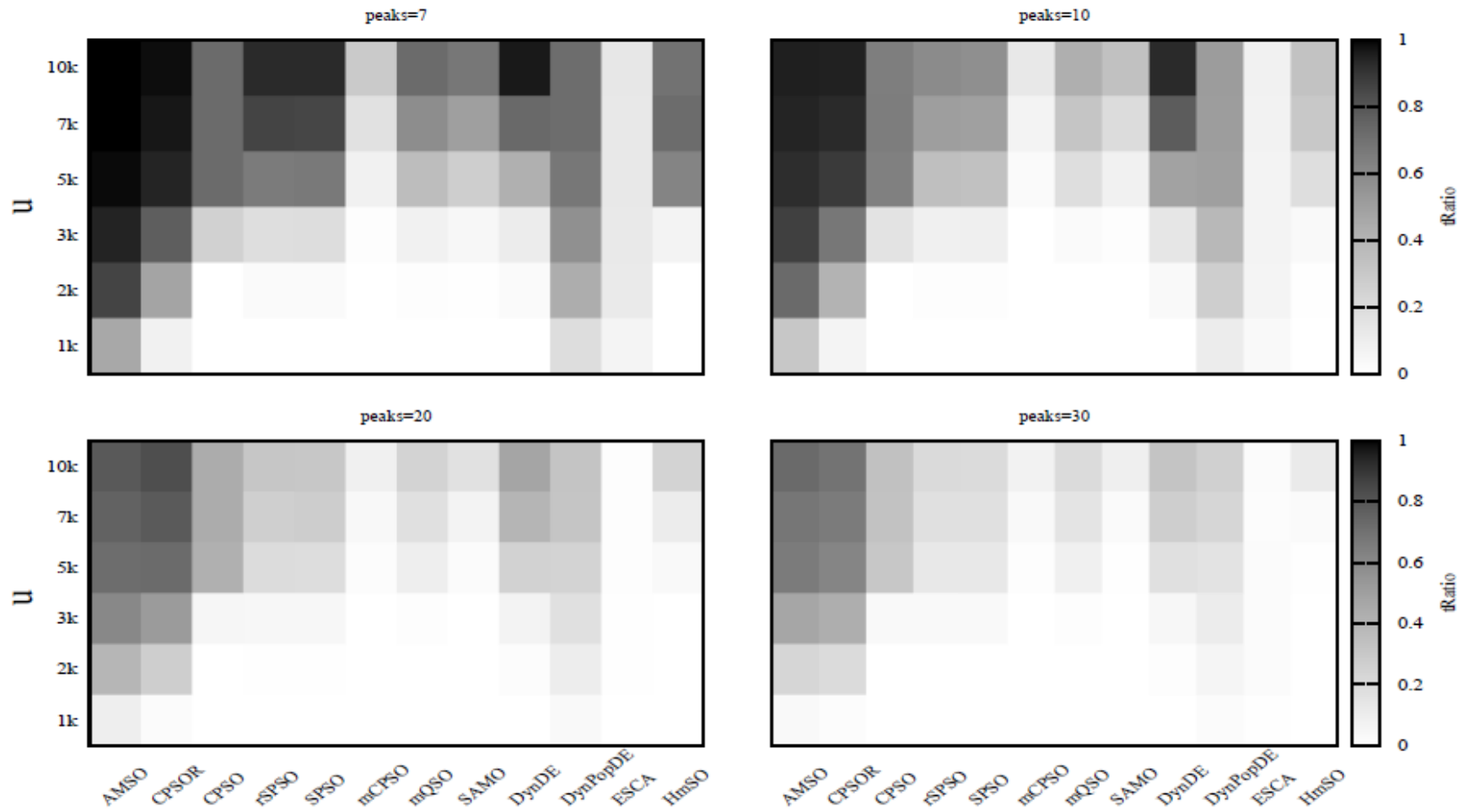
- S. Yang and C. Li. A clustering particle swarm optimizer for locating and tracking multiple optima in dynamic environments. IEEE Transactions on Evolutionary Computation, 14(6): 959-974, Dec. 2010
- C. Li and S. Yang. A clustering particle swarm optimizer for dynamic optimization. Proceedings of the 2009 IEEE Congress on Evolutionary Computation, pp. 439-446, 2009

# Adaptive Multi-Swarm Optimizer (AMSO)

- Recently, a framework of multi-population approaches
  - Use **single linkage hierarchical clustering** to create populations
  - Each population will search one peak in the fitness landscape
  - An overcrowding scheme to remove unnecessary populations
  - A special rule to decide proper moments to increase diversity without change detection
  - An adaptive method to create a proper number of populations needed
- C. Li and S. Yang. A general framework of multi-population methods with clustering in undetectable dynamic environments. *IEEE Transactions on Evolutionary Computation*, 16(4): 556-577, August 2012
- C. Li, S. Yang, and M. Yang. An adaptive multi-swarm optimizer for dynamic optimization problems. *Evolutionary Computation*, 22(4): 559-594, Winter 2014
- C. Li, T. T. Nguyen, M. Yang, M. Mavrovouniotis, and S. Yang. An adaptive multi-population framework for locating and tracking multiple optima. *IEEE Transactions on Evolutionary Computation*, 20(4):590-605, 2016

