山东大学 计算机科学与技术 学院

计算机视觉 课程实验报告

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201600181073

实验题目: Harris 角点检测

实验内容:

实现 Harris 角点检测算法, 并与 OpenCV 的 cornerHarris 函数的结果进行比较。

实验过程中遇到和解决的问题:

1. cornerHarris 函数

```
§ cornerHarris()
   void cv::cornerHarris ( InputArray src,
                                                                                                OutputArray dst,
                                                                                                   int
                                                                                                                                                                 blockSize.
                                                                                                int
                                                                                                                                                                 ksize,
                                                                                                double k,
                                                                                                   int
                                                                                                                                                                   borderType = BORDER_DEFAULT
Python:
       dst = cv.cornerHarris( src, blockSize, ksize, k[, dst[, borderType]] )
   \label{thm:control} The function runs the Harris corner detector on the image. Similarly to corner MinEigen Val and corner Eigen Vals And Vecs , for each pixel (x,y) it calculates the following the following the variable of the following three variables of three variables of the following three variables of the variables of the following three variables of th
   a 2 \times 2 gradient covariance matrix M^{(x,y)} over a 	extbf{blockSize} 	imes 	extbf{blockSize} neighborhood. Then, it computes the following characteristic
                                                                                                                                                                                                                                                      	extstyle	
   Corners in the image can be found as the local maxima of this response map.
                                                                                          Input single-channel 8-bit or floating-point image.
                                                                                   Image to store the Harris detector responses. It has the type CV_32FC1 and the same size as src.
                                blockSize Neighborhood size (see the details on cornerEigenValsAndVecs ).
                             ksize Aperture parameter for the Sobel operator.
                                                                                      Harris detector free parameter. See the formula below.
                               borderType Pixel extrapolation method. See BorderTypes.
```

2. 实现 Harris 角点检测算法

算法流程:

- 1) 读入待检测图片并转换为灰度图;
- 2) 对灰度图用 sobel 算子求得 x 及 y 方向梯度图 lx, ly;
- 3) 对 Ix, Iy 进一步处理得到 I_x^2 , I_y^2 , I_xI_y ;
- 4) 对上一步得到的图片分别进行高斯滤波得到 $g(I_x^2), g(I_x^2), g(I_x^2)$;

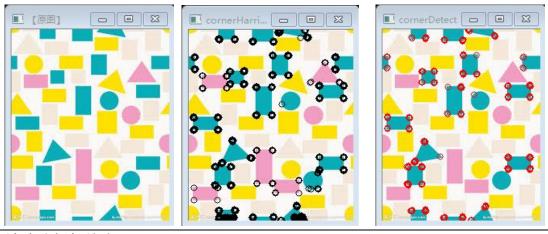
5) 由以下公式计算出角点响应:

$$R = \det[M(\sigma_{I}, \sigma_{D})] - \alpha[\operatorname{trace}(M(\sigma_{I}, \sigma_{D}))]^{2}$$

= $g(I_{x}^{2})g(I_{y}^{2}) - [g(I_{x}I_{y})]^{2} - \alpha[g(I_{x}^{2}) + g(I_{y}^{2})]^{2}$

6) 设置阈值 threshold, 小于阈值的点不视为角点。

阈值设为最大响应的一半,原图及检测结果如下(从左至右原图、cornerHarris函数结果、自己实现结果):



结论分析与体会: