# ECE250-Project 4

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#### 1. Overview of Classes

Class:

edge

Description:

this is an edge with vertices and weight.

Member variables:

Double weight;

int,x,y; x,y is the index of the vertices

Member functions:

~edge();default destructor

edge();initialize an edge with weight 0, index -1

edge(double w,int u, int v); initialize an edge with necessary info

functions for accessing private variables: int get\_x(), int get\_y()

#### Class:

node

#### Description:

this is an vertice with its index and next node. It is the basic unit of a linkedlist.

#### Member variables:

int vertex:

node \*next;

### Member functions:

node();default constructor

~node();default destructor

node(int vertex); initialize a node with an index

functions for accessing private variables: int get\_index(); node \*get\_next();

#### Class:

nodelist

#### Description:

This is a linked list, representing a set of elements

### Member variables:

node \*head;

node \*tail;

## Member functions:

nodelist();default constructor

~nodelist();default destructor

nodelist(node\*a);initialize a linked list with a node as its head and tail

functions for accessing private variables: node \*get\_head(); node \*get\_tail();

## Class:

set

### Description:

This is a universe set with several set represented as nodelist

# Member variables:

vector<nodelist> theSet;

### Member functions:

set();default constructor

~set();default destrucor

void makeset (int num); make a universe set with the number of vertices

node \*findset (int num); pass the index to the function and return its head to check if two vertices are in the same set. void merge (int a, int b); merge two vertices into the same set by setting them with same head and tail.

# Class:

graph

### Description:

This is the graph storing edge info and giving responds to the input command

## Member variables:

vector<vector<edge>> matrix; adjacency matrix

int size; the number of vertices

class illegal\_commal{}; handling failure

int edge\_count; the total number of edges

# Member functions:

graph(); constructor

~graph(); destructor

void set\_size(int m); set the size of the table

void print\_ecount(); print the number of edges

void insert(int u, int v, double w); connect index u and index v

void del(int u, int v);delete the edge between index u and index v

# 2. Class diagrams

edge	node
double weight;	int vertex;
int x,y;	node *next;
edge();	node()=default;
edge(double w,int u, int v);	~node()=default;
int get_x();//accessing private variables	node(int vertex);
int get_y();	int get_vertex();//accessing private
double get_weight();	variables
~edge()=default;	node *get_next();
	void set_next(node *a);
	bool operator==(const node &a);
	bool operator!=(const node &a);

nodelist	set
node *head;	vector <nodelist> theSet;</nodelist>
node *tail;	
nodelist()=default;	set()=default;
nodelist(node *a);	~set()=default;
~nodelist()=default;//accessing private	void makeset(int num); //consistent with
variables	lecture notes
node *get_head();	node *findset(int num);
node *get_tail();	void merge(int a, int b);
void set_head(node *a);	
void set_tail(node *a);	
graph	
vector <vector<edge>&gt; matrix;</vector<edge>	
int size;	
class illegal_argument{};	
int edge_count;	
void set_size(int m); //function name	
consistent with commands	
int get_size();	
void print_ecount();	
graph();	
~graph();	
void insert(int u,int v,double w);	
void del(int u,int v);//delete	
void degree(int u);	
void clear();	
void mst();	

# 3. Constructors/Destructor

Class edge: edge() initialize an edge with weight 0, index -1 edge(double w,int u, int v) initialize an edge with necessary info Class node: node(int vertex); initialize a node with an index.

== != operators are overloaded for the ease of comparison of nodes.

Class set: the destructor is modified to manually delete all the elements in the disjoint set to ensure there is no memory leak.

Other constructors and destructors are kept as default.

# 4. Test Cases

There are 2 cases I tested in addition to the example tests.

Test1: the size is 1, it should be successful but insert, delete should be failure.

Test2: insert a connected tree, calculate the mst. Delete some edges make it not connected. Add new edges with new weights and calculate the mst again.

Test3: update the weight of edge.

# 5. Performance

Analysis of applying Kruskal's algorithm:

the algorithm is applied in the member function named mst() under class graph. The number of edges is E, the number of vertices is N. Sorting the edges takes O(E|E) by std::sort(). Makeset() takes O(n). The for loop takes O(E)\*(Findset()) and merge()). Findset() which returns the head of a node takes O(1). In my implementation of disjoint-set, each node's head is updated at most IgN times, the total time spent in merge() during the for loop is O(N|E). The total time for applying Kruskal's algorithm is O(N|E)+E|E|E. Since |E|>=|N|-1, we can restate it as O(E|E|N).

However, the edges are initially stored in a 2d vector (adjacency matrix). Declaring an empty vector of edge takes O(1). Pushing all the existed edges to the vector takes  $O(N^2)$ . The total time complexity of the function mst() is  $O(N^2)$ .