

Max-Heaps

Abstract Data Type:

- Describes an object and its operations

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Data Structure:

- Some specific implementation of an Abstract Data Type

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Example of an Abstract Data Type: Priority Queues

Priority Queues

- Object : Set S of elements with “keys” (“priority”) that can be compared

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 - **Insert**(S, x): Insert element x in S

Priority Queues

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- **Operations**:
 - **Insert**(S, x): Insert element x in S
 - **Max**(S): Returns an element of highest priority in S

Priority Queues

- **Object** : Set S of elements with “keys” (“priority”) that can be compared
- **Operations**:
 - **Insert**(S, x): Insert element x in S
 - **Max**(S): Returns an element of highest priority in S
 - **Extract_Max**(S): returns $\text{Max}(S)$ and removes it from S .

An Application of Priority Queue

The OS can use a Priority Queue to maintain a set S of jobs and schedule them according to their priorities:

- When a new job x arrives, the OS does **Insert**(S,x).
- When a processor becomes available to execute a job, the OS does **Extract_Max**(S)

Simple Data Structures for implementing a Priority Queue

Worst Case Time For	Insert	Extract_Max
Unordered Linked List		

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Worst Case Time For	Insert	Extract_Max
Unordered Linked List	$\Theta(1)$	

Simple Data Structures for implementing a Priority Queue

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Simple Data Structures for implementing a Priority Queue

Worst Case Time For	Insert	Extract_Max
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Worst Case Time For	Insert	Extract_Max
Unordered Linked List	$\Theta(1)$	$\Theta(n)$
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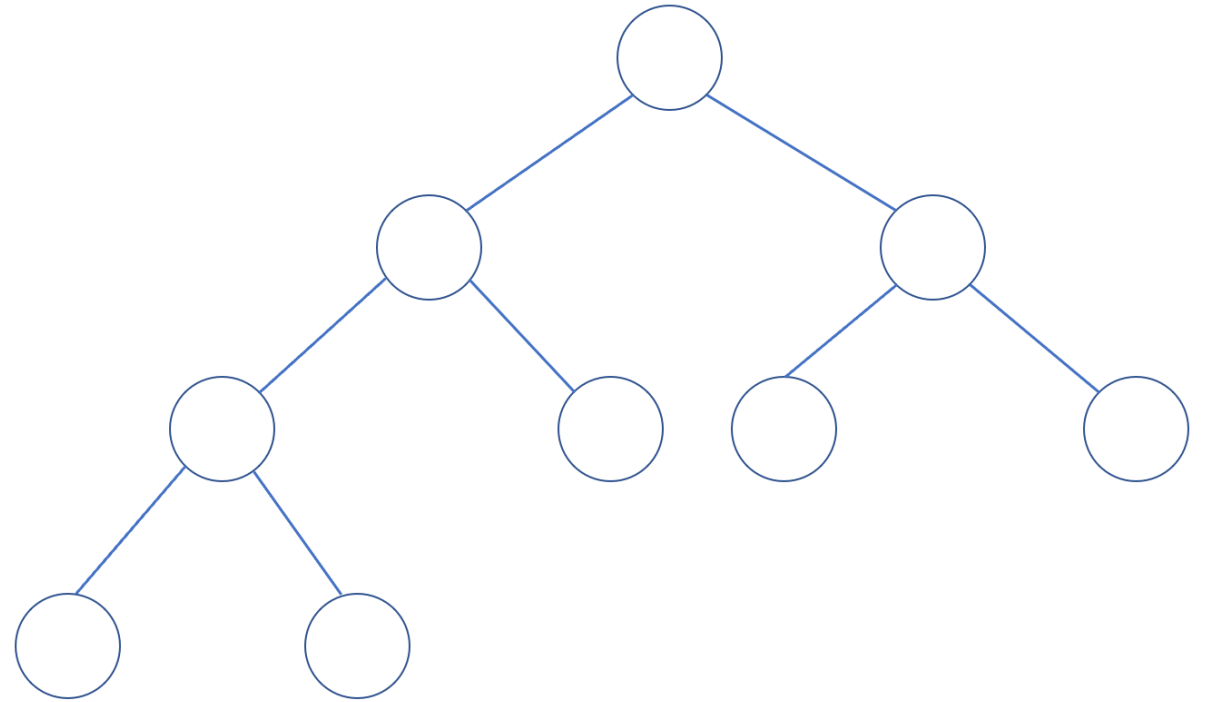
Goal: Data Structure that does each operation in $\Theta(\log n)$ time

Max-Heaps

Visualizing Max-Heaps

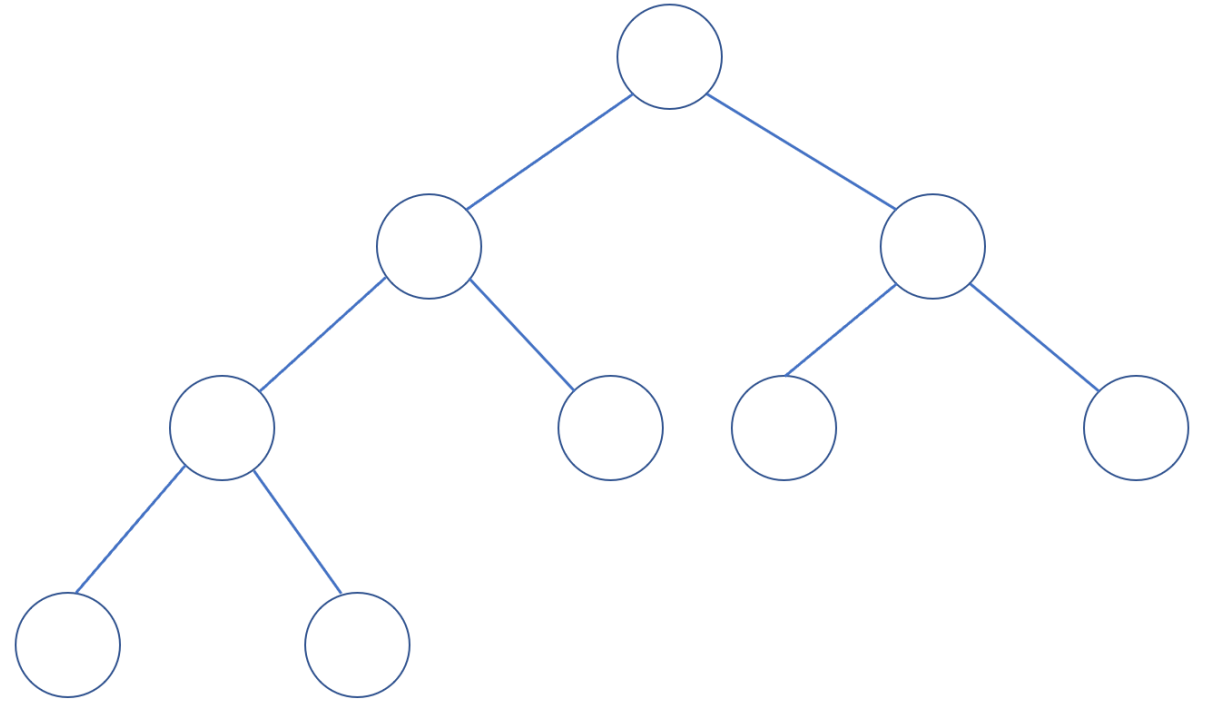
Elements of Max-Heap are stored in a Complete Binary Tree.

Complete Binary Tree (CBT)



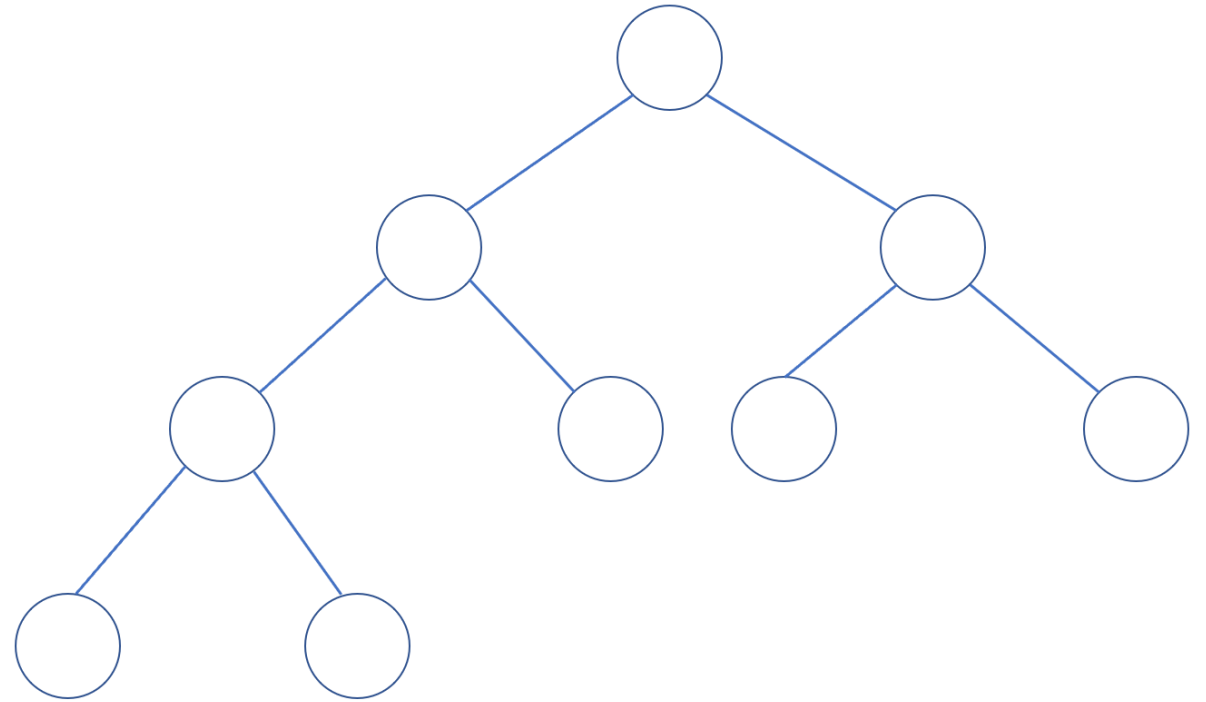
Complete Binary Tree (CBT)

- A Binary Tree



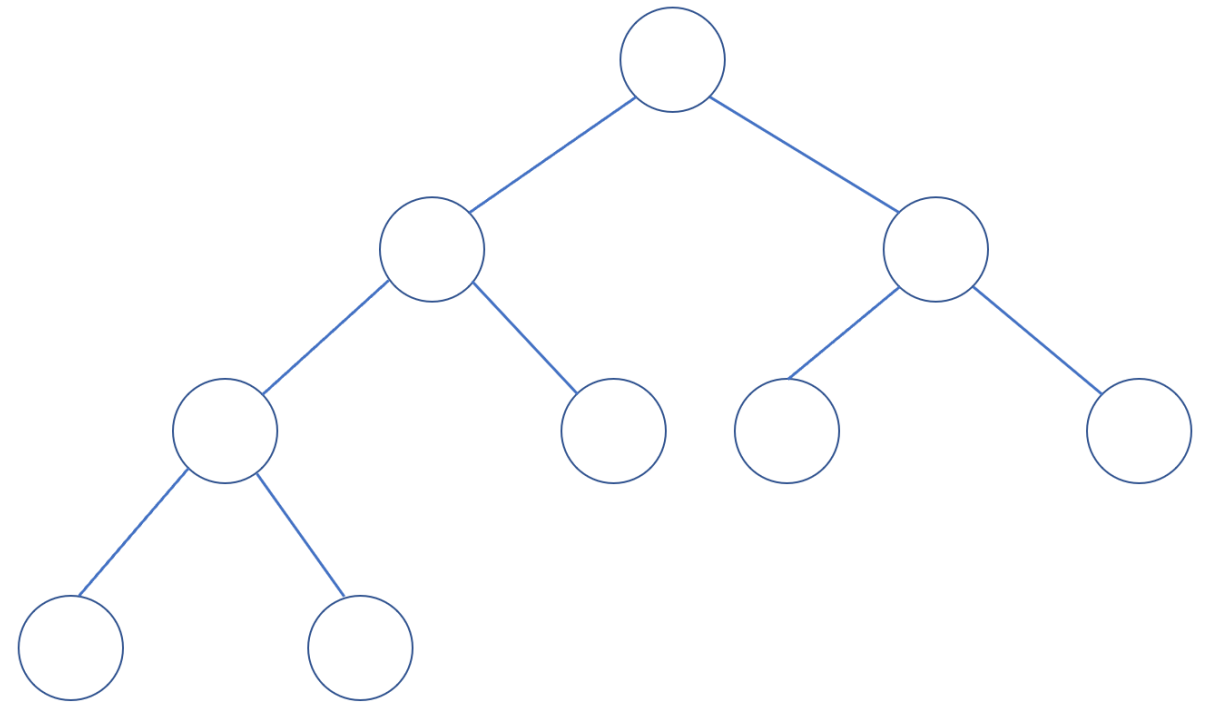
Complete Binary Tree (CBT)

- A Binary Tree
- Every level L , except maybe the bottom level, has 2^L nodes.

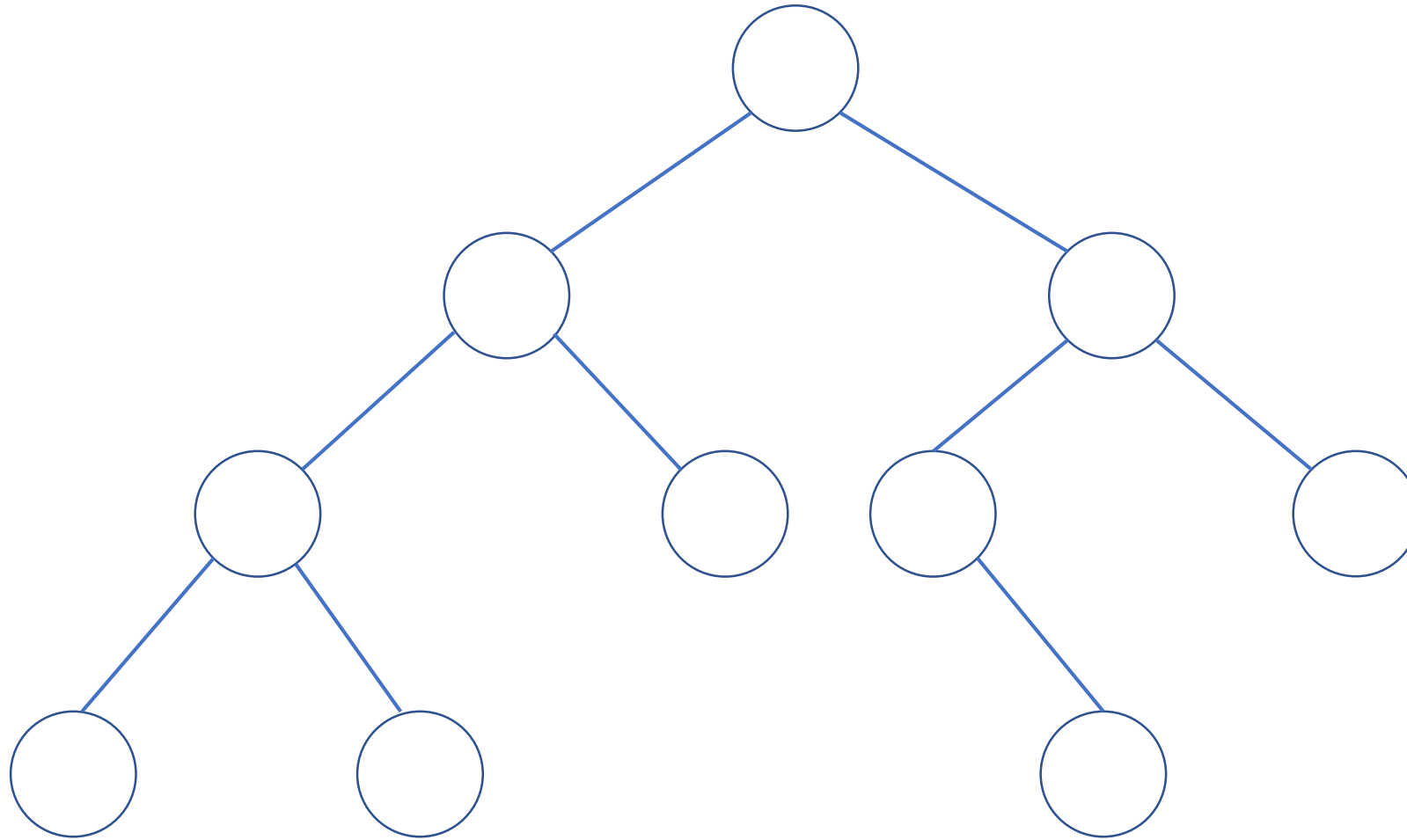


Complete Binary Tree (CBT)

- A Binary Tree
- Every level L , except maybe the bottom level, has 2^L nodes.
- All the nodes in the bottom level are as far to the left as possible.

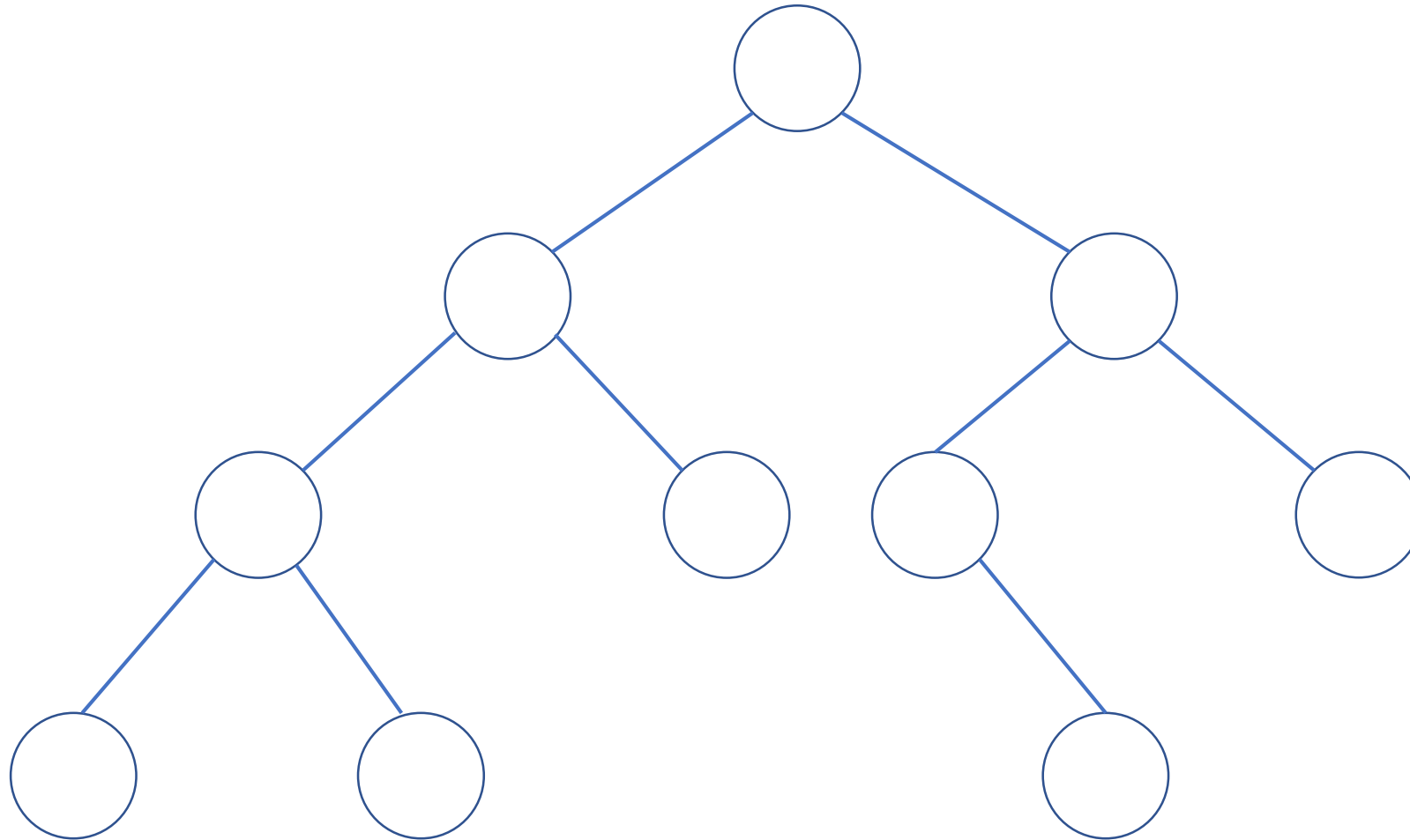


Is this a Complete Binary Tree?

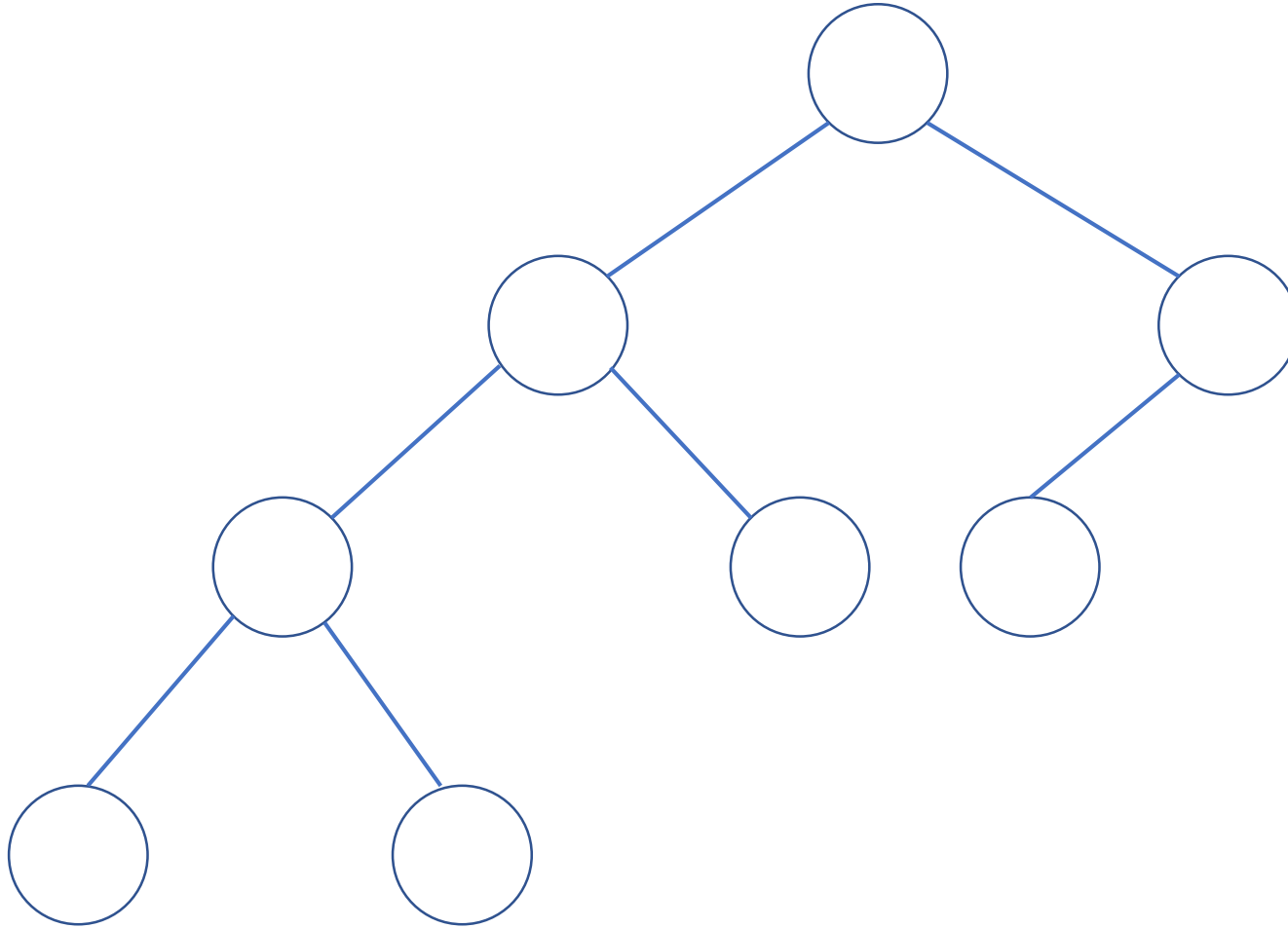


Is this a Complete Binary Tree?

No!

