## Hardware Session

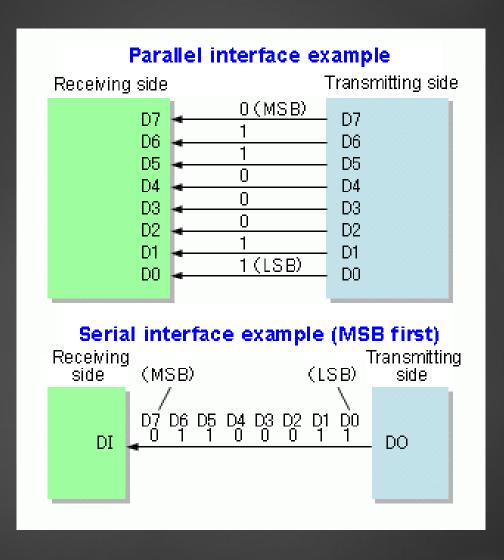
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## **Topics Overview**

- 1. Inside a FPGA
- 2. Standard memory on FPGA
- 3. Simulation, Implementation and Debugging skill on Vivado (Ex.1 using topic 2)
- 4. Serial and parallel communication
- 5. Image Capture and Pre-processing (EX.2)
- 6. How to design FPGA on Zynq
- 7. Schematic design for FPGA (Optional)

# 4. Serial and parallel communication

## Serial VS Parallel



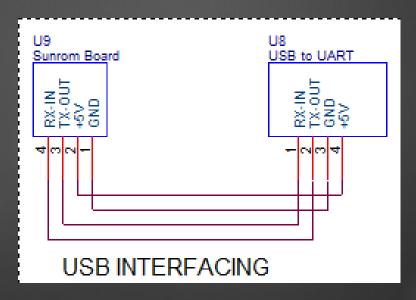
# Serial communication example

Asynchronous clock	Synchronous clock
Universal Asynchronous Receiver- Transmitter (UART)	Serial Peripheral Interface (SPI)
	I <sup>2</sup> C (Inter-Integrated Circuit)

#### **UART**

A universal asynchronous receiver-transmitter (UART) is a computer hardware device for asynchronous serial communication in which the data format and transmission speeds are configurable.

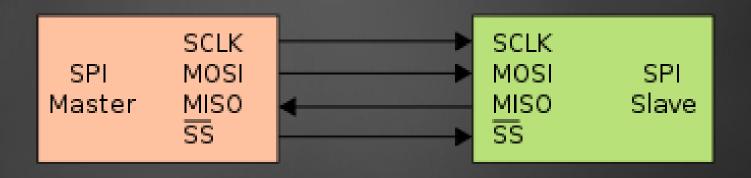




#### SP

The Serial Peripheral Interface (SPI) is a synchronous serial communication interface specification used for short distance communication, primarily in embedded system.

SPI devices communicate in full duplex mode using a master slave architecture with a single master. The master device originates the frame for reading and writing. Multiple slave devices are supported through selection with individual slave select (SS) lines.



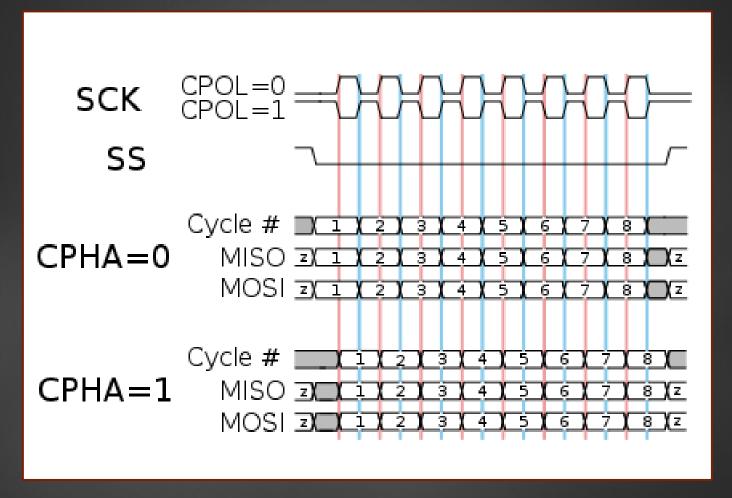
#### **SPI: PIN interface**



The SPI bus specifies four logic signals:

- SCLK: Serial Clock (output from master)
- MOSI: Master Output Slave Input, or Master Out Slave In (data output from master)
- MISO: Master Input Slave Output, or Master In Slave Out (data output from slave)
- SS: Slave Select (often active low, output from master)

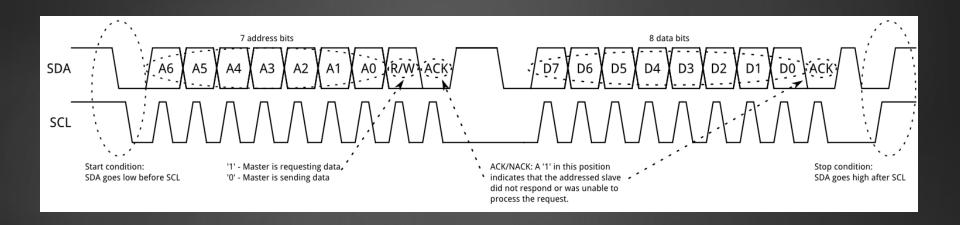
### SPI: Data transmission



CPOL = Clock Polarity CPHA = Clock Phase

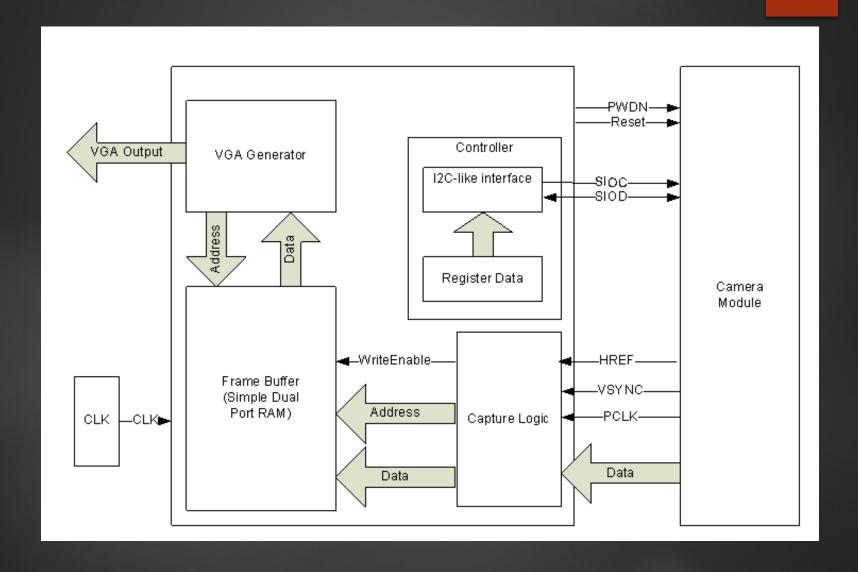
#### 12C

I<sup>2</sup>C (Inter-Integrated Circuit), pronounced *I-squared-C*, is a synchronous, multi-master, multi-slave, packet switched, single ended, serial computer bus invented in 1982 by Philips Semiconductor (now NXP Semiconductors). It is widely used for attaching lower-speed peripheral ICs to processors and microcontrollers in short distance, intra-board communication



# 5. Image Capture and Pre-Processing

## **Architecture of Image Capture**



#### EX.2 Design Gray and Binary image