

# Graph Algorithms I

## Breadth First Search

# Graphs

Graph  $G = (V, E)$

$V$ : Set of Nodes (Vertices)

$E$ : Set of Edges

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$V$ : Set of Nodes (Vertices)

$E$ : Set of Edges

Let  $|V| = n$

Let  $|E| = m$



## Undirected graph:

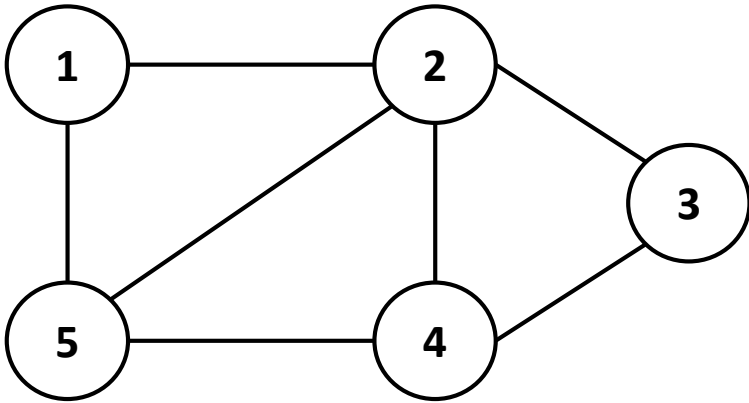
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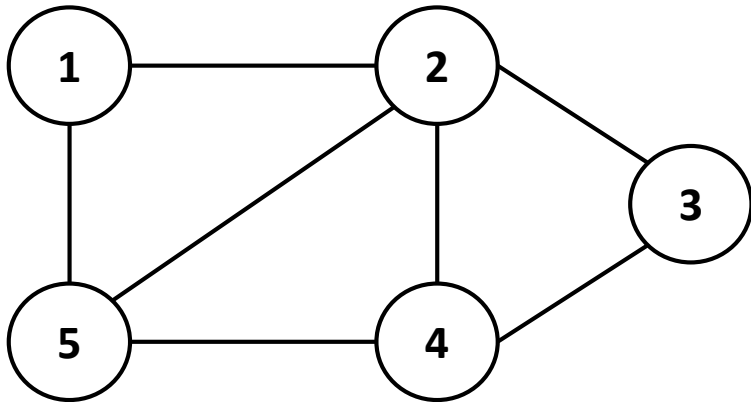
Example:



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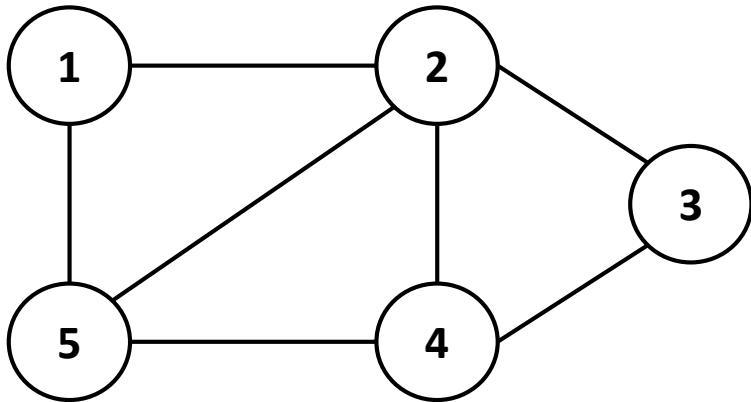


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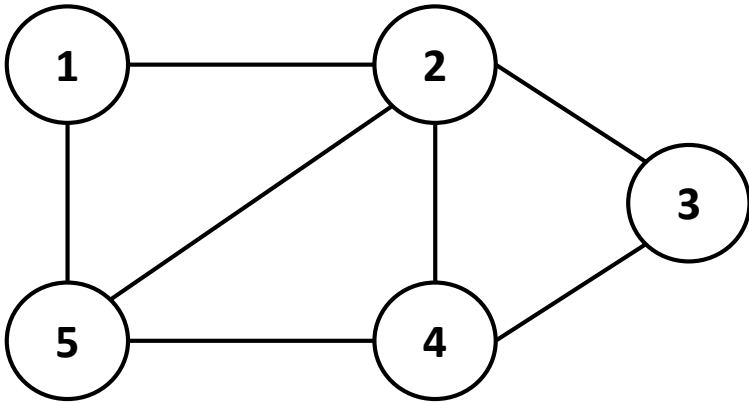
$$E = \{ (1, 2), (1, 5), (2, 5), (2, 4), \\ (4, 5), (3, 2), (3, 4) \}$$



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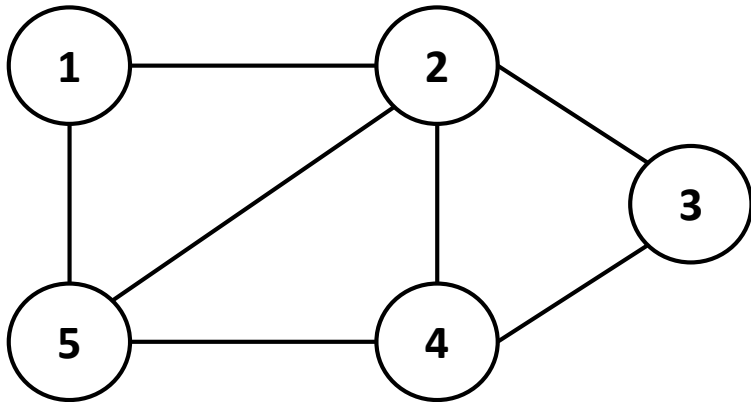
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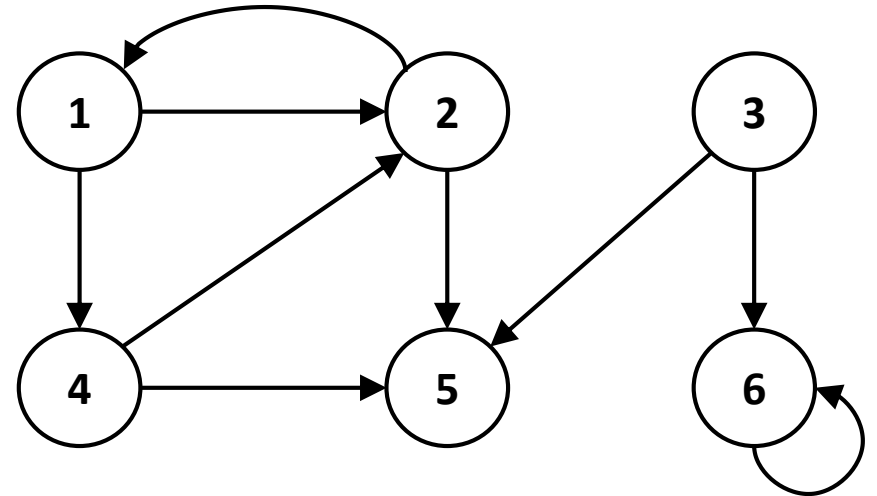
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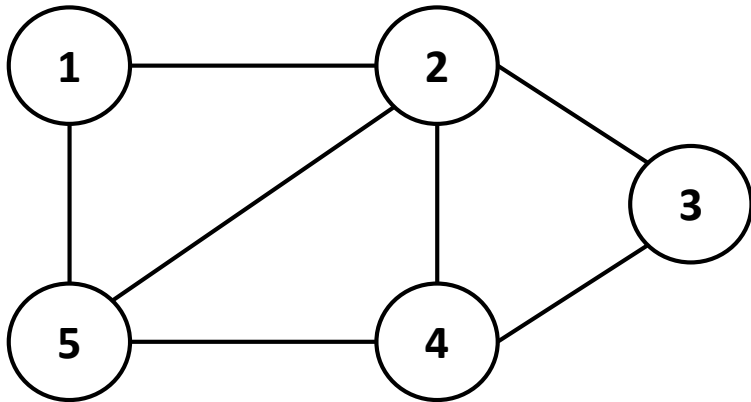
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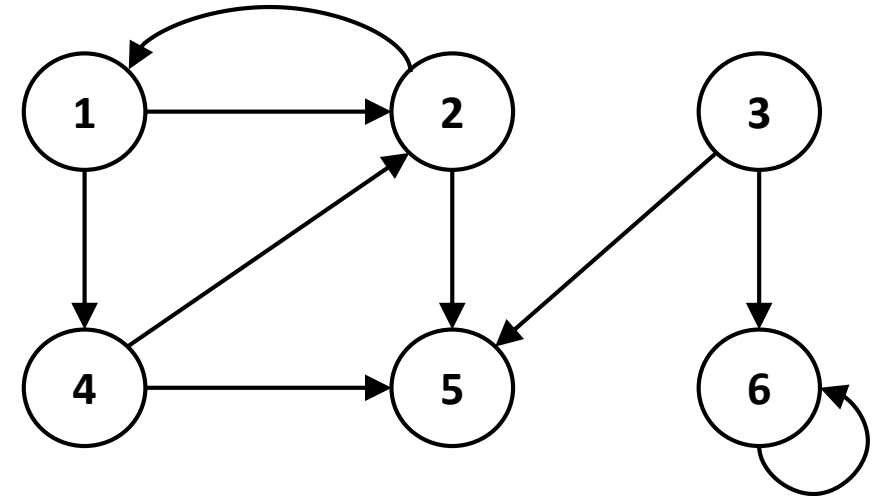
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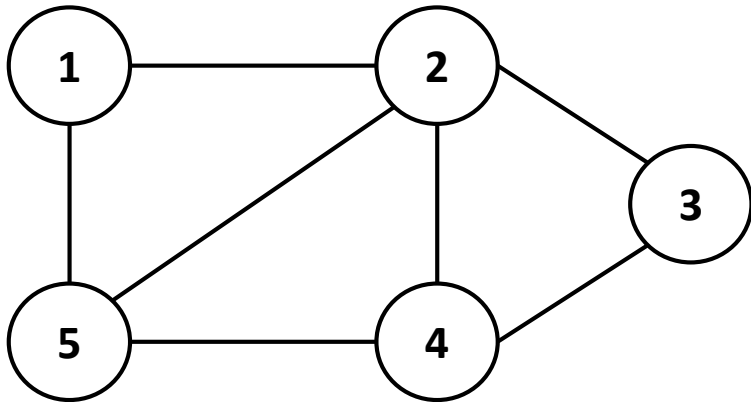