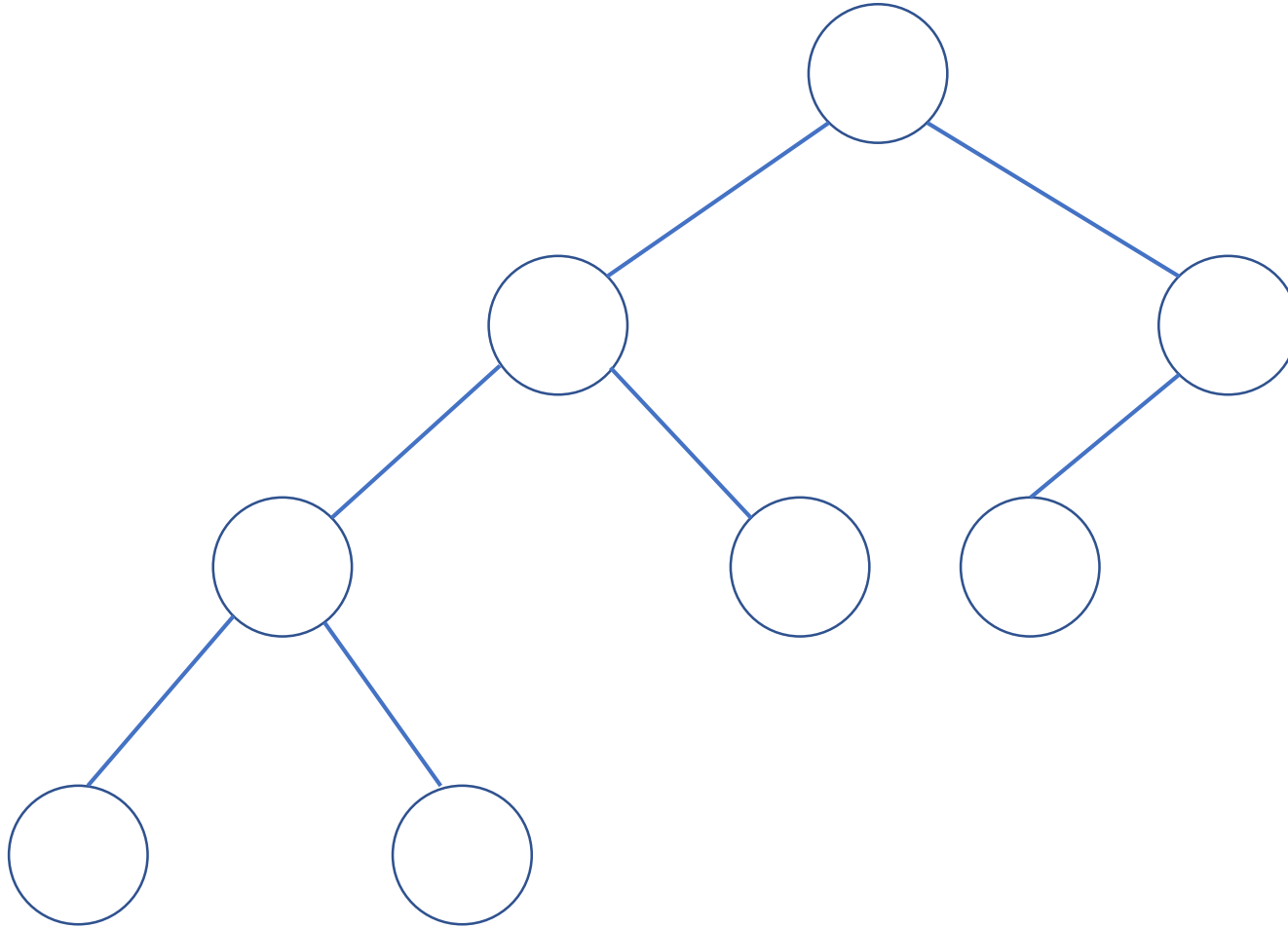


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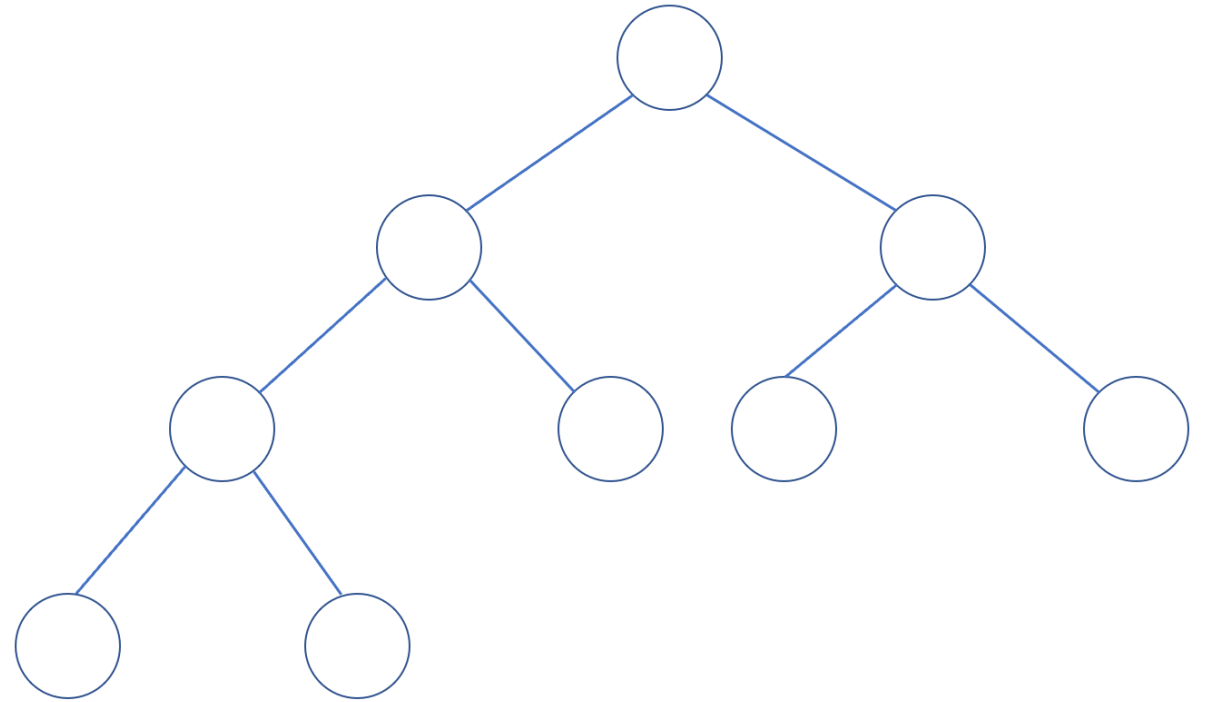


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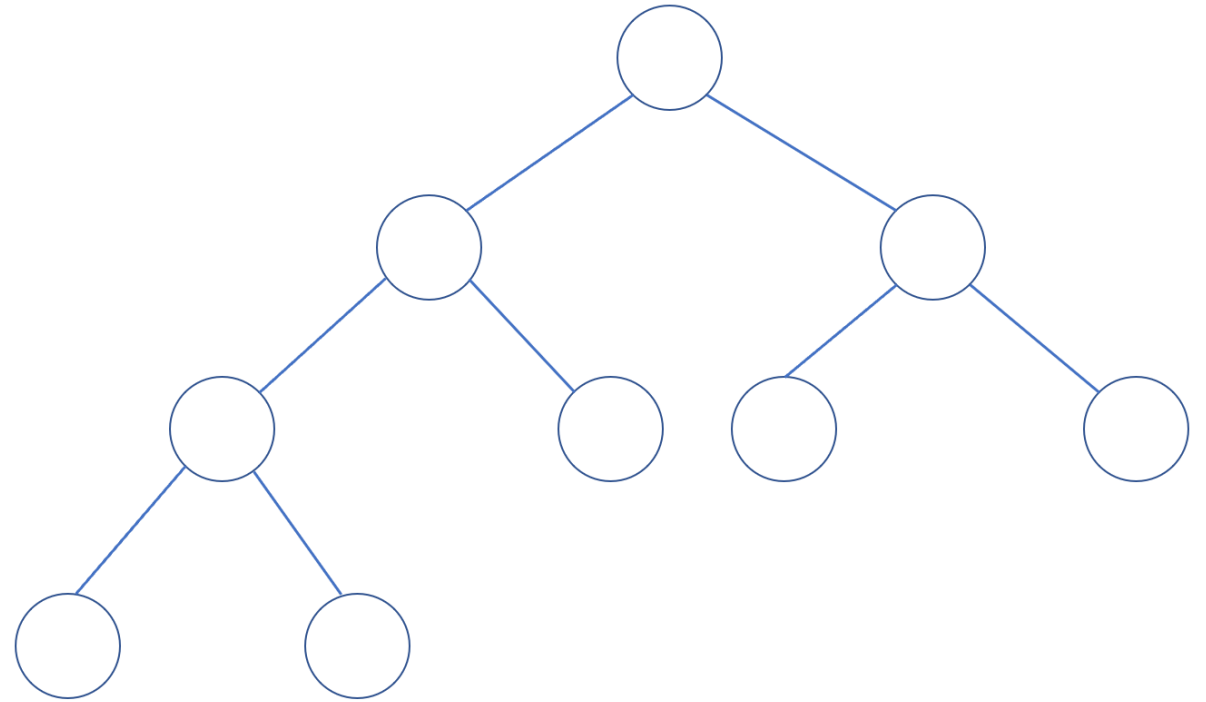


Height of a Tree



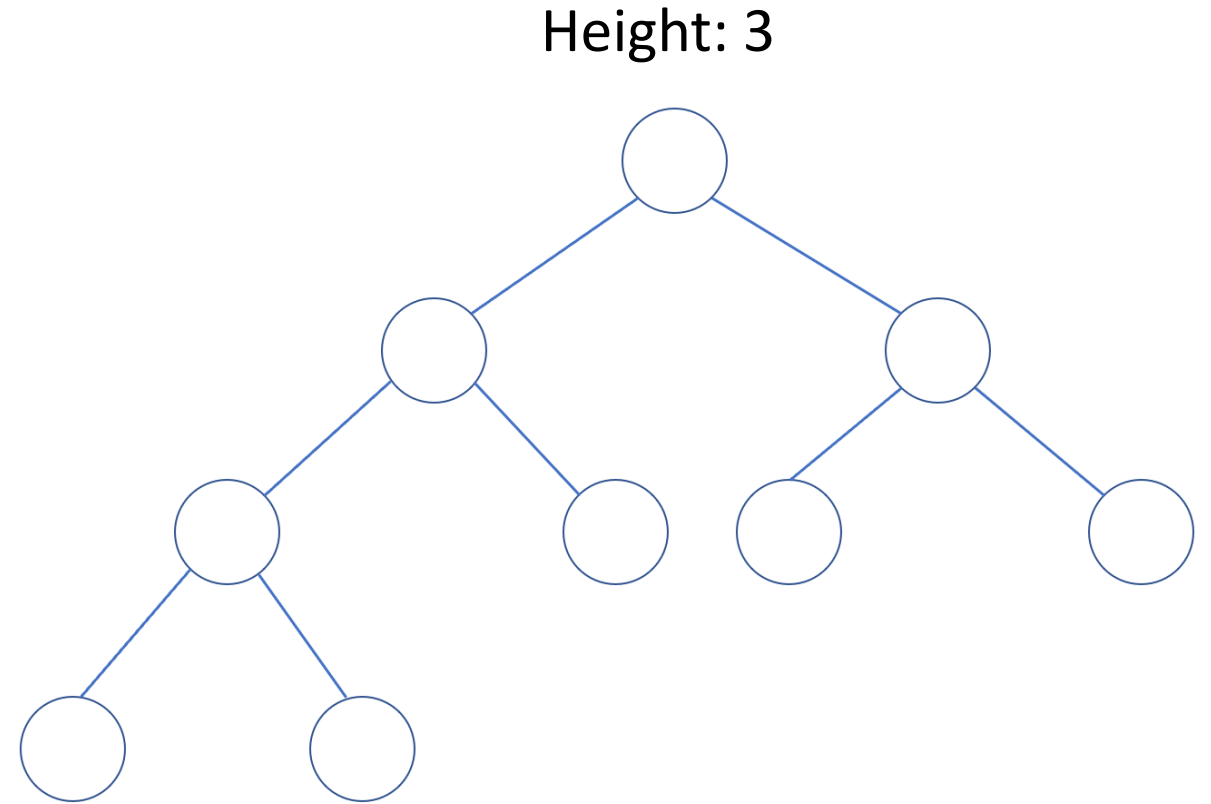
Height of a Tree

Number of edges in the longest path from root to any leaf.

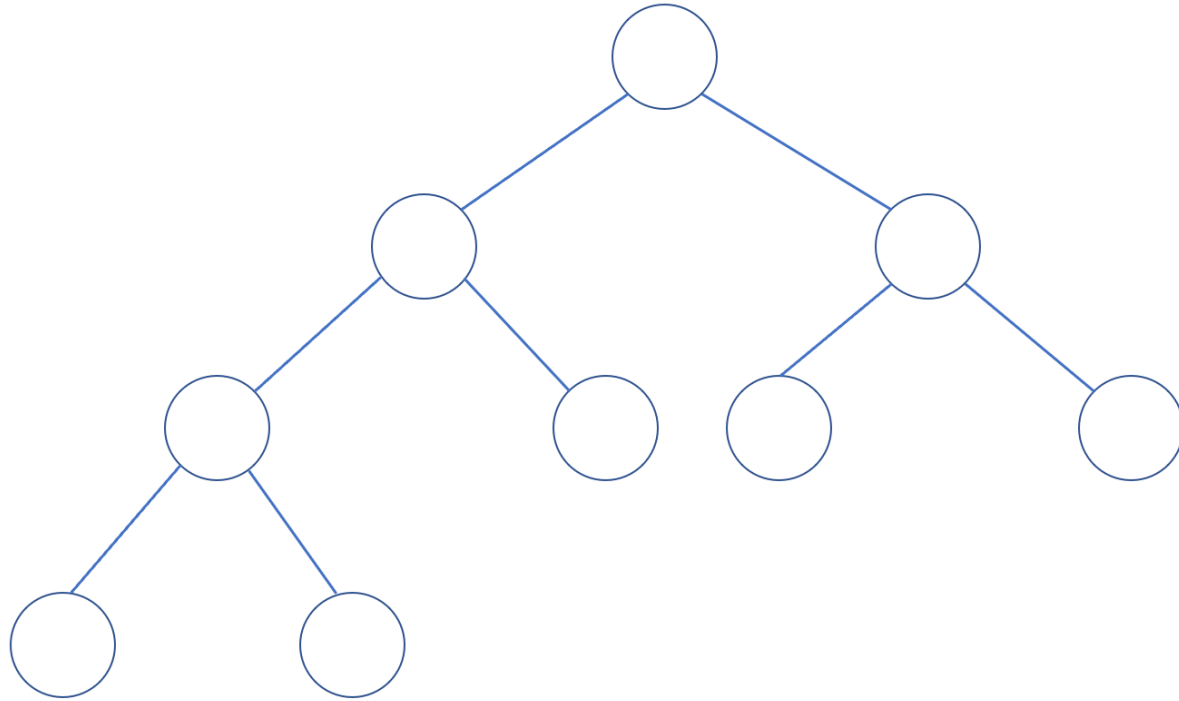


Height of a Tree

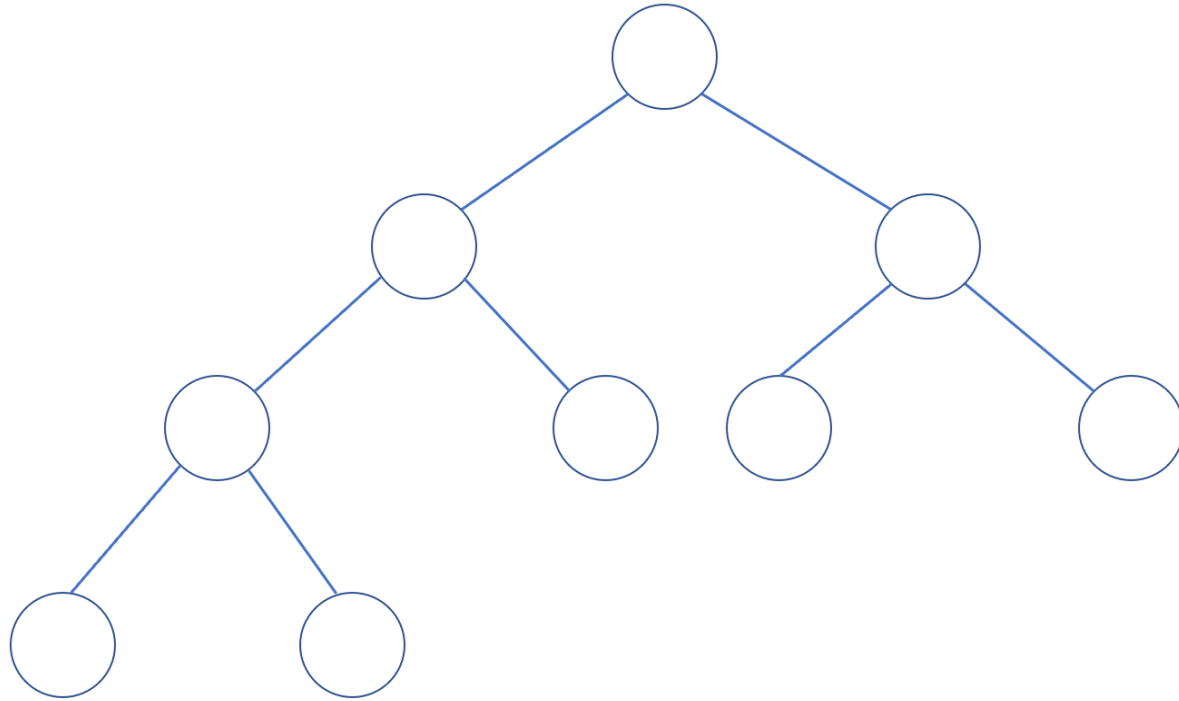
Number of edges in the longest path from root to any leaf.



FACT: Height of a CBT with n nodes is $\lfloor \log_2 n \rfloor$



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Here $n = 9$, and height = $\lfloor \log_2 9 \rfloor = 3$

Max-Heap: The n elements of a Max-Heap are stored in a CBT with n nodes such that the following property holds.

Max-Heap Property: Priority of each node \geq Priority of its children

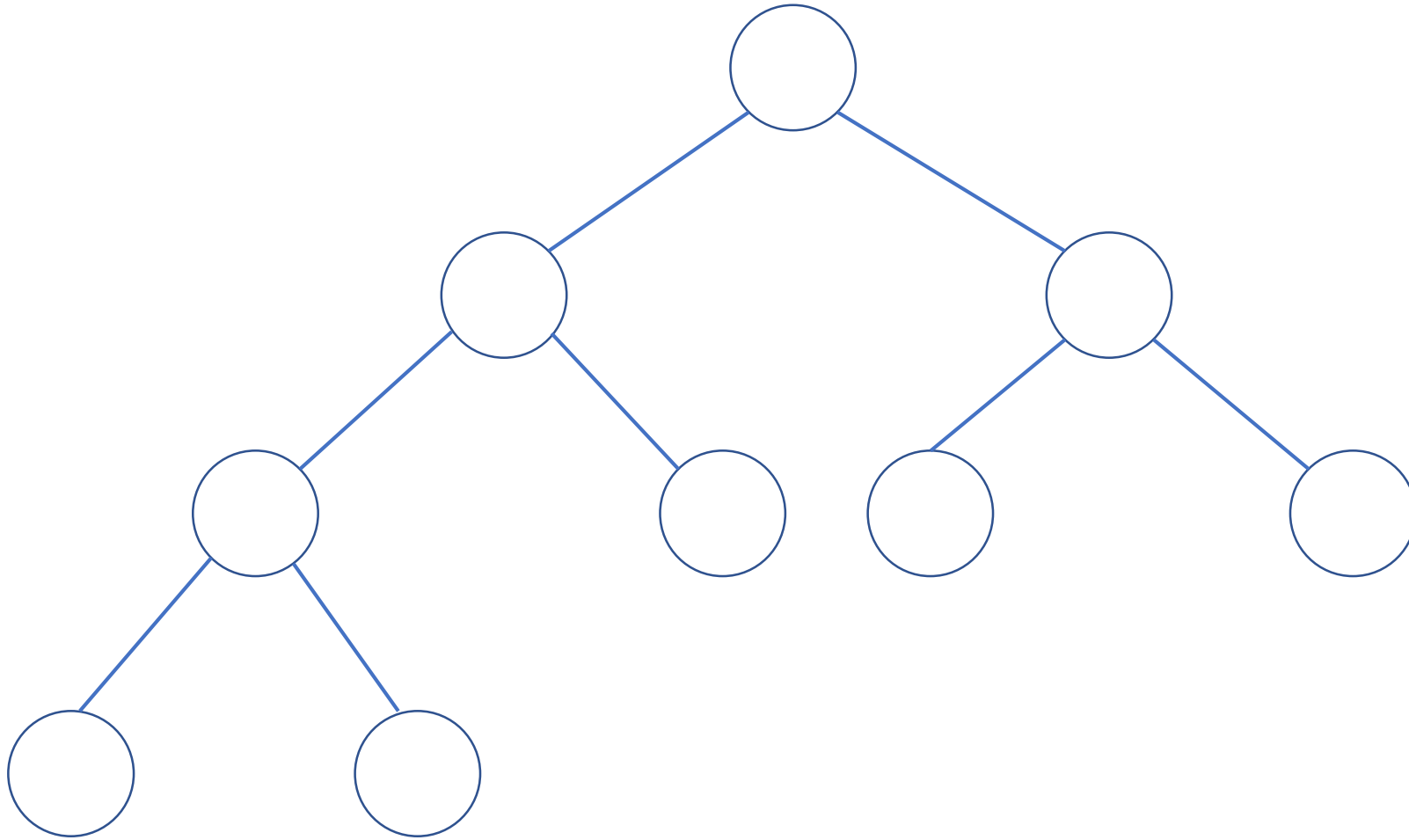
Example of a Max-Heap

$$S = \{3, 4, 5, 7, 7, 9, 9, 12, 17\}$$

(for simplicity, we identify each element with its priority)

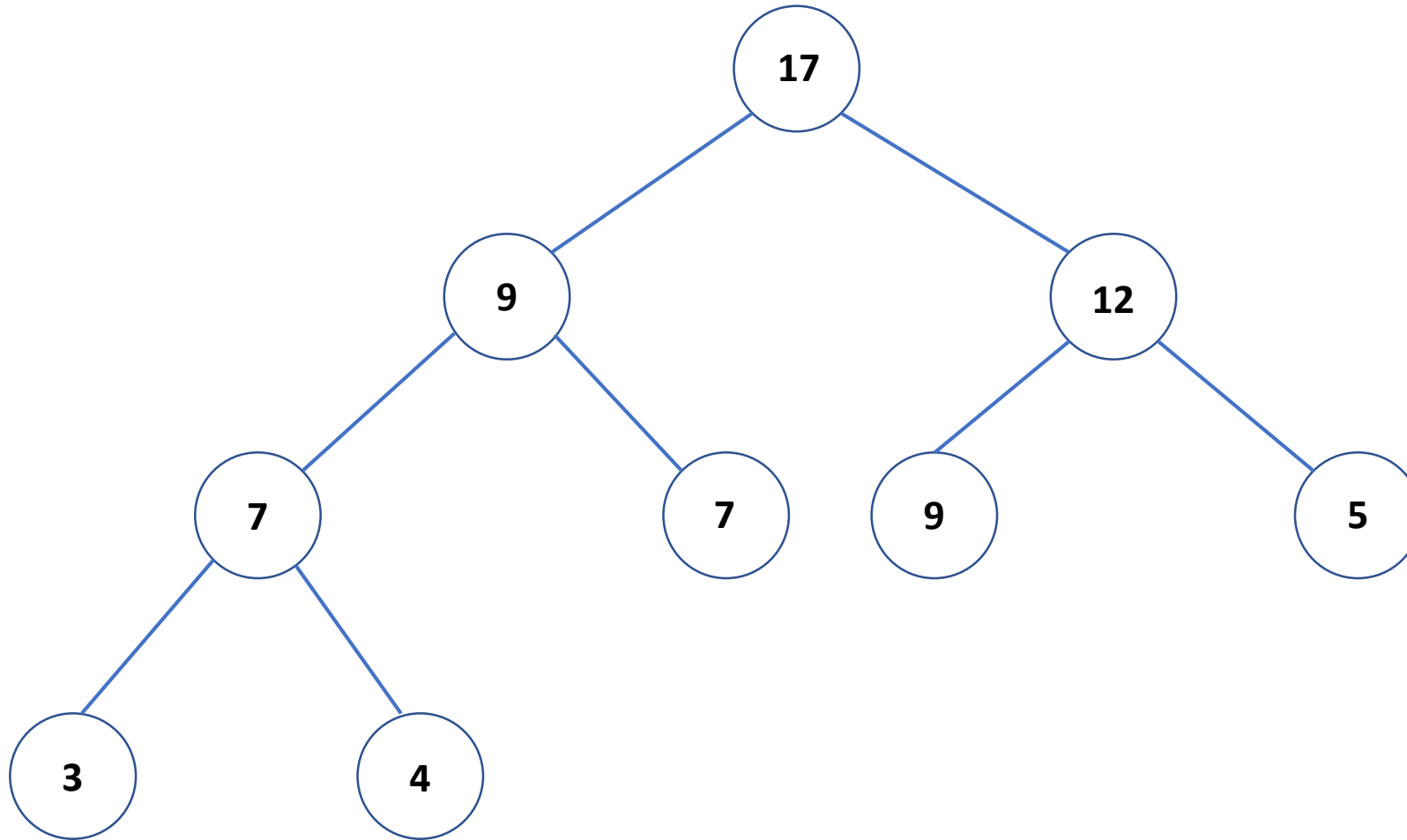
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Example of a Max-Heap

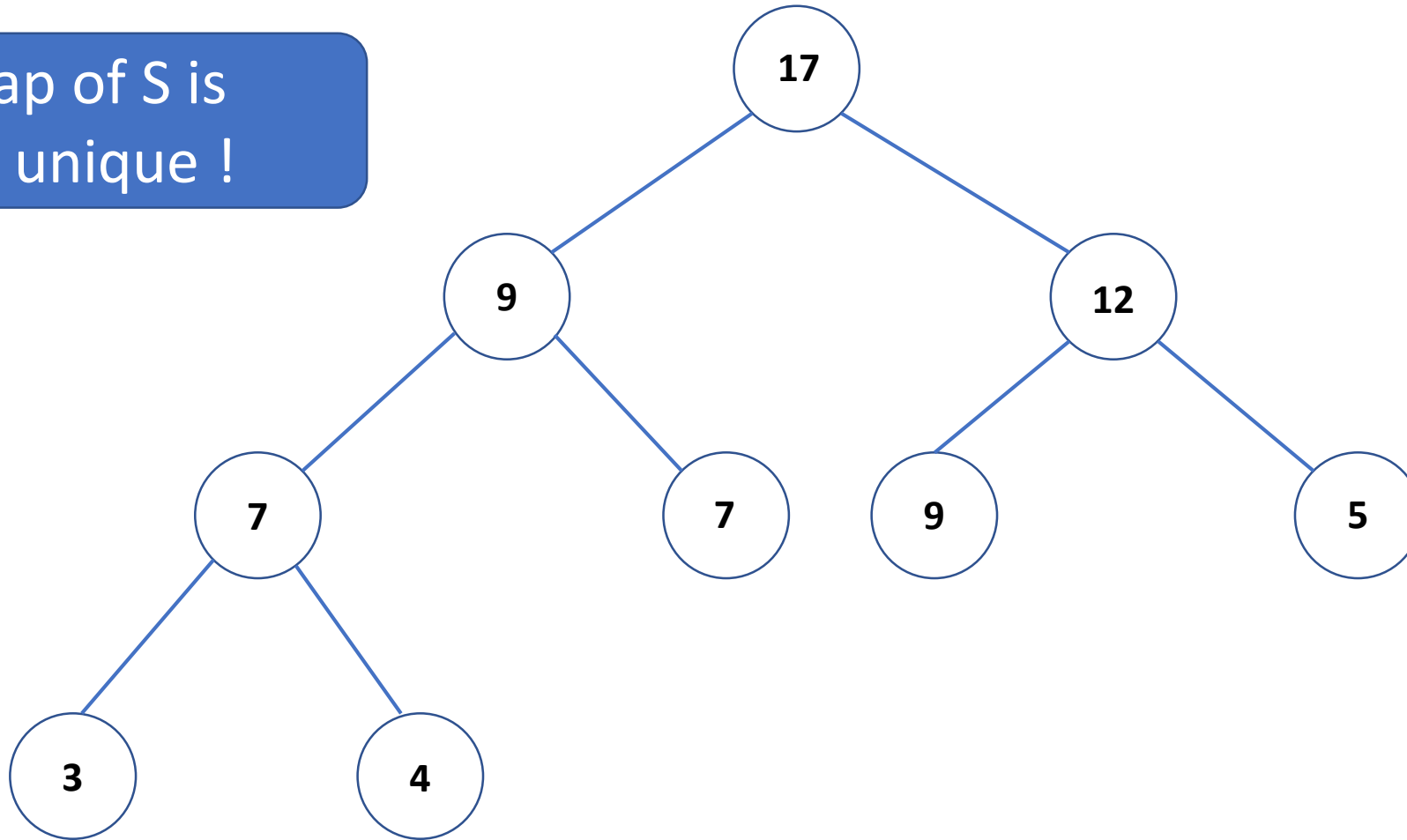
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$S = \{3, 4, 5, 7, 7, 9, 9, 12, 17\}$

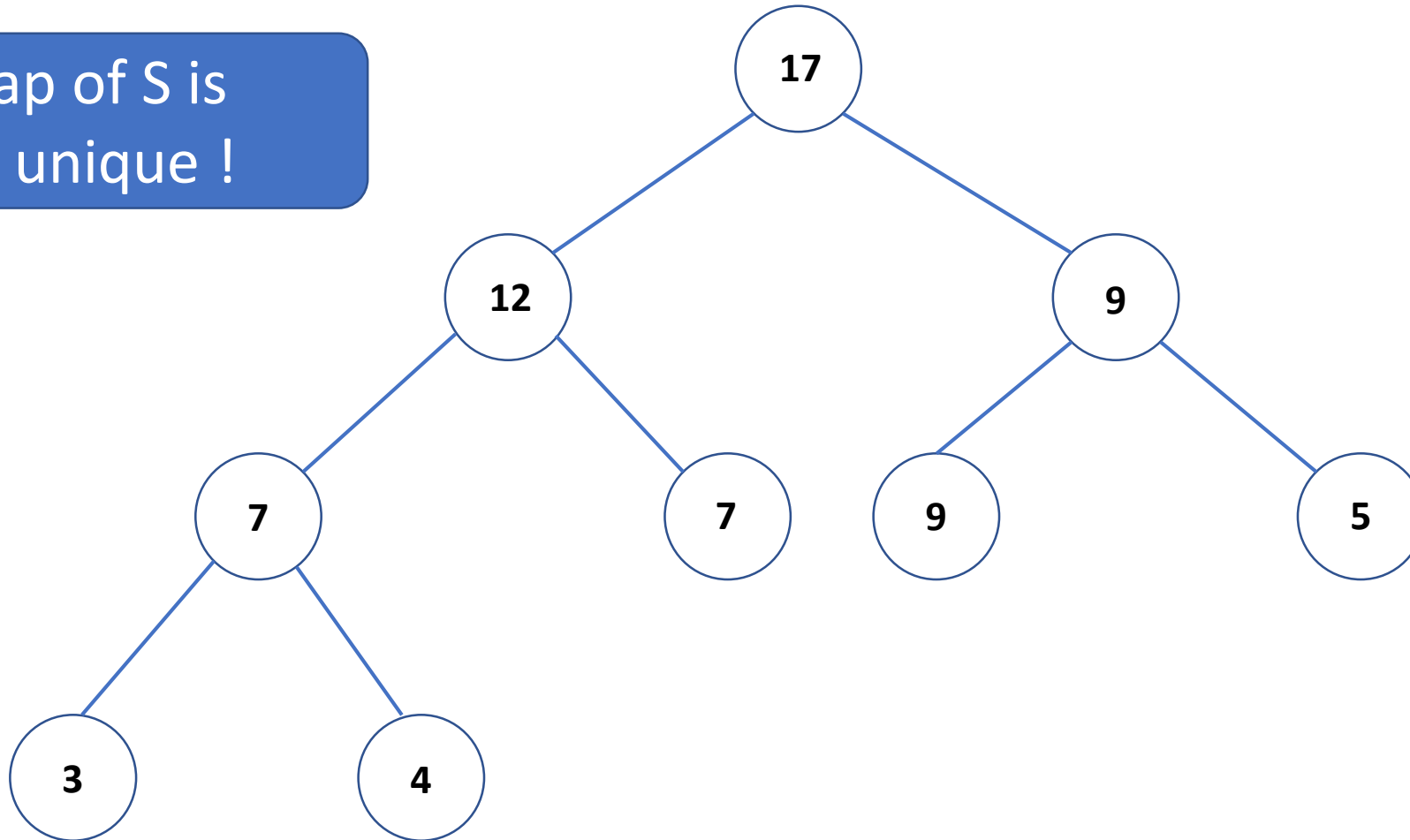
Heap of S is
not unique !