# Multi-Swarm PSO for DOPs: Results

Average tracking ratio on MPB with different change frequencies



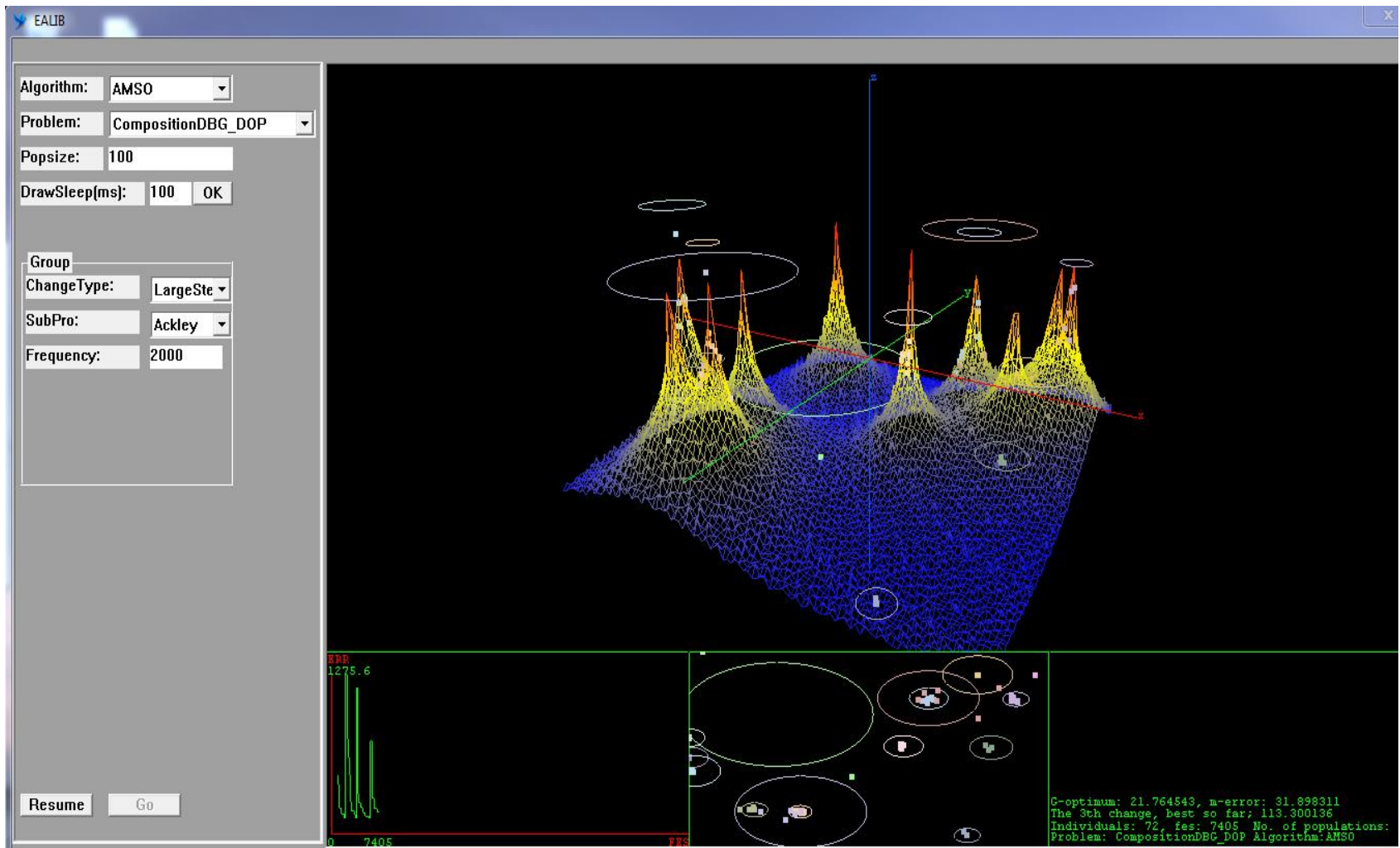
# Multi-Swarm PSO for DOPs: Results

- The offline error ( $E_{offline}$ ) and best-before-change error ( $E_{BBC}$ ) on the MPB with changing number of peaks

	Error	AMSO	CPSOR	CPSO	rSPSO	SPSO	mCPSO	mQSO	SAMO	DynDE	DynPopDE	ESCA	HmSO	SOS
Var1	$E_{offline}$	2.3	2.8 <sup>w</sup>	4 <sup>w</sup>	6 <sup>w</sup>	5.9 <sup>w</sup>	7.8 <sup>w</sup>	4.5 <sup>w</sup>	3.5 <sup>w</sup>	3.6 <sup>w</sup>	3.7 <sup>w</sup>	13 <sup>w</sup>	4.5 <sup>w</sup>	11 <sup>w</sup>
	$E_{BBC}$	±0.25	±0.17	±0.28	±0.55	±0.58	±0.62	±0.27	±0.24	±0.38	±0.26	±1.3	±0.19	±3.2
Var2	$E_{offline}$	2.9	3.3 <sup>w</sup>	5 <sup>w</sup>	4.6 <sup>w</sup>	4.9 <sup>w</sup>	7.3 <sup>w</sup>	4.4 <sup>w</sup>	4 <sup>w</sup>	3.5 <sup>w</sup>	4.2 <sup>w</sup>	13 <sup>w</sup>	5.4 <sup>w</sup>	9.4 <sup>w</sup>
	$E_{BBC}$	2	1.9 <sup>t</sup>	2.6 <sup>w</sup>	3.7 <sup>w</sup>	3.9 <sup>w</sup>	6.3 <sup>w</sup>	3.4 <sup>w</sup>	3.1 <sup>w</sup>	2.9 <sup>w</sup>	3.6 <sup>w</sup>	13 <sup>w</sup>	4 <sup>w</sup>	8.4 <sup>w</sup>
Var3	$E_{offline}$	2.7	2.9 <sup>w</sup>	4.5 <sup>w</sup>	4.9 <sup>w</sup>	4.8 <sup>w</sup>	7.4 <sup>w</sup>	4.1 <sup>w</sup>	3.7 <sup>w</sup>	3.4 <sup>w</sup>	4.8 <sup>w</sup>	13 <sup>w</sup>	5.3 <sup>w</sup>	9.6 <sup>w</sup>
	$E_{BBC}$	±0.45	±0.29	±0.36	±0.68	±0.66	±0.98	±0.55	±0.32	±0.5	±0.59	±2	±0.4	±3.5
		1.7	1.6 <sup>t</sup>	2.2 <sup>w</sup>	3.9 <sup>w</sup>	3.7 <sup>w</sup>	6.4 <sup>w</sup>	3.3 <sup>w</sup>	2.8 <sup>w</sup>	2.7 <sup>w</sup>	4.1 <sup>w</sup>	12 <sup>w</sup>	4.1 <sup>w</sup>	8.5 <sup>w</sup>

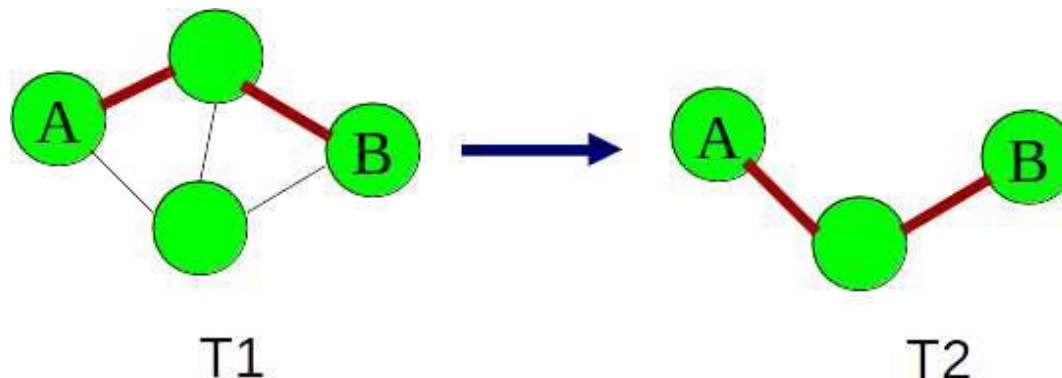


# Multi-swarm PSO for DOPs: Demo



# Case Study: GAs for Dynamic Routing in MANETs

- More and more mobile wireless networks, e.g., mobile ad hoc networks (MANETs), wireless mesh networks (WMNs)
- MANET: a wireless network set up temporarily without a wired infrastructure (routers, switches, servers, cables, access points, etc.)
- It is very suitable for disaster rescue and recovery battlefield communication, etc
- An important feature in MANETs is the topology dynamics due to energy conservation and/or node mobility
  - Node mobility  $\Rightarrow$  Topology change



# Dynamic Shortest Path Routing in MANETs

- Shortest path routing problem (SPRP) in a fixed network:
  - Find the shortest path between source and destination in a fixed topology
- In MANETs, the SPRP is a DOP
- Dynamic SPRP (DSPRP) in MANETs:
  - Find a series of shortest paths in a series of highly-related network topologies