$$V = \{1, 2, 3, 4, 5, 6\}$$

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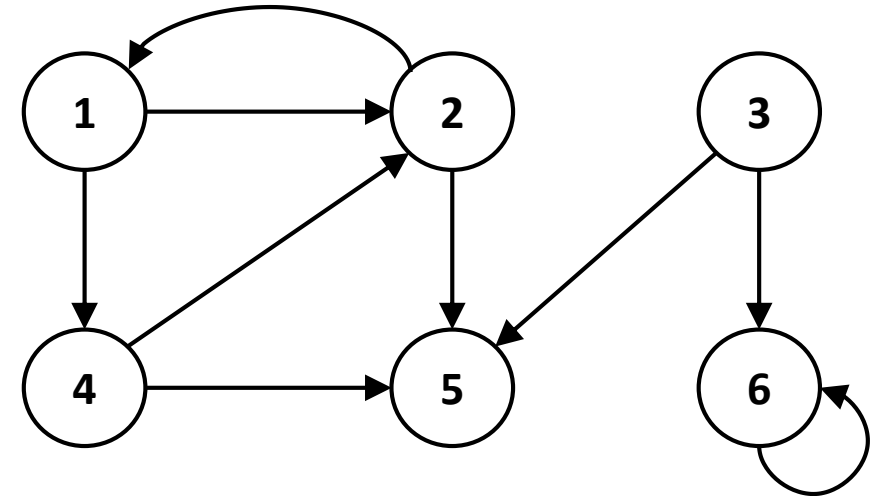
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$$V = \{1, 2, 3, 4, 5, 6\}$$

$$E = \{ (1, 2), (2, 1), (1, 4), (4, 2), (2, 5), \\ (4, 5), (3, 5), (3, 6), (6, 6) \}$$

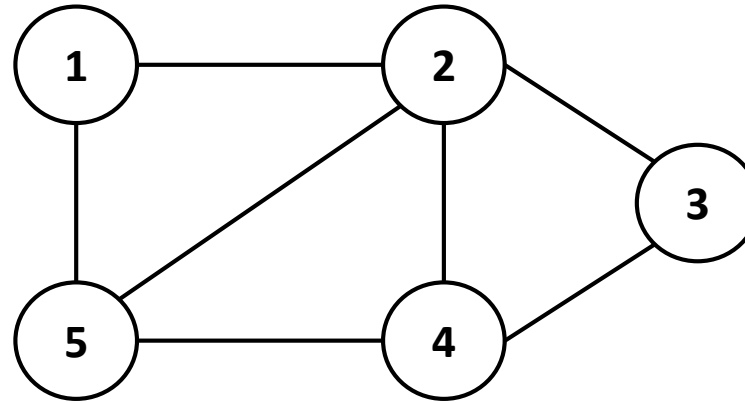
# Representing graphs

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Adjacency List of  $G = (V, E)$ :

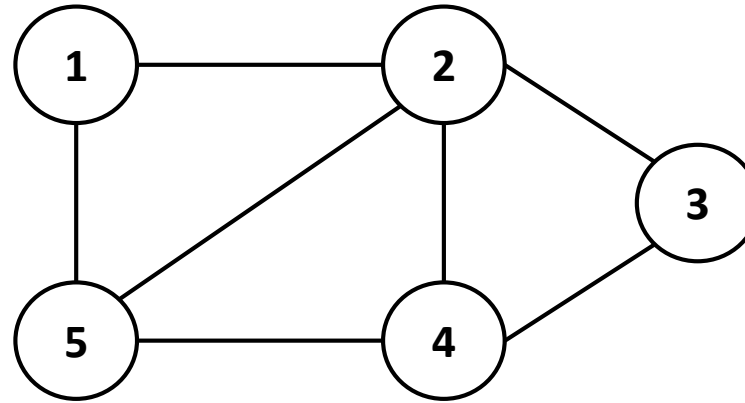
Array **Adj**[1...n] of  $n = |V|$  lists, one for each  $u \in V$ ,

**Adj**[u] is the list of all nodes  $v$  such that  $(u,v) \in E$

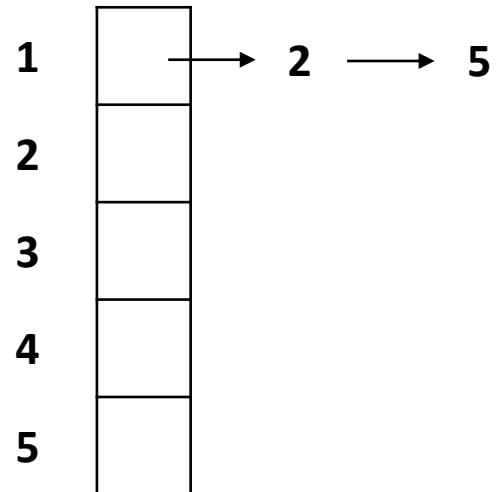


Adjacency list representation

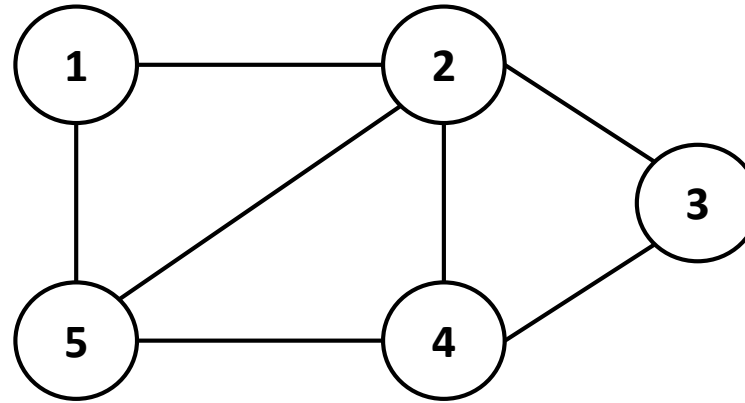
1	
2	
3	
4	
5	



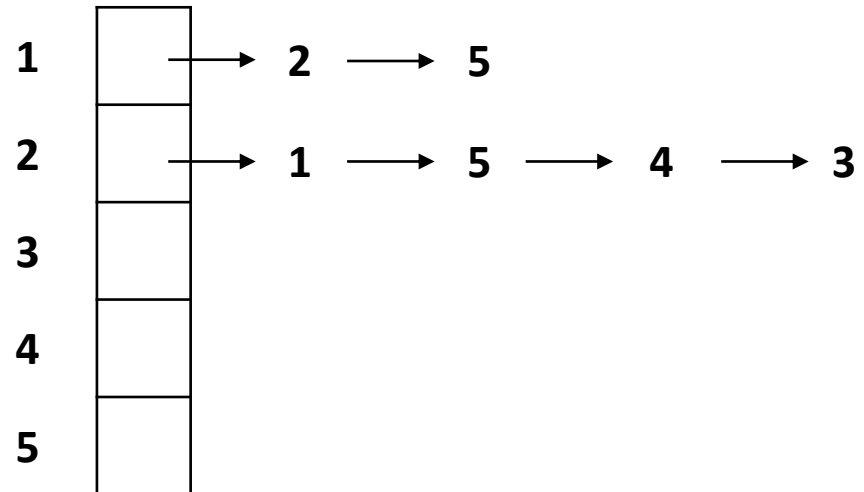
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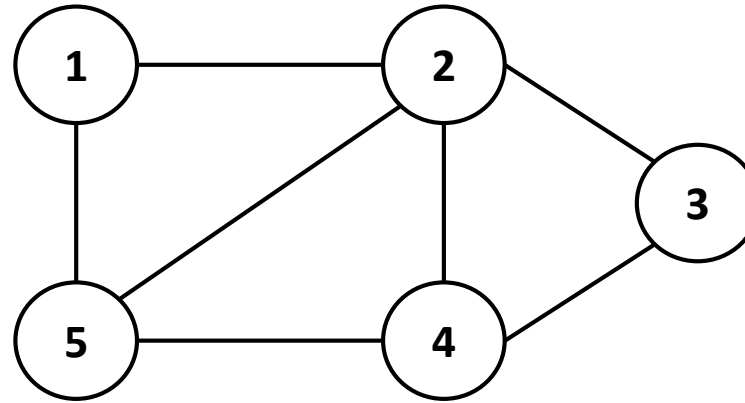




