



# CLOUD COMPUTING CONCEPTS

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## MEMBERSHIP

Lecture D

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WHICH IS THE BEST FAILURE DETECTOR?

# FAILURE DETECTOR PROPERTIES ...

- Completeness
- Accuracy
- Speed
  - Time to first detection of a failure
- Scale
  - Equal Load on each member
  - Network Message Load

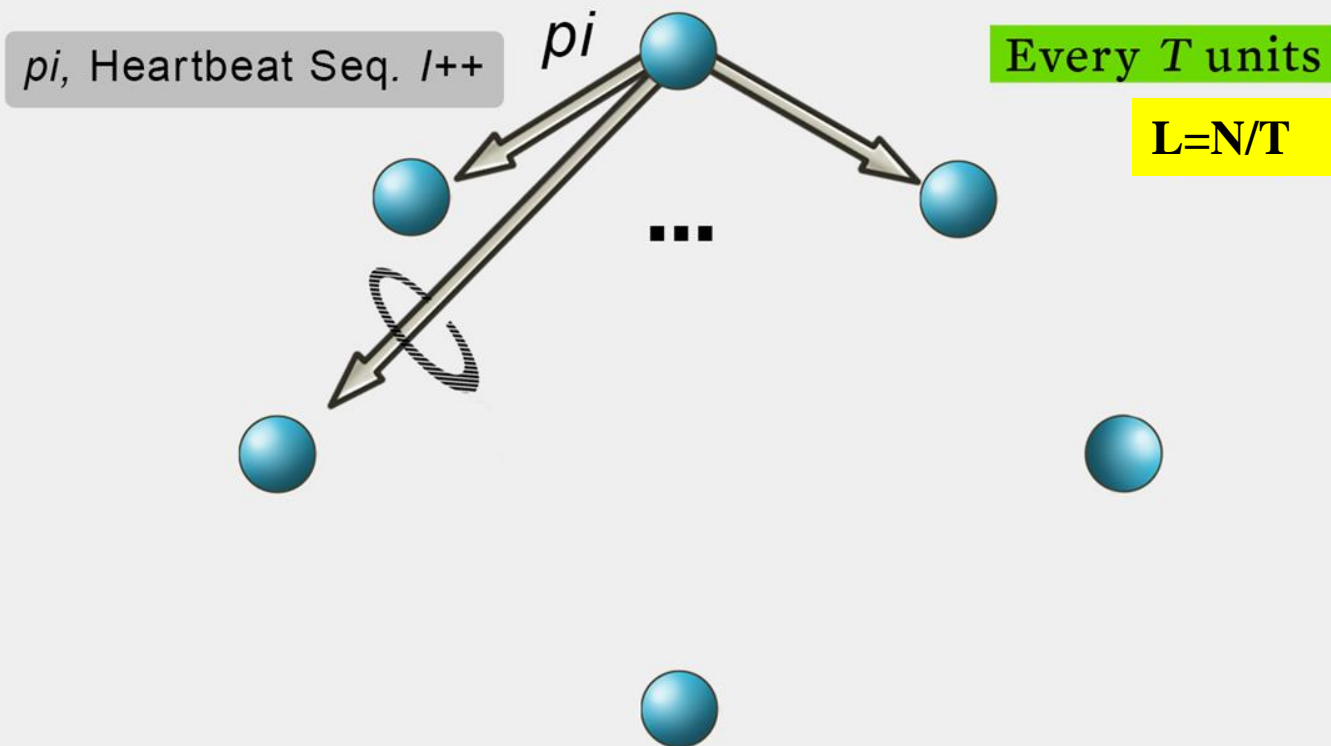
# FAILURE DETECTOR PROPERTIES ...

- Completeness Guarantee always
- Accuracy Probabillity  $PM(T)$
- Speed  $T$  time units
  - Time to first detection of a failure
- Scale
  - Equal Load on each member
  - Network Message Load

# FAILURE DETECTOR PROPERTIES ...

- Completeness Guarantee always
- Accuracy Probabillity  $PM(T)$
- Speed  $T$  time units
  - Time to first detection of a failure
- Scale  $N * L$  Compare this across protocols
  - Equal Load on each member
  - Network Message Load

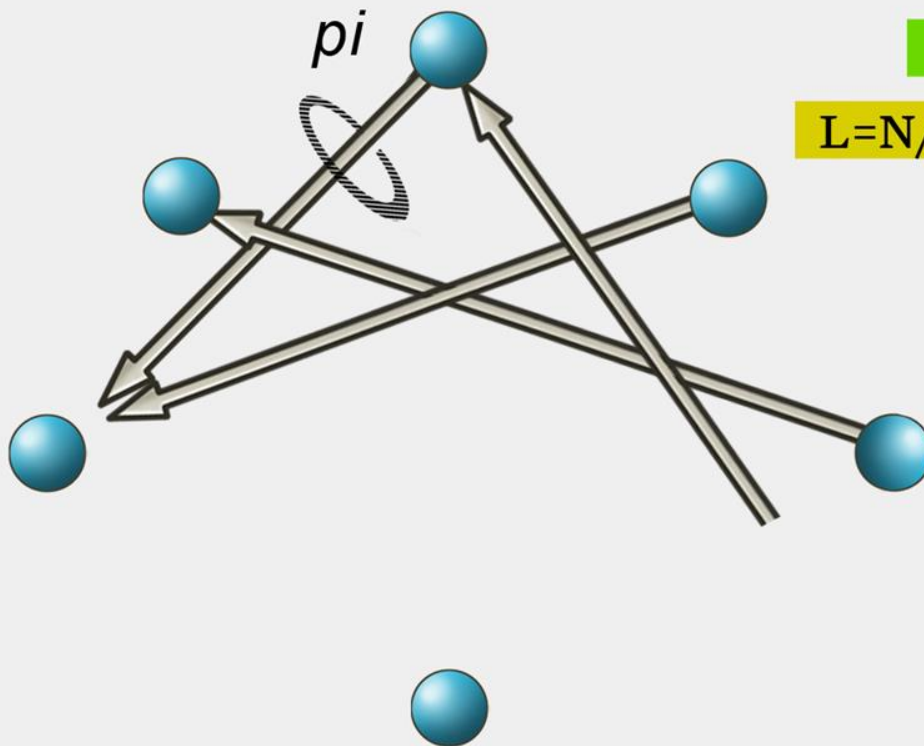
# ALL-TO-ALL HEARTBEATING



# ALL-TO-ALL HEARTBEATING

Array of  
Heartbeat seq.  $l$   
for member subset

Every  $tg$  units  
= gossip period,  
send  $O(N)$  gossip  
message



$$T = \log N * tg$$

$$L = N / tg = N * \log N / T$$

# WHAT'S THE BEST/OPTIMAL WE CAN DO?

- Worst case load  $L^*$

as a function of  $T$ ,  $PM(T)$ ,  $N$

Independent Message Loss probability  $p_{ml}$

$$L^* = \frac{\log(PM(T))}{\log(p_{ml})} \cdot \frac{1}{T}$$

(try to work out the proof)

# WHAT'S THE BEST/OPTIMAL WE CAN DO?

- Optimal  $L$  is independent of  $N$  (!)
- All-to-all and gossip-based: sub-optimal
  - $L=O(N/T)$
  - try to achieve simultaneous detection at **all** processes
  - fail to distinguish *Failure Detection* and *Dissemination* components

Key:

- Separate the two components
- Use a non heartbeat-based Failure Detection Component



# NEXT

- Is there a better failure detector?