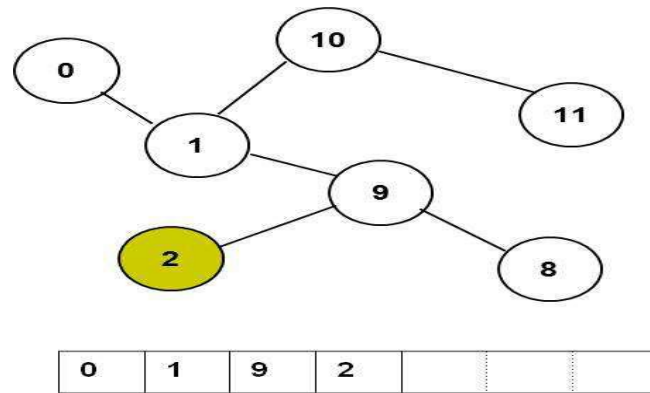
# Problem Model

- Given a MANET within a fixed geographical region, we model it by a undirected and connected topology graph  $G_0(V_0, E_0)$ 
  - $V_0$  represents the set of wireless nodes (i.e., routers)
  - $E_0$  represents the set of communication links connecting two neighboring routers within the radio transmission range
- Message transmission on a wireless communication link will incur remarkable delay and cost
- We model the network dynamics as follows:
  - For each change, a number of nodes are randomly selected to sleep or wake up based on their current status

# Specialized GA for DSPRP in MANETs

- Path-oriented encoding:

- A routing path is encoded by a string of integers that represent the IDs of nodes through which the path passes



- Fitness function: The less the path cost, the better

$$f(x) = \left[ \sum_{l \in P(s,r)} c_l \right]^{-1}$$

where  $P(s, r)$  is the path from source  $s$  to destination  $r$

- Pair-wise tournament selection

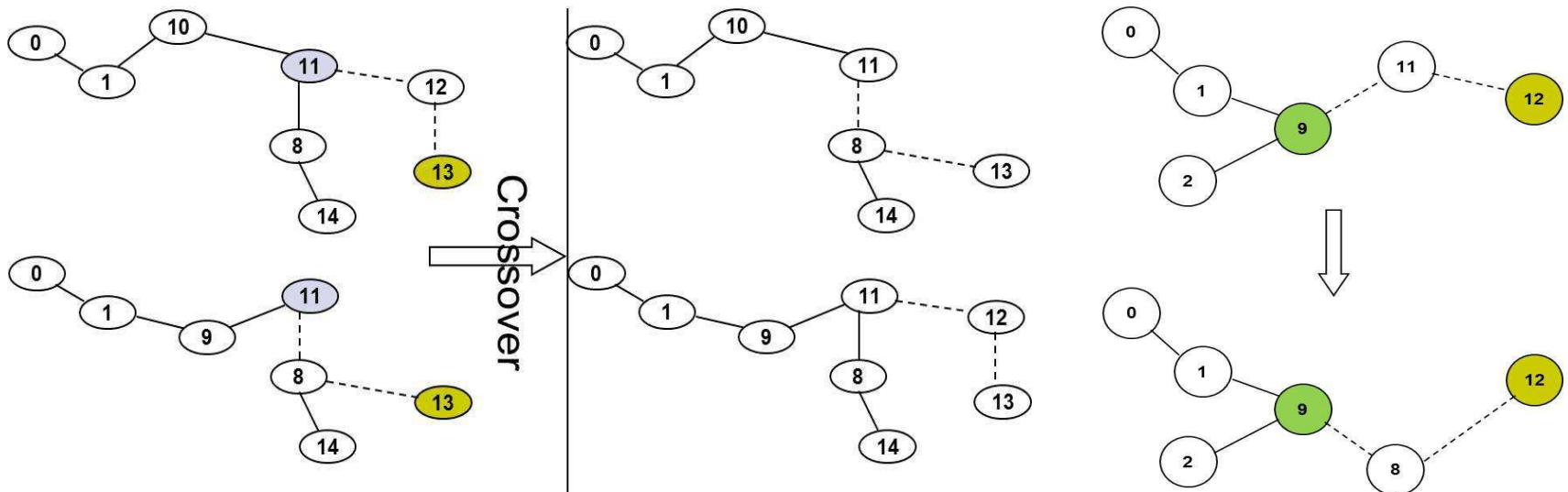
# Specialized GA for DSPRP in MANETs

- Path-oriented crossover with repair:

- Select two chromosomes with at least one common node
- Randomly select one common node, denoted as  $v$
- Exchange the two sub-paths from  $v$  to  $r$

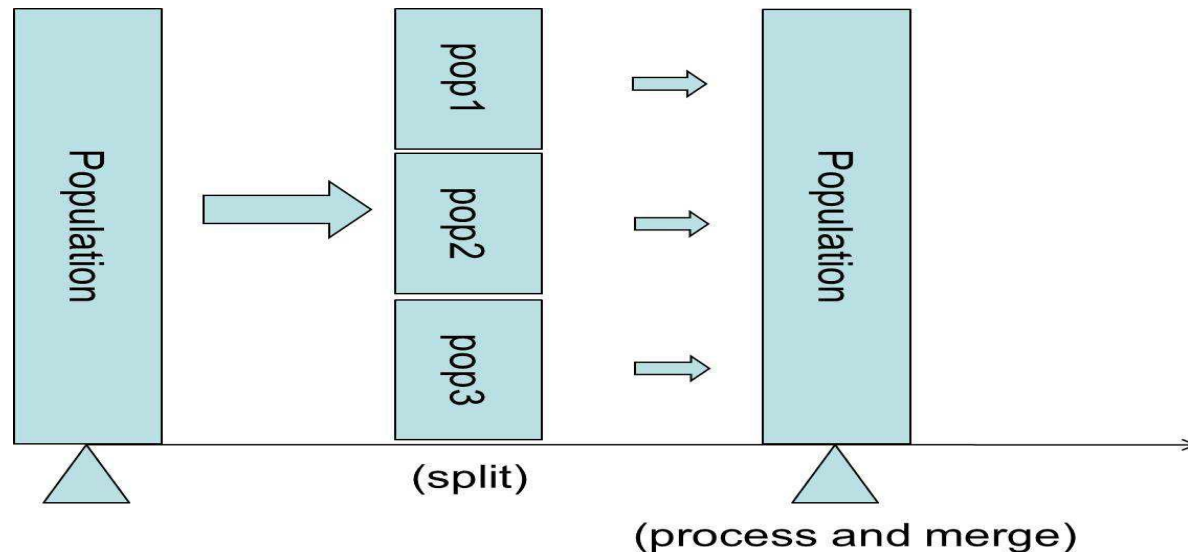
- Path-oriented mutation with repair

- Randomly select one node as the mutation point, denoted as  $v$
- Replace the sub-path from  $v$  to  $r$  by a new random one



# Immigrants Enhanced Multi-Pop GA (iMPGA)

- Enhance specialized GA with immigrants and multi-pop
- For a given change interval R
  - At the first half interval, the whole population evolve
  - Then, split the whole population into 3 subpops (2 child populations and 1 parent population)
- Each generation, a small number of random immigrants are added into parent subpop, responsible for exploration
- When a change interval ends, we process 3 subpops separately and then merge them





# Immigrants Enhanced Multi-Pop GA (iMPGA)

- Handling dynamic changes: When an environment change is detected, for each subpopulation:
  - If its best individual becomes infeasible, the whole subpop will be replaced by random solutions
  - If its best individual is feasible, only the infeasible individuals in the subpop will be replaced by random solutions

