

算法竞赛模板

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1 前期准备

1.1 Cpp 文件一键编译测试

Windows - build.bat

```
1 @echo off
2 set exe=.\output\%~n1.exe
3 if not exist output mkdir output
4 g++ %1 -o %exe% -std=c++17 -Wall -Wextra -g3 -O2 -D_GLIBCXX_DEBUG && (
5     echo [build done to %exe%]
6     %exe%
7 )
```

1.2 Cpp 模板

注意题目是不是多组样例

```
1 #include <bits/stdc++.h>
2
3 using i64 = long long;
4
5 #define LOG(...) std::cerr << "Line[" << __LINE__ << "]: " << __VA_ARGS__ << std::endl;
6 #define LOGV(_vec, _size) std::cerr << #_vec << " = " << '['; for (int _i = 0; _i <
   ↳ (_size); _i++) { std::cerr << (_vec)[_i]; if (_i != (_size) - 1) std::cerr << ", ";
   ↳ } std::cerr << ']' << std::endl;
7
8 void solve() {}
9
10 int main() {
11     std::cin.tie(nullptr)->sync_with_stdio(false);
12     int t; std::cin >> t; while (t--) solve();
13     return 0;
14 }
```

2 算法

2.1 快速幂

```
1 using i64 = long long;
2
3 i64 binpow(i64 a, i64 b) {
4     // a %= m;
5     i64 res = 1;
6     while (b > 0) {
7         if (b & 1) res = res * a; // % m;
8         a = a * a; // % m;
9         b >>= 1;
10     }
```

```
10     }
11     return res;
12 }
13
14 long long f(long long n, long long m) {
15     // 求的是 m 个 n 相乘, 这里 n 是一个正整数
16     if (m == 0)
17         return 1;
18     else if (m == 1)
19         return n;
20     else if (m % 2 == 0)
21         return f(n * n, m / 2); // 偶数时的降幂
22     return f(n * n, m / 2) * n; // 奇数时的降幂
23 }
```

2.2 DP

2.2.1 LIS

```
1  #include <bits/stdc++.h>
2
3  int main() {
4      std::vector<int> arr = {3, 1, 3, 4, 5, 3, 2};
5      int size = arr.size();
6      std::vector<int> low(size, INT_MAX);
7      int max_s = 0;
8      for (int i = 0; i < size; i++) {
9          int pos = std::lower_bound(low.begin(), low.end(), arr[i]) - low.begin();
10         low[pos] = arr[i];
11         max_s = std::max(max_s, pos + 1);
12     }
13     std::cout << max_s << std::endl;
14 }
```

2.2.2 LIS

```
1  #include <bits/stdc++.h>
2
3  void solve() {
4      std::string S, T;
5      std::cin >> S >> T;
6      std::vector dp(S.size() + 1, std::vector<int>(T.size() + 1));
7      for (int i = 1; i <= S.size(); i++) {
8          for (int j = 1; j <= T.size(); j++) {
9              if (S[i - 1] == T[j - 1]) {
10                 dp[i][j] = dp[i - 1][j - 1] + 1;
11             } else {
```

```
12         dp[i][j] = std::max(dp[i - 1][j], dp[i][j - 1]);
13     }
14 }
15 }
16
17 std::string ans;
18 int i = S.size(), j = T.size();
19 while (i > 0 && j > 0) {
20     if (S[i - 1] == T[j - 1]) {
21         ans += S[i - 1];
22         i--; j--;
23     } else {
24         dp[i - 1][j] > dp[i][j - 1] ? i-- : j--;
25     }
26 }
27 std::reverse(ans.begin(), ans.end());
28 std::cout << ans << std::endl;
29 }
```

2.2.3 01 背包

```
1  #include <bits/stdc++.h>
2
3  void solve() {
4      int N, M;
5      std::cin >> N >> M;
6      std::vector<std::pair<int, int>> items(N + 1); // Wi Di
7      for (int i = 1; i <= N; i++) {
8          std::cin >> items[i].first >> items[i].second;
9      }
10     std::vector<int> dp(M + 1, 0), last(M + 1, 0);
11
12     for (int i = 1; i <= N; i++) {
13         for (int j = 0; j <= M; j++) {
14             if (j - items[i].first >= 0)
15                 dp[j] = std::max(last[j], last[j - items[i].first] + items[i].second);
16             else
17                 dp[j] = last[j];
18         }
19         std::swap(dp, last);
20         std::fill(dp.begin(), dp.end(), 0);
21     }
22
23     std::cout << last.back() << std::endl;
24 }
```

2.2.4 完全背包

```

1  #include <bits/stdc++.h>
2  // #define CFMode
3
4  using i64 = long long;
5
6  #define TRACE(x) std::cout << "TRACE: " << #x << " = " << (x) << std::endl;
7  #define DEBUG(...) std::cerr << "DEBUG: " << __VA_ARGS__ << std::endl;
8  #define DEBUGV(vec, size) std::cerr << '['; for (int i = 0; i < size; i++) { std::cerr
    << vec[i]; if (i != size - 1) std::cerr << ", "; } std::cerr << ']' << std::endl;
9
10 void solve()
11 {
12     int T, M;
13     std::cin >> T >> M; // T: max time cost, M: herbs count
14     std::vector<int> herbTimes(M), herbValues(M);
15     for (int i = 0; i < M; i++)
16         std::cin >> herbTimes[i] >> herbValues[i];
17     // dp[i][j] = max(dp[i-1][j], dp[i][j-w[i]]+v[i]) // j >= w[i]
18     std::vector dp(std::vector<i64>(T + 1, 0));
19     // dp[i][j] = max value of first i herbs with time j
20     for (int i = 1; i <= M; i++) {
21         for (int t = 0; t <= T; t++) {
22             if (t < herbTimes[i - 1])
23                 dp[t] = dp[t];
24             else
25                 dp[t] = std::max(dp[t], dp[t - herbTimes[i - 1]] + herbValues[i - 1]);
26         }
27     }
28     std::cout << dp.back() << std::endl;
29 }
30
31
32 int main()
33 {
34     std::cin.tie(nullptr)->sync_with_stdio(false);
35     #ifdef CFMode
36         int t; std::cin >> t; while (t--) solve();
37     #else
38         solve();
39     #endif
40     return 0;
41 }