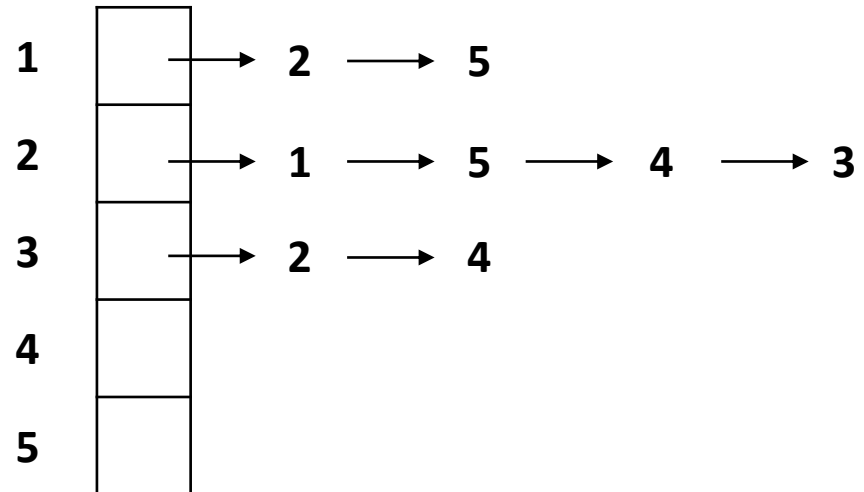


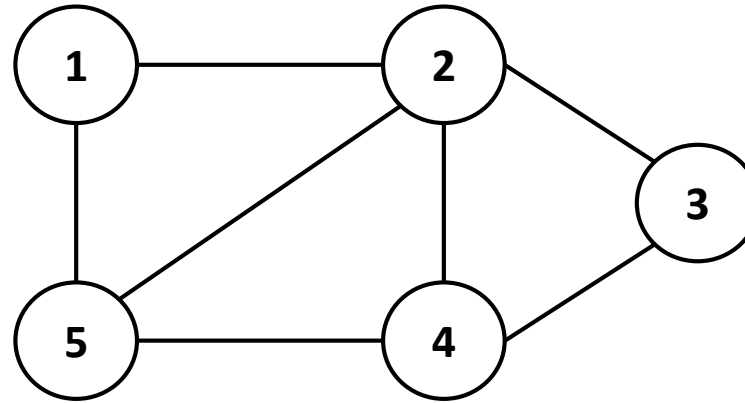
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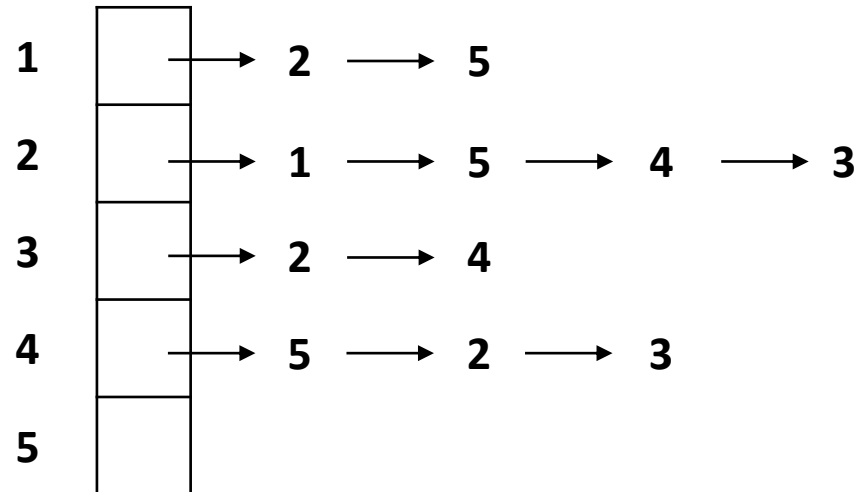


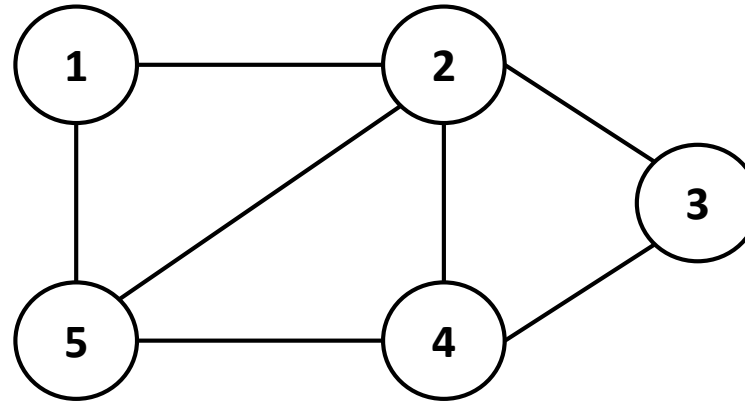
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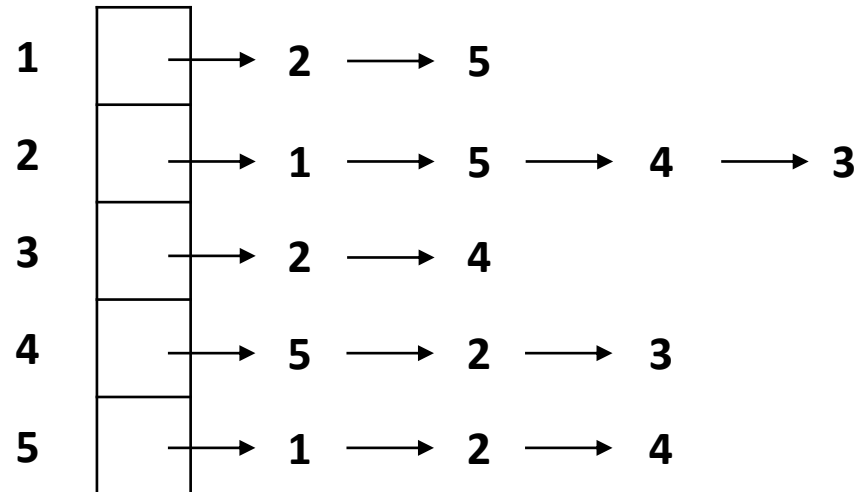


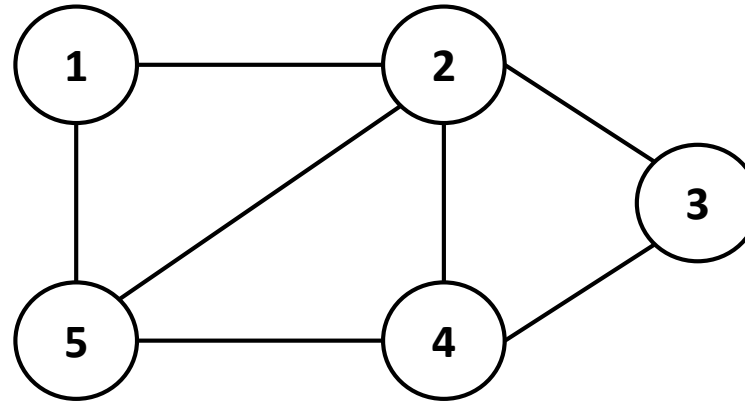
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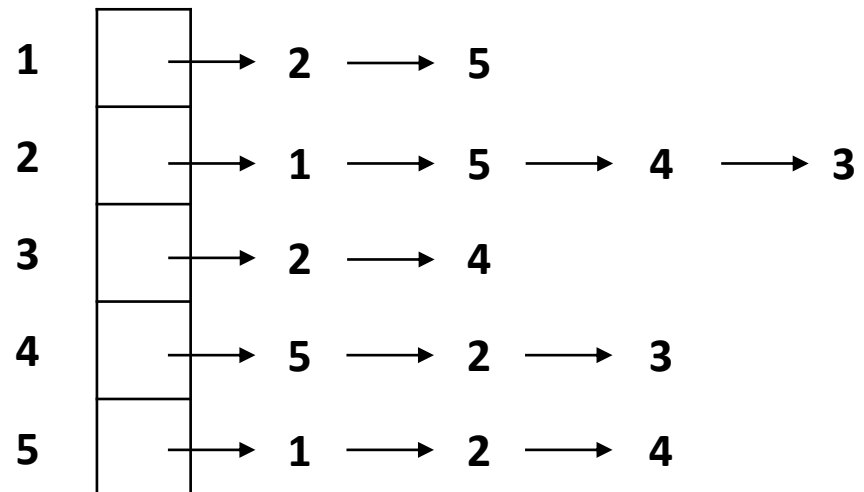


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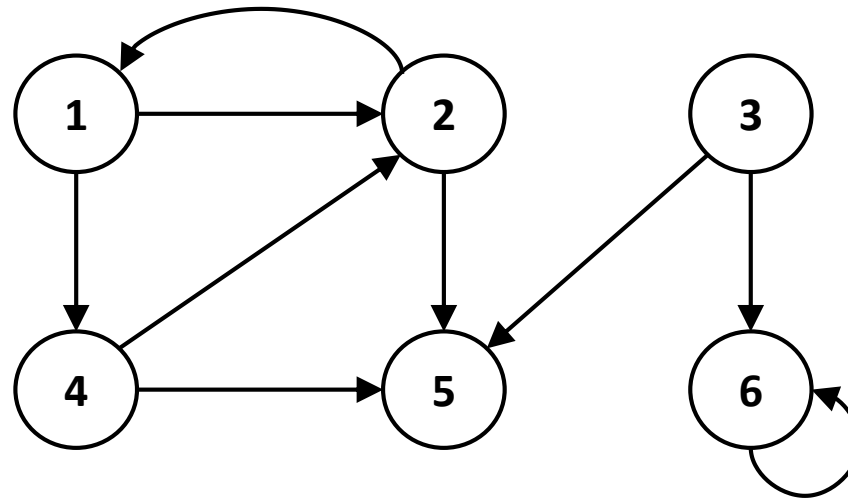


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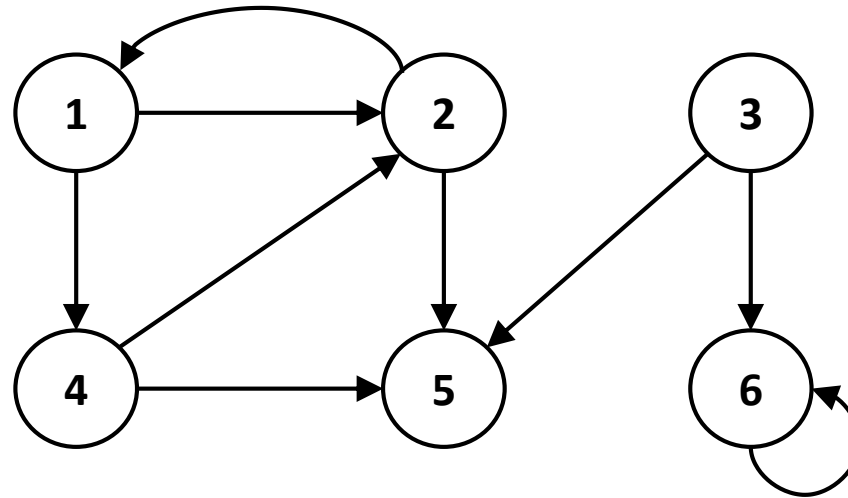
Size:  $\Theta(n + m)$

Note that  $m \leq n^2$

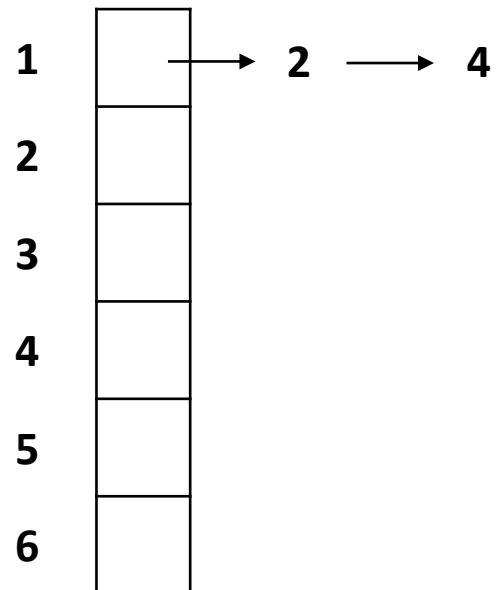


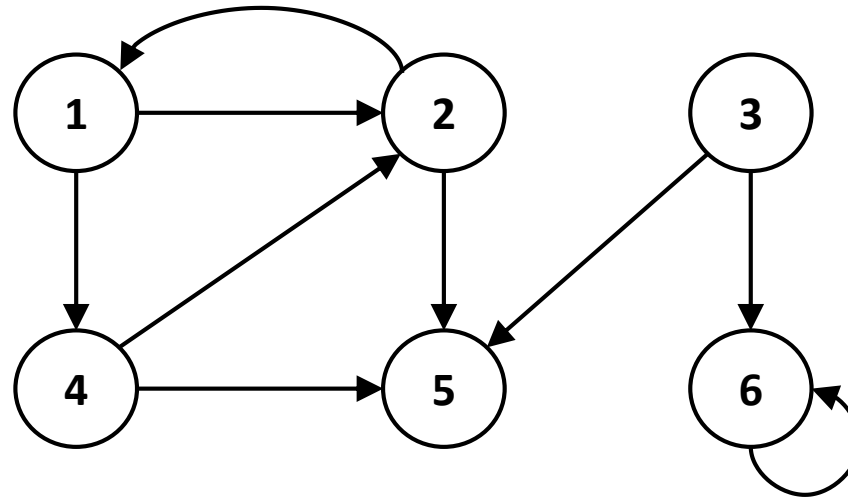
Adjacency list representation

<b>1</b>	
<b>2</b>	
<b>3</b>	
<b>4</b>	
<b>5</b>	
<b>6</b>	

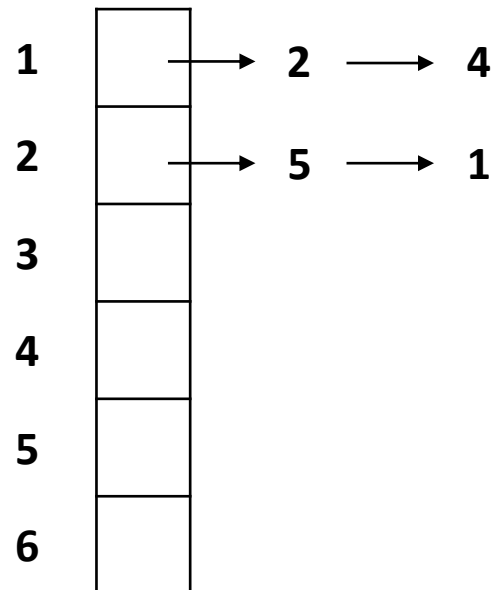


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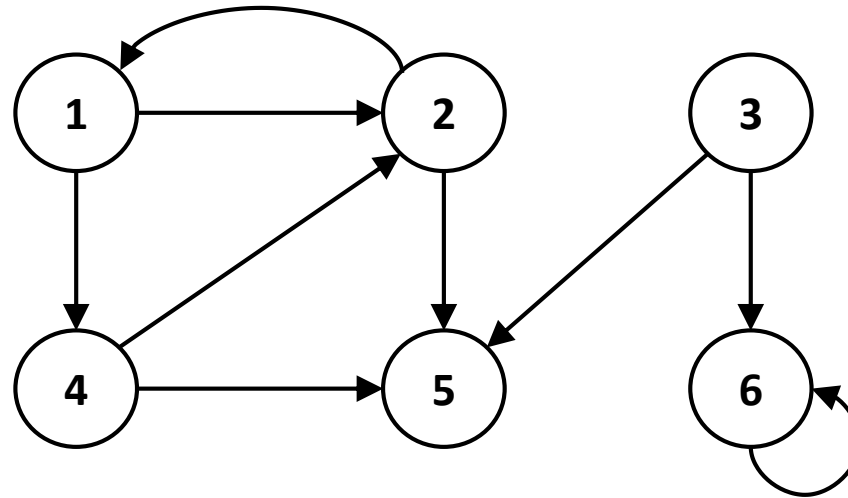




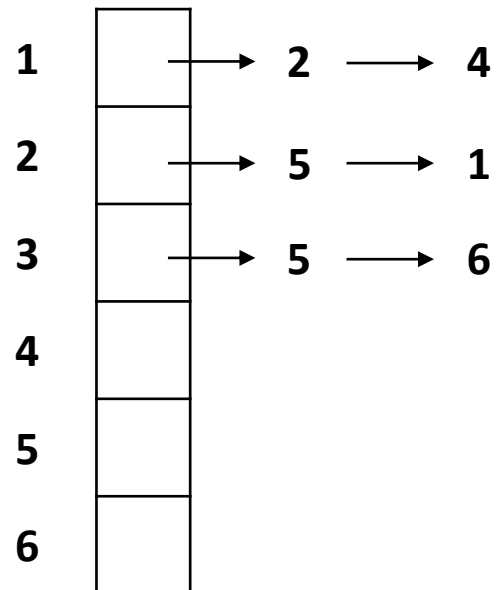
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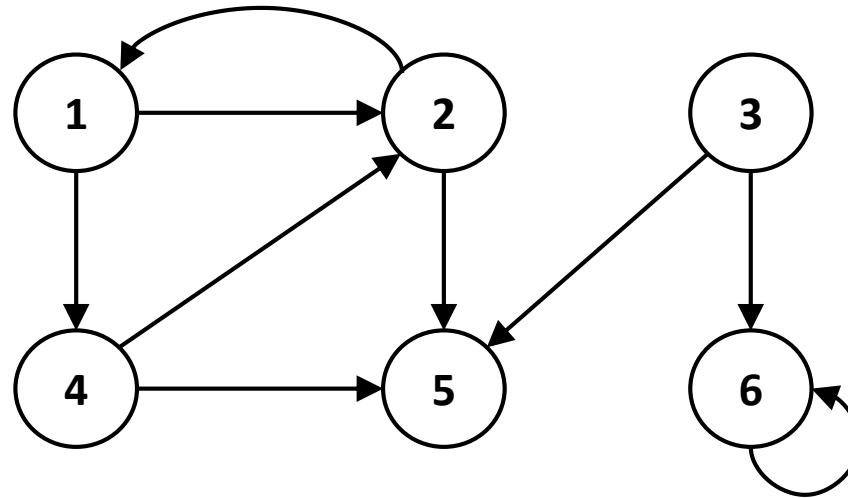




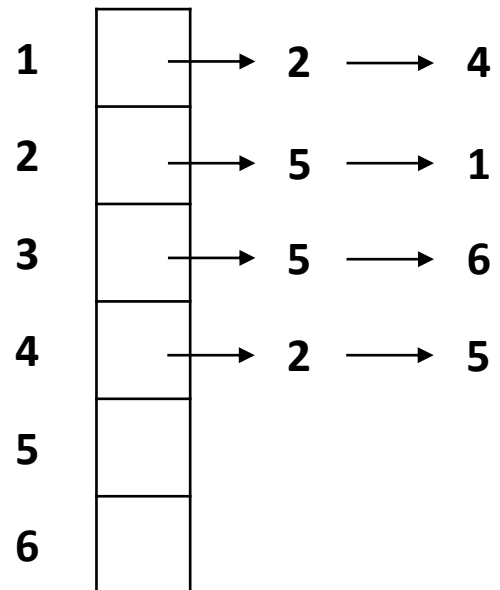


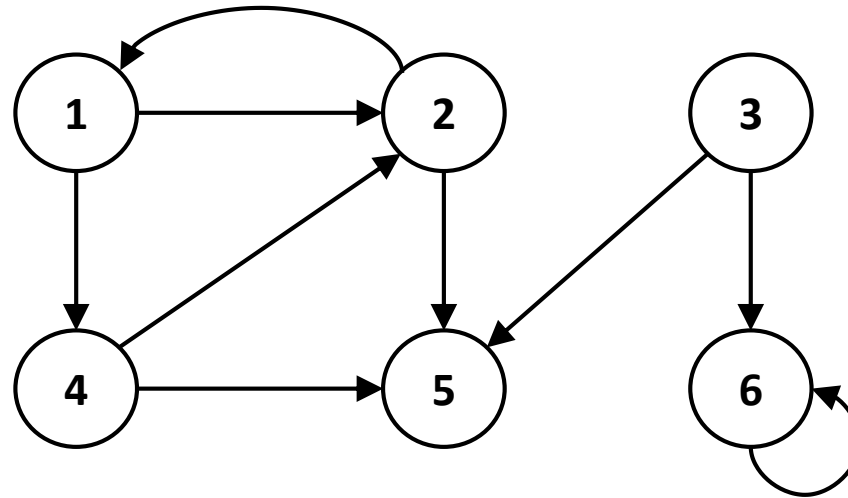
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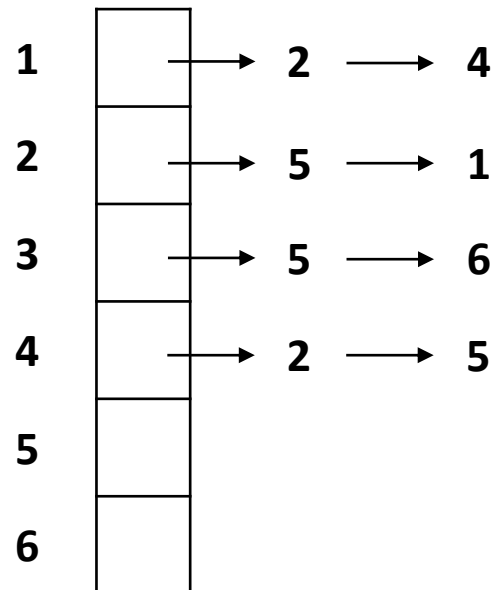


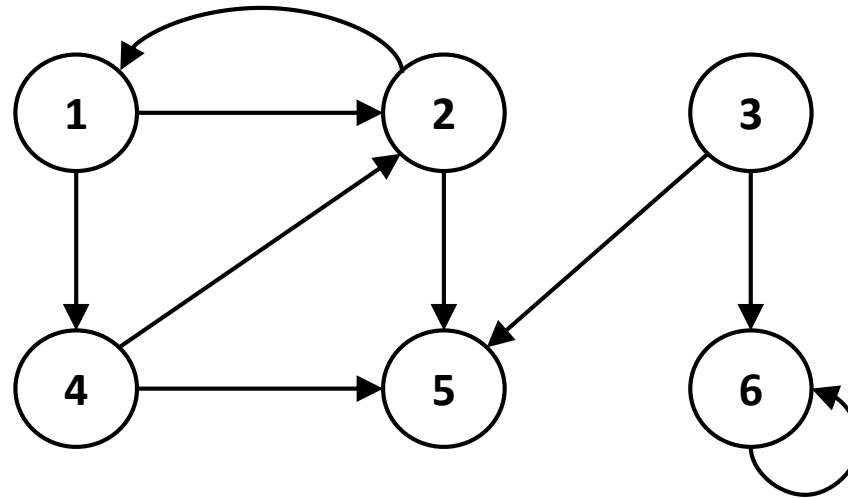
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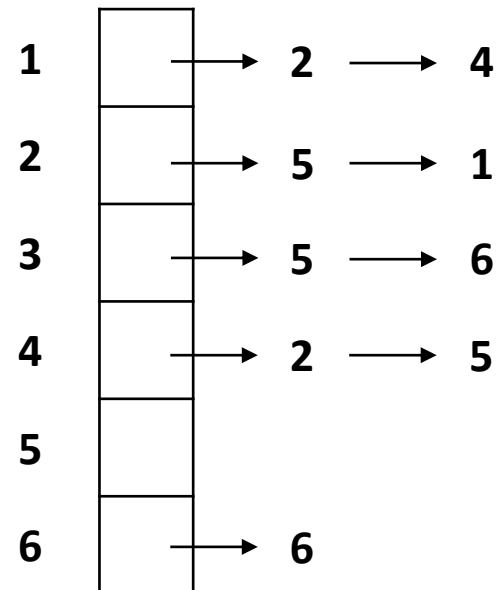


