Simulations of the Minimax Basis Reachability Graph

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Abstract

In this note we report the simulation results of three benchmarks based on the minimax basis reachability graph (minimax-BRG). All tests are executed based on a laptop with Intel i7-5500U 2.40 GHz processor and 8 GB RAM.

1 Benchmark I

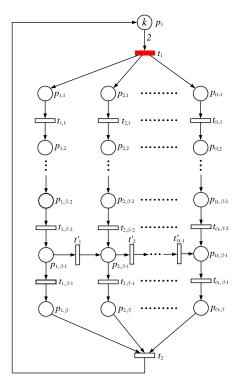


Fig. 1: Benchmark I

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As shown in Fig. 1, the first benchmark is a parameterized net system taken from [2] which represents a manufacturing system that contains a number of parallel production lines. However, a minor adjustment is made, i.e., the weight from p_1 to t_1 is increased to 2. There are three parameters, i.e., k, α and β . With the change of the two parameters α and β , the scale of the system changes correspondingly. k indicates the initial resource quantity, while α and β represent the number of parallel lines and the length of each production line, respectively. Let $T_E = \{t_1\}$ (marked in red). For different values of k, α and β , the number of minimax basis markings $\mathcal{M}_{\mathcal{B}_{\mathcal{M}}}$ and all reachable markings $M \in R(N, M_0)$, as well as their computing times are listed in Table 1.

Table 1: Analysis	of the RG and	l minimax-BRG for	the net in Fig.	1 with $T_E = \{t_1\}.$

Run	k	α	β	$ R(N, M_0) $	Time (s)	$ \mathcal{M}_{\mathcal{B}_{\mathcal{M}}} $	Time (s)	$ \mathcal{M}_{\mathcal{B}_{\mathcal{M}}} / R(N,M_0) $	Time ratio
1	5	4	3	10705	387	21	0.16	0.2%	<0.1%
2	6	4	4	72070	20447	52	5.2	< 0.1%	<0.1%
3	7	4	3	-	o.t.	88	18	-	-
4	8	4	3	-	o.t.	140	835	-	-
5	9	4	3	-	o.t.	239	3127	-	-
6	10	4	3	-	o.t.	-	o.t.	-	-
7	5	5	3	30961	3400	21	0.3	< 0.1%	<0.1%
8	6	5	3	-	o.t.	52	38	-	-
9	7	5	3	-	o.t.	88	155	-	-
10	8	5	3	-	o.t.	-	o.m.	-	-

^{*} The computing time is denoted by overtime (o.t.) if the program does not terminate within 36,000 seconds (10 hours) and out of memory (o.m.) if the program runs out of memory.

2 Benchmark II

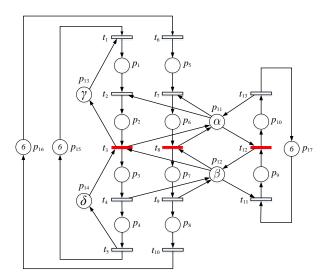


Fig. 2: Benchmark II

Selected from [3], a parameterized net system shown in Fig. 2 is the second benchmark. The four parameters α, β, γ , and δ represent the numbers of tokens in places p_{11}, p_{12}, p_{13} and p_{14} , respectively. This system contains 17 places and 13 transitions and its scale does not change with changes in parameters. With $T_E = \{t_3, t_8, t_{12}\}$ (marked in red) and $T_I = \{t_1, t_2, t_4, t_5, t_6, t_7, t_9, t_{10}, t_{11}, t_{13}\}$, the analysis of minimax-BRG in comparison with reachability graph is illustrated in Table 2.

Table 2: Analysis of the RG and minimax-BRG for the net in Fig. 1 with $T_E = \{t_3, t_8, t_{12}\}$.

Run	α	β	γ	δ	$ R(N, M_0) $	Time (s)	$ \mathcal{M}_{\mathcal{B}_{\mathcal{M}}} $	Time (s)	$ \mathcal{M}_{\mathcal{B}_{\mathcal{M}}} / R(N,M_0) $	Time ratio
1	2	2	1	1	4449	86	200	23	4%	26%
2	2	2	2	1	7523	253	312	65	4%	25%
3	2	2	2	2	12601	715	385	177	3%	24%
4	3	2	2	2	21026	2109	623	961	2.9%	45%
5	3	3	3	3	-	o.t.	1590	16580	-	-
6	3	4	3	3	-	o.t.	2369	57133	-	-
7	4	3	3	3	-	o.t.	2301	o.t.	-	-

^{*} The computing time is denoted by *overtime* (o.t.) if the program does not terminate within 57,600 seconds (16 hours).