```

2.2.5 多重背包

```
1  #include <bits/stdc++.h>
2
3  using i64 = long long;
4
5  void solve() {
6      int N, M;
7      std::cin >> N >> M;
8      std::vector<std::pair<int, int>> items; // weight, value
9
10     // 二进制拆分每种物品的数量
11     for (int i = 1; i <= N; i++) {
12         int V, W, m;
13         std::cin >> V >> W >> m;
14         int k = 1;
15         while(m > 0){
16             int cnt = std::min(k, m);
17             items.emplace_back(W * cnt, V * cnt);
18             m -= cnt;
19             k <= 1;
20         }
21     }
22
23     std::vector<int> dp(M + 1, 0);
24
25     // 0-1 背包标准遍历
26     for(auto &[weight, value] : items){
27         for(int j = M; j >= weight; j--){
28             dp[j] = std::max(dp[j], dp[j - weight] + value);
29         }
30     }
31
32     std::cout << dp[M] << std::endl;
33 }
34
35 int main(){
36     std::cin.tie(nullptr)->sync_with_stdio(false);
37     solve();
38     return 0;
39 }
```

2.3 二维差分

```
1  void best()
2  {
3      int N, M; std::cin >> N >> M;
```

```

4      std::vector map(N + 1, std::vector<int>(N + 1, 0));
5      std::vector diff(N + 2, std::vector<int>(N + 2, 0));
6      for (int i = 1; i <= N; i++) for (int j = 1; j <= N; j++) std::cin >> map[i][j];
7
8      while (M--) {
9          int x1, x2, y1, y2;
10         std::cin >> x1 >> y1 >> x2 >> y2;
11         diff[x1][y1]++;
12         diff[x1][y2 + 1]--;
13         diff[x2 + 1][y1]--;
14         diff[x2 + 1][y2 + 1]++;
15     }
16     // 修改
17     // ###+@@@-
18     // ###@@@@#
19     // ###-###+
20     for (int i = 1; i <= N; i++)
21         for (int j = 1; j <= N; j++)
22             diff[i][j] += diff[i - 1][j];
23
24     for (int i = 1; i <= N; i++)
25         for (int j = 1; j <= N; j++)
26             diff[i][j] += diff[i][j - 1];
27
28     for (int i = 1; i <= N; i++) {
29         for (int j = 1; j <= N; j++) {
30             std::cout << diff[i][j] + map[i][j] << ' ';
31         }
32         std::cout << '\n';
33     }
34 }

```

2.4 并查集

```

1  void solve()
2  {
3      int N, M;
4      std::cin >> N >> M;
5      std::vector<int> fa(N + 1);
6      for (int i = 0; i <= N; i++) {
7          fa[i] = i;
8      }
9      auto find = [&](auto&& find, int x) -> int {
10         return x == fa[x] ? x : fa[x] = find(find, fa[x]);
11     };
12
13     while (M--) {

```

```

14     int Z, X, Y;
15     std::cin >> Z >> X >> Y;
16     if (Z == 1) {
17         fa[find(find, Y)] = fa[find(find, X)];
18     } else if (Z == 2) {
19         std::cout << (fa[find(find, Y)] == fa[find(find, X)] ? 'Y' : 'N') <<
20             << std::endl;
21     }
22 }

```

2.5 图论

2.5.1 最短路 (Dijkstra)

```

1  #include <bits/stdc++.h>
2
3  struct node {
4      std::vector<std::pair<int, int>> to;
5      bool visit = false;
6      int dis = INT_MAX;
7  };
8
9  void solve()
10 {
11     int N, M, S; // 点 边 出发点
12     std::cin >> N >> M >> S;
13     std::vector<node> graph(N + 1);
14     for (int i = 0; i < M; i++) {
15         int u, v, len;
16         std::cin >> u >> v >> len;
17         graph[u].to.emplace_back(v, len);
18         // graph[v].to.emplace_back(u, len);
19     }
20
21     // <dis, id>
22     std::priority_queue<std::pair<int, int>, std::vector<std::pair<int, int>>,
23         < std::greater<std::pair<int, int>>> Q;
24     graph[S].dis = 0; Q.emplace(0, S); //! 记得
25     int cnt = 0;
26     while(!Q.empty() && cnt < N) {
27         auto [dis, x] = Q.top(); // 取出最近的
28         Q.pop();
29         if (graph[x].visit) continue; //? 可改成 cur.dis != dis
30         graph[x].visit = true;
31         cnt++;
32         for (auto [son, cost] : graph[x].to) {

```



```

32         if (graph[son].visit) continue; //? 可省略, 下一个 if 也会筛掉, 不过最小生成树时候
           ↪ 不能删
33         if (graph[x].dis + cost < graph[son].dis) { // 松弛边
34             graph[son].dis = graph[x].dis + cost;
35             Q.emplace(graph[x].dis + cost, son);
36         }
37     }
38 }
39
40 for (int i = 1; i <= N; i++) {
41     std::cout << graph[i].dis << ' ';
42 }
43 }
44
45 int main()
46 {
47     std::cin.tie(nullptr)->sync_with_stdio(false);
48     solve();
49     return 0;
50 }

