Project Title:

Controlling Firebird V using EEG sensor (Brainwave sensor)

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Abstract

If suppose using our attention and meditation power we could control any specific activity then it would reduce the human effort. With increase in field of technology everything is obtained very easily. This has made a normal person go away from understanding what his/her brain can achieve. This project of Controlling Firebird V using EEG sensor is a prototype of controlling any activity using concentration power of human. In this project, Neurosky Mindwave mobile is used as EEG sensor which measures attention and meditation power of a person. This data is manipulated and made to control Firebird V. Bluetooth is used as a medium to communicate from sensor to bot. The velocity of forward motion is varied depending upon the attention level of the person, while detection of two eye-blinks will make the bot rotate left. The left motion continues until the third eye-blink is detected making the bot move forward again depending upon the velocity which is proportional to the attention level of the user. When the sensor is removed from head, the bot stops to move.

Introduction

We are living in 21^{st} century-an era for automation, modern technology. In India nearly 1.5% of total population are affected by paralysis. In America 1.9% of total population is affected by paralysis. In paralysis the crucial condition is not able to move any of the body part. Around 1 out of 50 children is mentally challenged all over the world according to data calculated in 2013. Considering these conditions, this project is developed in order to help reduce the effort for paralysed people and to increase the mind capacity of the mentally challenged children.

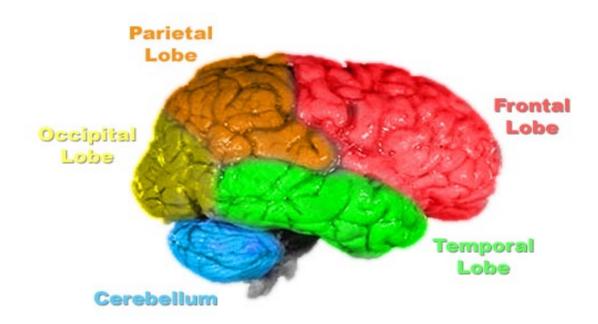


1. About EEG:

Electroencephalography (EEG) is a non-invasive method to record electrical activity of the brain along the scalp. EEG measures voltage fluctuations resulting from ionic current within the neurons of the brain. In clinical contexts, EEG refers to the recording of the brain's spontaneous electrical activity over a period of time, as recorded from multiple electrodes placed on the scalp.

The brain's electrical charge is maintained by billions of neurons. Neurons are electrically charged (or "polarized") by membrane transport proteins that pump ions across their membranes. Neurons are constantly exchanging ions with the extracellular milieu, for example to maintain resting potential and to propagate action potentials. Ions of similar charge repel each other, and when many ions are pushed out of many neurons at the same time, they can push their neighbours, who push their neighbours, and so on, in a wave. This process is known as volume conduction. When the wave of ions reaches the electrodes on the scalp, they can push or pull electrons on the metal on the electrodes. Since metal conducts the push and pull of electrons easily, the difference in push or pull voltages between any two electrodes can be measured by a voltmeter. Recording these voltages over time gives us the EEG.

2. About Brainwayes:



- (a) Gamma waves are oscillating waves with frequencies around 40 Hz, although they can be as high as 100 Hz and as low as 24 Hz. These originate from the thalamus (buried deep in the centre of the brain) and are responsible for states of high attention and concentration.
- (b) Beta waves are between 12 and 30 Hz and are the states associated with normal waking consciousness. These are emitted from the motor cortex, a region of the cerebral cortex, which is the outermost layer of tissue on the brain. Beta waves are split into three sections: Low Beta Waves (12.5-16 Hz, Beta 1 power); Beta Waves (16.520 Hz, Beta 2 power); and High Beta Waves (20.5-28 Hz, Beta 3 power).
- (c) Alpha waves originate at the Occipital lobe and have a frequency of 8-12Hz. These are most present when you are awake but are very drowsy or relaxed.
- (d) Theta waves are oscillating waves that are located in the Hippocampus and are associated with dreaming. They are in the 4-7Hz range.
- (e) Delta wavis are associated with very deep, dreamless sleep cycles and are high amplitude waves, which have a 0 to 3Hz frequency. These waves emit from both the thalamus and the cortex.