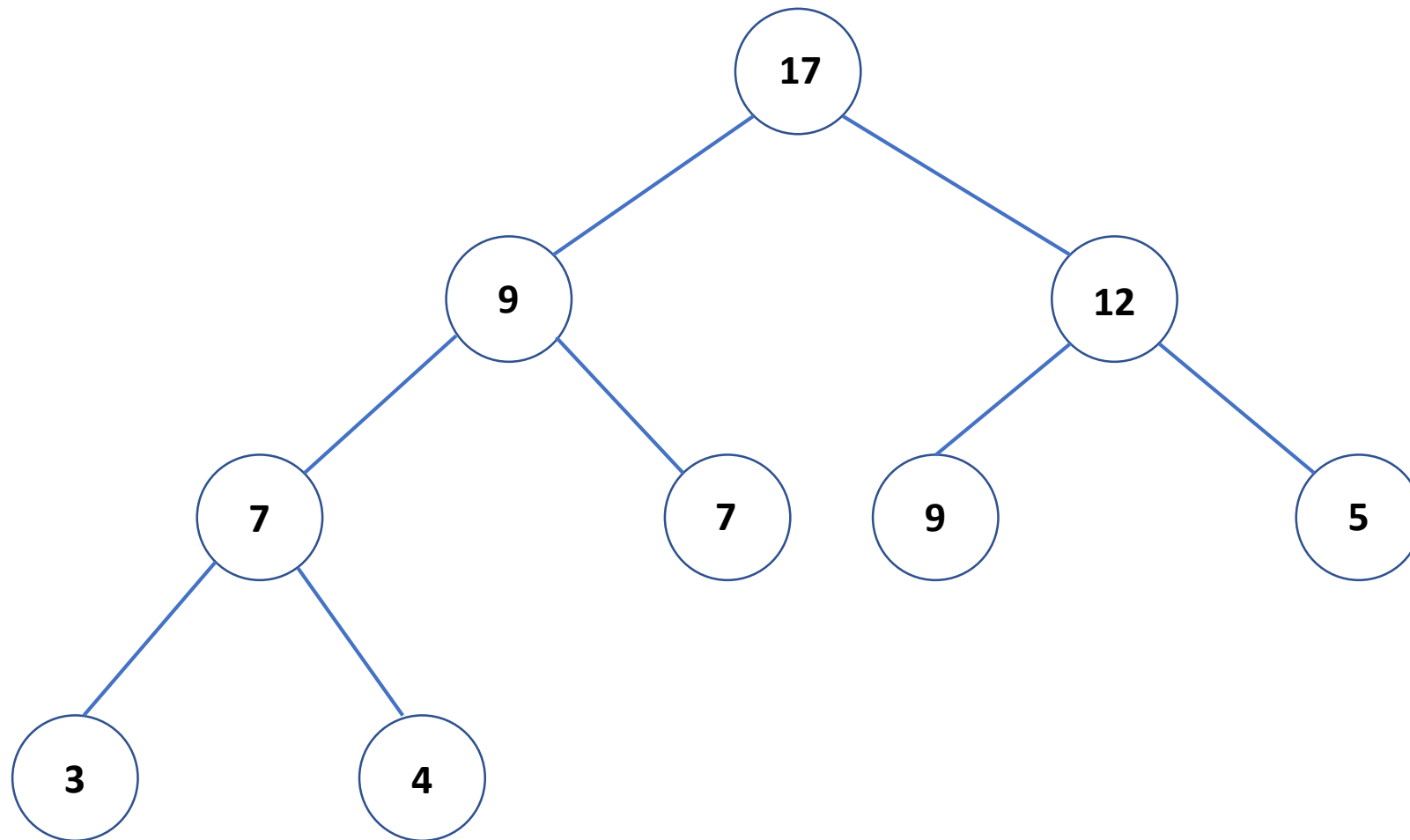
Example of a Max-Heap

$S = \{3, 4, 5, 7, 7, 9, 9, 12, 17\}$

Heap of S is
not unique !



Array Representation of a Heap



A:

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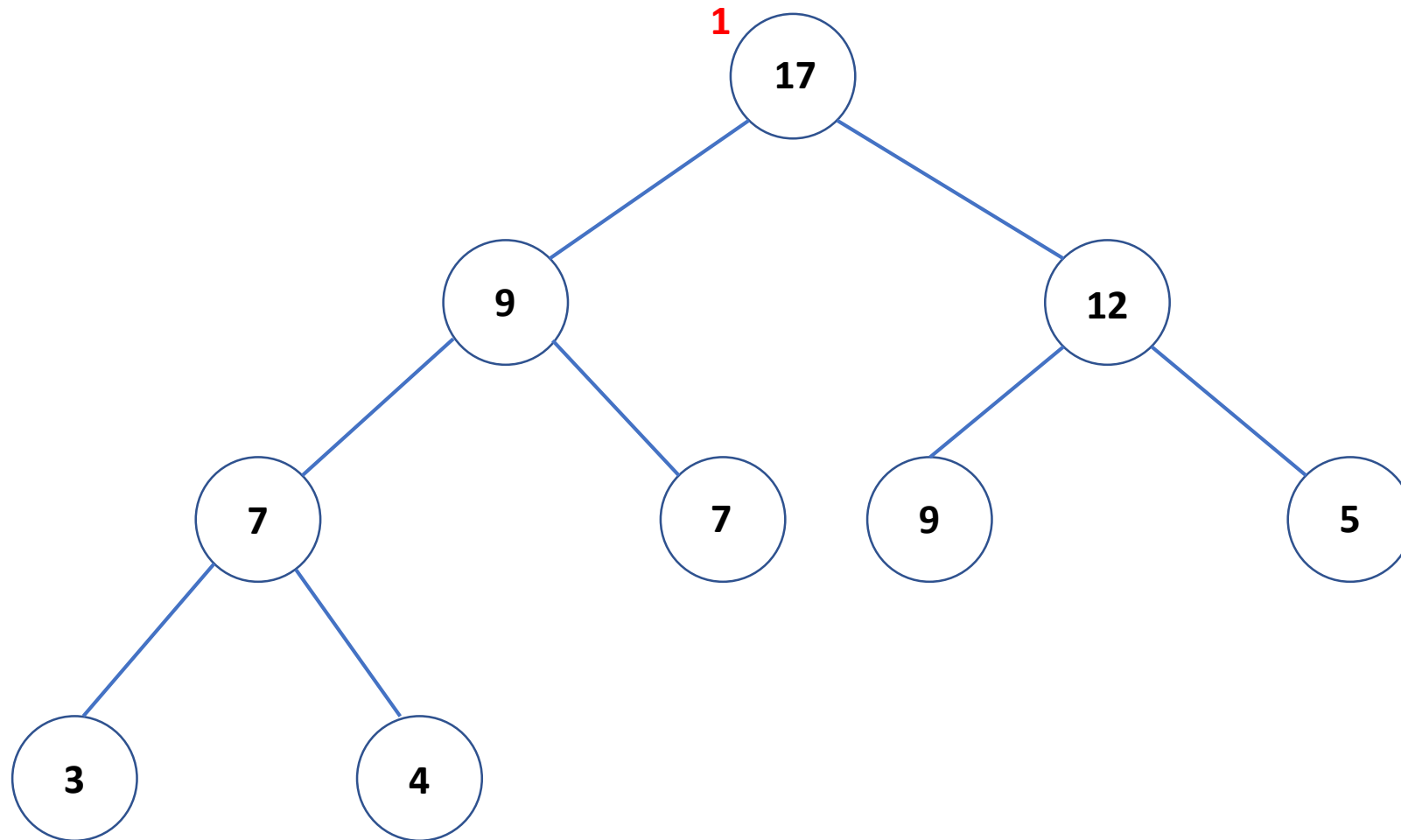
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A:

17								
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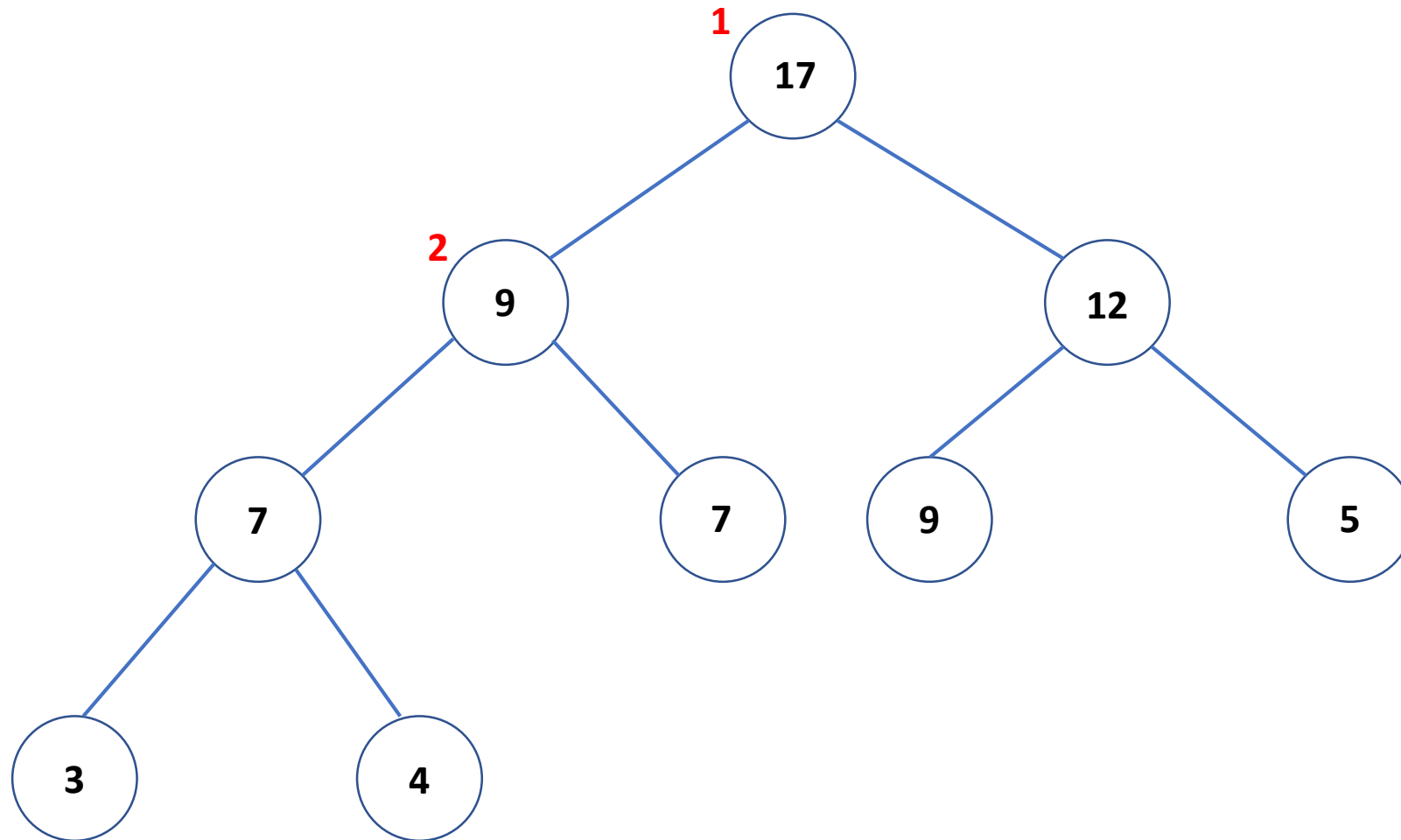
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A:

17	9							
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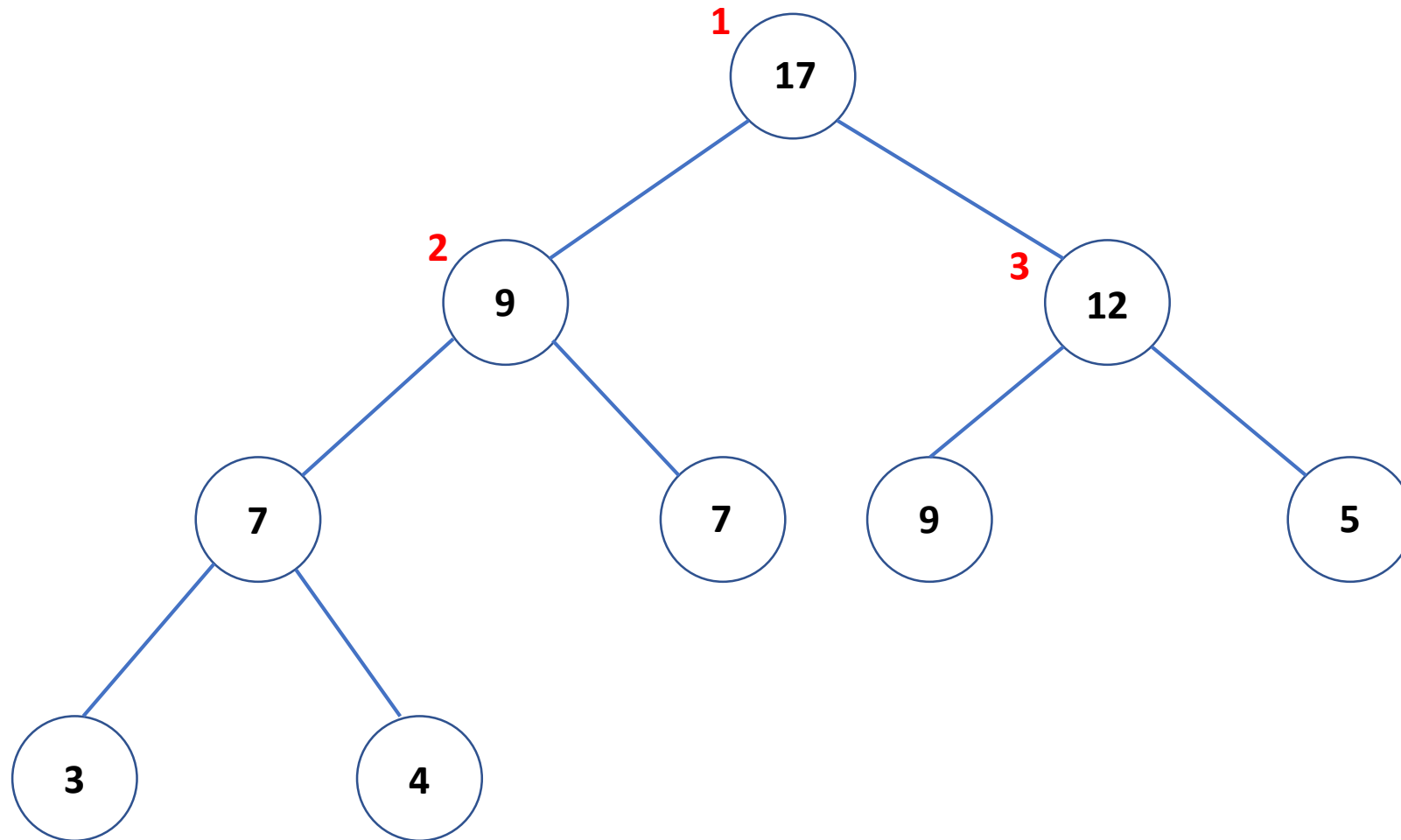
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A:

17	9	12						
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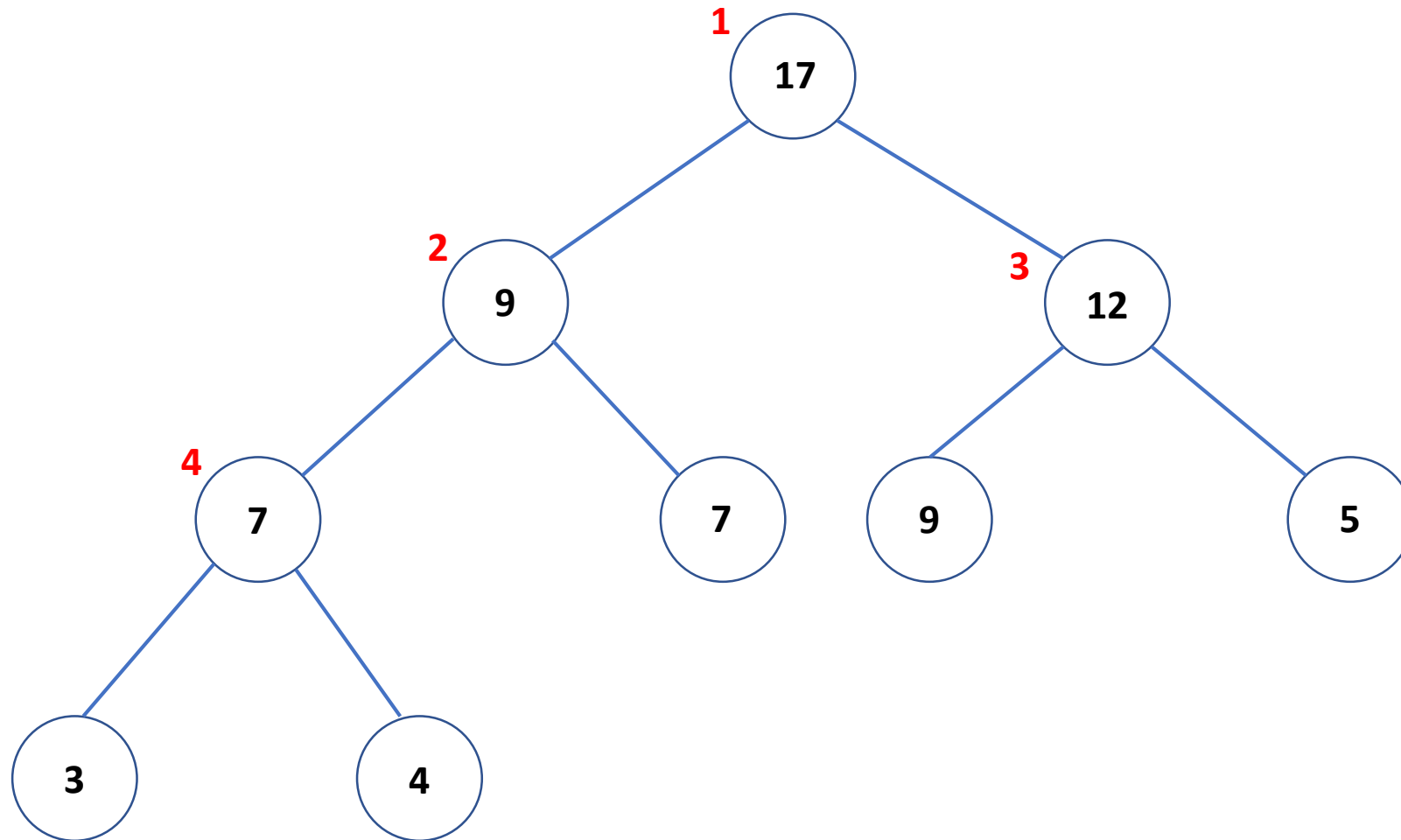
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A:

17	9	12	7					
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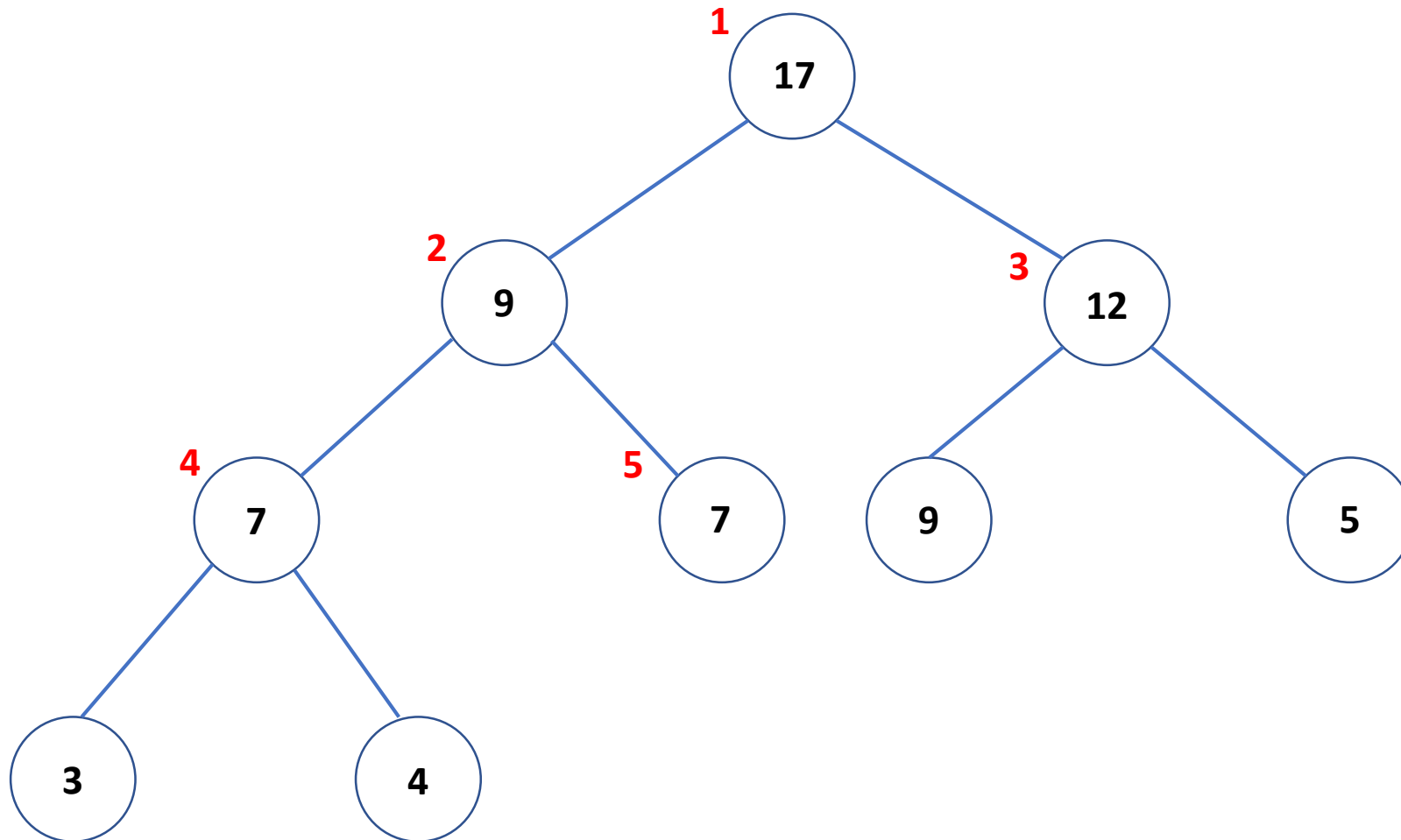
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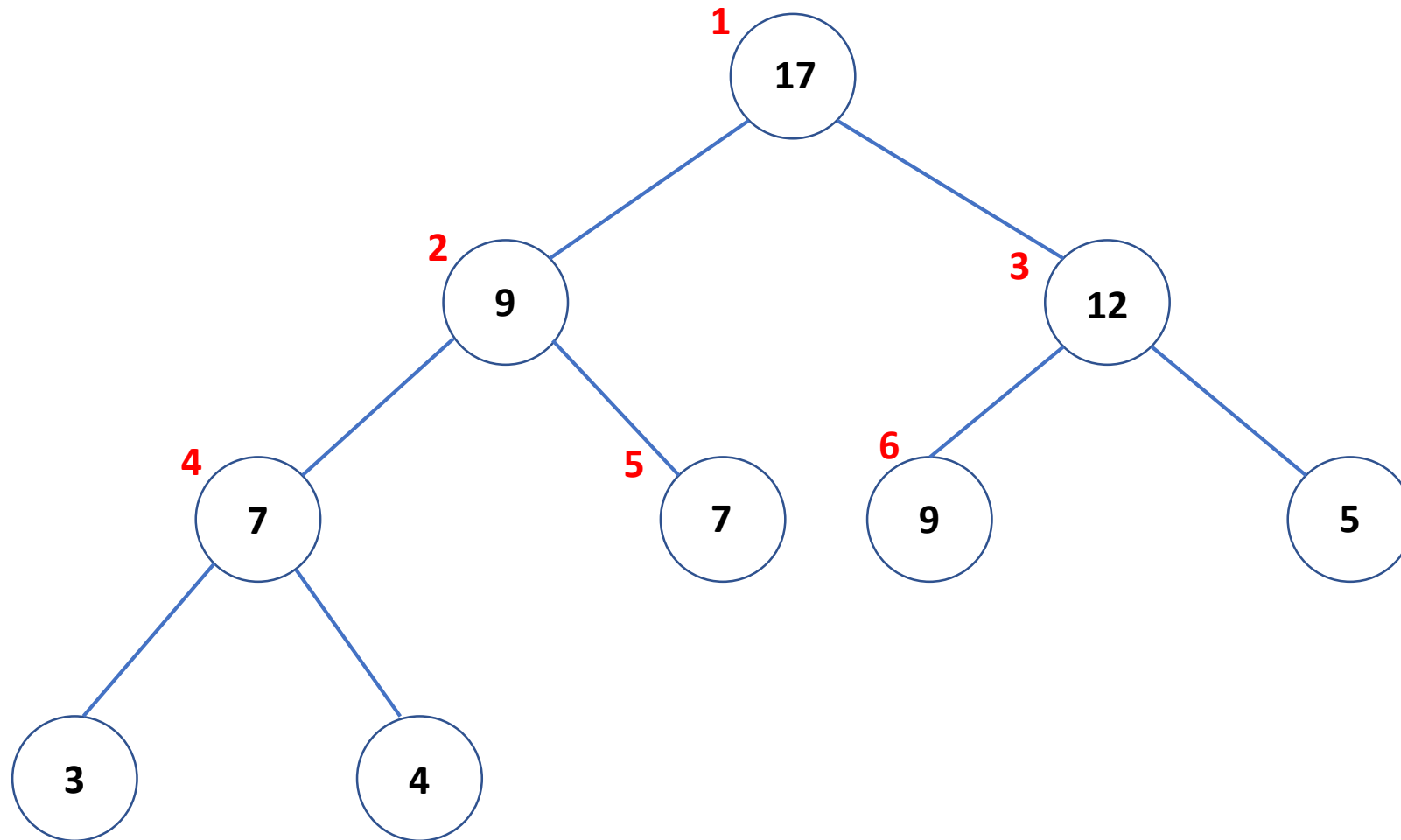
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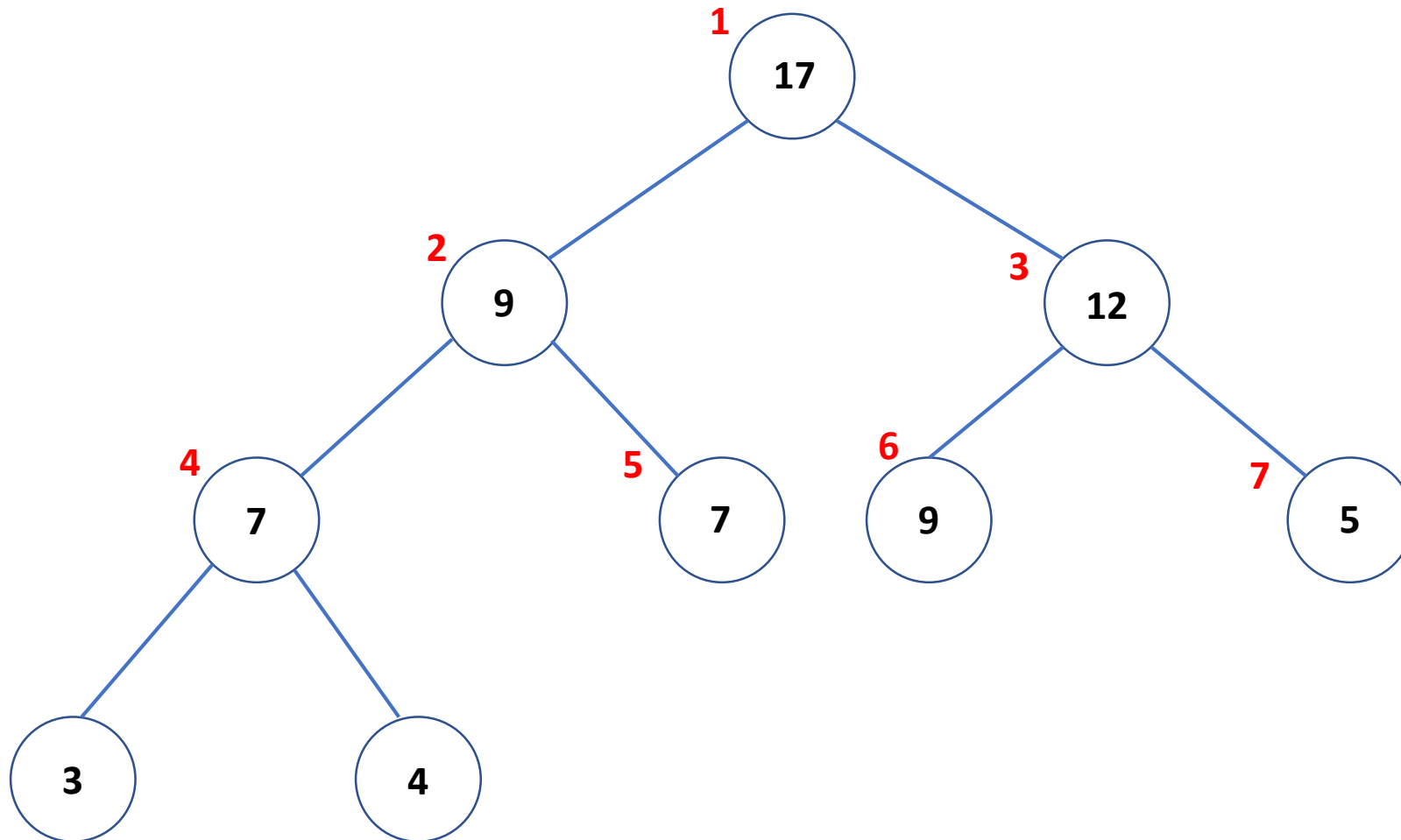
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A:

17	9	12	7	7	9	5		
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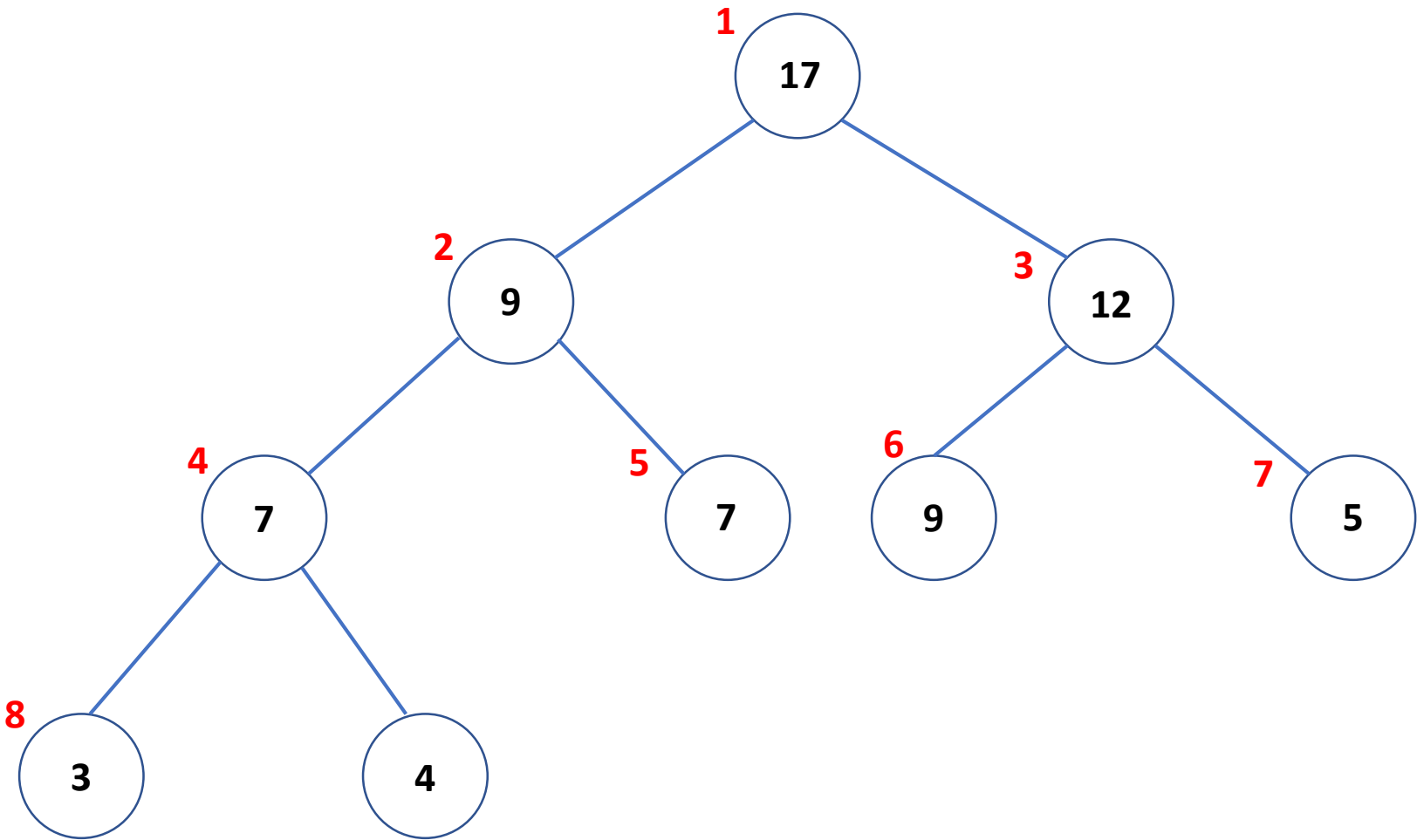
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A:

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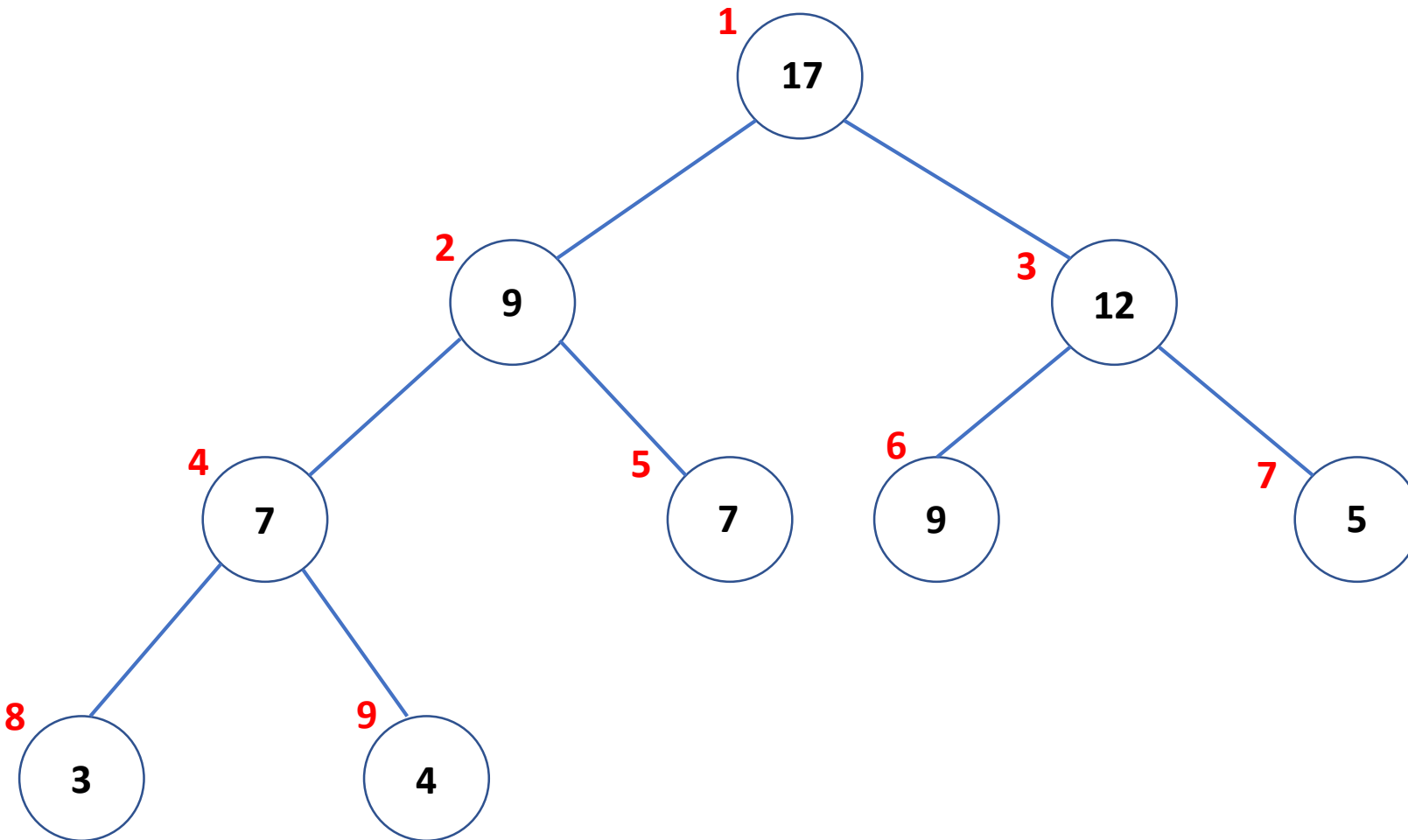
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A:

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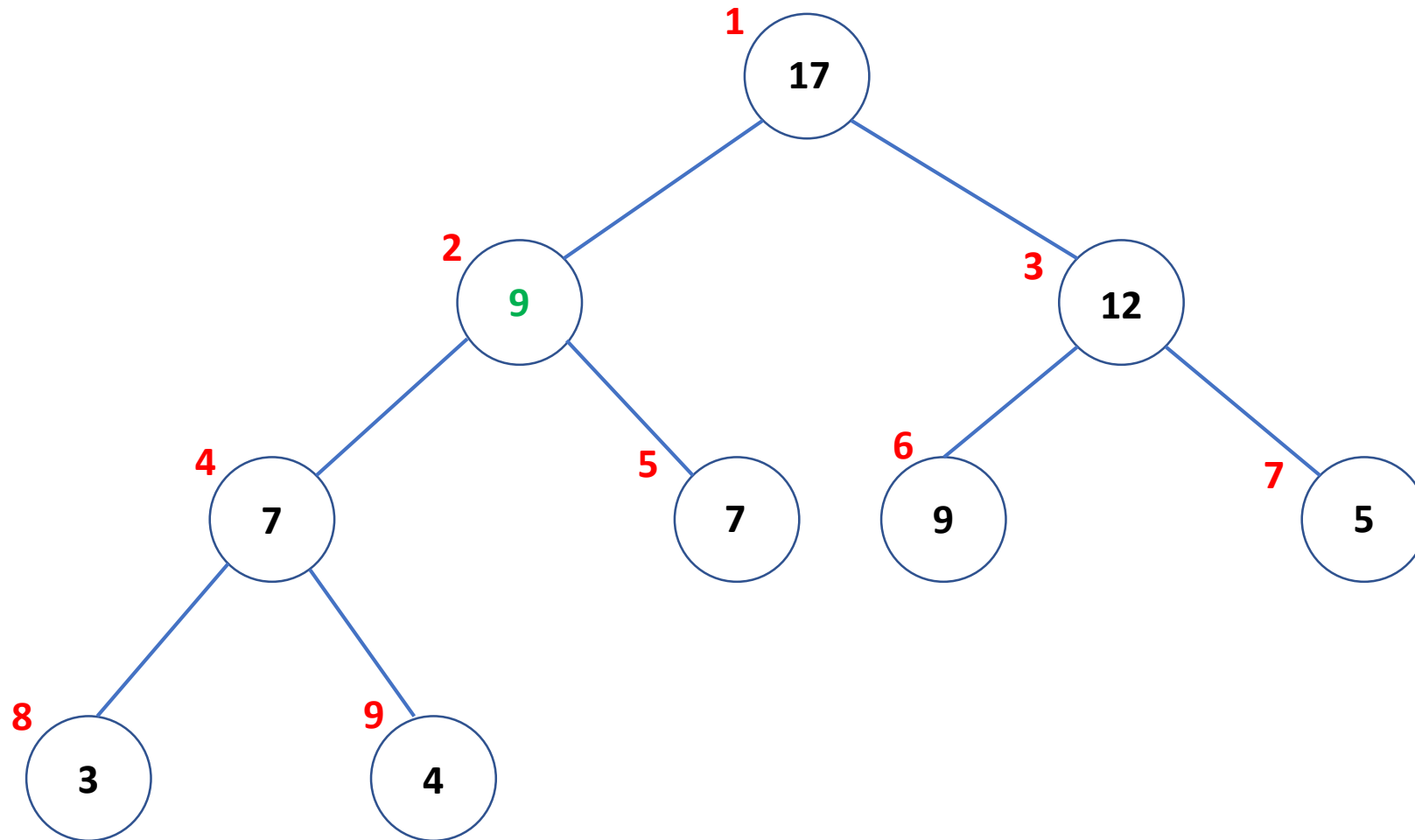
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A.Heapsize = 9



A:

17	9	12	7	7	9	5	3	4
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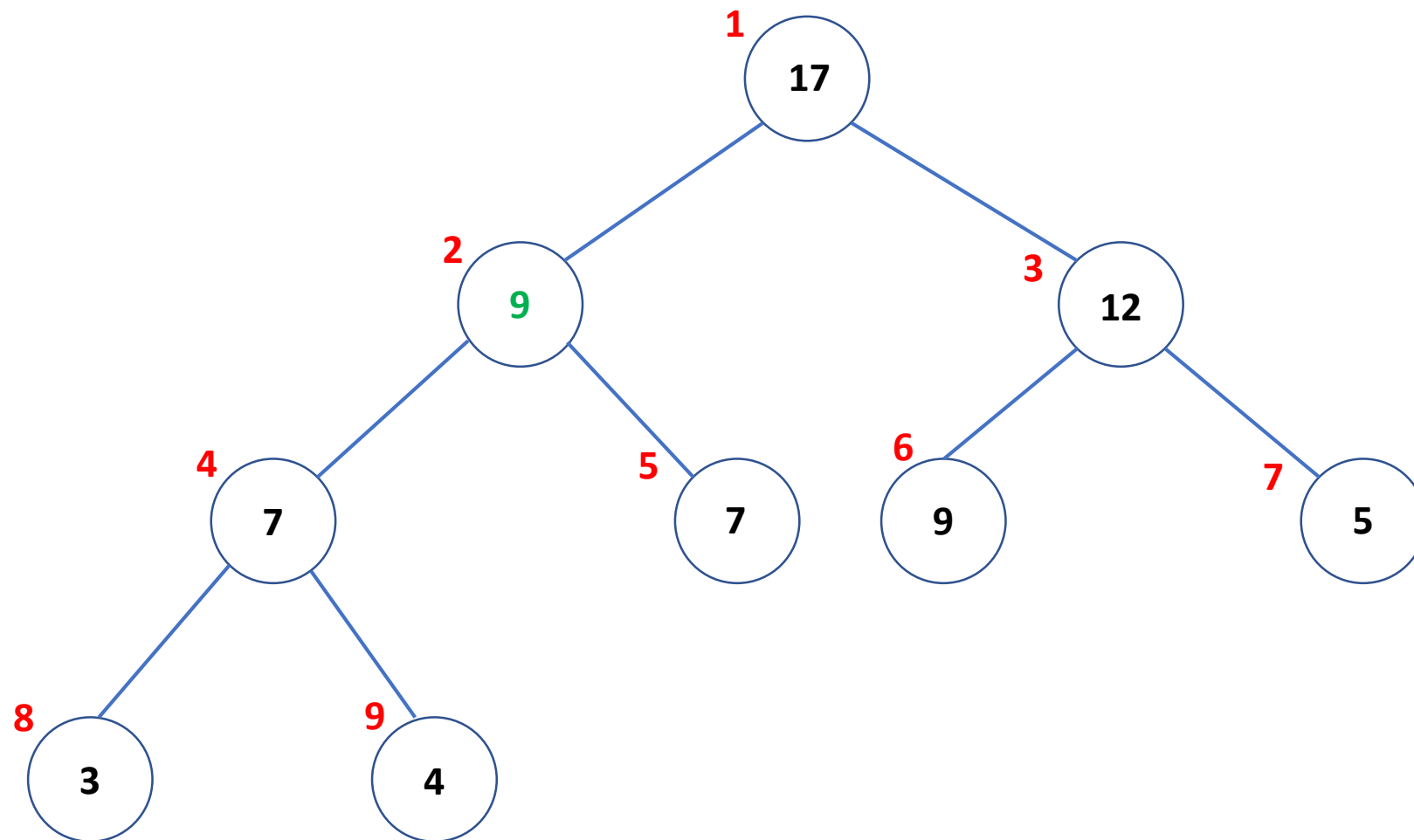
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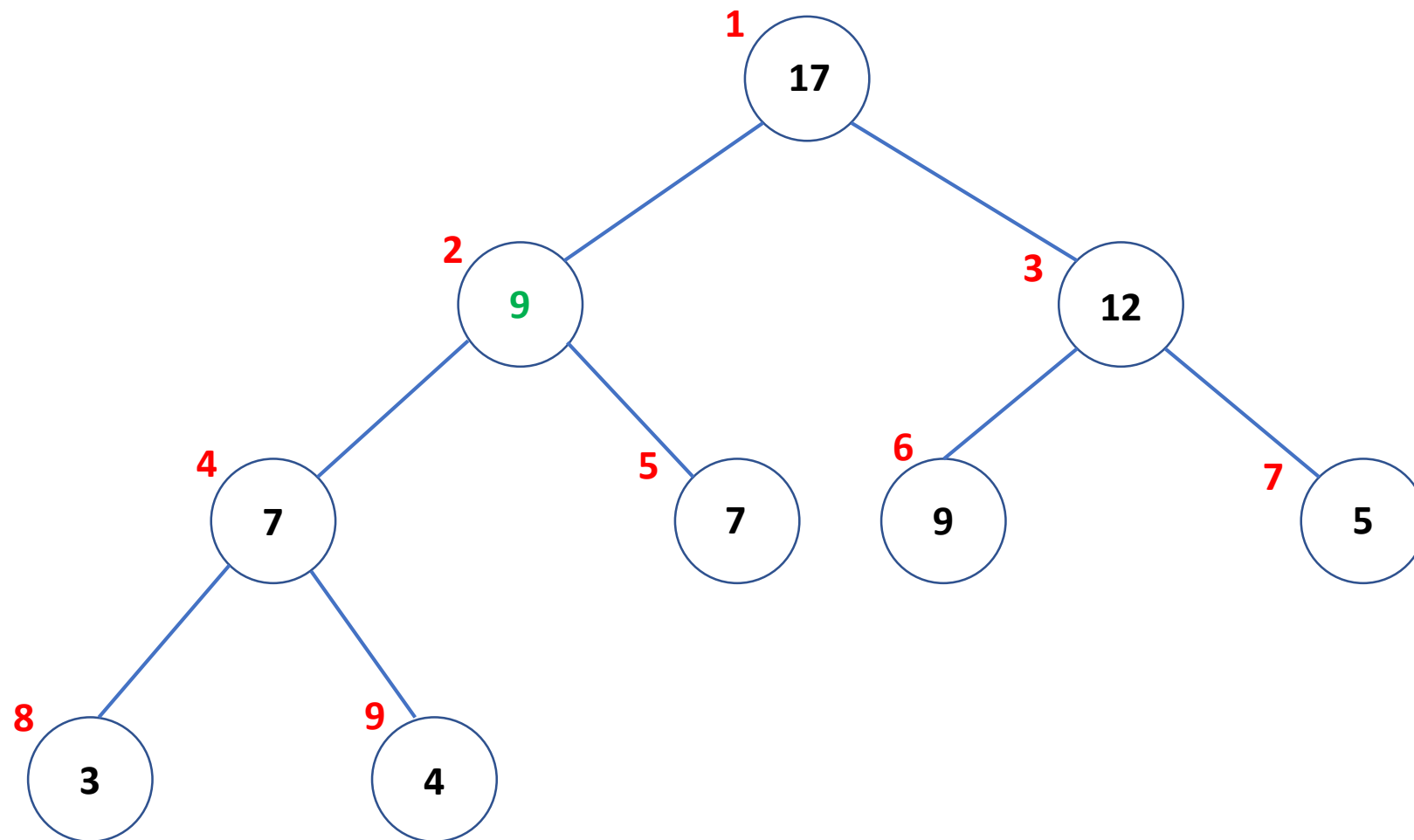
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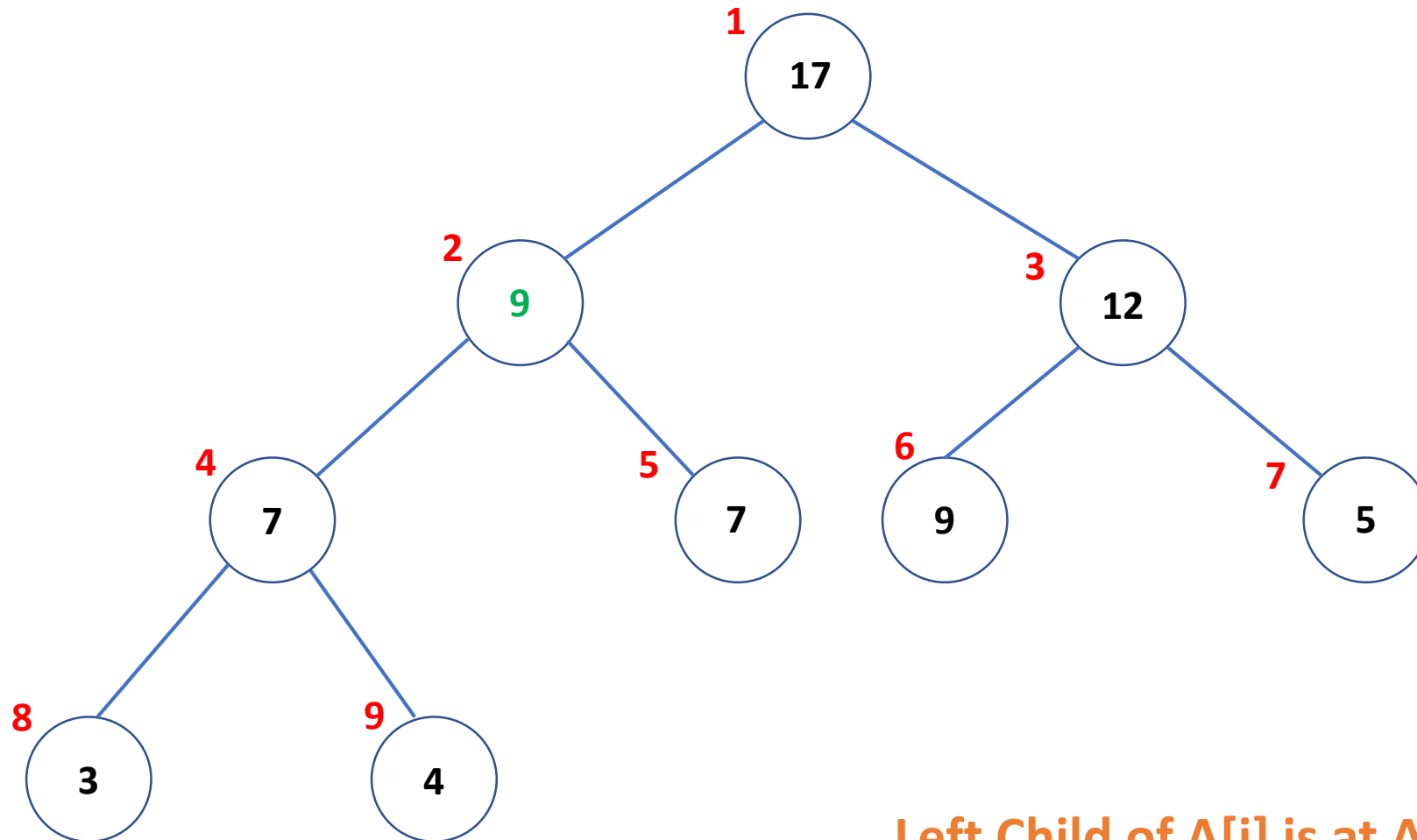
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Left Child of $A[i]$ is at $A[2i]$
Right Child of $A[i]$ is at $A[2i+1]$

A:

17	9	12	7	7	9	5	3	4
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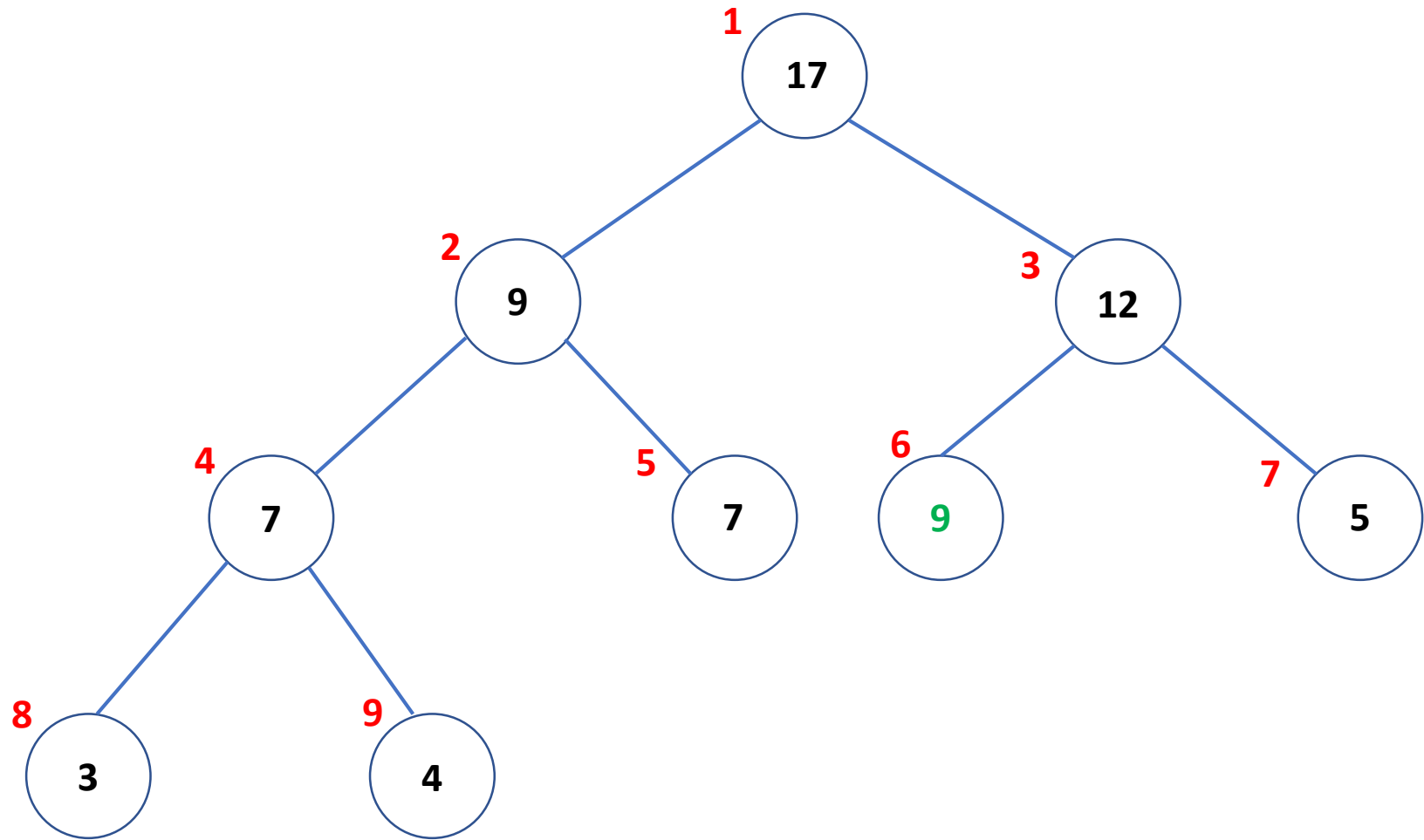
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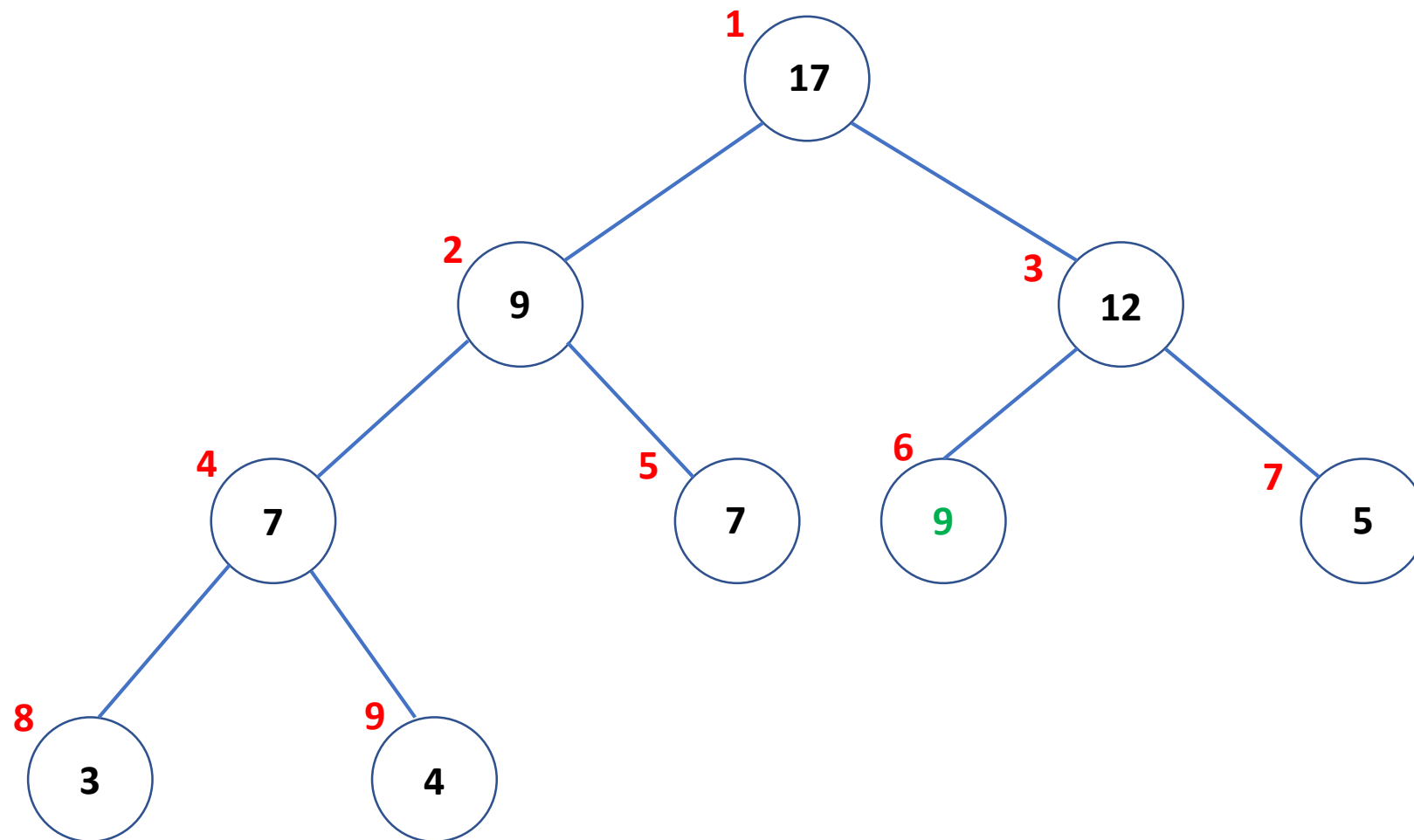
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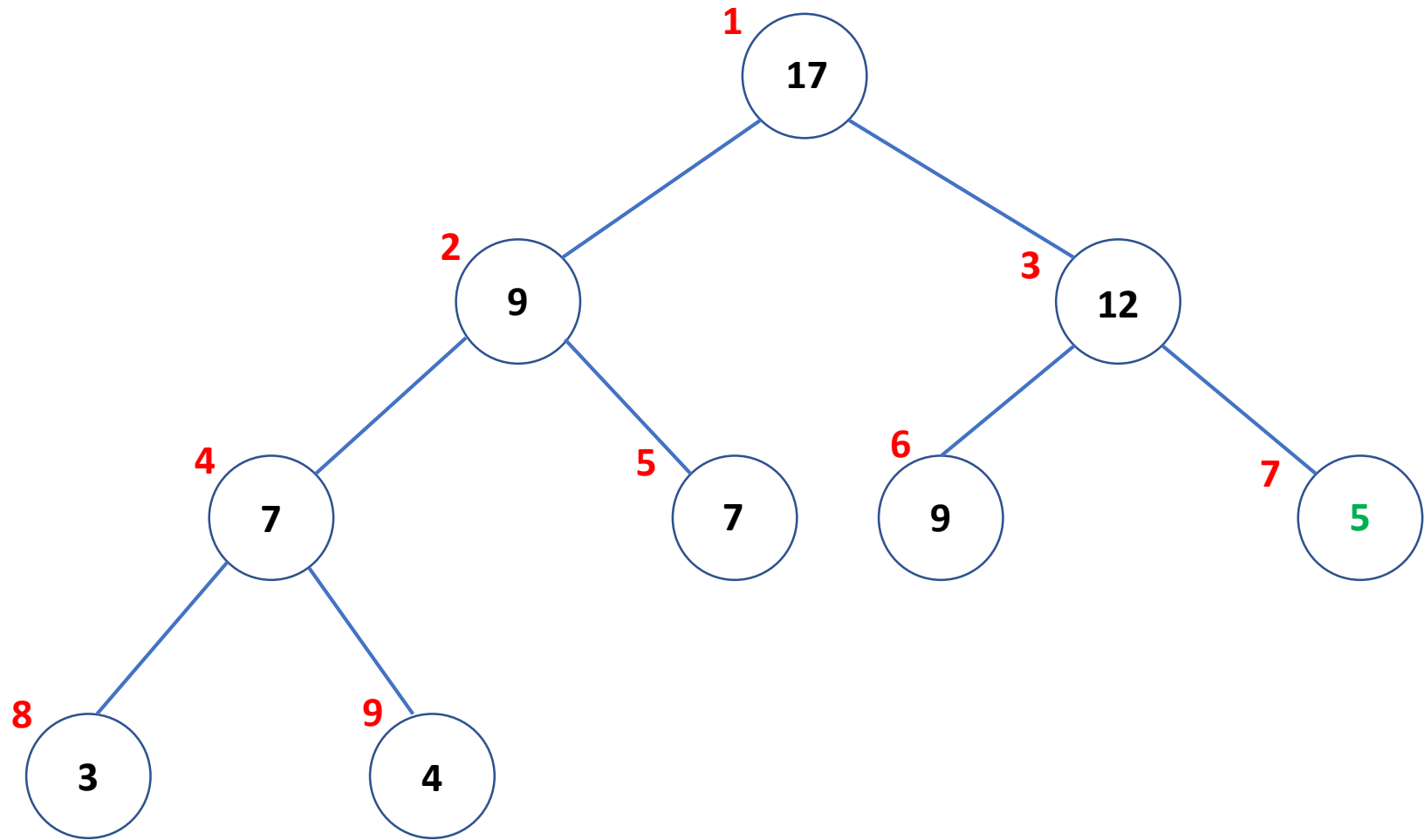
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A:

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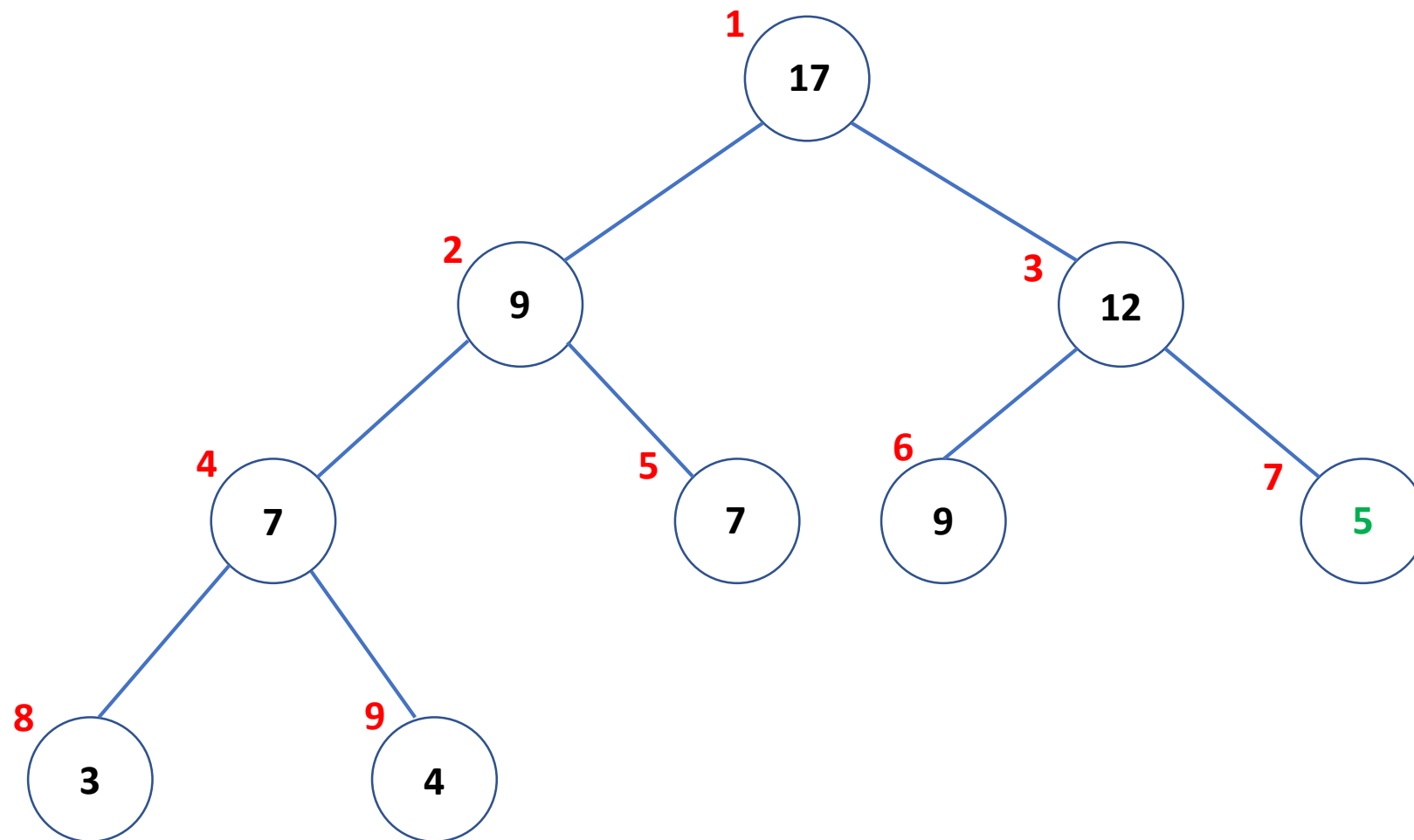
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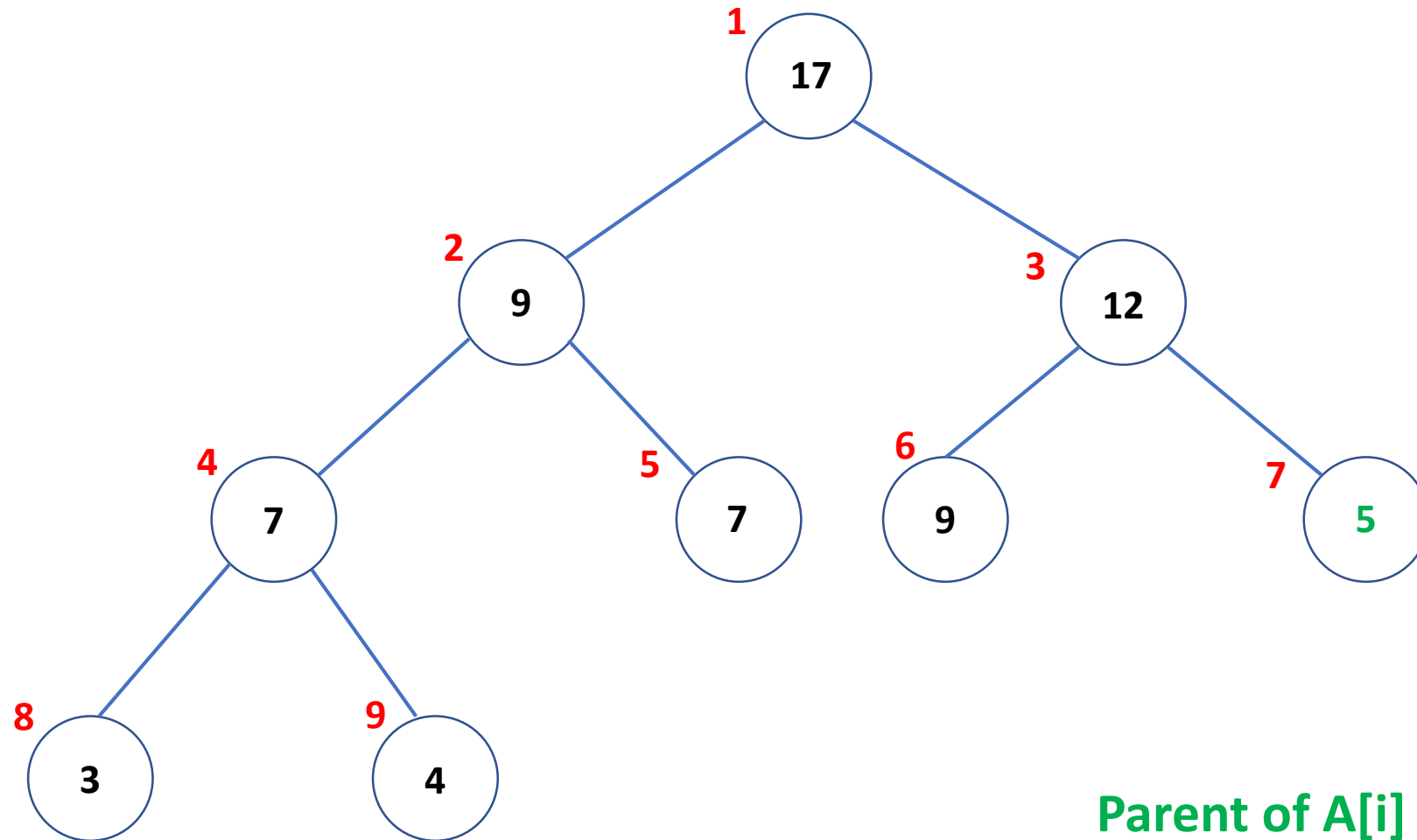
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Parent of $A[i]$ is $A[\lfloor i/2 \rfloor]$

A:

17	9	12	7	7	9	5	3	4
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Efficient navigation in the tree

- Left Child of $A[i]$ is at $A[2i]$
- Right Child of $A[i]$ is at $A[2i+1]$
- Parent of $A[i]$ is $A[\lfloor i/2 \rfloor]$

Heap Operations

We will implement the following operations:

- **Insert(A, x)**
- **Max(A)**
- **Extract_Max(A)**

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High-Level idea for operations:

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High-Level idea for operations:

1) Maintain the CBT shape

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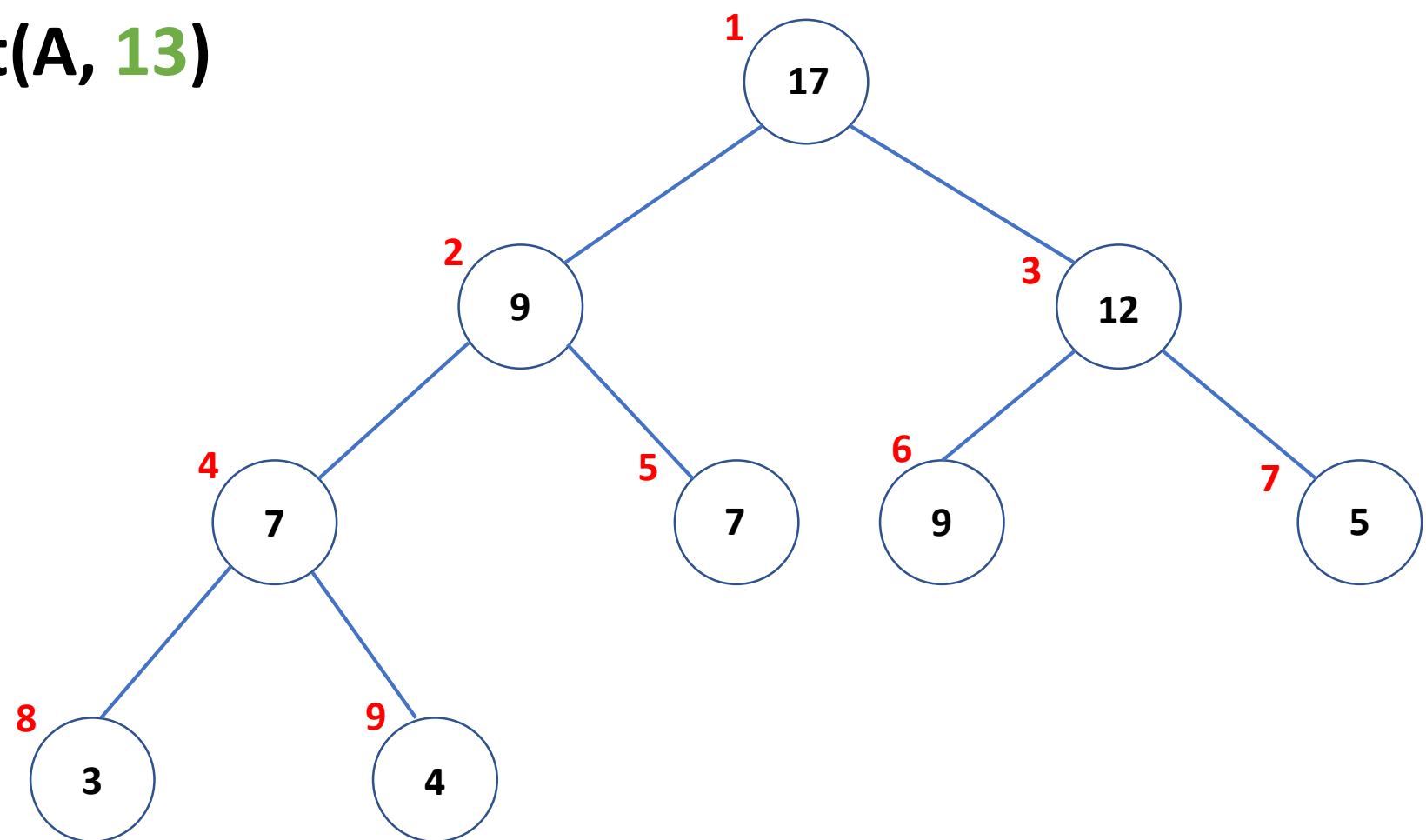
- **Insert(A, x)**
- **Max(A)**
- **Extract_Max(A)**

High-Level idea for operations:

- 1) Maintain the CBT shape
- 2) Maintain the Max-Heap property

Insert(A, x)

Insert(A, 13)



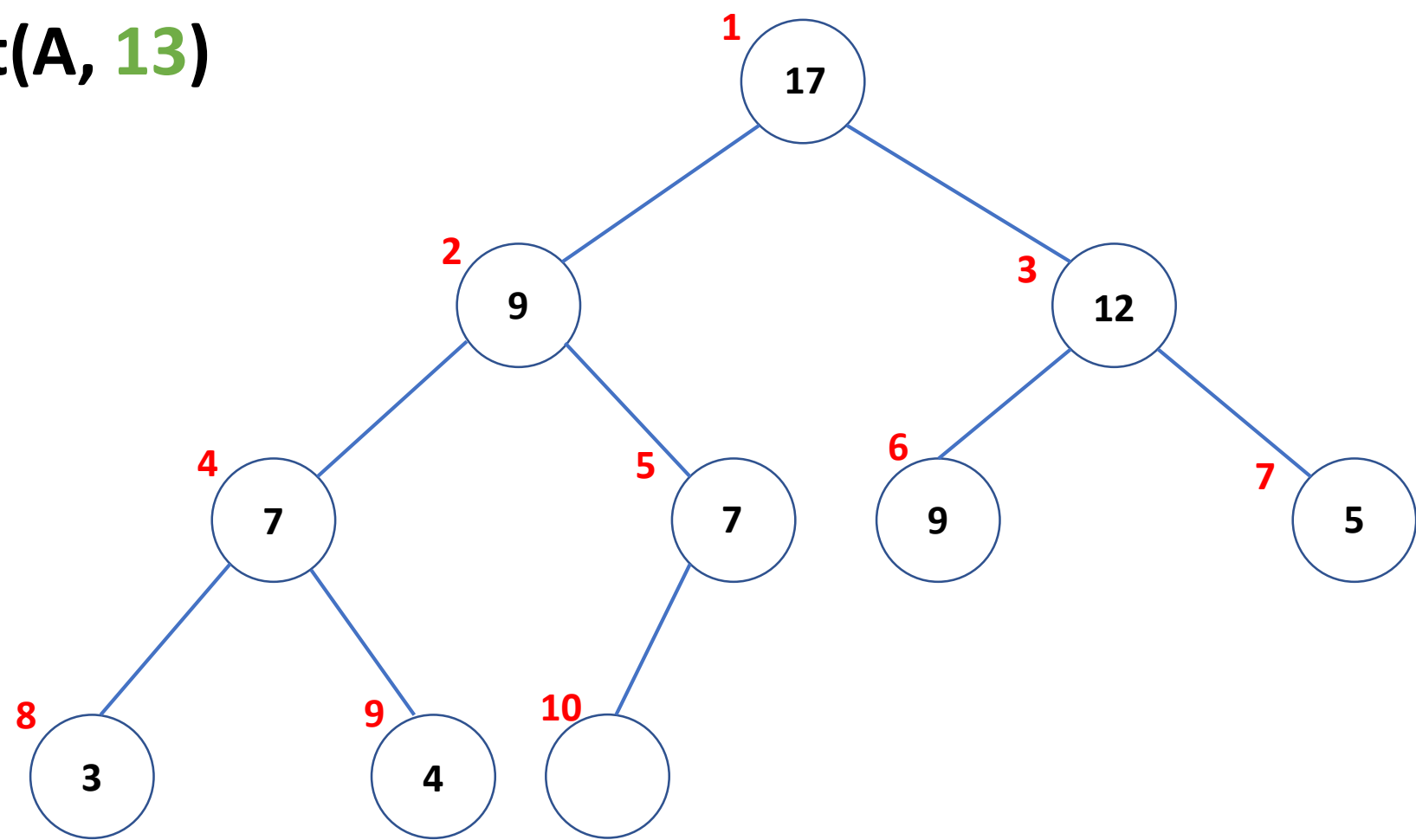
A:

17	9	12	7	7	9	5	3	4
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A.Heapsize = 9

Index 1 2 3 4 5 6 7 8 9

Insert(A, 13)



A:

17	9	12	7	7	9	5	3	4	
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A.Heapsize = 10

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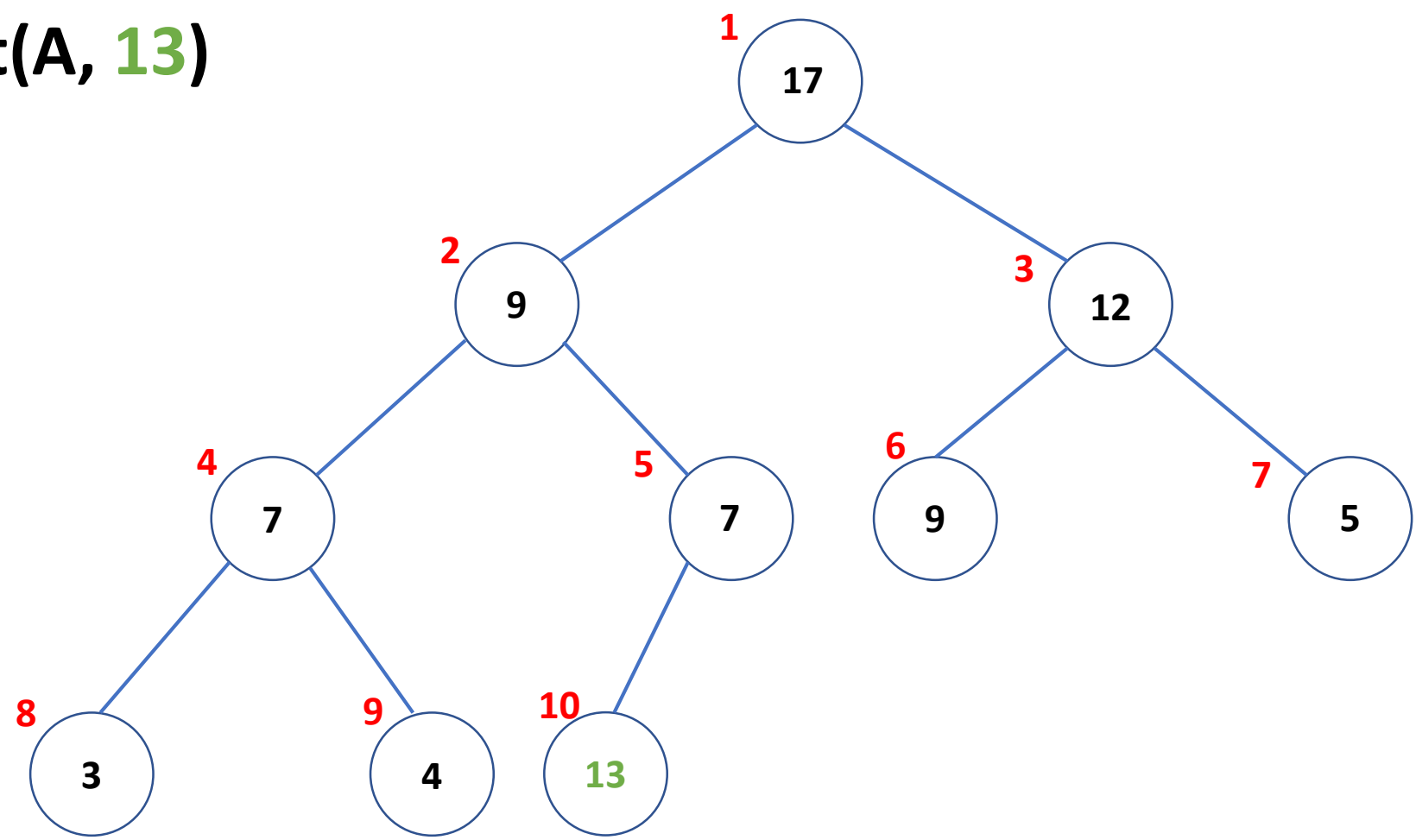
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Insert(A, 13)