```

2.5.2 最短路 (SPFA)

```

1  #include <bits/stdc++.h>
2
3  struct node {
4      std::vector<std::pair<int, int>> to;
5      int dis = INT_MAX;
6      bool inQueue = false; // 是否已经在 spfa 队列中
7      int cnt = 0; // 最后一次访问到该节点的 spfa 的轮数
8  };
9
10 void solve() {
11     int N, M;
12     std::cin >> N >> M;
13     std::vector<node> graph(N + 1);
14     for (int i = 0; i < M; i++) {
15         int u, v, c;
16         std::cin >> u >> v >> c;
17         if (c >= 0) {
18             graph[u].to.emplace_back(v, c);
19             graph[v].to.emplace_back(u, c);
20         } else {
21             graph[u].to.emplace_back(v, c);
22         }
23     }
24 }

```

```

25  /* SPFA
26  graph[1].cnt = 0, graph[1].dis = 0, graph[1].inQueue = true;
27  std::queue<int> Q;
28  Q.push(1);
29  while (!Q.empty()) {
30      int x = Q.front();
31      Q.pop();
32      graph[x].inQueue = false;
33      for (auto [son, cost] : graph[x].to) {
34          if (graph[x].dis + cost < graph[son].dis) { // 尝试松弛边，松弛成功就加入下一轮
35              graph[son].dis = graph[x].dis + cost;
36              graph[son].cnt = graph[x].cnt + 1;
37              if (graph[son].cnt >= N) {
38                  std::cout << "YES" << std::endl; // 存在负环
39                  return;
40              }
41              if (!graph[son].inQueue) {
42                  Q.emplace(son);
43                  graph[son].inQueue = true;
44              }
45          }
46      }
47  }
48
49  std::cout << "NO" << std::endl;
50  }

```

2.5.3 最小生成树

```

1  #include <bits/stdc++.h>
2
3  struct node {
4      std::vector<std::pair<int, int>> to;
5      bool visit = false;
6      int dis = INT_MAX;
7  };
8
9  void solve()
10 {
11     int N, M, S; // 点 边 出发点
12     std::cin >> N >> M >> S;
13     std::vector<node> graph(N + 1);
14     for (int i = 0; i < M; i++) {
15         int u, v, len;
16         std::cin >> u >> v >> len;
17         graph[u].to.emplace_back(v, len);
18         //graph[v].to.emplace_back(u, len);

```

```

19     }
20
21     // <dis, id>
22     std::priority_queue<std::pair<int, int>, std::vector<std::pair<int, int>>,
23     ↪ std::greater<std::pair<int, int>>> Q;
24     graph[S].dis = 0; Q.emplace(0, S); //! 记得
25     int cnt = 0;
26     while(!Q.empty() && cnt < N) {
27         auto [dis, x] = Q.top(); // 取出最近的
28         Q.pop();
29         if (graph[x].visit) continue; //? 可改成 cur.dis ≠ dis
30         graph[x].visit = true;
31         cnt++;
32         for (auto [son, cost] : graph[x].to) {
33             if (graph[son].visit) continue; //? 可省略, 下一个 if 也会筛掉, 不过最小生成树时候
34             ↪ 不能删
35             if (graph[x].dis + cost < graph[son].dis) { // 松弛边
36                 graph[son].dis = graph[x].dis + cost;
37                 Q.emplace(graph[x].dis + cost, son);
38             }
39         }
40     }
41
42     for (int i = 1; i <= N; i++) {
43         std::cout << graph[i].dis << ' ';
44     }
45 }
46
47 int main()
48 {
49     std::cin.tie(nullptr)->sync_with_stdio(false);
50     solve();
51     return 0;
52 }

```

2.5.4 最近公共祖先 LCA

```

1  #include <bits/stdc++.h>
2
3  using i64 = long long;
4
5  #define LOG(...) std::cerr << "Line[" << __LINE__ << "]: " << __VA_ARGS__ << std::endl;
6  #define LOGV(_vec, _size) std::cerr << #_vec << " = " << '['; for (int _i = 0; _i <
7  ↪ (_size); _i++) { std::cerr << (_vec)[_i]; if (_i ≠ (_size) - 1) std::cerr << ", ";
8  ↪ } std::cerr << ']' << std::endl;
9
10 struct node {

```

```

9      std::vector<int> to;
10     int depth = -1;
11 };
12
13 void solve() {
14     int N, Q, S;
15     std::cin >> N >> Q >> S;
16     std::vector<node> tree(N + 1);
17     for (int i = 0; i < N - 1; i++) {
18         int u, v;
19         std::cin >> u >> v;
20         tree[u].to.push_back(v);
21         tree[v].to.push_back(u);
22     }
23
24     std::array<std::vector<int>, 20> f;
25     std::fill(f.begin(), f.end(), std::vector<int>(N + 1, 0));
26
27     auto dfs_dep = [&](auto&& self, int x, int dep, int fa) -> void {
28         if (tree[x].depth != -1) return;
29         tree[x].depth = dep;
30         f[0][x] = fa;
31         for (int son : tree[x].to) {
32             self(self, son, dep + 1, x);
33         }
34     };
35
36     dfs_dep(dfs_dep, S, 1, 0);
37
38     for (int i = 1; i <= 19; i++) {
39         for (int j = 1; j <= N; j++) {
40             f[i][j] = f[i - 1][f[i - 1][j]];
41         }
42     }
43
44     auto get_lca = [&](int a, int b) -> int {
45         if (tree[a].depth > tree[b].depth) std::swap(a, b); // a <= b
46         int gap = tree[b].depth - tree[a].depth, cnt = 0;
47         while (gap) { // ? 补齐到同一个高度
48             if (gap & 1) {
49                 b = f[cnt][b];
50             }
51             cnt++;
52             gap >>= 1;
53         }
54         if (a == b) return a;
55         for (int i = 19; i >= 0; i--) { // ? 在同一个高度基础上往上跳, 跳到最近公共祖先的子节点