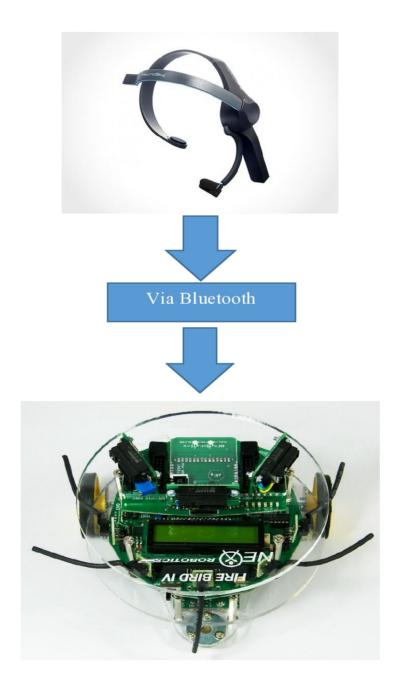
3. Objectives:

- (a) The main objective is to Control Firebird V bot using EEG sensor (brainwave sensor) which records the attention, meditation power and eye-blink of the user and not his/her thoughts.
- (b) This theme can be implemented to control Wheelchair for paralyzed people.
- (c) We can also play games in which the person with more concentration power wins.

4. Tasks performed and Deadlines:

Sr. No.	Tasks	Deadlines
1.	Understanding Brainwaves and about EEG sensor(Mindwave mobile headset)	3 days
2.	Configuring bluetooth module with sensor	2 days
3.	Avalysing and Processing Brainwave values.	4 days
4.	Interfacing Sensor to Firebird V via BVuetooth.	3 days
5.	LED Bar graph blinking based on Attention level	5 days
6.	Controlling Firebird V motions using attention level and eye-blink	6 days
7.	Documentation	5 days

Block Diagram



- $\bullet\,$ Velocity proportional to Attention level of the person.
- Two eye-blink will give left turn continuously.
- Furthermore one eye-blink will again make bot to move forward.

Working of the project

Neurosky Mindwave headset (Brainwave sensor) communicates with the help of data packets. Following is the pattern in which data bytes are sent:
[SYNC] [SYNC] [PLENGTH] [PAYLOAD...] [CHKSUM]

^^^^^^ (Header) ^^^^^^ (Payload) ^^ (Checksum)

The two [SYNC] bytes are used to signal the beginning of a new arriving Packet and are bytes with the value 0xAA (decimal 170). Synchronization is two bytes long, instead of only one, to reduce the chance that [SYNC] (0xAA) bytes occurring within the Packet could be mistaken for the beginning of a Packet. The [PLENGTH] byte indicates the length, in bytes, of the Packet's Data Payload [PAYLOAD] section, and may be any value from 0 up to 169. Any higher value indicates an error (PLENGTH TOO LARGE). Be sure to note that [PLENGTH] is the length of the Packet's Data Payload, NOT of the entire Packet. The Packet's complete length will always be [PLENGTH] + 4.

The [CHKSUM] Byte must be used to verify the integrity of the Packet's Data Payload. The Payload's Checksum is defined as:

- summing all the bytes of the Packet's Data Payload
- taking the lowest 8 bits of the sum
- performing the bit inverse (one's compliment inverse) on those lowest 8 bits

Program the bot according to the data packets being received. Following are the analysed data from the Neurosky Mindwave mobile:

- We obtain only two types of data packets. Payload length of 0x04 and 0x20.
- The 0x04 payload length data packet consists of raw values which indicates mainly the connection of headset on head, pairing values, and eye-blink data values which are send when scalp touched to cathode and anode are moved.
- The 0x20 payload length data packet consists of poor quality indication, attention level indication and meditation level indication.
- 0x02 indicates poor quality detection. The next byte to that indicates poor quality signal level. For eye-blink detection this value should be 0.
- 0x04 indicates attention level detection. The next byte to that indicates level of attention.
- \bullet 0x05 indicates meditation level detection. The byte next to 0x05 indicates meditation level achieved.
- 0x02 always appear next to 0x20 i.e. next to payload length.
- 0x04 always appear at 28th position of payload data and 0x05 always appear at 30th position of payload data.
- For attention, meditation and poor quality detection 0x20 byte long payload data is useful.
- \bullet For eye-blink detection 0x04 byte long payload data is useful.