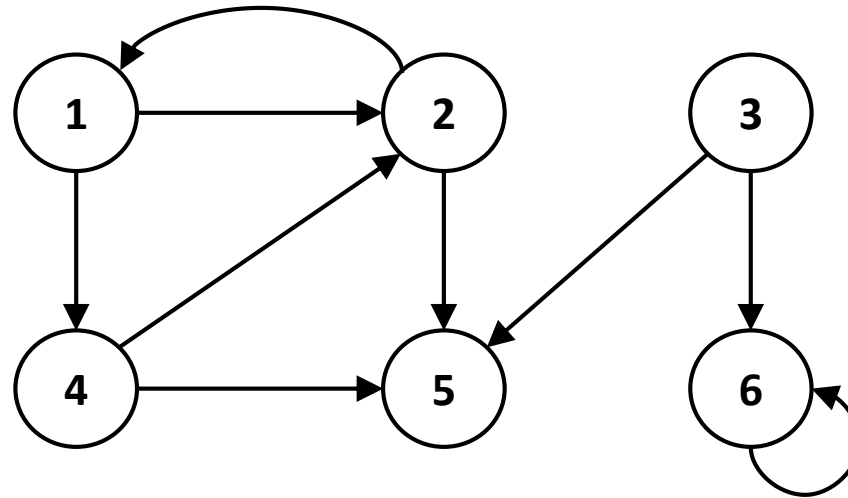
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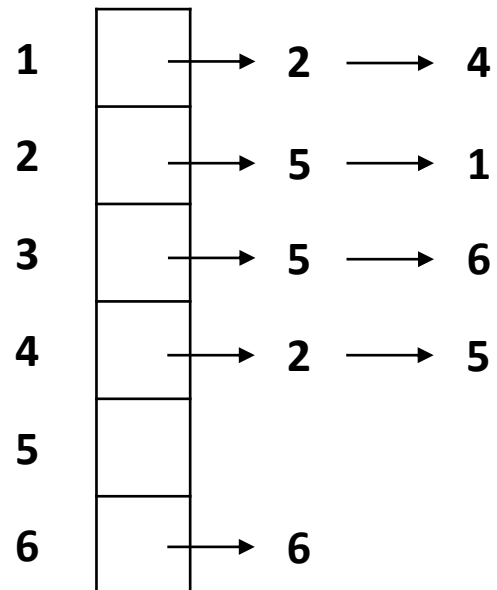


Adjacency list representation





Adjacency list representation



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# Representing graphs

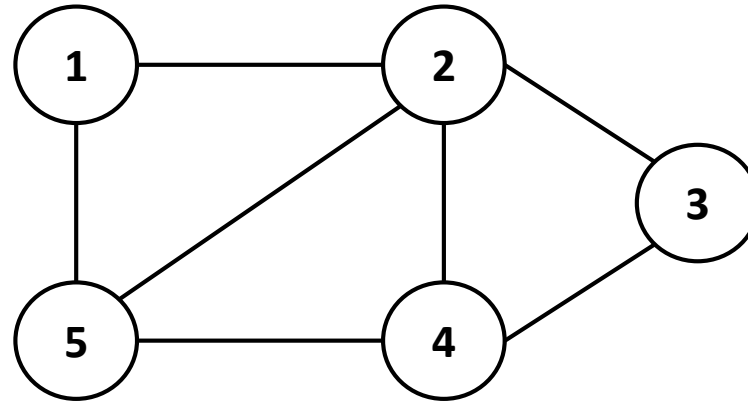
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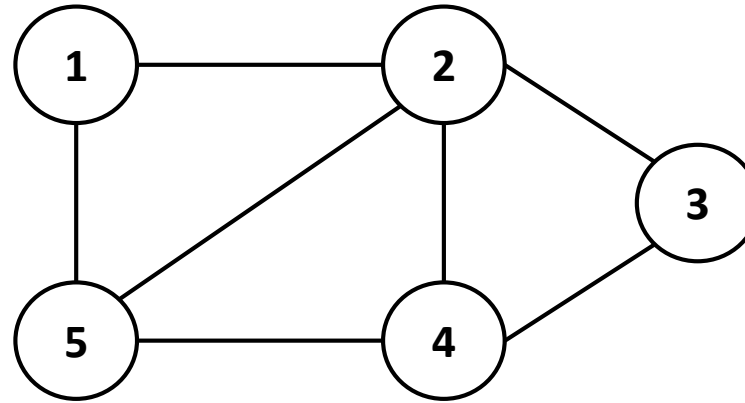
$n \times n$  matrix  $A$  such that for  $1 \leq i, j \leq n$ ,

$$A[i, j] = \begin{cases} 1 & \text{if } (i, j) \in E \\ 0 & \text{otherwise} \end{cases}$$



Adjacency matrix representation

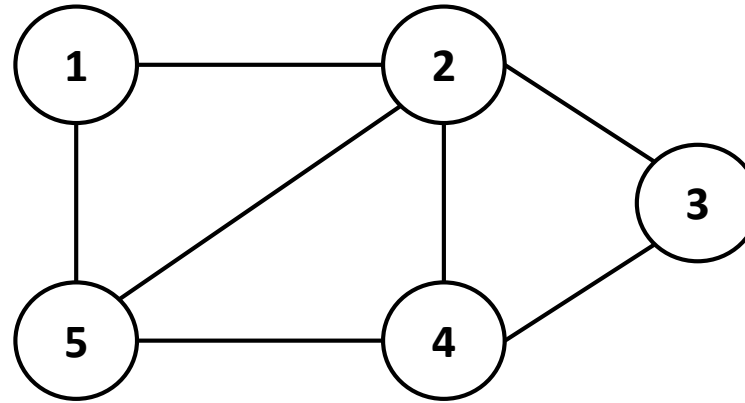
	1	2	3	4	5
1					
2					
3					
4					
5					



Adjacency matrix representation

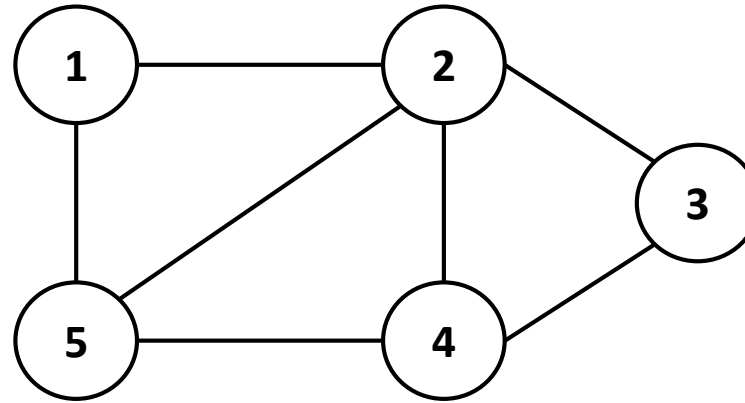
	<b>1</b>	<b>2</b>	<b>3</b>	<b>4</b>	<b>5</b>
<b>1</b>	0	1	0	0	1
<b>2</b>					
<b>3</b>					
<b>4</b>					
<b>5</b>					





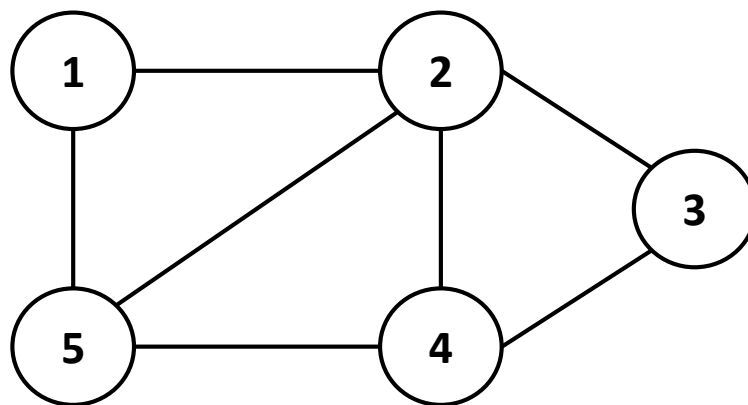
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<b>1</b>	0	1	0	0	1
<b>2</b>	1	0	1	1	1
<b>3</b>					
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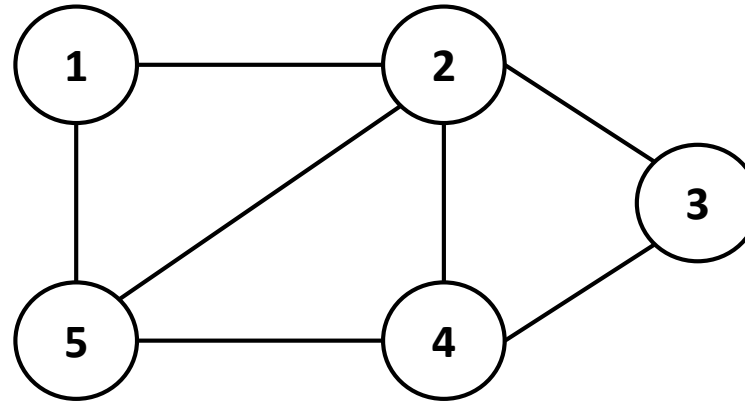
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<b>3</b>	0	1	0	1	0
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<b>5</b>					