```

```

56         if (f[i][a] != f[i][b]) {
57             a = f[i][a];
58             b = f[i][b];
59         }
60     }
61     return f[0][a];
62 };
63
64 while (Q--) {
65     int a, b;
66     std::cin >> a >> b;
67     std::cout << get_lca(a, b) << std::endl;
68 }
69 }
70
71 int main() {
72     std::cin.tie(nullptr)->sync_with_stdio(false);
73     solve();
74     return 0;
75 }

```

3 数据结构

3.1 树状数组

```

1  #include <bits/stdc++.h>
2  using i64 = long long;
3
4  template <class T, class Merge = std::plus<T>>
5  struct BIT {
6      const Merge merge;
7      std::vector<T> t;
8
9      BIT(int n) : t(n + 1), merge(Merge()) {}
10
11     // O(n) build BIT
12     BIT(const std::vector<T>& a) : BIT(a.size()) {
13         int n = a.size();
14         for (int i = 1; i <= n; i++) {
15             t[i] = merge(t[i], a[i - 1]);
16             int j = i + (i & -i);
17             if (j <= n)
18                 t[j] = merge(t[j], t[i]);
19         }
20     }
21
22     void add(int i, const T &x) {

```

```

23         for (i += 1; i < t.size(); i += i & -i)
24             t[i] = merge(t[i], x);
25     }
26
27     T posQuery(int i) {
28         T res = T();
29         for (i += 1; i; i -= i & -i)
30             res = add(res, t[i]);
31         return res;
32     }
33
34     T rangeQuery(int l, int r) { // [l, r]
35         return posQuery(r) - posQuery(l - 1);
36     }
37 };
38
39 template<typename T>
40 class TreeArray
41 {
42 private:
43     int size;
44     std::vector<T> arr;
45
46 public:
47     TreeArray(int len) : size(len), arr(len + 1, 0) {}
48
49     TreeArray(std::vector<T>& source) : size(source.size()), arr(size + 1, 0)
50     {
51         for (int i = 1; i <= size; i++) {
52             add(i, source[i]);
53         }
54     }
55
56     inline static int lowbit(int x) { return x & -x; }
57
58     void add(int pos, T value)
59     {
60         while (pos <= size) {
61             arr[pos] += value;
62             pos += lowbit(pos);
63         }
64     }
65
66     i64 query(int pos)
67     {
68         i64 sum = 0;
69         while (pos >= 1) {

```

```

70         sum += arr[pos];
71         pos -= lowbit(pos);
72     }
73     return sum;
74 }
75
76 i64 query(int l, int r) { return query(r) - query(l - 1); }
77 };

```

实现区间查询区间修改

```

1  void solve()
2  {
3      int N, M;
4      std::cin >> N >> M;
5      std::vector<int> diff(N + 1, 0);
6      std::vector<i64> diff2(N + 1, 0);
7      int last = 0;
8      for (int i = 1; i <= N; i++) {
9          int temp;
10         std::cin >> temp;
11         diff[i] = temp - last;
12         diff2[i] = 1LL * (i - 1) * diff[i];
13         last = temp;
14     }
15
16     BIT<int> tr1(diff);
17     BIT<i64> tr2(diff2);
18     // pre[i] = k*Σ(D[i]) - Σ((i-1)*D[i])
19     while (M--) {
20         int op;
21         std::cin >> op;
22         if (op == 1) {
23             int x, y, k;
24             std::cin >> x >> y >> k;
25             tr1.add(x, k);
26             tr1.add(y + 1, -k);
27             tr2.add(x, 1LL * (x - 1) * k);
28             tr2.add(y + 1, -1LL * y * k);
29         } else if (op == 2) {
30             int x, y;
31             std::cin >> x >> y;
32             i64 sum1 = 1LL * y * tr1.query(y) - tr2.query(y);
33             i64 sum2 = 1LL * (x - 1) * tr1.query(x - 1) - tr2.query(x - 1);
34             std::cout << sum1 - sum2 << std::endl;
35         }
36     }

```

```
37 }

```

3.2 ST 表

```

1  #include <bits/stdc++.h>
2
3  template<class T, class getFunc>
4  class ST
5  {
6  private:
7      std::vector<std::vector<T>> dp;
8      getFunc get = getFunc();
9
10 public:
11     ST(const std::vector<T>& inputs) {
12         size_t len = inputs.size();
13         int exp = log2(len);
14         // dp[s][k] 代表从 s 出发走 2^k 步内的最值
15         dp.resize(len, std::vector<T>(exp + 1, 0));
16         for (size_t s = 0; s < len; s++) {
17             dp[s][0] = inputs[s];
18         }
19
20         for (int k = 1; k <= exp; k++) {
21             for (size_t s = 0; s + (1 << k) <= len; s++) {
22                 dp[s][k] = get(dp[s][k - 1], dp[s + (1 << (k - 1))][k - 1]);
23             }
24         }
25     }
26
27     T query(size_t start, size_t end) {
28         int exp = log2(end - start + 1);
29         return get(dp[start][exp], dp[end - (1 << exp) + 1][exp]);
30     }
31 };
32
33 int main() {
34     struct GET {
35         int operator()(int a, int b) {
36             return std::min(a, b);
37         }
38     };
39     ST<int, GET> st({12, 3, 4, -21, 2, 8});
40     std::cout << st.query(0, 5) << std::endl;
41 }