A:

17	9	12	7	7	9	5	3	4	13
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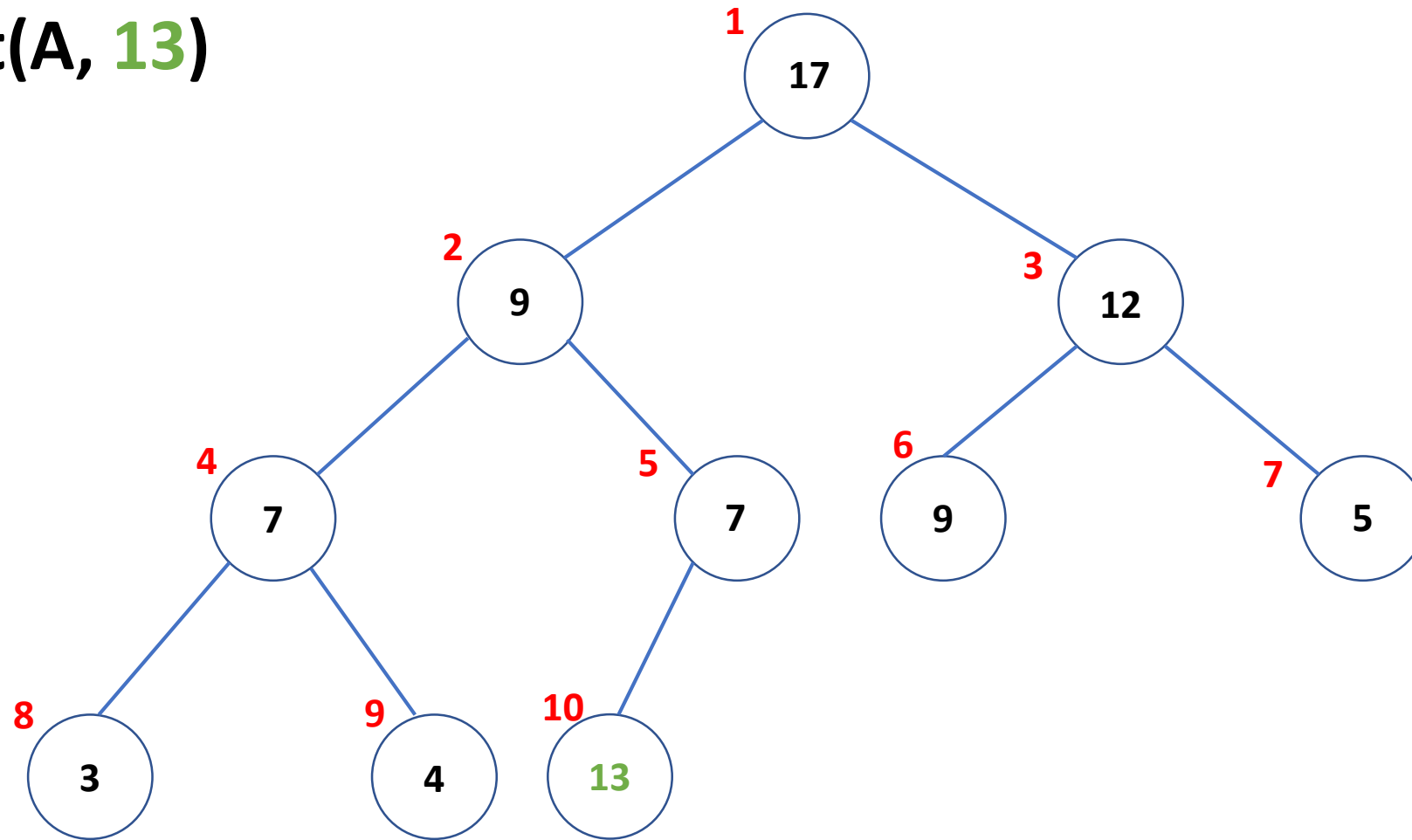
A.Heapsize = 10

Index

1 2 3 4 5 6 7 8 9 10

Insert(A, 13)

This is a CBT,
but Max-Heap
Property has
been violated.



A:

17	9	12	7	7	9	5	3	4	13
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A.Heapsize = 10

Index

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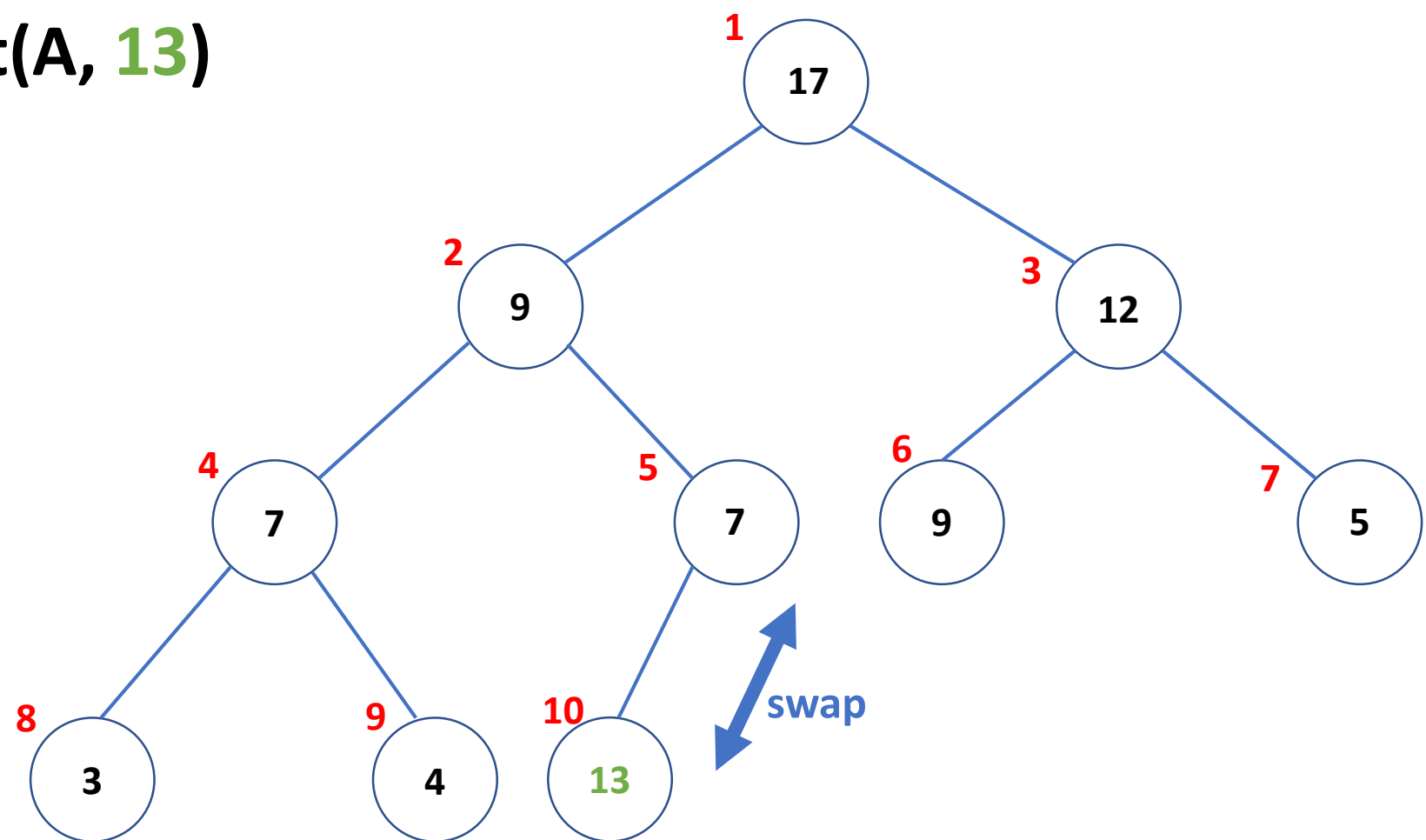
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Insert(A, 13)



A:

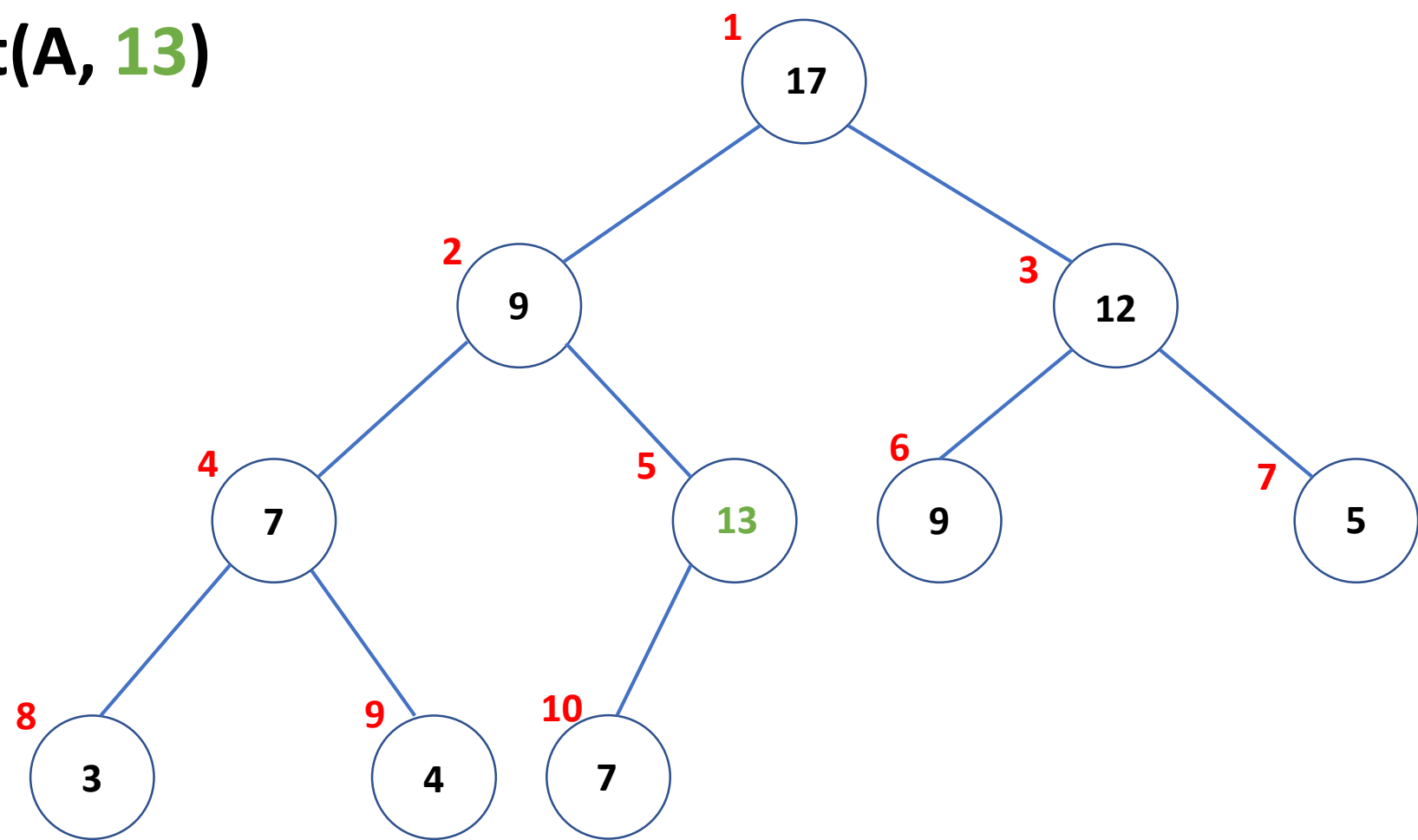
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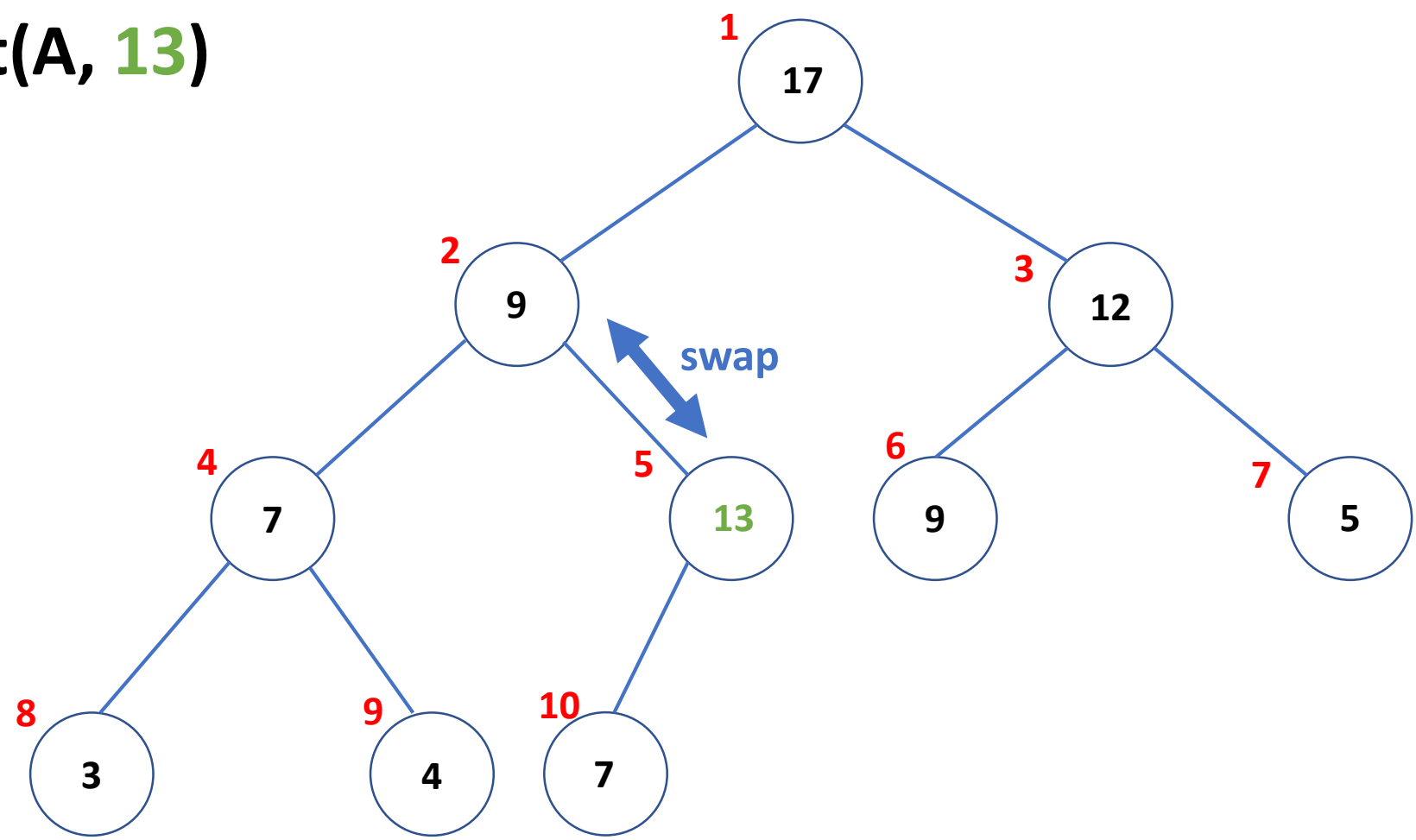
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Insert(A, 13)



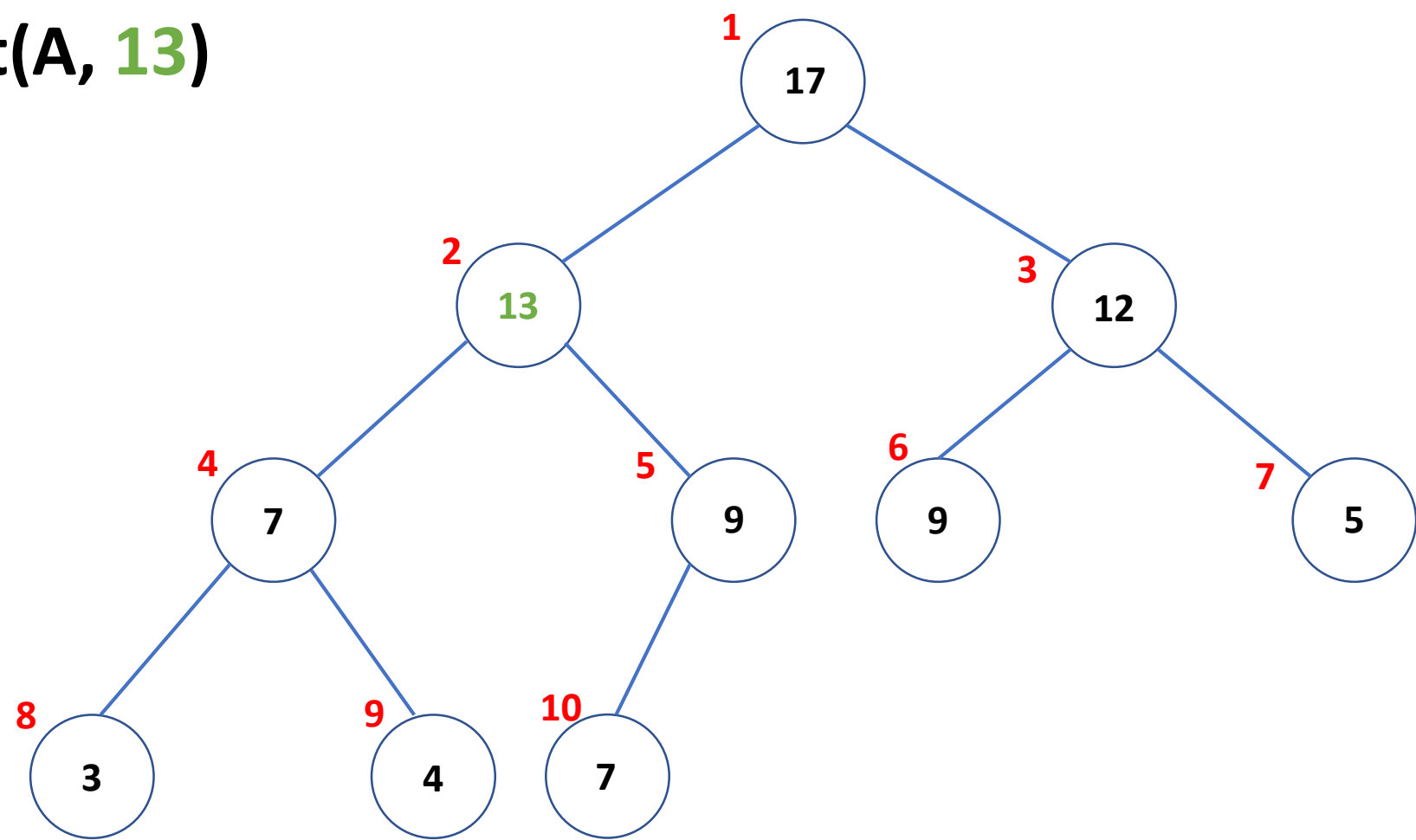
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A.Heapsize = 10

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Insert(A, 13)



A:

17	13	12	7	9	9	5	3	4	7
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A.Heapsize = 10

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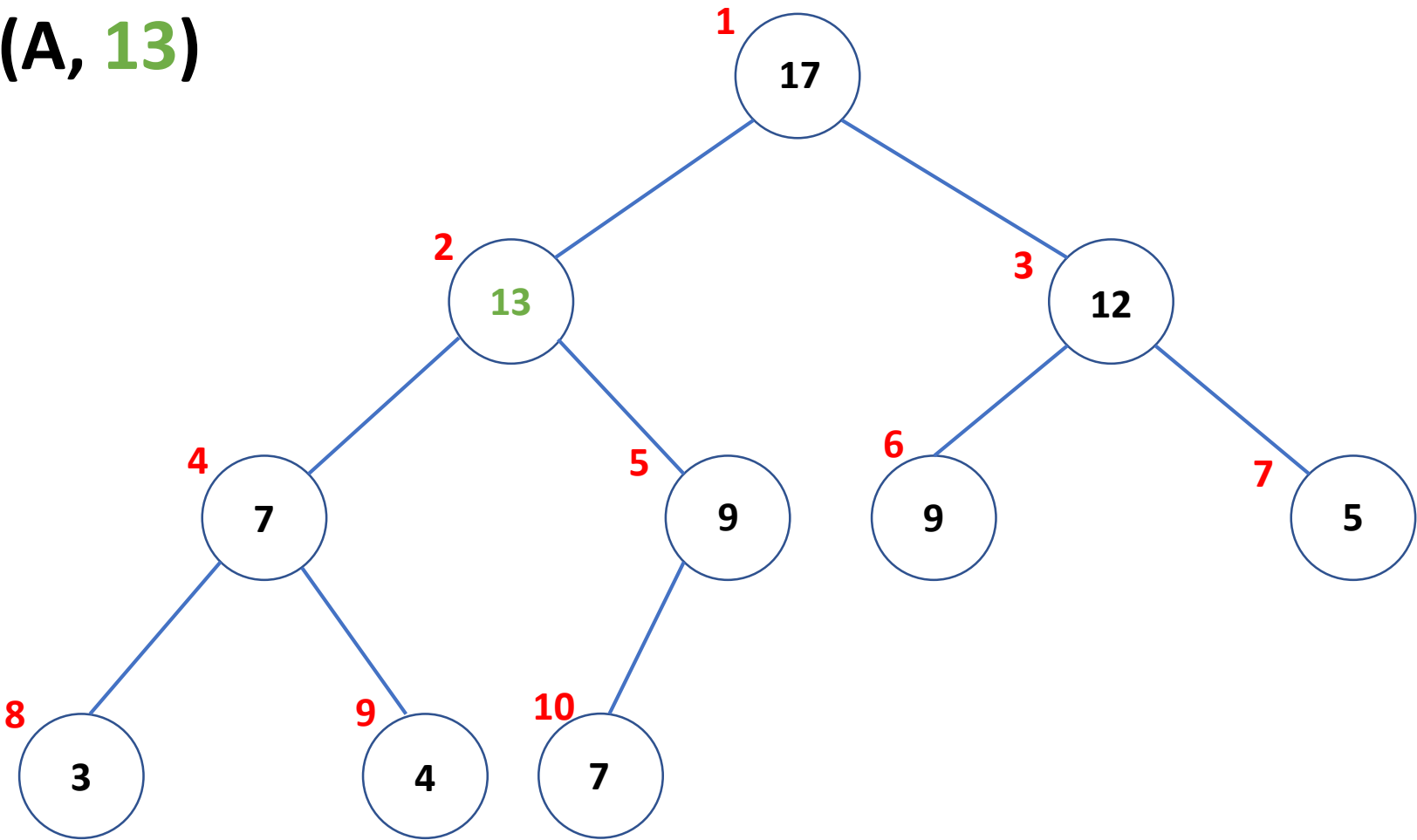
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Insert(A, 13)

Max-Heap
Property has
been restored!



A:

17	13	12	7	9	9	5	3	4	7
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A.Heapsize = 10

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Insert(A, x)

1. Put x at the bottom left of the tree:

Increment A.heapsize and set $A[A.\text{heapsize}] = x$

2. Percolate x up the tree:

While priority of x > priority of its parent

Swap x with parent

Insert(A, x)

1. Put x at the bottom left of the tree:

Increment A.heapsize and set $A[A.\text{heapsize}] = x$

2. Percolate x up the tree:

While x is not root AND priority of x > priority of its parent

Swap x with parent

Insert(A, x)

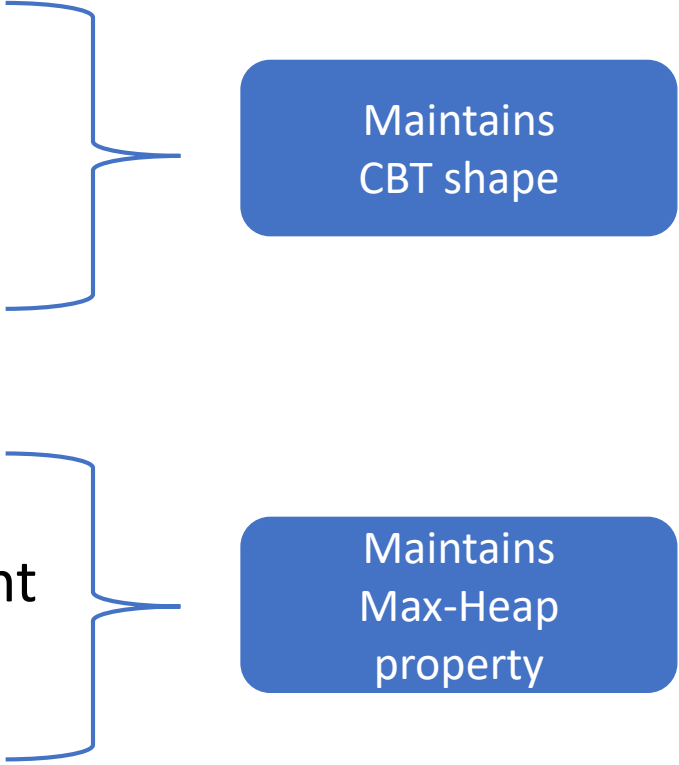
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Increment A.heapsize and set $A[A.heapsize] = x$

2. Percolate x up the tree:

While x is not root AND priority of x > priority of its parent

Swap x with parent



Maintains
CBT shape

Maintains
Max-Heap
property

What is the Worst-Case Complexity of **Insert(A,x)** ?

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$O(\log n)$

For **every** input A,x of size n,
the algorithm takes
at most $c_1 \cdot \log n$ steps.

What is the Worst-Case Complexity of $\text{Insert}(A,x)$?

$$O(\log n)$$

For **every** input A,x of size n ,
the algorithm takes
at most $c_1 \cdot \log n$ steps.

$$\Omega(\log n)$$

For **some** input A,x of size n ,
the algorithm takes
at least $c_2 \cdot \log n$ steps.

What is the Worst-Case Complexity of $\text{Insert}(A,x)$?

$O(\log n)$

For **every** input A,x of size n ,
the algorithm takes
at most $c_1 \cdot \log n$ steps.

