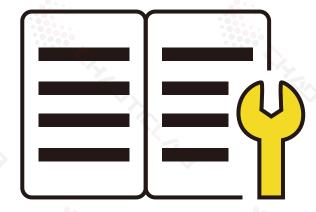




VORON 2.4 CNC XY JOINT KIT BUILD GUIDE

VERSION 2024-05-23

READ BEFORE ASSEMBLY WWW.CHAOTICLAB.COM

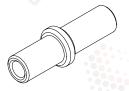


- Parts highlighted in blue are included in this CNC XY Joint Kit.
- Parts highlighted in red are NOT included and will need to be prepared separately.





1pc



**BEARING STANDOFF** 

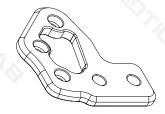
4pcs



**BUTTON HEAD CAP SCREW(BHCS)** 

M5x10

6pcs



**XY JOINT UPPER RIGHT** 

1pc



**SUPPORT COLUMN** 

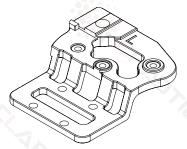
2pcs



SOCKET HEAD CAP SCREW(SHCS)

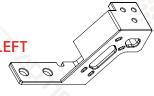
M3x25

6pcs



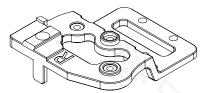
XY JOINT LOWER LEFT

1p



**CABLE DRAG CHAIN BRIDGE** 

1pc



XY JOINT LOWER RIGHT

1pc



DROP-IN T-NUT, M5 (2020)

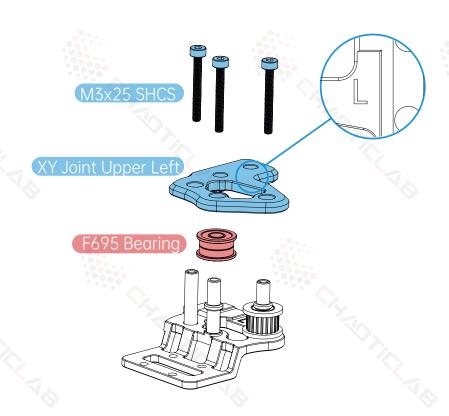
6pcs

XY JOINT LEFT WWW.CHAOTICLAB.COM

# Support Column Bearing Standoff 2GT-20T Idler

# **IDLERS**

The XY Joint is designed to be compatible with idlers that have a thickness of 9mm or less. Due to tolerance difference of idlers from different manufacturers, the XY Joint stand off has been designed with extra tolerance. Please use 0.1mm precision shims to adjust the idler height and eliminate axial movement of the Idler to ensure smooth belt motion. Stack the shims as evenly as possible at the top and bottom of your idler. You will need to self source the shims.