```


3.3 线段树

```

1  #include <bits/stdc++.h>
2
3  using i64 = long long;
4
5  #define LOG(...) std::cerr << "Line[" << __LINE__ << "]: " << __VA_ARGS__ << std::endl;
6  #define LOGV(_vec, _size) std::cerr << #_vec << " = " << '['; for (int _i = 0; _i <
   ↳ (_size); _i++) { std::cerr << (_vec)[_i]; if (_i != (_size) - 1) std::cerr << ", ";
   ↳ } std::cerr << ']' << std::endl;
7
8  template<class InfoT>
9  struct SGT {
10     std::vector<InfoT> tree;
11     int size;
12
13     inline int lson(int p) { return p << 1; } /* 左子节点
14
15     inline int rson(int p) { return p << 1 | 1; } /* 右子节点
16
17     void pull_up(int p) { /* 用子节点 Info 更新父节点
18         tree[p] = tree[lson(p)] + tree[rson(p)];
19     }
20
21     template<class T>
22     SGT(std::vector<T>& source) {
23         size = source.size() - 1;
24         int bottom = 1;
25         while (bottom < size) bottom <= 1;
26         tree.resize(bottom << 1);
27         auto build = [&](auto&& self, int p, int curL, int curR) -> void {
28             if (curL == curR) {
29                 tree[p] = source[curL];
30                 return;
31             }
32             int mid = (curL + curR) >> 1;
33             self(self, lson(p), curL, mid);
34             self(self, rson(p), mid + 1, curR);
35             pull_up(p);
36         };
37         build(build, 1, 1, size);
38     }
39
40     /* 区间查询
41     InfoT query(int L, int R) {
42         auto search = [&](auto&& self, int p, int curL, int curR) -> InfoT {
43             if (L <= curL && curR <= R) return tree[p];
44             InfoT res;

```

```

45         int mid = (curL + curR) >> 1; ///  
        ↪ [curL, mid], [mid+1, curR] 中一定有至少一个  
        ↪ 与 [L, R] 有交集  
46         bool flag = false;  
47         if (L <= mid) res = self(self, lson(p), curL, mid), flag = true;  
48         if (R >= mid + 1) res = flag ? res + self(self, rson(p), mid + 1, curR) :  
        ↪ self(self, rson(p), mid + 1, curR);  
49         return res;  
50     };  
51     return search(search, 1, 1, size);  
52 }  
53  
54 /* 单点修改  
55 void modify(int pos, const InfoT& newVal) {  
56     auto update = [&](auto&& self, int p, int curL, int curR) -> void {  
57         if (curR == curL && curR == pos) {  
58             tree[p] = newVal;  
59             return;  
60         }  
61         int mid = (curL + curR) >> 1;  
62         if (pos <= mid) self(self, lson(p), curL, mid);  
63         else self(self, rson(p), mid + 1, curR);  
64         pull_up(p);  
65     };  
66     update(update, 1, 1, size);  
67 }  
68  
69 /* 单点修改 (使用 Delta)  
70 template<class DeltaT>  
71 void modify(int pos, const DeltaT& delta) {  
72     auto update = [&](auto&& self, int p, int curL, int curR) -> void {  
73         if (curR == curL && curR == pos) {  
74             delta.applyTo(tree[p]);  
75             return;  
76         }  
77         int mid = (curL + curR) >> 1;  
78         if (pos <= mid) self(self, lson(p), curL, mid);  
79         else self(self, rson(p), mid + 1, curR);  
80         pull_up(p);  
81     };  
82     update(update, 1, 1, size);  
83 }  
84 };  
85  
86 template<class InfoT, class TagT>  
87 class LSGT {  
88 public:  
89     struct Node {

```

```

90     InfoT info = InfoT();
91     TagT tag = TagT();
92 };
93 std::vector<Node> tree;
94 int size;
95
96 inline int lson(int p) { return p << 1; } /* 左子节点
97
98 inline int rson(int p) { return p << 1 | 1; } /* 右子节点
99
100 void addTag(int p, int curL, int curR, const TagT& delta) { /* 给代表 [l,r] 区间的
    ↳ Info 打 Tag
101     tree[p].tag.applyTo(tree[p].info, curL, curR, delta);
102 }
103
104 void pull_up(int p) { /* 用子节点 Info 更新父节点
105     tree[p].info = tree[lson(p)].info + tree[rson(p)].info;
106 }
107
108 void push_down(int p, int curL, int curR) { /* 下传 Tag
109     if (!tree[p].tag.isVaild()) return;
110     int mid = (curL + curR) >> 1;
111     addTag(lson(p), curL, mid, tree[p].tag);
112     addTag(rson(p), mid + 1, curR, tree[p].tag);
113     tree[p].tag = TagT();
114 }
115
116 template<class T>
117 LSGT(std::vector<T>& source) {
118     size = source.size() - 1;
119     int bottom = 1;
120     while (bottom < size) bottom <= 1;
121     tree.resize(bottom < 1);
122     auto build = [&](auto&& self, int p, int curL, int curR) -> void {
123         if (curL == curR) {
124             tree[p].info = source[curL];
125             return;
126         }
127         int mid = (curL + curR) >> 1;
128         self(self, lson(p), curL, mid);
129         self(self, rson(p), mid + 1, curR);
130         pull_up(p);
131     };
132     build(build, 1, 1, size);
133 }
134
135 /* 区间查询