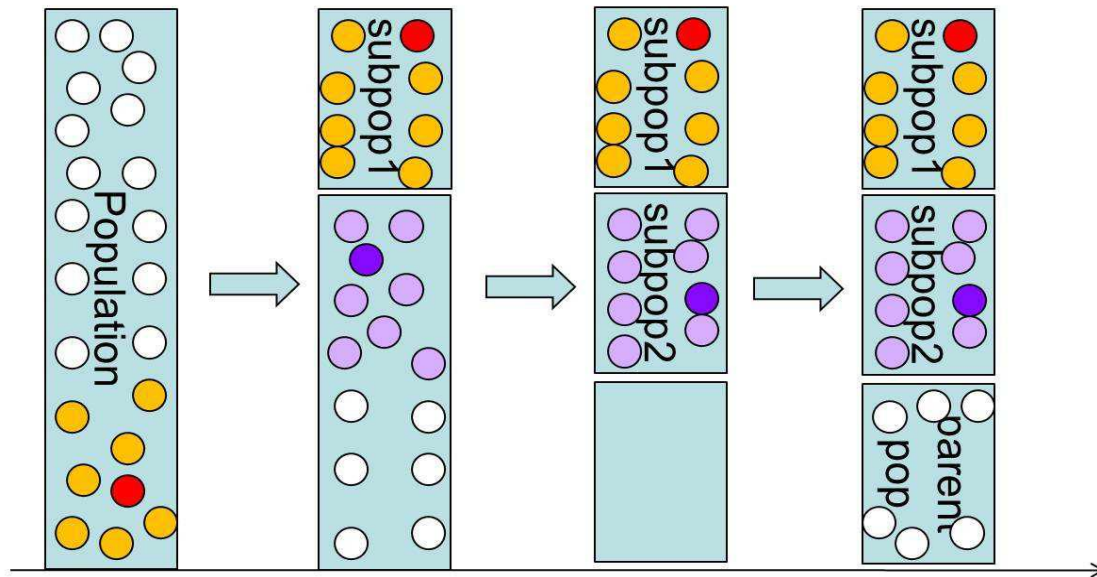
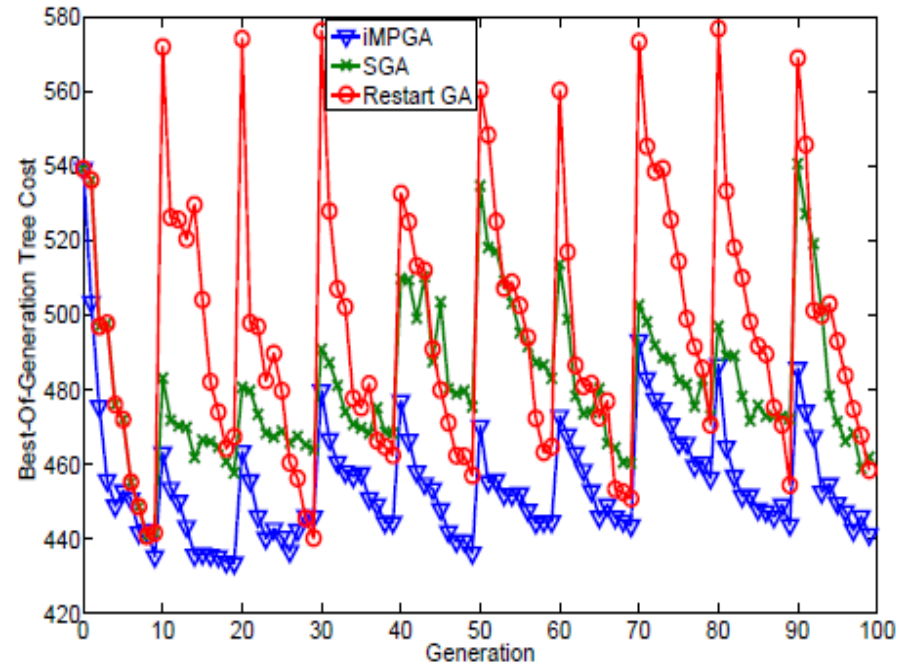
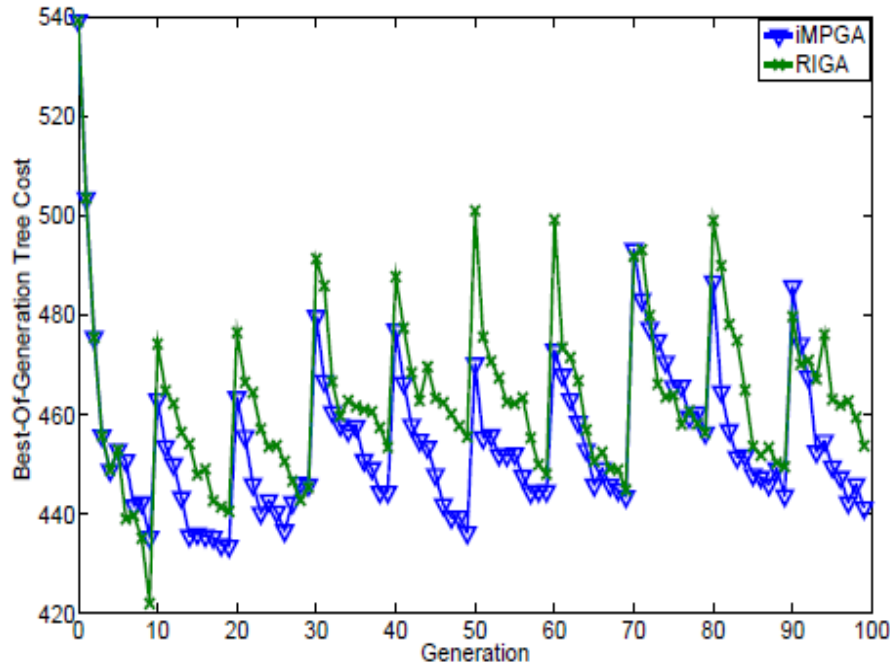


Illustration of the splitting

parent subpop: explore

two child subpops: exploit

# Immigrants Enhanced Multi-Pop GA (iMPGA)



- iMPGA outperforms traditional Gas
- Restart GA shows the worst performance
- iMPGA beats random immigrants GA (RIGA)
  - Multi-population improves GAs in handling dynamic environments

H. Cheng and S. Yang. Multi-population genetic algorithms with immigrants scheme for dynamic shortest path routing problems in mobile ad hoc networks. *EvoApplications 2010: Applications of Evolutionary Computing, Part I, LNCS*, vol. 6024, pp. 562-571, 2010

# Immigrants and Memory Based GAs

- Enhance the above specialized GA with immigrants and memory schemes
  - Random immigrants GA (RIGA)
  - Elitism-based immigrants GA (EIGA)
  - Hybrid immigrants GA (HIGA)
  - Memory-enhanced GA (MEGA)
  - Memory-enhanced random immigrants GA (MRIGA)
  - Memory-based immigrants GA (MIGA)

# Experimental Results

- Both immigrants and memory enhance GA's performance for the DSPRP in MANETs
- Immigrants schemes show their power in acyclic environments
- Memory related schemes work well in cyclic environments

Table: *t*-test results in acyclic environments

<i>t</i> -test Result	Topology Series #2			Topology Series #3		
Dynamics <i>R</i>	5	10	15	5	10	15
<i>RIGA</i> – <i>SGA</i>	s+	s+	s+	s+	s+	s+
<i>EIGA</i> – <i>SGA</i>	s+	s+	s+	s+	s+	s+
<i>HIGA</i> – <i>SGA</i>	s+	s+	s+	s+	s+	s+
<i>RIGA</i> – <i>HIGA</i>	+	+	+	–	–	–
<i>EIGA</i> – <i>HIGA</i>	–	–	–	–	–	–
<i>MEGA</i> – <i>HIGA</i>	s–	s–	s–	s–	s–	s–
<i>MRIGA</i> – <i>HIGA</i>	s–	s–	s–	s–	s–	s–
<i>MIGA</i> – <i>HIGA</i>	s–	s–	s–	s–	s–	s–