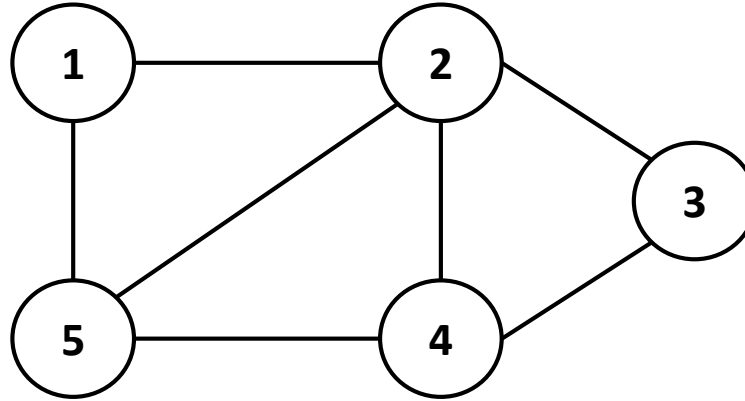
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<b>1</b>	0	1	0	0	1
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<b>3</b>	0	1	0	1	0
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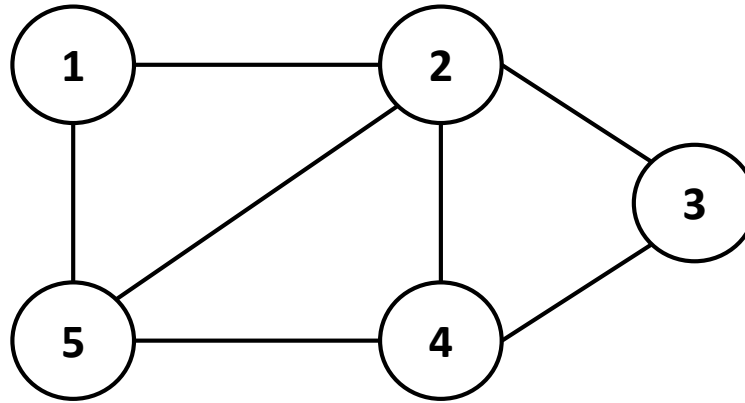
	<b>1</b>	<b>2</b>	<b>3</b>	<b>4</b>	<b>5</b>
<b>1</b>	0	1	0	0	1
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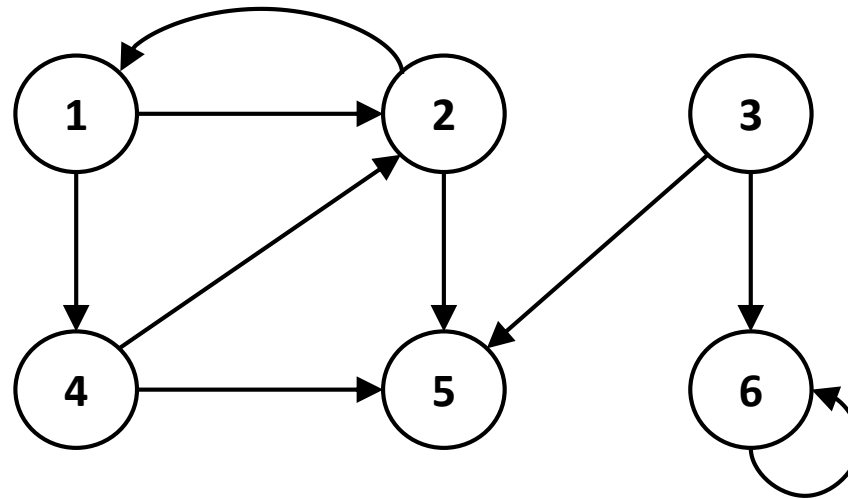
Adjacency matrix of an undirected graph is symmetric about its diagonal



Adjacency matrix representation

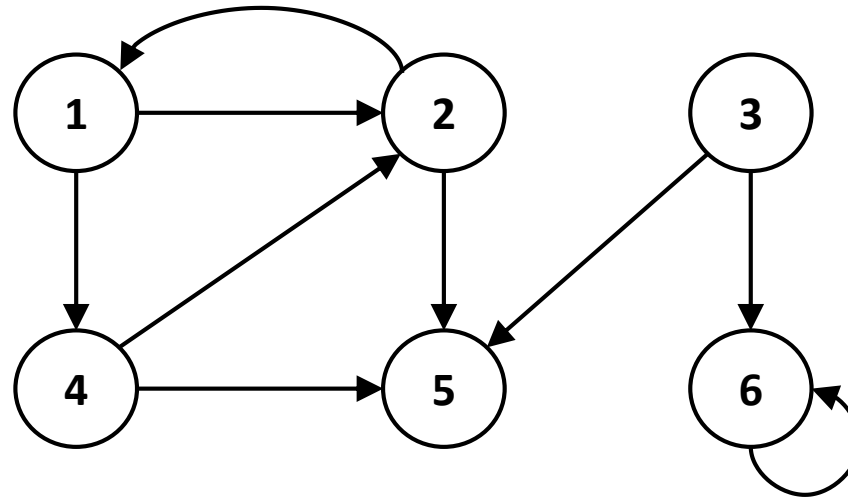
	1	2	3	4	5
1	0	1	0	0	1
2	1	0	1	1	1
3	0	1	0	1	0
4	0	1	1	0	1
5	1	1	0	1	0

Size:  $\Theta(n^2)$



Adjacency matrix representation

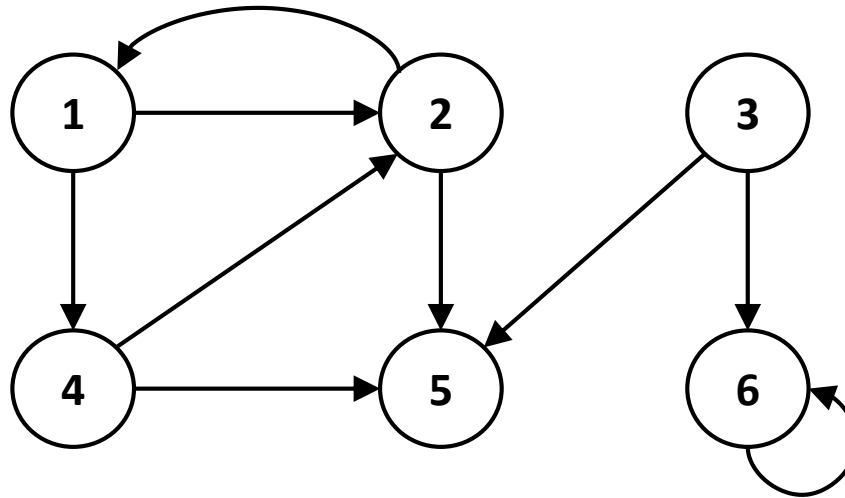
	1	2	3	4	5	6
1						
2						
3						
4						
5						
6						



Adjacency matrix representation

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<b>1</b>	0	1	0	1	0	0
<b>2</b>	1	0	0	0	1	0
<b>3</b>	0	0	0	0	1	1
<b>4</b>	0	1	0	0	1	0
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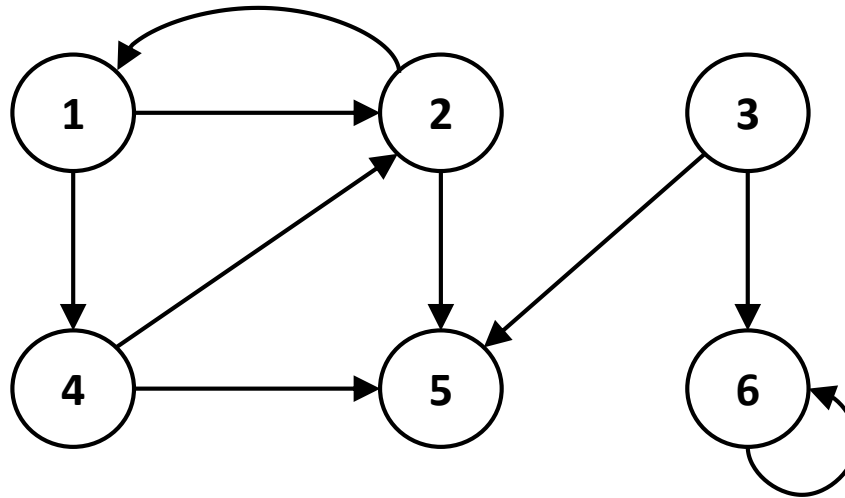