```

```

136 InfoT query(int L, int R) {
137     auto search = [&](auto&& self, int p, int curL, int curR) -> InfoT {
138         if (L <= curL && curR <= R) return tree[p].info;
139         push_down(p, curL, curR);
140         InfoT res;
141         int mid = (curL + curR) >> 1; //? [curL, mid], [mid+1, curR] 中一定有至少一个
            ↳ 与 [L, R] 有交集
142         bool flag = false;
143         if (L <= mid) res = self(self, lson(p), curL, mid), flag = true;
144         if (R >= mid + 1) res = flag ? res + self(self, rson(p), mid + 1, curR) :
            ↳ self(self, rson(p), mid + 1, curR);
145         return res;
146     };
147     return search(search, 1, 1, size);
148 }
149
150 void modify(int L, int R, const TagT& delta) {
151     auto update = [&](auto&& self, int p, int curL, int curR) -> void {
152         if (L <= curL && curR <= R) {
153             addTag(p, curL, curR, delta);
154             return;
155         }
156         push_down(p, curL, curR);
157         int mid = (curL + curR) >> 1;
158         if (L <= mid) self(self, lson(p), curL, mid);
159         if (R >= mid + 1) self(self, rson(p), mid + 1, curR);
160         pull_up(p);
161     };
162     update(update, 1, 1, size);
163 }
164 };
165
166 struct Info {
167     i64 val;
168     Info() = default; // * 无参初始化 (重置时候用)
169     Info(i64 v) : val(v) {} //? 从其他类型转换 (Build 时候用)
170
171     friend Info operator+(const Info& a, const Info& b) { // * 合并操作, a 左 b 右
172         return Info(a.val + b.val);
173     }
174 };
175
176 //! Only for LSGT
177 struct Tag {
178     i64 add;
179     Tag() : add(0) {} // * 初始化 (push_down 结束重置时候用)
180     Tag(i64 d) : add(d) {} //? 从其他类型转换 (Modify 时候用)

```

```

181     bool isValid() const { /* tag 是否生效
182         return add != 0;
183     }
184     void applyTo(Info& info, int l, int r, const Tag& delta) { /* 对代表 [l,r] 区间的
        ↪ info 打上 tag
185         add += delta.add;
186         info.val += delta.add * (r - l + 1);
187     }
188 };
189
190 //! Only for SGT
191 struct Delta {
192     i64 val;
193     Delta(i64 v) : val(v) {}
194     void applyTo(Info& info) const {
195         info.val += val;
196     }
197 };
198
199
200 int main() {
201     std::vector<i64> test = {0, 1, 2, 4, 5, 7};
202     LSGT<Info, Tag> A(test);
203     std::cout << A.query(1, 3).val << std::endl;
204     std::cout << A.query(2, 5).val << std::endl;
205     std::cout << A.query(1, 5).val << std::endl;
206     A.modify(1, 3, Tag(1));
207     std::cout << A.query(1, 3).val << std::endl;
208     std::cout << A.query(2, 5).val << std::endl;
209     std::cout << A.query(1, 5).val << std::endl;
210 }
211
212 /*struct SumInfo {
213     modint val;
214     SumInfo() : val(0) {} // 初始化（重置时候用）
215     SumInfo(modint v) : val(v) {} // 从其他类型转换（Build 时候用）
216     SumInfo mergeWith(const SumInfo& other) const { // 合并操作
217         return SumInfo(val + other.val);
218     }
219 };
220
221 struct AddMulTag {
222     modint add, mul;
223     AddMulTag() : add(0), mul(1) {} // 初始化（重置时候用）
224     bool isValid() const { // tag 是否生效
225         return add != modint(0) || mul != modint(1);
226     }

```

```

227 void applyTo(SumInfo& info, int l, int r, AddMulTag delta) { // 对代表 [l,r] 区间的
    ↪ info 打上 tag
228     mul *= delta.mul;
229     add *= delta.mul;
230     add += delta.add;
231     info.val *= delta.mul;
232     info.val += delta.add * (r - l + 1);
233 }
234 };*/

```

4 计算几何

4.1 Point

```

1  #include <bits/stdc++.h>
2
3  using i64 = long long;
4  using d64 = double;
5  using d128 = long double;
6
7  template<class T, class G> struct Vector2Base {
8      T x, y;
9      constexpr Vector2Base() : Vector2Base(T(), T()) {}
10     constexpr Vector2Base(T x, T y) : x(x), y(y) {}
11
12     /* 运算
13     constexpr Vector2Base operator+(Vector2Base a) const { return Vector2Base(x + a.x,
    ↪ y + a.y); }
14     constexpr Vector2Base operator-(Vector2Base a) const { return Vector2Base(x - a.x,
    ↪ y - a.y); }
15     constexpr Vector2Base operator-() const { return Vector2Base(-x, -y); }
16     constexpr G operator*(Vector2Base a) const { return (G)x * a.x + (G)y * a.y; }
17     constexpr G operator%(Vector2Base a) const { return (G)x * a.y - (G)y * a.x; }
18     constexpr Vector2Base rotate() const { return Vector2Base(-y, x); } /* 逆 90 度
19     template<class F> constexpr Vector2Base rotate(F theta) const {
20         Vector2Base b(std::cos(theta), std::sin(theta));
21         return Vector2Base(x * b.x - y * b.y, x * b.y + y * b.x);
22     }
23     constexpr friend Vector2Base operator*(const T& a, Vector2Base b) { return
    ↪ Vector2Base(a * b.x, a * b.y); }
24
25     /* 比较
26     constexpr bool operator<(Vector2Base a) const {
27         if (x == a.x) return y < a.y;
28         return x < a.x;
29     }
30     constexpr bool operator>(Vector2Base a) const {