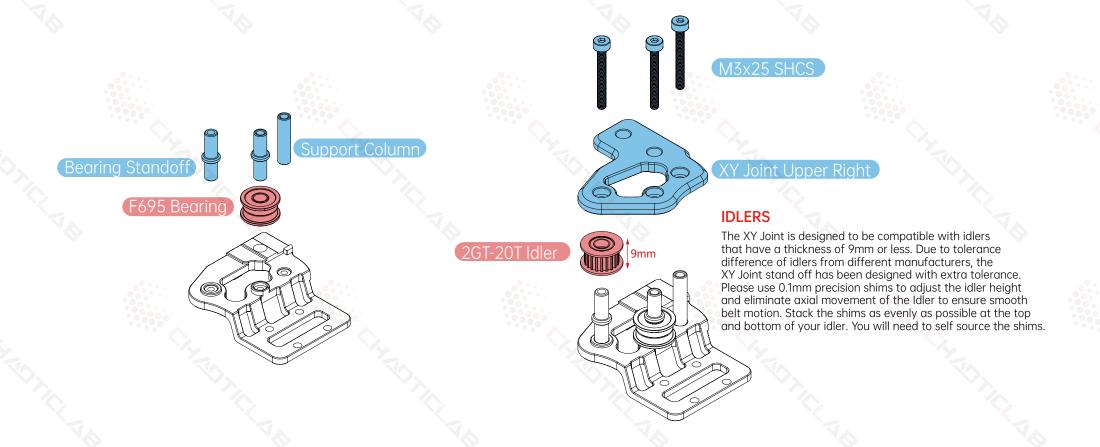
# **XY JOINT LOWER LEFT**

Marked with "L" or "R" to help you distinguish between the left and right parts.

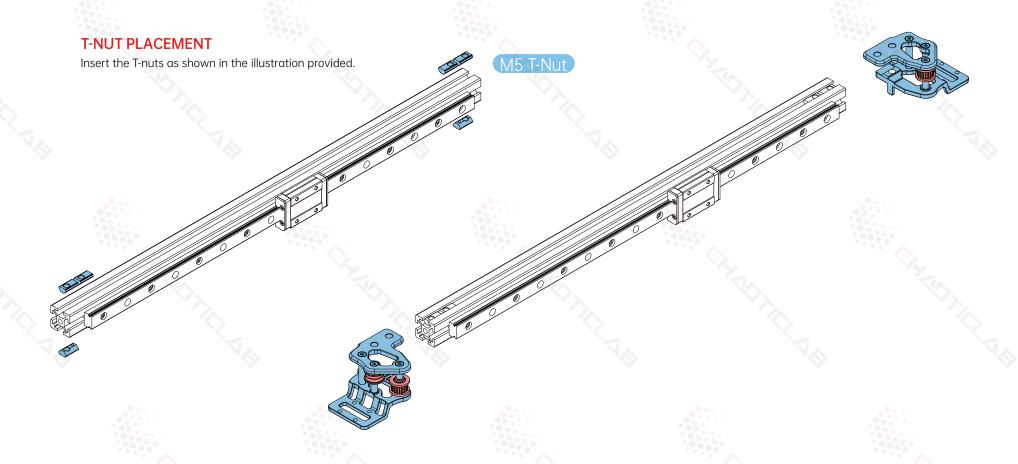
### XY JOINT UPPER LEFT

Marked with "L" or "R" to help you distinguish between the left and right parts.