Adjacency matrix representation

	1	2	3	4	5	6
1	0	1	0	1	0	0
2	1	0	0	0	1	0
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4	0	1	0	0	1	0
5	0	0	0	0	0	0
6	0	0	0	0	0	1

$$A[2, 4] \neq A[4, 2]$$

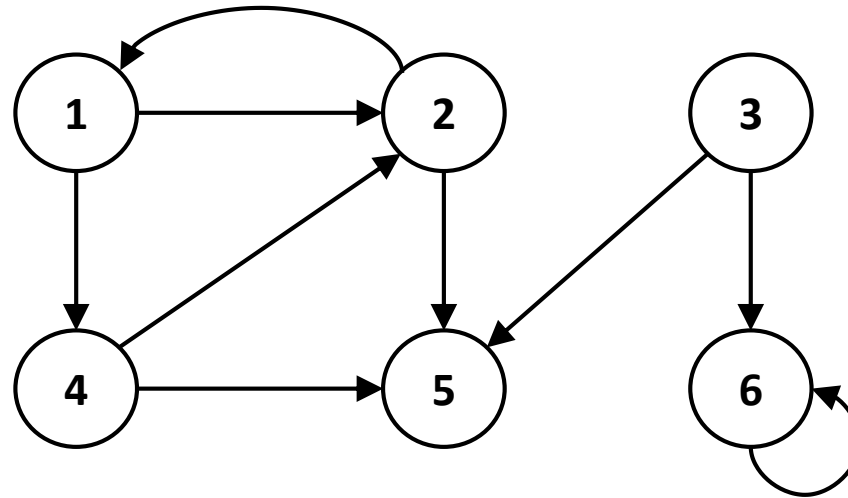
Adjacency matrix of a directed graph is not necessarily symmetric about its diagonal



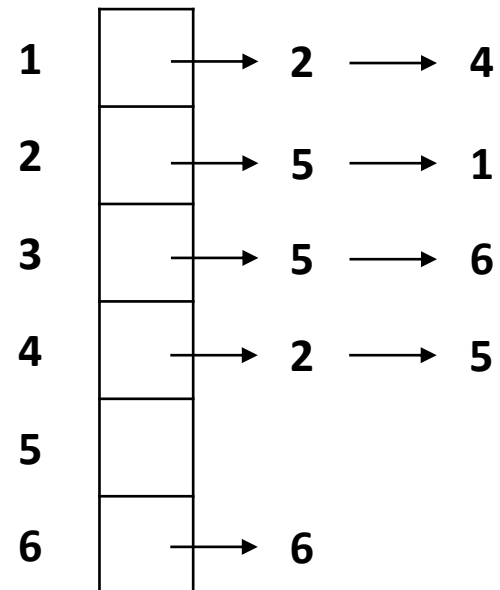
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	1	2	3	4	5	6
1	0	1	0	1	0	0
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3	0	0	0	0	1	1
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Size:  $\Theta(n^2)$



Adjacency list representation



Adjacency matrix representation

	1	2	3	4	5	6
1	0	1	0	1	0	0
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- For sparse graphs ( $m \ll n^2$ ), Adjacency List is more space-efficient.

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- For sparse graphs ( $m \ll n^2$ ), Adjacency List is more space-efficient.
- Finding whether a certain  $(u, v) \in E$ :
  - Is  $O(1)$  with Adjacency Matrix
  - Is  $O(n)$  with Adjacency List

# Graph Search

Systematic exploration of graph:

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- Start at some node and explore it



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i.e., follow its edges to discover new nodes

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Is  $G$  connected?

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Is  $G$  connected?

Does  $G$  have a cycle?

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i.e., follow its edges to discover new nodes
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Graph searches reveal structural properties of  $G$ :

Is  $G$  connected?

Does  $G$  have a cycle?

Shortest path info,

etc...

# Graph Search

Two basic types of graph searches:

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Two basic types of graph searches:

- Breadth First Search (BFS)
- Depth First Search (DFS)



# Breadth First Search

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BFS started at a node  $s$

# Breadth First Search

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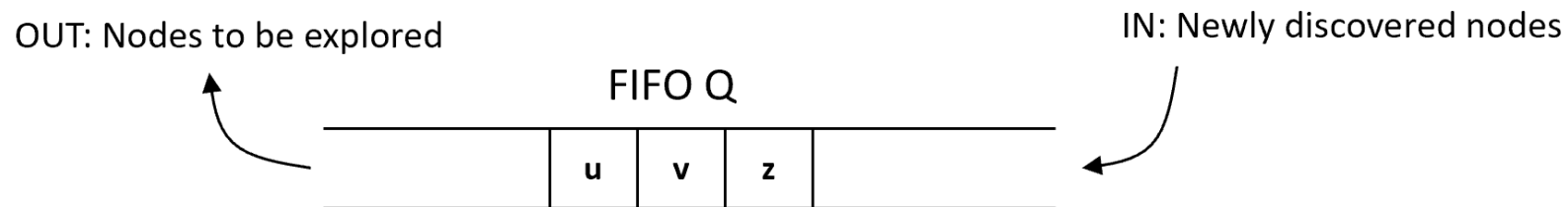
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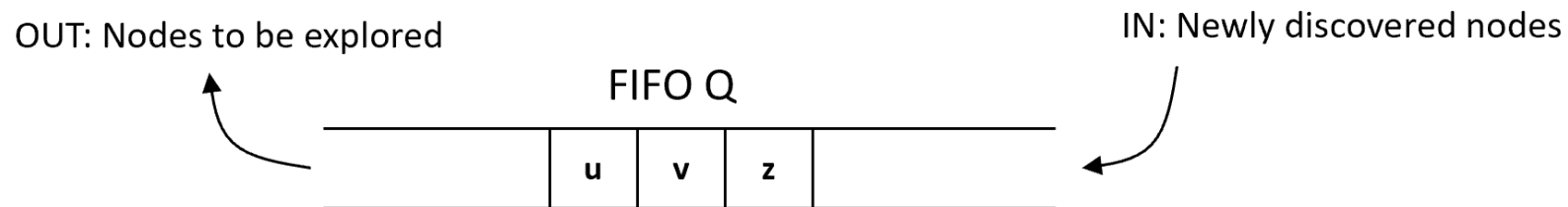
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Do (2) until all discovered nodes are explored



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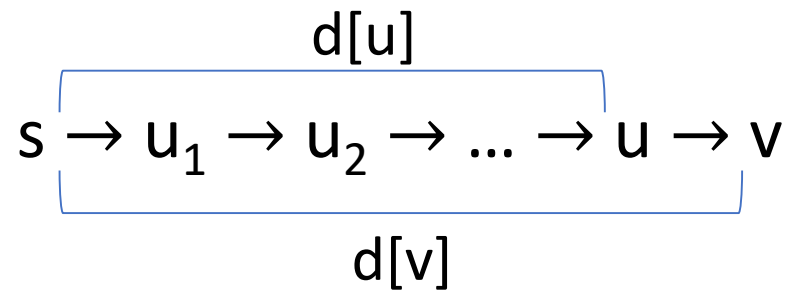
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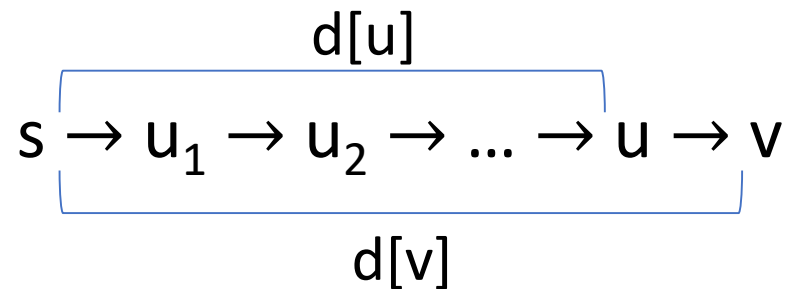
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Clearly,  $d[v] = d[u] + 1$

## BFS( $G, s$ )

*/\*  $G = (V, E)$  and  $s \in V$  \*/*

color[s]  $\leftarrow$  grey ; d[s]  $\leftarrow$  0 ; p[s]  $\leftarrow$  NIL

**For each**  $v \in V - \{s\}$  **do**

color[v]  $\leftarrow$  white

d[v]  $\leftarrow$   $\infty$

p[v]  $\leftarrow$  NIL

Q  $\leftarrow$  empty ; ENQ(Q, s)

*/\* Q: nodes that are discovered but not yet explored \*/*

**While** Q is not empty **do**

u  $\leftarrow$  DEQ(Q)

**For each**  $(u, v) \in E$  **do**

**If** color[v] = white **then do**

color[v]  $\leftarrow$  grey

d[v]  $\leftarrow$  d[u] + 1

p[v]  $\leftarrow$  u

ENQ(Q, v)

**End If**

**End For**

color[u]  $\leftarrow$  black

*/\* Explore u \*/*

*/\* Explore edge (u,v) \*/*

*/\* If v is first discovered \*/*

*/\* Done exploring u \*/*

**End While**

**End BFS**