```

```

31         if (x == a.x) return y > a.y;
32         return x > a.x;
33     }
34     constexpr bool operator<=(Vector2Base a) const {
35         if (x == a.x) return y <= a.y;
36         return x <= a.x;
37     }
38     constexpr bool operator>=(Vector2Base a) const {
39         if (x == a.x) return y >= a.y;
40         return x >= a.x;
41     }
42     constexpr bool operator==(Vector2Base a) const { return x == a.x && y == a.y; }
43     constexpr bool operator!=(Vector2Base a) const { return x != a.x || y != a.y; }
44
45     /* 输入输出
46     friend std::istream& operator>>(std::istream& in, Vector2Base& p) { return in >>
47         ↪ p.x >> p.y; }
48     friend std::ostream& operator<<(std::ostream& ot, Vector2Base p) {
49         return ot << '(' << p.x << ", " << p.y << ')';
50     }
51 };
52
53 /* 点距平方
54 template<class T, class G> G dis2(Vector2Base<T, G> a, Vector2Base<T, G> b =
55     ↪ Vector2Base<T, G>(0, 0)) {
56     Vector2Base<T, G> p = a - b;
57     return p * p;
58 }
59
60 using Vector2 = Vector2Base<int, i64>;
61
62 /* ===== */
63
64 /* 象限确认
65 int sgn(Vector2 p) {
66     if (p.x < 0 or p.x == 0 and p.y > 0) { //? 23 象限 + 正 y 轴 (左)
67         return 1;
68     } else {
69         return 0; //? 14 象限 + 负 y 轴 + 原点 (右)
70     }
71 }
72
73 /* 按极角排序, 4123 象限顺序
74 bool polarCmp(Vector2 p, Vector2 q) {
75     if (sgn(p) == sgn(q)) {
76         if (p % q == 0) {
77             return dis2(p) < dis2(q); // 重合返回短的

```

```

76         } else {
77             return p % q > 0; // true 代表 p 在 q 顺时针方向
78         }
79     } else {
80         return sgn(p) < sgn(q);
81     }
82 }
83
84 /* 计算 ∠AOB(弧度)
85 template<class Float = d128> Float getAngle(Vector2 a, Vector2 b, Vector2 o = Vector2(0,
86     0)) {
87     Vector2 A = a - o, B = b - o;
88     return std::atan2<Float>(A % B, A * B);
89 }
90
91 /* 把角度缩到范围 [0,π]
92 template<class Float = d128> Float normAngle(Float angle) {
93     angle = std::abs(angle);
94     return std::min(angle, 2 * std::numbers::pi_v<Float> - angle);
95 }
96
97 /* 点距
98 template<class Float = d128> Float dis(Vector2 a, Vector2 b = Vector2(0, 0)) {
99     return std::sqrt<Float>(dis2(a, b));
100 }
101
102 /* =====Line===== */
103 /* 点 A 是否在 * 直线 *BC 上
104 bool onLine(Vector2 a, Vector2 b, Vector2 c) {
105     b = b - a;
106     c = c - a;
107     return b % c == 0;
108 }
109
110 /* 点 A 是否在 * 线段 *BC 上
111 bool onSeg(Vector2 a, Vector2 b, Vector2 c) {
112     b = b - a;
113     c = c - a;
114     return b % c == 0 and b * c <= 0;
115 }
116
117 /* 点 A 到 * 直线 *BC 的距离
118 template<class Float = d128> Float disToLine(Vector2 a, Vector2 b, Vector2 c) {
119     Vector2 v1 = b - c, v2 = a - c;
120     return std::abs<Float>(v1 % v2) / std::sqrt<Float>(v1 * v1);
121 }

```



```

122
123  /* 点 A 到 * 线段 *BC 的距离
124  template<class Float = d128> Float disToSeg(Vector2 a, Vector2 b, Vector2 c) {
125      if ((a - b) * (c - b) <= 0 or (a - c) * (b - c) <= 0) {
126          return std::min<Float>(dis<Float>(a, b), dis<Float>(a, c));
127      }
128      return disToLine<Float>(a, b, c);
129  }
130
131  /* 点 A 在直线 BC 上的投影点
132  Vector2 foot(Vector2 a, Vector2 b, Vector2 c) {
133      Vector2 u = a - b, v = c - b;
134      return b + (u * v) / (v * v) * v;
135  }
136
137  /* 点 A 关于直线 BC 的对称点
138  Vector2 symmetry(Vector2 a, Vector2 b, Vector2 c) {
139      Vector2 ft = foot(a, b, c);
140      return 2 * ft - a;
141  }
142
143  /* 直线 AB 和直线 CD 的交点
144  Vector2 cross(Vector2 a, Vector2 b, Vector2 c, Vector2 d) {
145      Vector2 v = c - d;
146      auto sa = v % (a - d), sb = (b - d) % v;
147      return sa / (sa + sb) * (b - a) + a;
148  }
149
150  // 对四个不同的点判断四点共圆
151  // d 在 abc 外接圆外 return 1, 内 return -1
152  template<class Float = d128> int inCircle(Vector2 a, Vector2 b, Vector2 c, Vector2 d) {
153      const Float PI = acosl(-1);
154      Float ag1 = getAngle(a, b, c), ag2 = getAngle(d, c, b);
155      auto sgn = [](Float x) { return x < 0 ? -1 : (x > 0); };
156      if (sgn(ag1) == sgn(ag2)) {
157          return sgn(PI - std::abs(ag1 + ag2));
158      } else {
159          return sgn(std::abs(ag1) - std::abs(ag2));
160      }
161  }
162
163  /*=====*/
164
165  using Vertexs = std::vector<Vector2>;
166
167  /* Graham 法求凸包
168  Vertexs getConvexHull(Vertexs S) {