For different values of the parameters α, β, γ and δ , we report in different columns the sizes of the reachability graph $|R(N, M_0)|$ and the minimax-BRG $|\mathcal{M}_{\mathcal{B}_{\mathcal{M}}}|$ as well as the time required to compute them. The ratio of $|\mathcal{M}_{\mathcal{B}_{\mathcal{M}}}|$ to $|R(N, M_0)|$ is also demonstrated.

With the increase of the four parameters α, β, γ , and δ , one can see that by selecting basis partition appropriately, the size of the minimax-BRG and the time required to construct it in the considered net are both smaller than that of the corresponding RG. Meanwhile, the ratios of $|\mathcal{M}_{\mathcal{B}_{\mathcal{M}}}|$ to $|R(N, M_0)|$ decrease significantly.

3 Benchmark III

As shown in Fig. 3, the third benchmark is selected from [1] while we make some minor adjustments, i.e., two self-looped arcs $t_{33} \leftrightarrow p_6$ and $t_{36} \leftrightarrow p_{21}$ and one directed arcs $t_{39} \rightarrow p_{46}$ are removed. This system contains 46 places and 39 transitions and its scale does not change with changes in parameters. The initial marking shown in the figure is parameterized as:

Let $T_E = \{t_1, t_3, t_7, t_9, t_{14}, t_{20}, t_{22}, t_{24}, t_{29}, t_{32}, t_{35}\}$ (marked in red). For different values of α and β , the number of minimax basis markings $\mathcal{M}_{\mathcal{B}_{\mathcal{M}}}$ and all reachable markings $M \in R(N, M_0)$, as well as their computing times are listed in Table 3.

Table 3: Analysis of the RG and minimax-BRG for the net in Fig. 3 with $T_E = \{t_1, t_3, t_7, t_9, t_{14}, t_{20}, t_{22}, t_{24}, t_{29}, t_{32}, t_{35}\}.$

Run	α	β	$ R(N, M_0) $	Time (s)	$ \mathcal{M}_{\mathcal{B}_{\mathcal{M}}} $	Time (s)	$ \mathcal{M}_{\mathcal{B}_{\mathcal{M}}} / R(N,M_0) $	Time ratio
1	1	1	1966	19	361	5	18%	26%
2	1	2	12577	544	1724	42	14%	7%
3	2	2	76808	21304	9294	502	12%	2%
4	2	3	-	o.t.	25031	3520	-	-
5	2	4	-	o.t.	46388	11998	-	-
6	3	3	-	o.t.	71753	30584	-	-
7	3	4	-	o.t.	130857	o.t.	-	-

^{*} The computing time is denoted by overtime (o.t.) if the program does not terminate within 36,000 seconds (10 hours).

References

- [1] M. P. Cabasino, A. Giua, M. Pocci, and C. Seatzu. Discrete event diagnosis using labeled Petri nets. an application to manufacturing systems. *Control Engineering Practice*, 19(9):989–1001, 2011.
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- [3] G. Y. Liu and Z. W. Li. General mixed integer programming-based liveness test for system of sequential systems with shared resources nets. IET control theory & applications, 4(12):2867-2878, 2010.

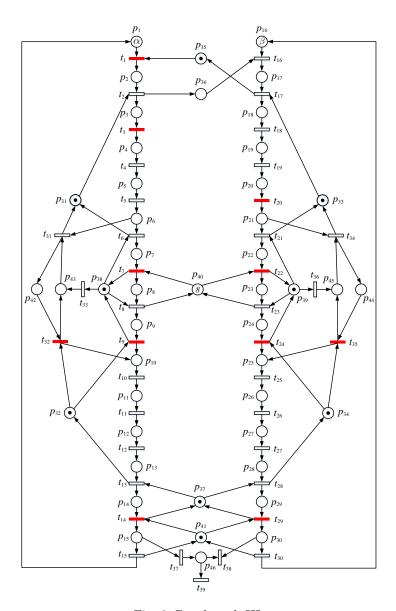


Fig. 3: Benchmark III