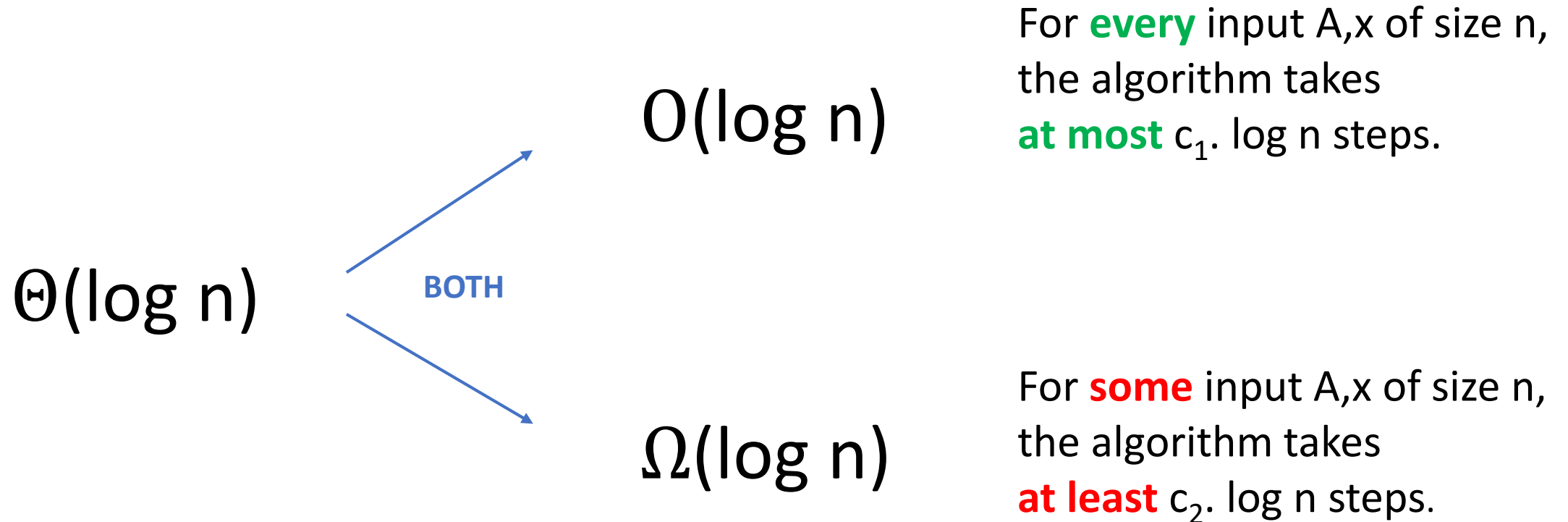
$\Omega(\log n)$

For **some** input A,x of size n ,
the algorithm takes
at least $c_2 \cdot \log n$ steps.



Priority of x is $>$ Priority of root

What is the Worst-Case Complexity of $\text{Insert}(A,x)$?



Max(A)

Max(A):

Return A[1]

Max(A):

Return A[1]



Root of the CBT

Max(A):

Return A[1]

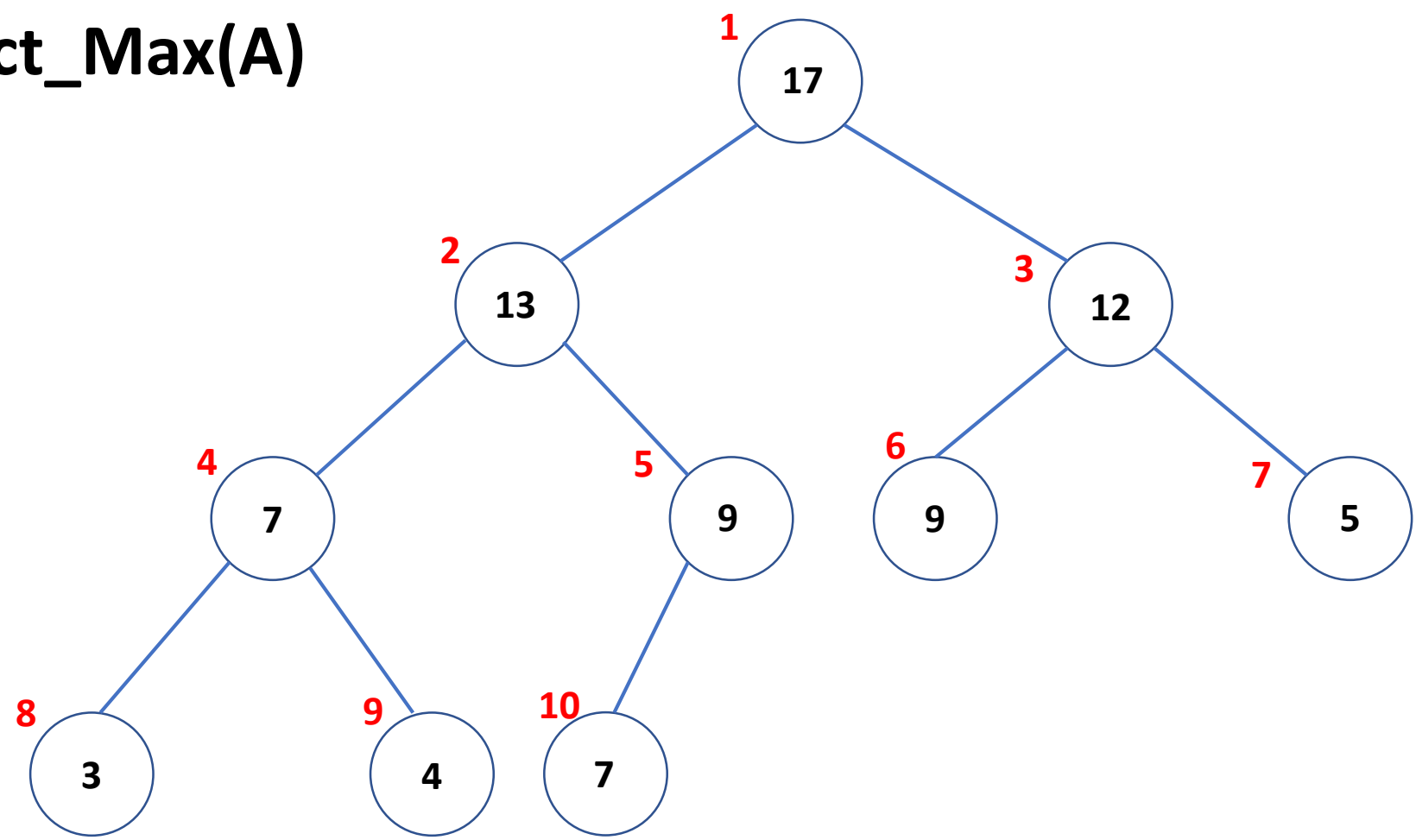


Root of the CBT

Worst-Case Time Complexity is $\Theta(1)$

Extract_Max(A)

Extract_Max(A)



A:

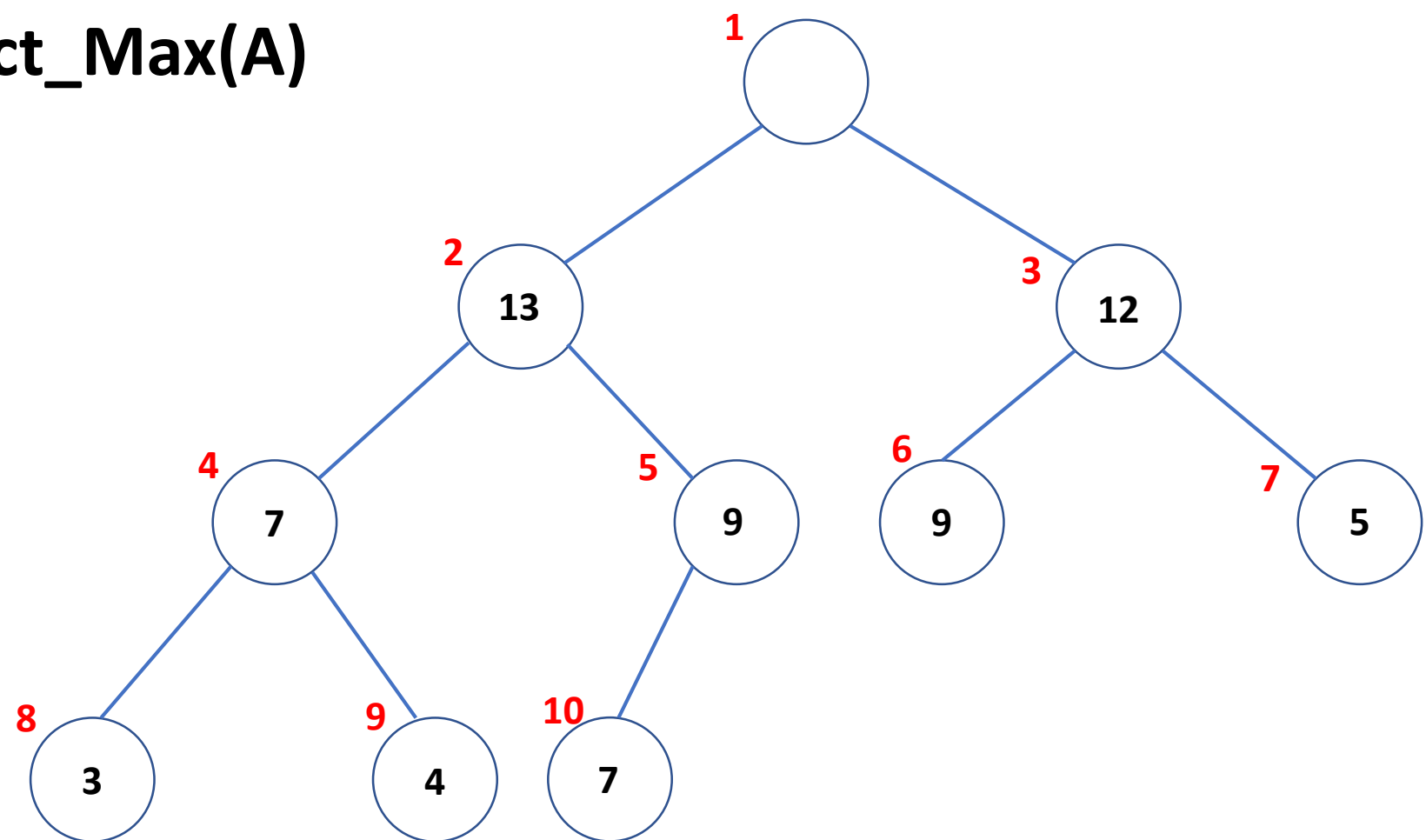
17	13	12	7	9	9	5	3	4	7
----	----	----	---	---	---	---	---	---	---

A.Heapsize = 10

Index

1 2 3 4 5 6 7 8 9 10

Extract_Max(A)



A:

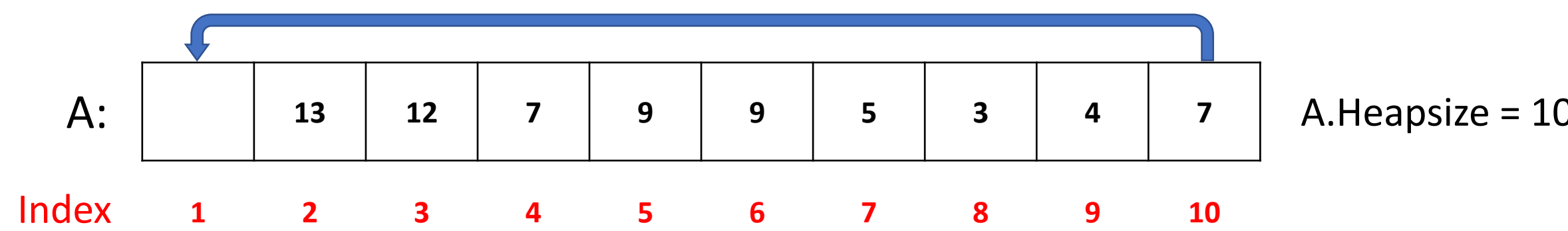
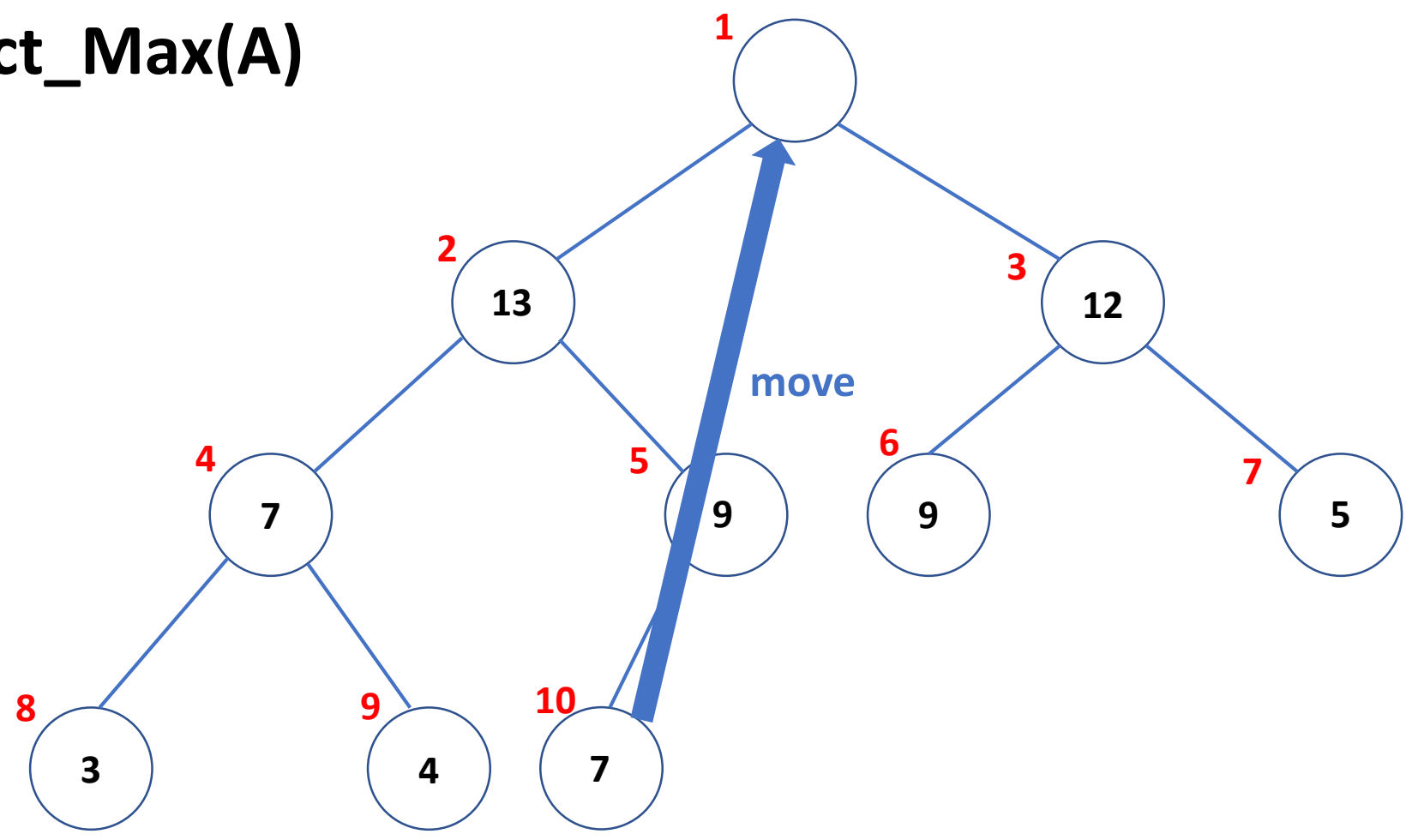
	13	12	7	9	9	5	3	4	7
--	----	----	---	---	---	---	---	---	---

A.Heapsize = 10

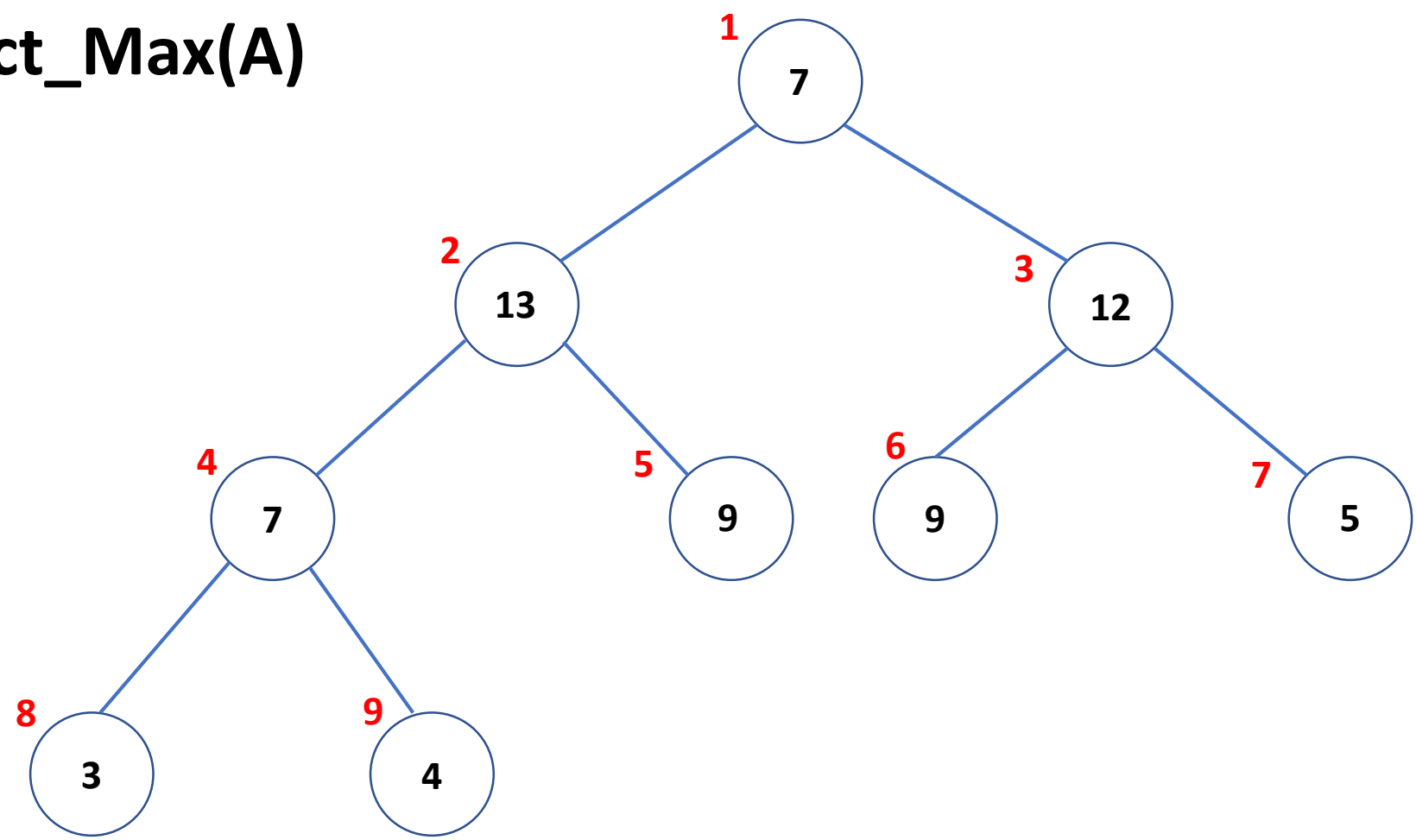
Index

1 2 3 4 5 6 7 8 9 10

Extract_Max(A)



Extract_Max(A)



A:

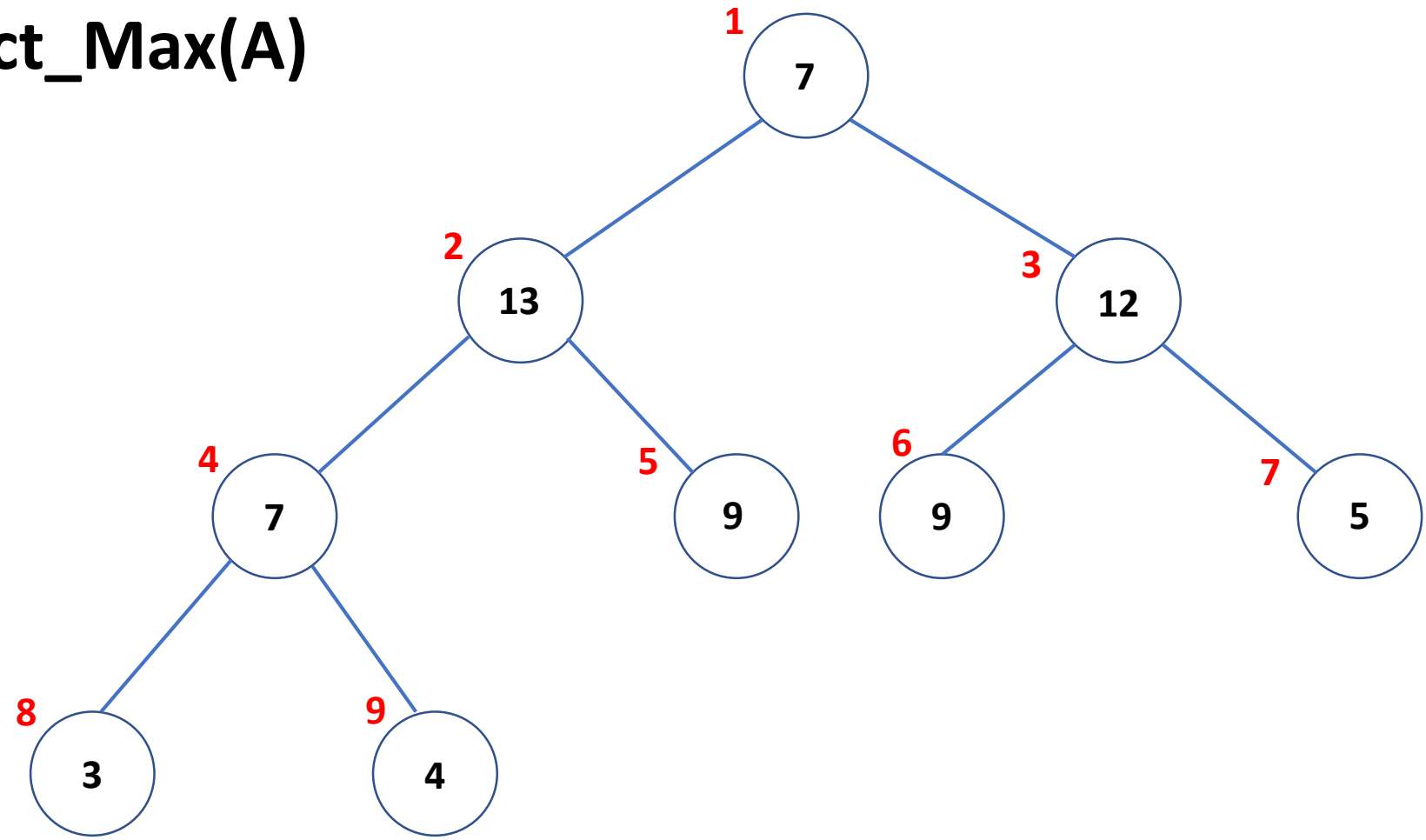
7	13	12	7	9	9	5	3	4
---	----	----	---	---	---	---	---	---

A.Heapsize = 9

Index 1 2 3 4 5 6 7 8 9

Extract_Max(A)

This is a CBT,
but Max-Heap
Property has
been violated.



A:

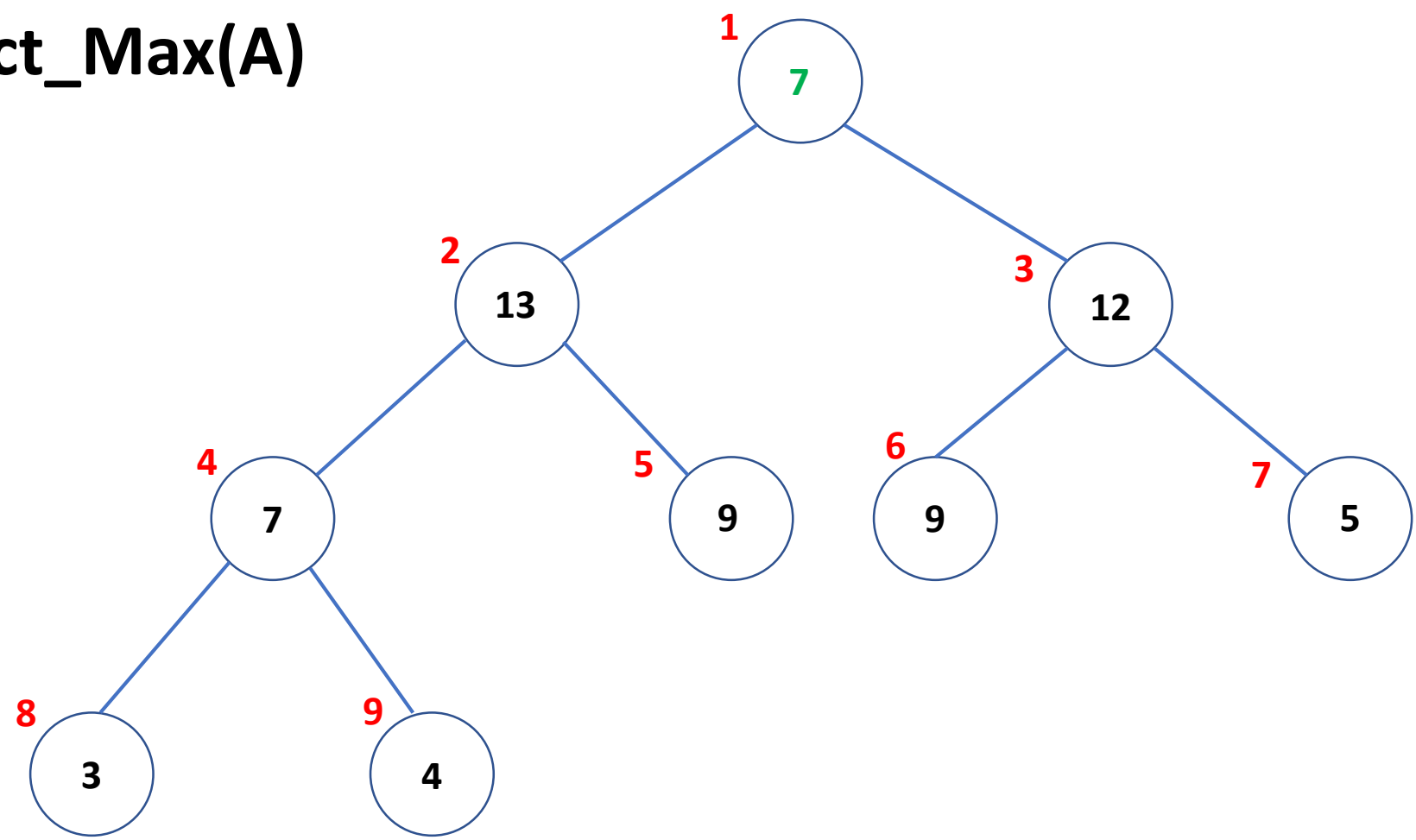
7	13	12	7	9	9	5	3	4
---	----	----	---	---	---	---	---	---