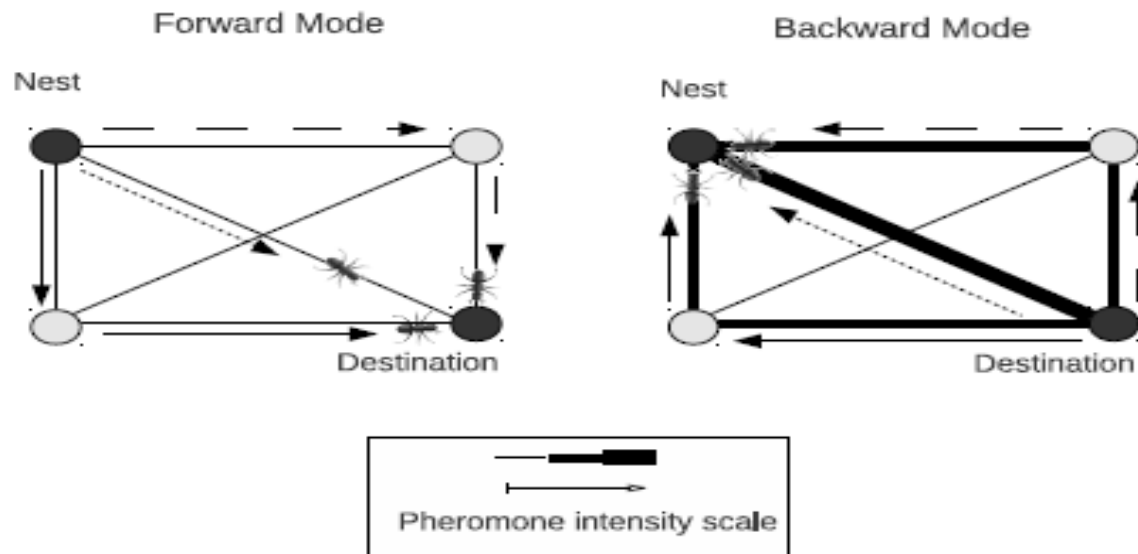
Table: *t*-test results in cyclic environments

<i>t</i> -test Result	Topology Series #1		
Environmental Dynamics <i>R</i>	5	10	15
<i>MEGA</i> – <i>SGA</i>	s+	s+	s+
<i>MRIGA</i> – <i>SGA</i>	s+	s+	s+
<i>MIGA</i> – <i>SGA</i>	s+	s+	s+
<i>MEGA</i> – <i>HIGA</i>	s+	s+	s+
<i>MRIGA</i> – <i>HIGA</i>	s+	s+	s+
<i>MIGA</i> – <i>HIGA</i>	s+	s+	s+

S. Yang, H. Cheng, and F. Wang. Genetic algorithms with immigrants and memory schemes for dynamic shortest path routing problems in mobile ad hoc networks. IEEE Transactions on Systems, Man, and Cybernetics Part C: Applications and Reviews, 40(1): 52-63, Jan. 2010.

# Case Study: ACO for Combinatorial DOPs

- Proposed by Dorigo et al. (1996)
- ACO mimics the behaviour of ants searching for food
- The idea: ants “walk” on the arcs of graph while “reading” and “writing” **pheromones** until they converge into a path
- The shorter the path the more pheromone deposited
- Standard ACO consists of two phases:
  - **Forward mode**: Construct solutions
  - **Backward mode**: Pheromone update

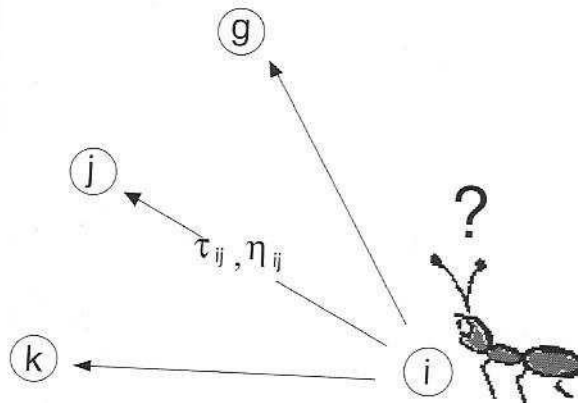


# Forward Mode: Construct Solutions

- Ant  $k$  constructs a tour probabilistically

$$p_{ij}^k = \frac{[\tau_{ij}]^\alpha [\eta_{ij}]^\beta}{\sum_{l \in N_i^k} [\tau_{il}]^\alpha [\eta_{il}]^\beta}, \text{ if } j \in N_i^k$$

- $\tau_{ij}$  is the existing pheromone between cities  $i$  and  $j$
- $\eta_{ij}$  is the heuristic information between cities  $i$  and  $j$
- $N_i^k$  is the list of nearest unvisited cities of city  $i$
- $\alpha$  and  $\beta$  are constant parameters that determine the influence of  $\tau$  and  $\eta$ , respectively



# Backward Mode: Pheromone Update

- Ant k updates its pheromone trails

- Deposit pheromone

$$\tau_{ij} \leftarrow \tau_{ij} + \Delta\tau_{ij}^k, \forall (i, j) \in T^k$$

- $T^k$  is the tour constructed by ant k
- $\Delta\tau_{ij}^k$  is the amount of pheromone to be deposited

- Evaporate pheromone

$$\tau_{ij} \leftarrow (1 - \rho) \tau_{ij}, \forall (i, j)$$

- where  $\rho$  is the evaporation rate
- Helps ants to “forget” bad decisions (poor solutions) made in the past (previous iteration): If an arc is not chosen by ants for a number of iterations, its associated pheromone value decreases exponentially

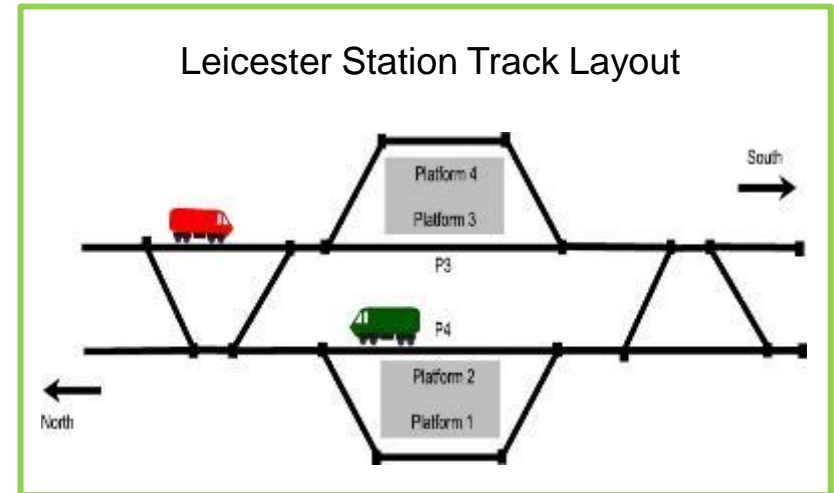


# ACO for Combinatorial DOPs

- A train that arrives late at a station will miss its scheduled time slot and may have to be reallocated to a new platform
- Multiple trains may be delayed in succession, each new delay changes the problem
- **Dynamic Railway Platform Reallocation Problem (DPRP)** reallocates multiple successive delayed trains to new timeslots on railway platforms to **minimise the ongoing delay in the system**