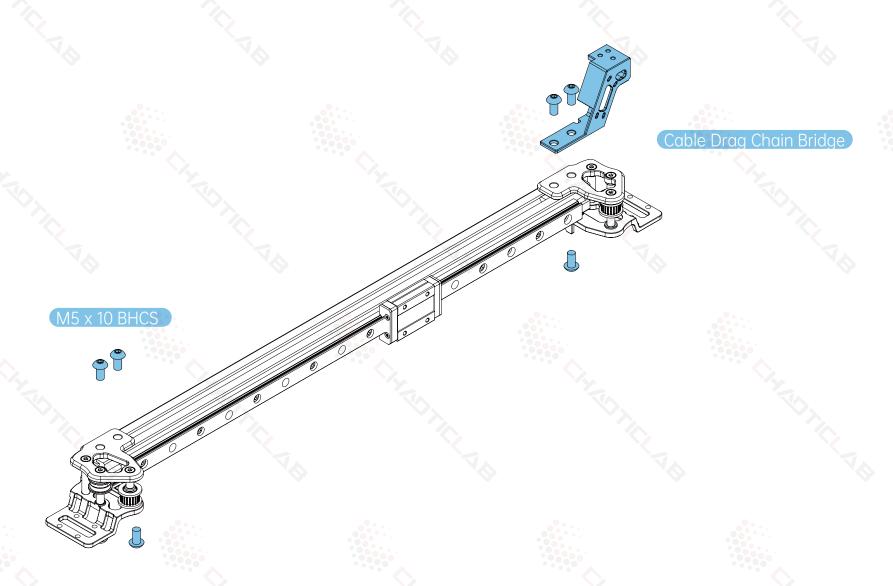
XY JOINT RIGHT WWW.CHAOTICLAB.COM



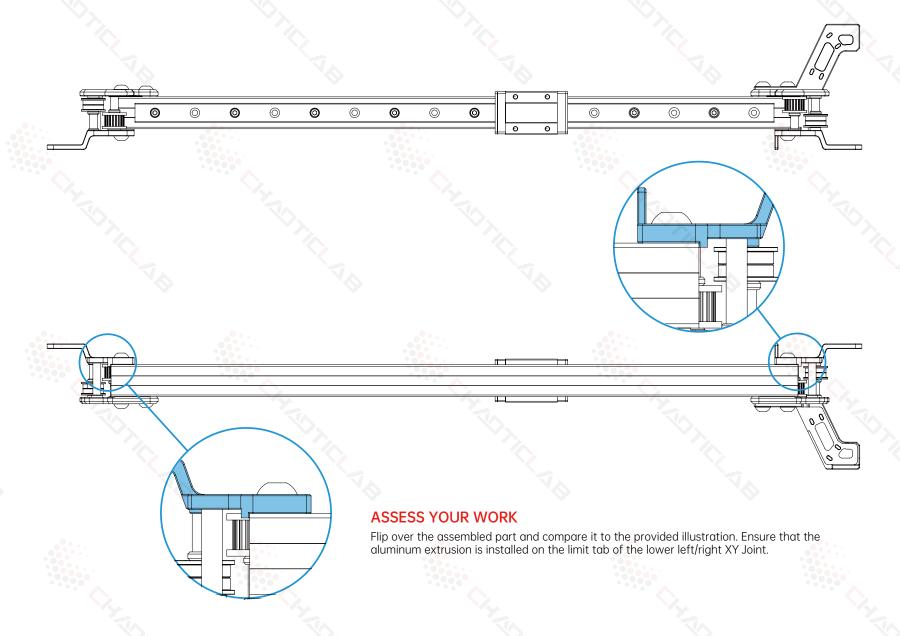




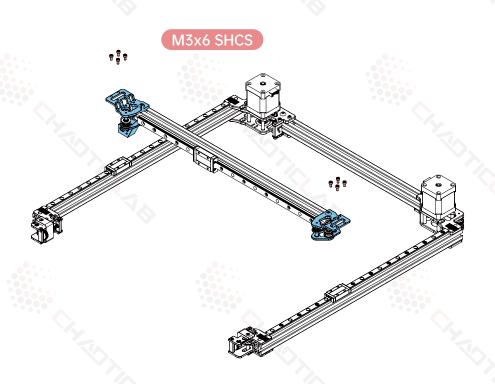
X AXIS WWW.CHAOTICLAB.COM



X AXIS WWW.CHAOTICLAB.COM



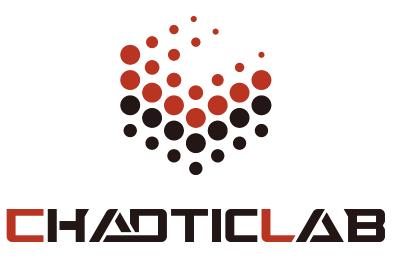
X AXIS WWW.CHAOTICLAB.COM



## **ENSURING PROPER GANTRY ALIGNMENT**

Since the CNC parts in the kit have higher precision and rigidity compared to the printed parts, it's important to keep the whole gantry relatively level before fully tightening the eight screws. Follow these steps for optimal setup:

Push the X-axis to the far end towards the XY motor, making sure it is completely parallel to the gantry motor side profile, then fully tighten the screws. Alternatively, after the assembly is complete, you can slightly loosen these 8 screws. Perform the initial QGL, then move the Z-axis to the appropriate height. Unlock the motor, push the X-axis towards the X-MAX direction, and then re-tighten the screws.





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