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Index 1 2 3 4 5 6 7 8 9

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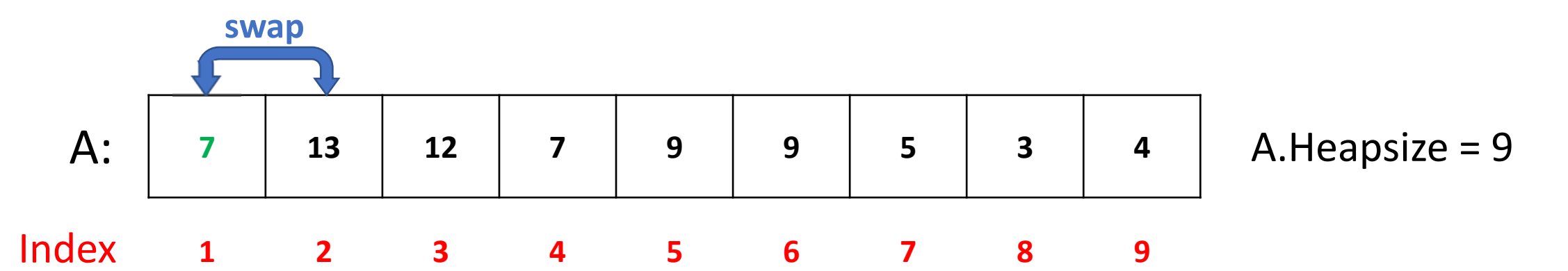
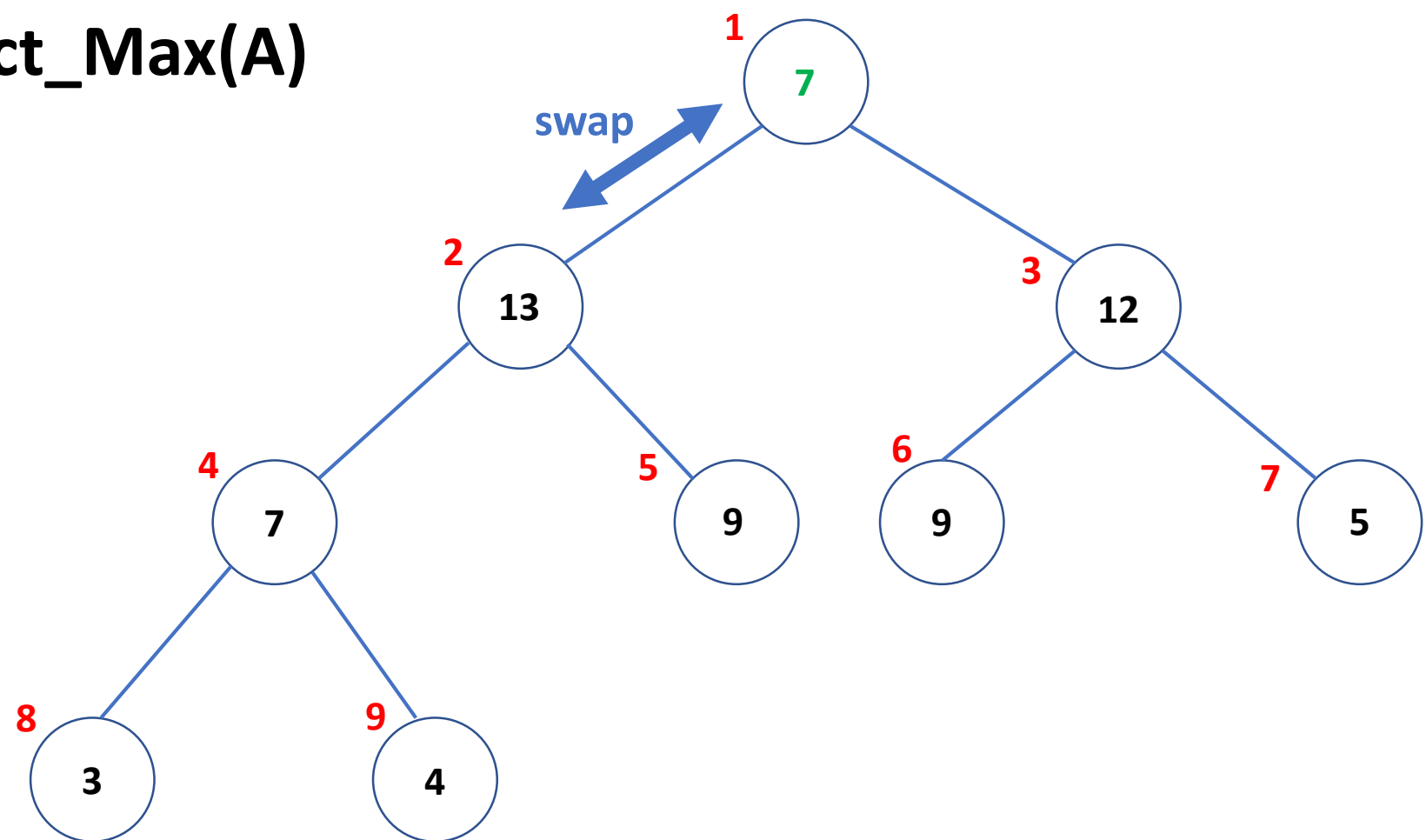
A:

7	13	12	7	9	9	5	3	4
---	----	----	---	---	---	---	---	---

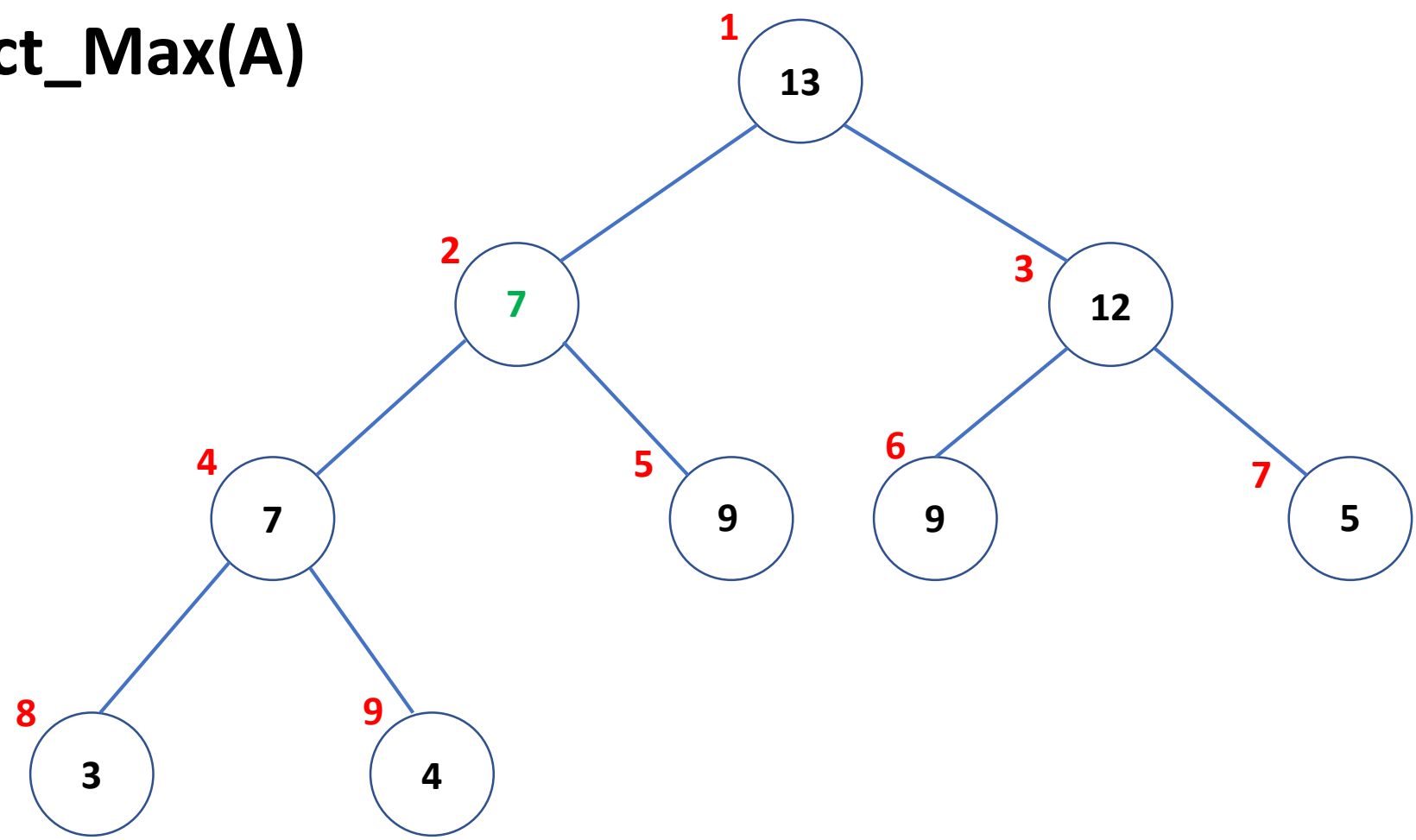
A.Heapsize = 9

Index 1 2 3 4 5 6 7 8 9

Extract_Max(A)



Extract_Max(A)



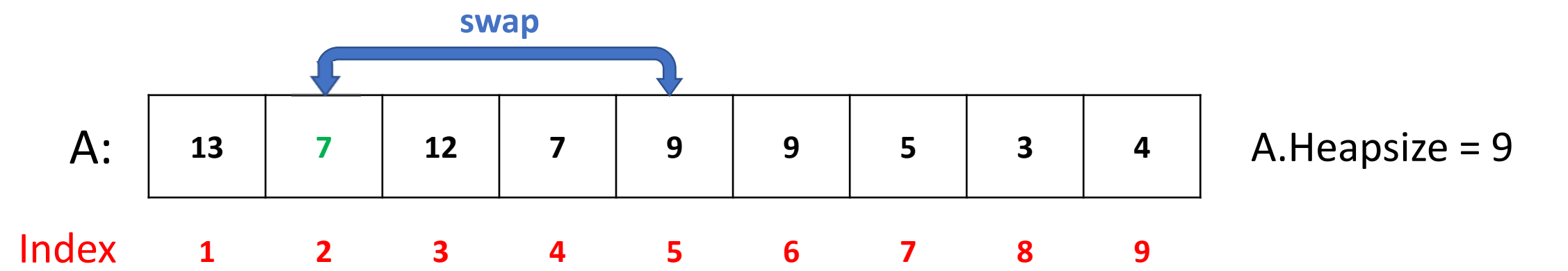
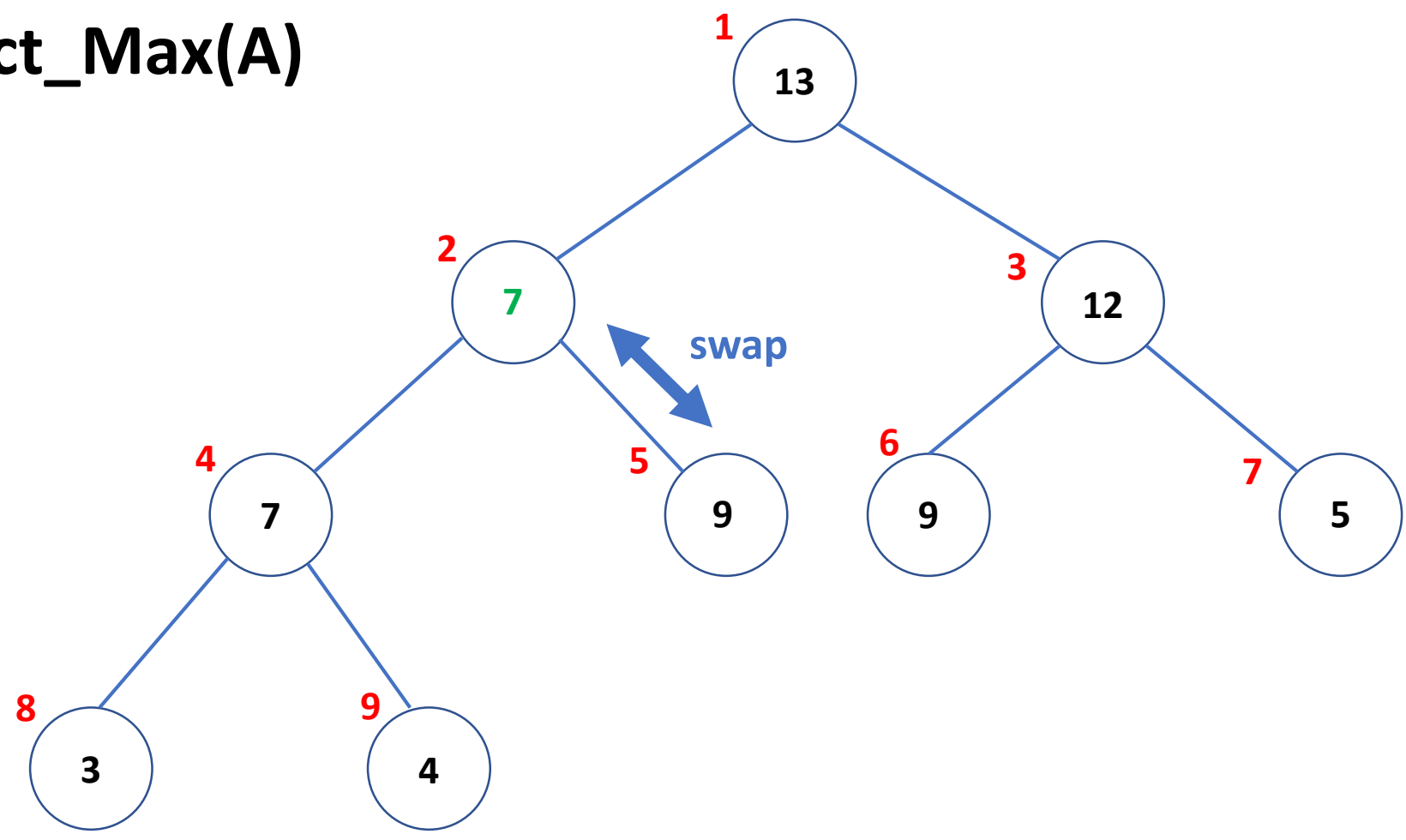
A:

13	7	12	7	9	9	5	3	4
----	---	----	---	---	---	---	---	---

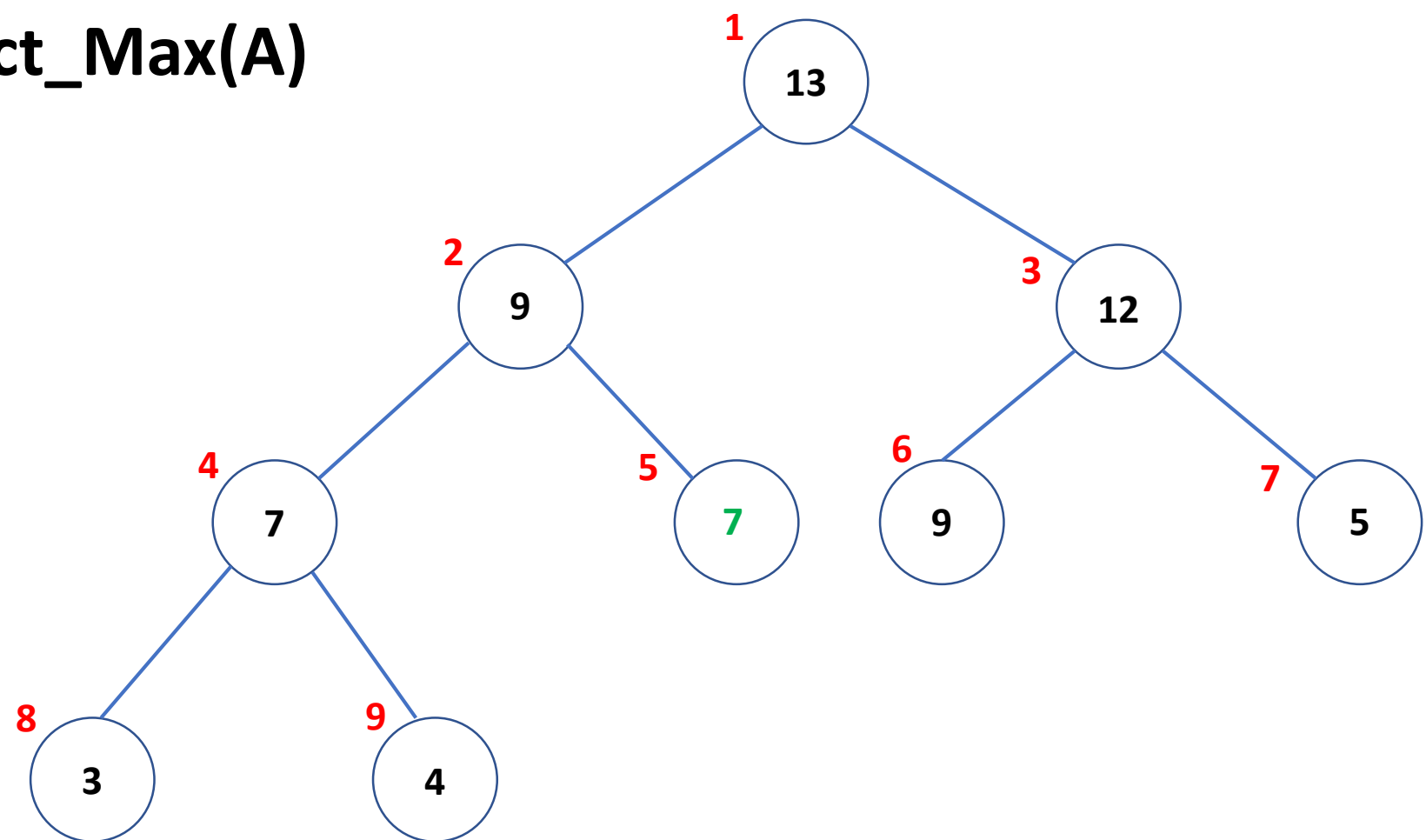
A.Heapsize = 9

Index 1 2 3 4 5 6 7 8 9

Extract_Max(A)



Extract_Max(A)



A:

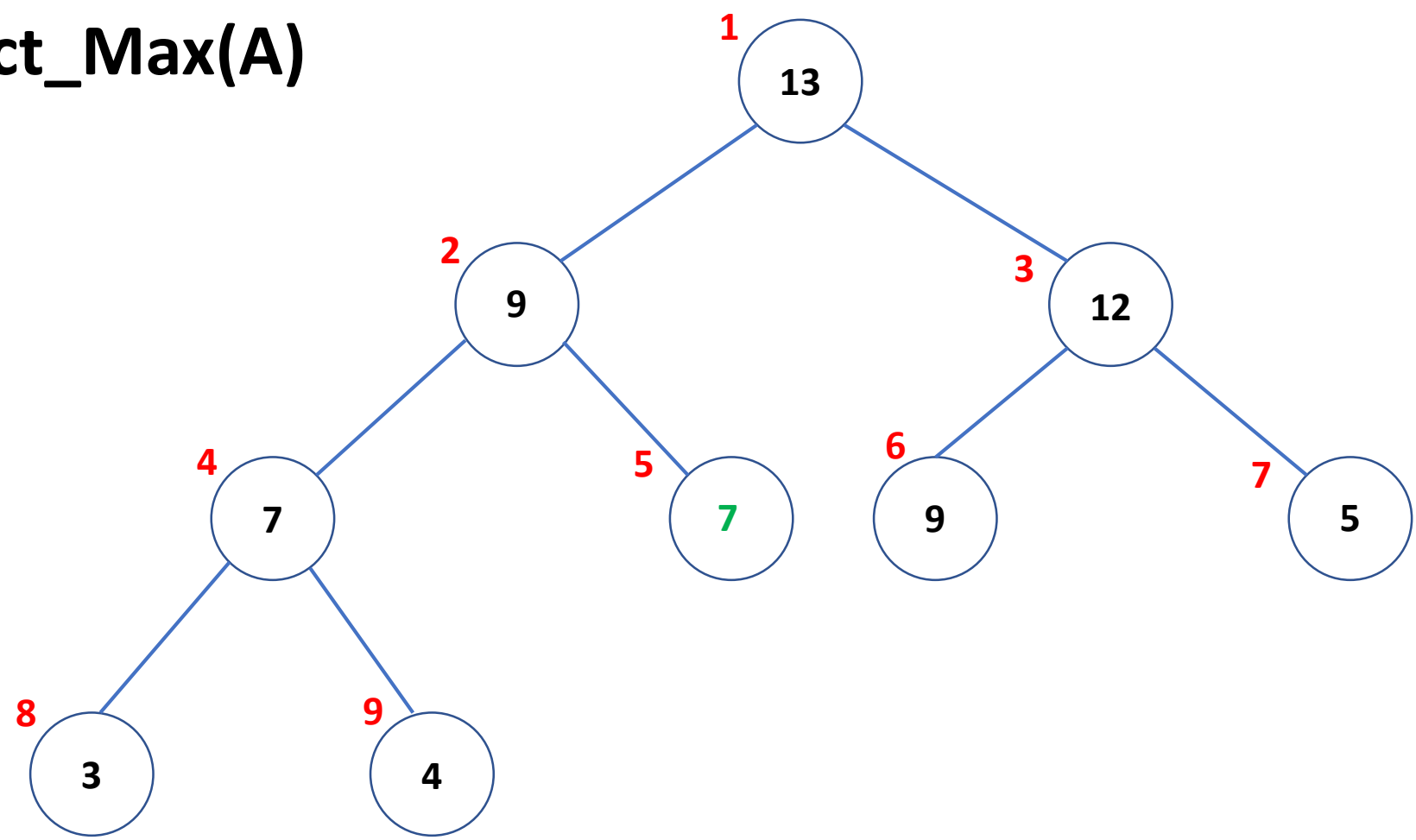
13	9	12	7	7	9	5	3	4
----	---	----	---	---	---	---	---	---

A.Heapsize = 9

Index 1 2 3 4 5 6 7 8 9

Extract_Max(A)

Max-Heap
Property has
been restored!



A:

13	9	12	7	7	9	5	3	4
----	---	----	---	---	---	---	---	---

A.Heapsize = 9

Index 1 2 3 4 5 6 7 8 9

Extract_Max(A)

1. Return the root $A[1]$.
2. Remove the returned element from the heap:
Set $A[1] = A[A.\text{heapsize}]$ and decrement $A.\text{heapsize}$
3. Drip the element in $A[1]$ down the tree:
Let x be the element in $A[1]$
While priority of some child of $x >$ priority of x
Swap x with the highest-priority child of x

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Index of $x \leq \lfloor n/2 \rfloor$

Extract_Max(A)

1. Return the root A[1].

2. Remove the returned element from the heap:

Set $A[1] = A[A.\text{heapsize}]$ and decrement A.heapsize

3. Drip the element in A[1] down the tree:

Let x be the element in A[1]

While x is not a leaf AND priority of some child of x > priority of x

Swap x with the highest-priority child of x

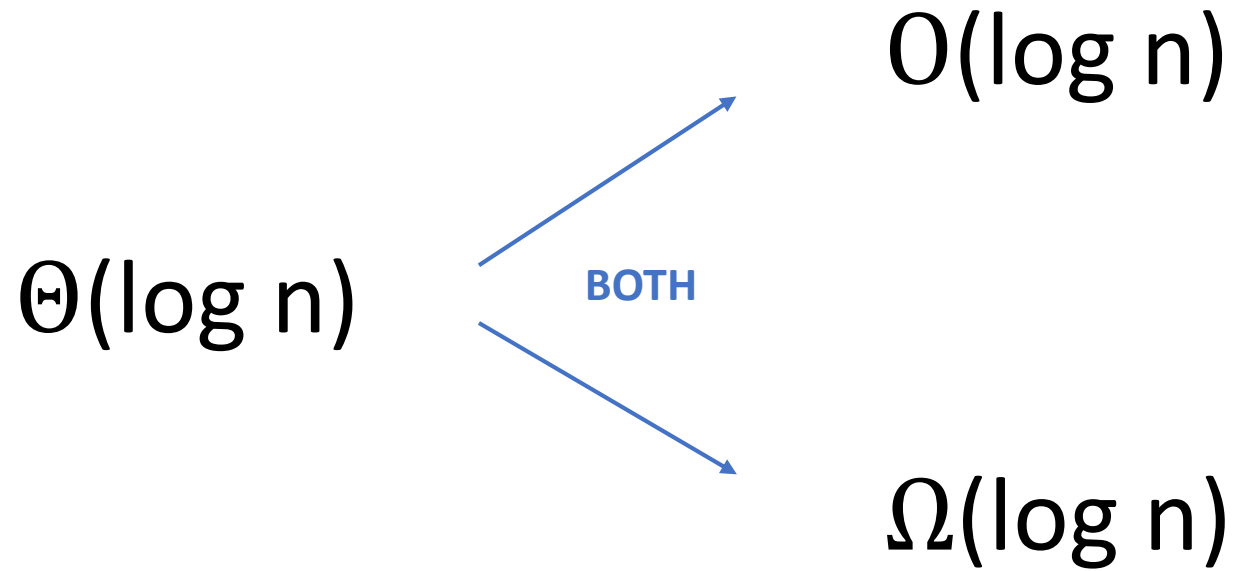
Maintains
CBT shape

Maintains
Max-Heap
property

Index of x $\leq \lfloor n/2 \rfloor$

What is the Worst-Case Complexity of **Extract_Max(A)** ?

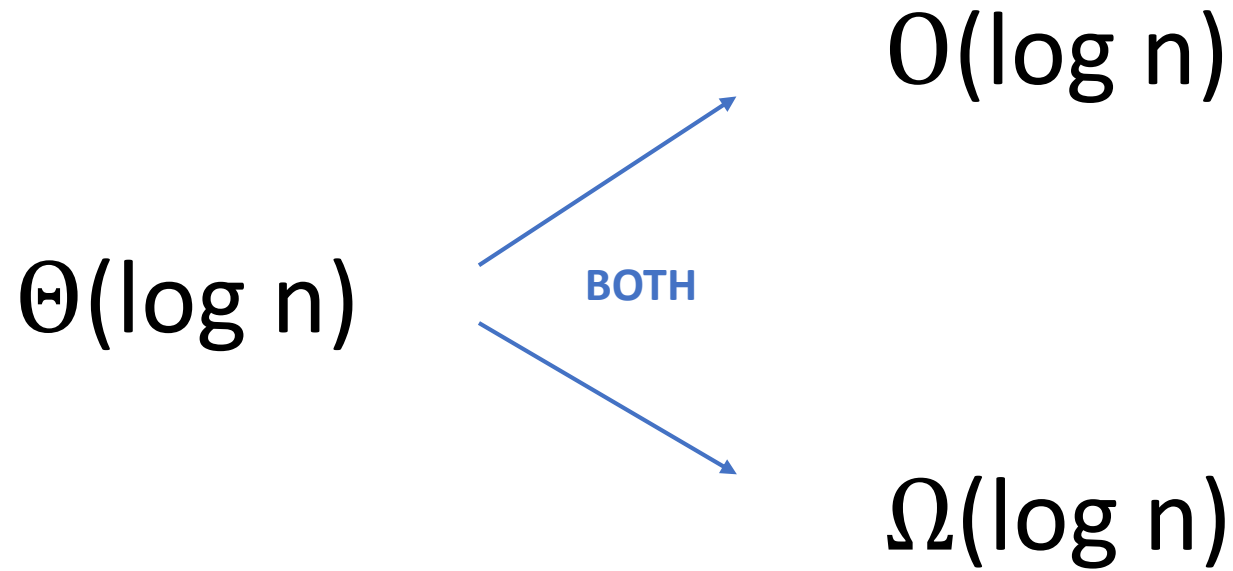
What is the Worst-Case Complexity of **Extract_Max(A)** ?



For **every** input A of size n,
the algorithm takes
at most $c_1 \cdot \log n$ steps.

For **some** input A of size n,
the algorithm takes
at least $c_2 \cdot \log n$ steps.

What is the Worst-Case Complexity of `Extract_Max(A)` ?



For **every** input A of size n ,
the algorithm takes
at most $c_1 \cdot \log n$ steps.

For **some** input A of size n ,
the algorithm takes
at least $c_2 \cdot \log n$ steps.

$A[A.\text{heapsize}]$ has the smallest
priority

Application: HeapSort

To sort an Array A of n elements:

Application: HeapSort

To sort an Array A of n elements:

- Make a heap out of the elements of A

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How do you do
this?

Application: HeapSort

To sort an Array A of n elements:

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This can be done in $\Theta(n)$ time !

Application: HeapSort

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Worst-Case time complexity is $\Theta(n \log n)$

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To sort an Array A of n elements:

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This sorting can be done “in-place” in A (Refer CLRS Section 6.4)