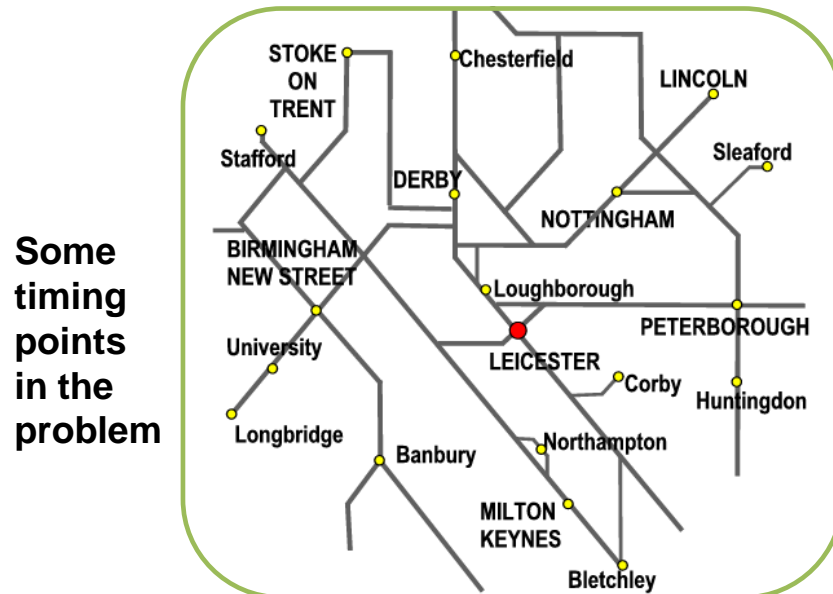
Image source: [https://en.wikipedia.org/wiki/Leicester\\_railway\\_station](https://en.wikipedia.org/wiki/Leicester_railway_station)



- We considered Leicester station
- A busy UK railway station with 4 bi-directional platforms and trains arriving from 4 different directions
- We consider the effect of the reallocation decisions not only at the station but also on the remainder of these trains' journey

# Modelling the Problem

- The model was created from Network Rail's train schedule data from Integrated Train Planning System (ITPS)
- From this we extract details of the movement of trains through the station and the movement of all trains at each timing point on each train's route
- We consider timing points within 50 miles of Leicester station (225 timing points)



### An example of the schedule feed data

H06408,NA,NA,D,600,D,NA,28  
LO,RATCFHH,NA,0434,NA,NA,NA,NA,NA,GL  
LI,TRENTJ,NA,NA,NA,NA,0437,NA,NA,NA  
LI,TRENT,NA,NA,NA,NA,0438,NA,NA,NA  
LI,BESTNSJ,NA,NA,NA,NA,0445H,NA,NA,NA  
LI,BESTONS,0447H,0516H,NA,NA,NA,NA,NA  
LI,BESTNSJ,NA,NA,NA,NA,0518H,NA,NA,NA  
LI,TRENT,NA,NA,NA,NA,0523,NA,NA,NA  
LI,TRENTJ,NA,NA,NA,NA,0525,NA,NA,GL  
LI,RATCLFJ,NA,NA,NA,NA,0527,NA,NA,SL  
LI,LOGHBRO,NA,NA,NA,NA,0536,USL,NA,NA  
LI,SILEBYJ,NA,NA,NA,NA,0542,NA,NA,NA  
LI,SYSTNSJ,NA,NA,NA,NA,0546,NA,NA,NA  
**LI,LESTER,NA,NA,NA,NA,0554H,3,SL,FL**  
LI,WGSTNNJ,NA,NA,NA,NA,0600,NA,NA,NA  
LI,CROFTS,NA,NA,NA,NA,0606,NA,NA,NA  
LI,HINCKLY,NA,NA,NA,NA,0616,NA,NA,NA  
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LI,STAFFRD,NA,NA,NA,NA,0717,5,SL,SL  
LI,NTNB,NA,NA,NA,NA,0724,NA,SL,SL

# Leicester Station Simulation

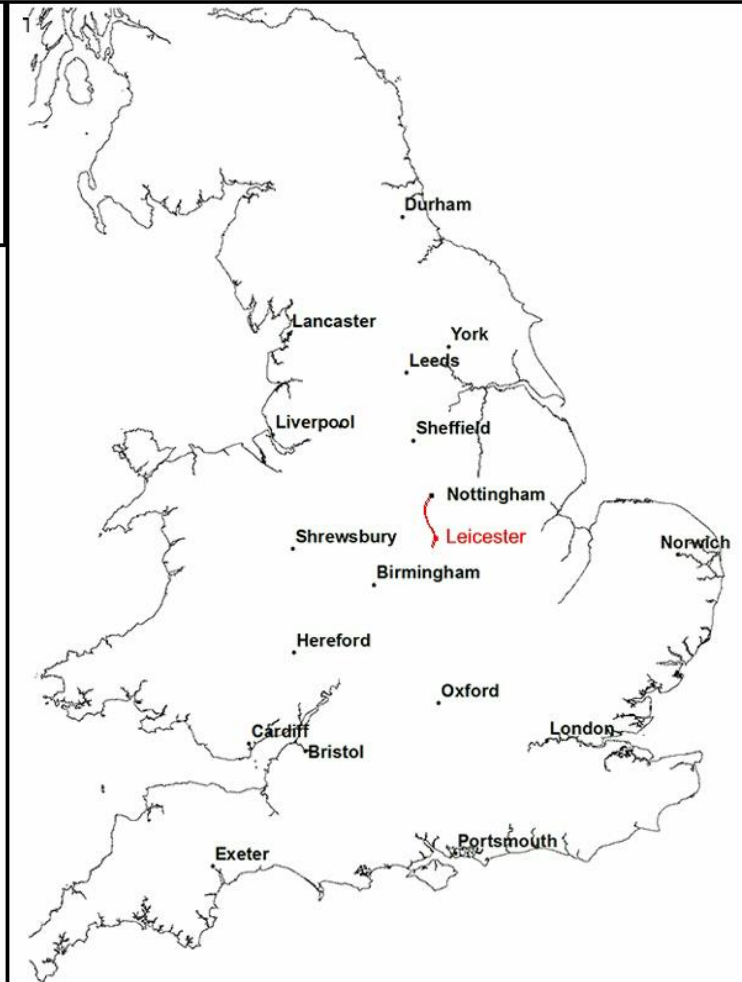
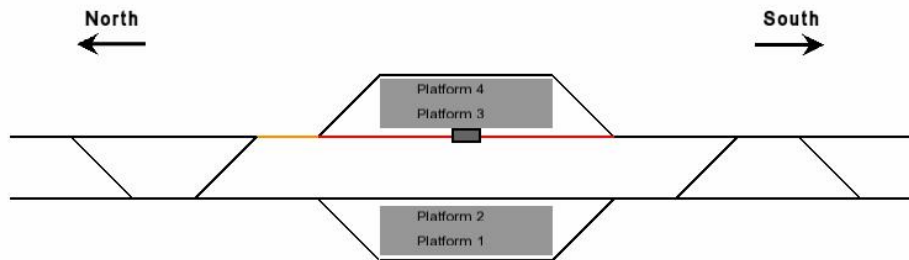
Leicester Station