```

```

169 Vector2 base = *std::min_element(S.begin(), S.end()); // 以左下角为原点
170 for (int i = 0; i < (int)S.size(); i++) {
171     S[i] = S[i] - base;
172 }
173 std::sort(S.begin(), S.end(), polarCmp); // 按极角排序
174
175 /*
176 ? 不删共线点加上
177 int e = S.size() - 1;
178 while (e > 1) {
179     if (S[e] % S.back() == 0) e--;
180     else break;
181 }
182 std::reverse(S.begin() + e + 1, S.end());
183 */
184
185 std::deque<Vector2> Q;
186 Q.push_back(S[0]);
187 Q.push_back(S[1]);
188 for (int i = 2; i < (int)S.size(); i++) {
189     Vector2 B = Q.back(); Q.pop_back(); Vector2 A = Q.back(); // B 后 A 前
190     while ((S[i] - B) % (B - A) >= 0) { // ? 不删共线点就去掉等号
191         B = A; // 删 A
192         Q.pop_back();
193         A = Q.back();
194     }
195     Q.push_back(B);
196     Q.push_back(S[i]);
197 }
198 Vertexs ans(Q.size());
199 int pos = 0;
200 while (!Q.empty()) {
201     ans[pos++] = Q.front() + base;
202     Q.pop_front();
203 }
204 return ans;
205 }
206
207
208 //! test
209 int main() {
210     int N;
211     std::cin >> N;
212     Vertexs vs(N);
213     for (int i = 0; i < N; i++) {
214         std::cin >> vs[i];
215     }

```

```
216     Vertexs hull = getConvexHull(vs);
217     for (int i = 0; i < (int)hull.size(); i++) {
218         std::cout << hull[i] << std::endl;
219     }
220 }
```

5 数学相关

5.1 模运算

```
1  i64 add(i64 a, i64 b, i64 p) { // 加
2      return (a % p + b % p) % p;
3  }
4
5  i64 sub(i64 a, i64 b, i64 p) { // 减
6      return (a % p - b % p) % p;
7  }
8
9  i64 mul(i64 a, i64 b, i64 p) { // a > p 乘
10     a %= p;
11     b %= p;
12     i64 ans = 0;
13     while (b > 0) {
14         if (b & 1) {
15             ans += a;
16             ans %= p;
17         }
18         a <<= 1;
19         a %= p;
20         b >>= 1;
21     }
22     return ans;
23 }
```

5.2 素数筛 & 欧拉函数

```
1  #include <bits/stdc++.h>
2
3  bool isPrime(int num)
4  {
5      if (num == 1) return 0;
6      if (num == 2 || num == 3) return 1;
7      if (num % 6 != 1 && num % 6 != 5) return 0;
8      int tmp = sqrt(num);
9      for (int i = 5; i <= tmp; i += 6)
10         if (num % i == 0 || num % (i + 2) == 0) return 0;
11     return 1;
```

```
12 }
13
14 /* 埃氏筛  $O(N \log \log N)$ 
15 void E_sieve(int N) {
16     std::vector<bool> isP(N + 1, true);
17     for (int i = 2; i <= N; i++) {
18         if (!isP[i]) continue;
19         for (int j = i * i; j <= N; j += i) {
20             isP[j] = false;
21         }
22     }
23     isP[0] = isP[1] = false;
24 }
25
26 /* 线性欧拉筛  $O(N)$ 
27 void euler_sieve(int N) {
28     std::vector<int> prime(N + 1); //? 可小于 N, 约  $\ln N$ 
29     std::vector<bool> vis(N + 1);
30     int cnt = 0;
31     for (int i = 2; i <= N; i++) {
32         if (!vis[i]) prime[cnt++] = i;
33         for (int j = 0; j < cnt; j++) {
34             if (i * prime[j] > N) break;
35             vis[i * prime[j]] = true;
36             if (i % prime[j] == 0) break;
37         }
38     }
39     for (int i = 0; i < static_cast<int>(prime.size()); i++) {
40         if (!prime[i]) {
41             prime.resize(i);
42             break;
43         }
44     }
45 }
46
47 /* 预处理求欧拉函数
48 void euler_pre(int N) {
49     std::vector<int> phi(N + 1);
50     std::iota(phi.begin() + 1, phi.end(), 1);
51     for (int i = 1; i <= N; i++) {
52         for (int j = 2 * i; j <= N; j += i) {
53             phi[j] -= phi[i];
54         }
55     }
56 }
57
58 int main() {
```

```
59     euler_pre(11);  
60 }
```

6 杂项

6.1 快速读入

```
1  inline int read()  
2  {  
3      int x = 0, sgn = 1;  
4      char ch = getchar();  
5      while (ch < '0' || ch > '9') {  
6          if (ch == '-') sgn = -1;  
7          ch = getchar();  
8      }  
9      while (ch >= '0' && ch <= '9') {  
10         x = x * 10 + ch - '0';  
11         ch = getchar();  
12     }  
13     return x * sgn;  
14 }
```