Thus by using above analysed data Firebird V is programmed to move forward according to attention level and turn left depending upon eye-blink strength.

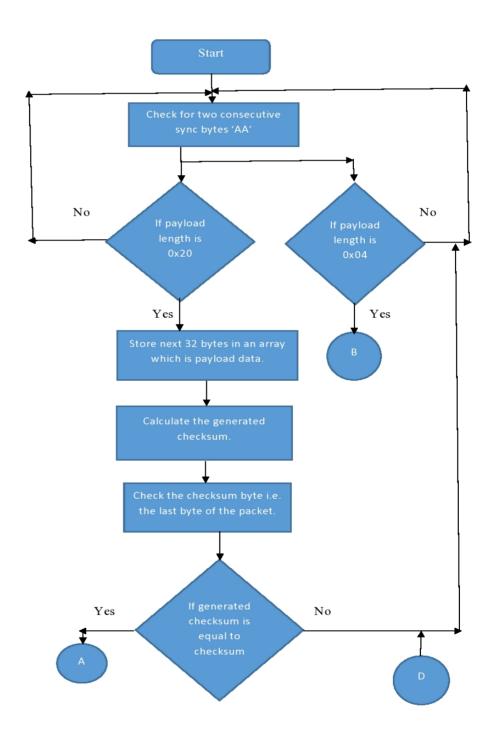
Progarm Description

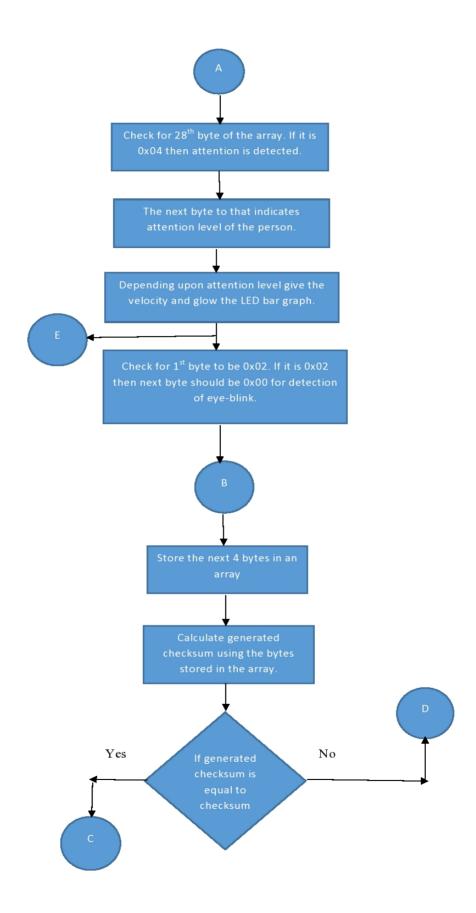
Program to display Attention level of a person on LED bargraph and give the velocity of bot depending on it. Rotate left after detection to two eyeblinks..

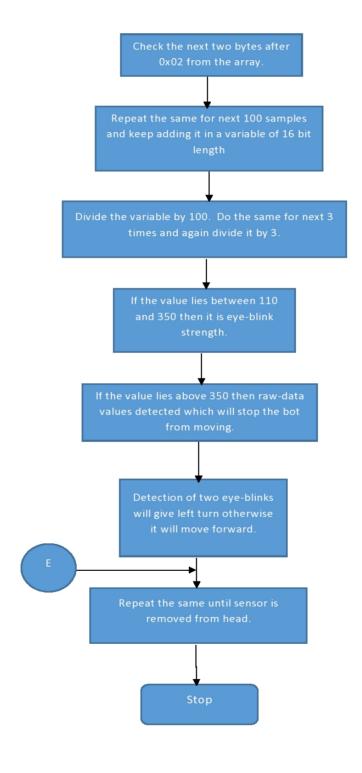
1. Algorithm:

- (a) Initialize all required ports.
- (b) Check for two consecutive SYNC bytes AA.
- (c) Check for third byte which is the payload length.
- (d) If payload length is 0x20, then store the next 32 bytes in an array. If payload length is 0x04 then move to step no. 11
- (e) Calculate the generated checksum.
- (f) If the last byte i.e. checksum byte of the data packet is equal to the generated checksum then check for 28th byte of the array.
- (g) If 28th byte is 0x04, then attention detected.
- (h) Then 29th byte indicates attention level of the person between 0-100.
- (i) Give velocity to the bot depending on the attention level.
- (j) Check for 1st byte of the array. If it is 0x02, then next byte to it should be 0x00, then eye-blink can be detected.
- (k) If payload length is 0x04, then store the next 4 bytes in an array.
- (l) Store the 1st and 2nd byte after 0x02 of the array in a variable and keep adding it for next 100 data packets.
- (m) After taking average by 100, Eye-blink strength is between 110 and 350 and raw data values ranges above 350.
- (n) Now repeat from step 11 and 12 three times and check the eye-blink strength.
- (o) If eye- blink is given then its value will range between 110 and 350.
- (p) Detection of such two eye-blinks will turn the bot left.
- (q) In order to stop the bot, remove the sensor from head. It will give values above 350.

2. Flowchart:







Components and its Configuration

1. Bluetooth module (JY-MCU):

This bluetooth module is interfaced on Firebird V robot. Following are the AT commands given:

- AT
- AT+NAME=EEG
- AT+PSWD=0000
- AT+CMODE=0
- AT+UART=9600,0,0
- AT+ROLE=1
- AT+BIND=XXXX,YY,ZZZZZZ (Mindwave Unique Number (20:68:9d:88:c1:d7))
- AT+IAC=9E8B33
- AT+CLASS=0
- AT+INQM=1

2. Firebird V connecniots:

- (a) Connect Bluetooth on Firebird V.
- (b) Make use of expansion slot of UART connections.
- (c) Connect to 37 and 38 pin no. of expansion slot. 37 pin no. indicates TXD and 38 pin no. indicates RXD.
- (d) Connect RXD of bluetooth module to TXD of Firebird V and vice versa.
- (e) Connect VCC to pin no.1 of and GND to pin no.2 of expansion slot.
- (f) Now pair your headset with bluetooth module.

3. Neurosky Mindwave mobile:

This is an EEG sensor which communicates via bluetooth sending data packets.

Problems faced and resolved:

1. UART problem:

Initially we used UART 2 for interfacing bluetooth but it created the problem and half of data values were not getting received. This was because the same UART was used for bootloader.

Solution:

We changed the connection to UART 1 in the expansion slot.

2. ISR problem:

The given ISR SIGNAL(SIG_USART1_RECV) used to receive the incoming data and store in a variable. Mindwave mobile sends data at 512 symbols per second. Due to low processing speed most of the data values used to get lost.

Solution: Instead of using a single variable to store the incoming data, we used buffer were data values were stored without getting lost.

3. Eye-bink data values:

The eye-blink data values are similar to the raw-data values when sensor is removed from the head. So to distinguish between them is the problem faced.

Future Scope

- In the society there are many children around who are mentally disabled and cannot have their mind stable. If there is a game available for them in which they are made to control a robot or a car according to the attention and meditation power then they will try to control it. This might increase their concentration power over a period of time if they practice it every day.
- Similarly Paralysed people who cannot move their body parts can be able to control their wheelchair using their attention level and eye-blink.
- Using this project if we make game based on the attention and meditation level of a person, there will be definitely growth in his/her mental ability.

References

- Firebird V hardware and software manuals.
- Neurosky Mindwave Headset datasheets.
- \bullet JY-MCU and HC-05 Bluetooth module data sheets.
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- $\bullet \ \, \text{https://www.pantechsolutions.net/mind-meditation-control-led-using-arduino}$
- https://www.pantechsolutions.net/eye-blink-control-led-using-arduino

Softwares used:

- Atmel Studio 6.0
- AVR bootloader
- Arduino
- Arduino Processing