**Leicester Station**

**06:24**

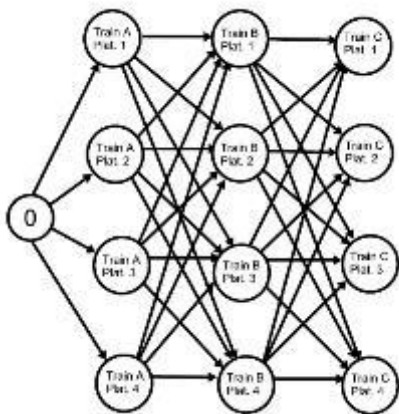
C82330- Platform: 3

Originates at Station

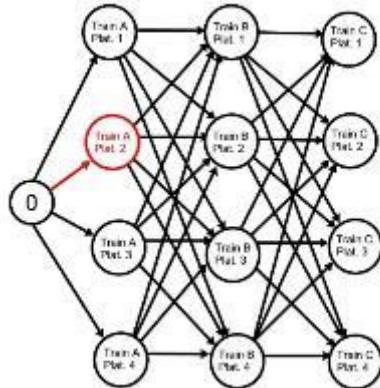


# Max-Min Ant System (MMAS)

- In ACO ants communicate indirectly via pheromone trails
- We model the problem with a directed edge graph
- Ants choose next node based on pheromone trails and problem-specific heuristics

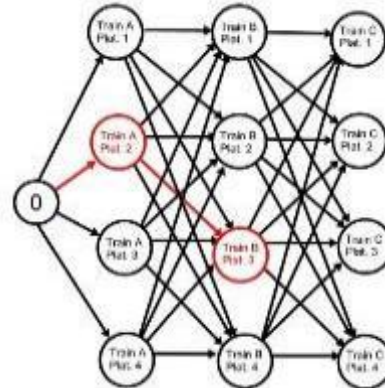


Each node in the graph represents a train and the platform to assign the train to



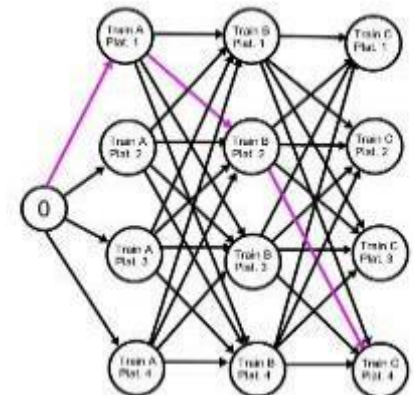
An ant starts on node 0  
The ant chooses next node probabilistically

**Ant Solution:**  
<Train A on Platform 2>



The ant now chooses the next train & platform

**Ant Solution:**  
<Train A on Platform 2,  
Train B on Platform 3>



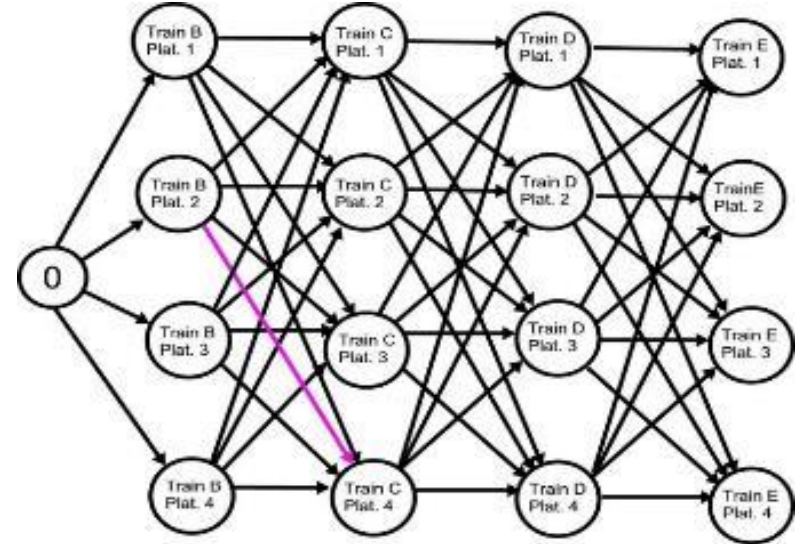
- After all ants have made a tour, all pheromone trails are evaporated
- Pheromone is laid down on the best ant's tour



# Algorithm Design

## After a Dynamic Change:

- More trains have arrived but some trains have passed through the station
- The graph is updated but pheromones are kept between changes to retain useful information from before change



## Unnecessary Platform Reallocation:

- MMAS has no mechanism to persuade it against unnecessarily reallocating trains to platforms. To resolve this we:
  1. Add a heuristic based on the physical distance between platforms
  2. Introduce a best-so-far ant replacement scheme that discourages unnecessary reallocations of trains to new platforms



Image source: <http://www.adelaidenow.com.au//>

# Comparison Algorithm

## First Free Platform (FFP)

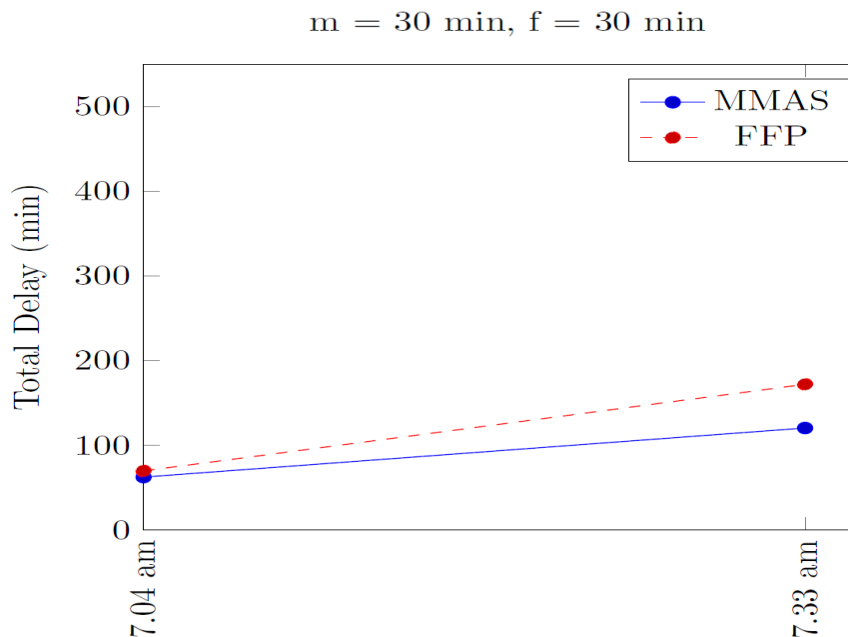
- Discussions with a Network Rail Station Master established that a technique often used to reallocate delayed trains to platforms is **to find the first free platform as close as possible to the original platform**
  - We compared our MMAS algorithm to a heuristic using this principle
- 

## Modelling Dynamism

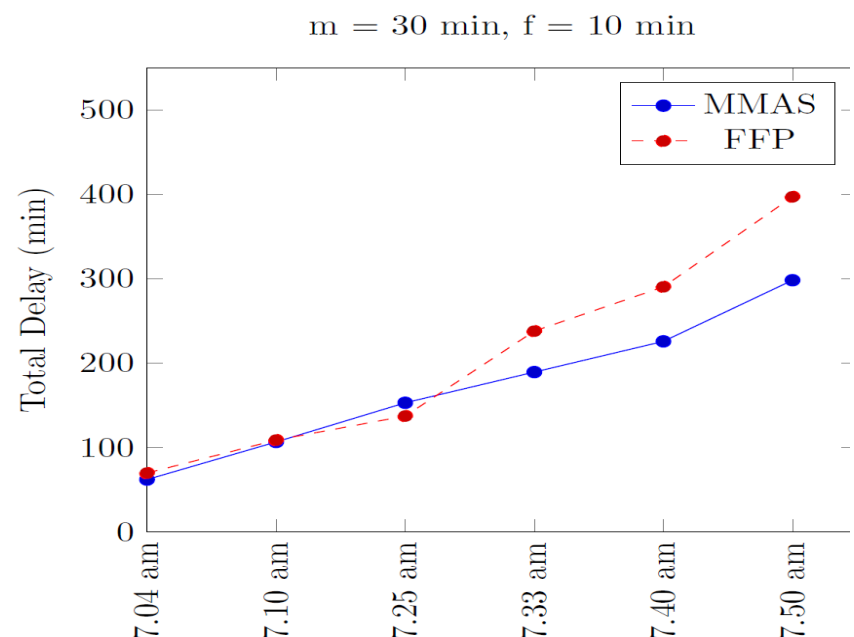
The **frequency of change  $f$**  is the time interval between delayed trains.  
The **magnitude of change  $m$**  is how much the train is delayed by

In this investigation trains were delayed by 10, 20 and 30 min with gaps of 10, 20 and 30 min to give 9 different dynamic scenarios

# Experimental Results



Low frequency, high magnitude changes



High frequency, high magnitude changes

**Table 1.** One-Sample Wilcoxon Signed Rank Test Results at 0.05 Significance

Algorithms	m=30			m=20			m=10		
	f=10	f=20	f=30	f=10	f=20	f=30	f=10	f=20	f=30
MMAS $\Leftrightarrow$ FFP	s+	s+	s+	s+	s+	s+	s+	s+	s+



# Part III: Advanced Topics

- EC for Dynamic Multi-objective Optimization
- EC for DOPs: Theoretical Development
- EC for DOPs: Challenging Issues
- EC for DOPs: Future Work

# EC for Dynamic Multi-objective Optimization

- So far, mainly dynamic single-objective optimization
- Dynamic multi-objective optimization problems (DMOPs)
  - Even more challenging
- Recently, rising interest in studying EC for DMOPs
  - Farina et al. (2004) classified DMOPs by changes on Pareto optimal solutions
  - Goh & Tan (2009) proposed a competitive-cooperative coevolutionary algorithm for DMOPs
  - Zeng et al. (2006) proposed a dynamic orthogonal multi-objective EA (DOMOEa) to solve a DMOP with continuous decision variables
  - Zhang & Qian (2011) proposed an artificial immune system to solve constrained DMOPs
  - Jiang & Yang (2017a) proposed a new benchmark MDOP generator
  - Jiang & Yang (2017b) proposed a Steady-Generational EA for DMOPs
  - Ruan et al. (2017) analyzed the effect of diversity maintenance on prediction for DMOPs
  - Eaton et al. (2017) applied ACO for the dynamic multi-objective railway junction rescheduling problem

# EC for DOPs: Theoretical Development

- So far, mainly empirical studies. Theoretical analysis has recently appeared
- Runtime analysis:
  - Stanhope & Daida (1999) first analyzed (1+1) EA on the dynamic bit matching problem (DBMP)
  - Droste (2002) analyzed first hitting time of (1+1) ES on the DBMP
  - Rohlfshagen et al. (2010) analyzed how the magnitude and speed of change may affect the performance of the (1+1) EA on two functions constructed from the XOR DOP generator

- S. Droste. Analysis of the (1+1) EA for a dynamically changing onemax-variant. CEC'02, pp. 55-60, 2002
- S.A. Stanhope, J.M. Daida. (1+1) genetic algorithm fitness dynamics in a changing environments. Proceedings of the 1999 IEEE Congress on Evol Comput, vol. 3, pp. 1851-1858, 1999.
- P. Rohlfshagen, P.K. Lehre, X. Yao. Dynamic evolutionary optimisation: An analysis of frequency and magnitude of change. GECCO'09, pp. 1713-1720, 2009.

# EC for DOPs: Theoretical Development

- Analysis of dynamic fitness landscape:
  - Branke et al. (2005) analyzed the changes of fitness landscape due to changes of the underlying problem instance
  - Richter (2010) analyzed the properties of spatio-temporal fitness landscapes constructed from Coupled Map Lattices (CML)
  - Tinos & Yang (2010, 2014) analyzed properties of the XOR DOP generator based on the dynamical system approach of the GA

- J. Branke, E. Salihoglu, S. Uyar. Towards an analysis of dynamic environments. GECCO'05, pp. 1433-1439, 2005.
- H. Richter. Evolutionary optimization and dynamic fitness landscapes: From reaction-diffusion systems to chaotic cml. Evolutionary Algorithms and Chaotic Systems, Springer, pp. 409-446, 2010.
- R. Tinos, S. Yang. An analysis of the XOR dynamic problem generator based on the dynamical system. PPSN XI, LNCS 6238, Part I, pp. 274-283, 2010.
- R. Tinos, S. Yang. Analysis of fitness landscape modifications in evolutionary dynamic optimization. Inform. Sci., 282: 214-236, 2014.

# EC for DOPs: Challenging Issues

- Detecting changes:
  - Most studies assume that changes are easy to detect or visible to an algorithm whenever occurred
  - In fact, changes are difficult to detect for many DOPs
- Understanding the characteristics of DOPs:
  - What characteristics make DOPs easy or difficult?
  - Little work, needs much more effort
- Analysing the behaviour of EC methods for DOPs:
  - Requiring more theoretical analysis tools
  - Big question: Which EC methods for what DOPs?
- Real world applications:
  - How to model real-world DOPs?

# EC for DOPs: Future Work

- The domain has attracted a growing interest recently
  - But, far from well-studied
- New approaches needed: esp. hybrid approaches
- Theoretical analysis: greatly needed
- EC for DMOPs: deserves much more effort
- Real world applications: also greatly needed
  - Fields: logistics, transport, MANETs, data streams, social networks, ...



# Summary

- EC for DOPs: important area
  - The domain is still young and active
  - Many challenges to be taken
- More young researchers are greatly welcome!



Thanks!

# Relevant Information

- IEEE CIS Task Force on EC in Dynamic and Uncertain Environments
  - <http://ieee-tf-ecidue.cug.edu.cn/>
- Source codes:
  - <http://www.tech.dmu.ac.uk/~syang/publications.html>
- Two EPSRC funded projects on EC for DOPs
  - “EAs for DOPs: Design, Analysis and Applications”
    - Funding/Duration: over £600K/3.5 years (1/2008–7/2011)
    - <http://gtr.rcuk.ac.uk/project/B807434B-E9CA-41C7-B3AF-567C38589BAC>
  - “EC for Dynamic Optimisation in Network Environments”
    - Funding/Duration: ~£1M/4.5 years (2/2013–8/2017)
    - <http://gtr.rcuk.ac.uk/project/C43F34D3-16F1-430B-9E1F-483BBADCD8FA>