

## Algorithm – 11

### ——Single-Source Shortest Paths

#### **A. Problem Description**

In a shortest-paths problem, we are given a weighted, directed graph  $G = (V, E)$ , with weight function  $w: E \rightarrow \mathbb{R}$  mapping edges to real-valued weights. The weight  $w(p)$  of path  $p = \{v_0, v_1, \dots, v_n\}$  is the sum of the weights of its constituent edges:

$$w(p) = \sum_{i=1}^k w(v_{i-1}, v_i)$$

We define the shortest-path weight  $D(u, v)$  from  $u$  to  $v$  by

$$D(u, v) = \begin{cases} \min\{w(p) : u \rightarrow p\} \\ \infty \end{cases}$$

A shortest path from vertex  $u$  to vertex  $v$  is then defined as any path  $p$  with weight  $w(p) = D(u, v)$ .

#### **B. Description of the algorithm**

**DIJKSTRA( $G, w, s$ )**

**INITIALIZE-SINGLE-SOURCE( $G, s$ )**

$S = \{\text{NULL}\}$      // make the set  $S$  empty

$Q = G.V$              // put all vertices into  $G$

```

while Q != NULL

    // extract the vertex who has the smallest d-value

    u = EXTRACT-MIN(Q)

    S = S + {u}

    // if there exists one vertex that can be directly reached from u
    and the distance[s -> u -> x] is shorter than that stored in x.d,
    then change the x.d

    for each vertex v in G.Adj[u]

        RELEX(u, v, w)    // With 'DECREASE-KEY(Q)' inside

```

### ***C. Time complexity***

Step "INITIALIZE-SINGLE-SOURCE( $G, s$ )"  $\rightarrow \theta(V)$

Step " $Q = G.V$ "  $\rightarrow \theta(V)$

Step "while"  $\rightarrow \theta(V)$

Therefore, the total time  $T$  is

### ***D. Code[Python]***

```

#!/usr/bin/python
# Filename: Dijkstra.py

inf = float('inf')

class vertex:
    def __init__(self, start, end, value = inf , distance = inf, isTaken =
False):
        self.start = start

```

```

self.end = end
self.value = value
self.distance = distance
self.isTaken = isTaken

def Dijkstra(S, G, n, source):
    G[source][source].distance = 0
    for i in range(0, n):
        for j in range(0, n):
            if G[source][j].isTaken == False:
                index = j
                break
        for j in range(0, n):
            if G[source][j].distance < G[source][index].distance and
G[source][j].isTaken == False:
                index = j
            G[source][index].isTaken = True # delete vertex[index] from G
            S.append(G[source][index]) # insert vertex[index] into S
        for j in range(0, n):
            if G[source][j].isTaken == False and G[index][j].value < inf:
                availableDistance = G[source][index].distance + G[index]
[j].value
                originalDistance = G[source][j].distance
                G[source][j].distance = availableDistance if availableDistance
< originalDistance else originalDistance

```