

Theoretical Model

1. Yoffe-Shaibani-Hazzeldine Model for an Inclined Threading dislocation

In the original derivation by Yoffe (1961) [1], two auxiliary coordinate systems are utilized by rotating the right-handed standard Cartesian coordinates around the x axis: x, η, ζ and x, η', ζ' . The dislocation terminating at the origin $(0, 0, 0)$ is in the $-z$ half space with an inclination angle of α to the $-z$ axis. Yoffe's original analytical solution for a threading dislocation was later revisited by Shaibani and Hazzeldine (1981) who introduced a number of simplifications in addition to several typographical corrections [2]. The relationships between the different coordinate systems are expressed as:

$$\eta = y \cos \alpha - z \sin \alpha, \quad (1a)$$

$$\zeta = z \cos \alpha + y \sin \alpha, \quad (1b)$$

$$\eta' = -y \cos \alpha - z \sin \alpha, \quad (1c)$$

$$\zeta' = -z \cos \alpha + y \sin \alpha, \quad (1d)$$

$$R^2 = x^2 + y^2 + z^2 = x^2 + \eta^2 + \zeta^2 = x^2 + \eta'^2 + \zeta'^2. \quad (1e)$$

For a Burgers vector $\mathbf{b} = b_x \mathbf{e}_x + b_y \mathbf{e}_y + b_z \mathbf{e}_z$, the YSH model aligns a screw dislocation's Burgers vector along the $-\zeta'$ axis and an edge dislocation's Burgers vector along the $-\eta'$ axis:

$$b_e = b_y \cos \alpha + b_z \sin \alpha, \quad (2a)$$

$$b_s = b_z \cos \alpha - b_y \sin \alpha, \quad (2b)$$

with a special case when the Burgers vector of the edge dislocation is perpendicular to the y - z plane, i.e., along the x direction (b_x). In the case of a mixed dislocation, the Burgers vector \mathbf{b} can be resolved into edge (b_e) and screw (b_s) components using equations 2. The total displacement field of a mixed dislocation also follows the superposition principle.

To reduce the complexity of the analytical forms, a few auxiliary parameters are introduced:

$$\omega = \arctan \frac{y}{x} - \arctan \frac{\eta}{x} + \arctan \frac{xR \sin \alpha}{y\eta + x^2 \cos \alpha}, \quad (3a)$$

$$\omega' = \arctan \frac{y}{x} - \arctan \frac{\eta'}{x} + \arctan \frac{xR \sin \alpha}{y\eta' - x^2 \cos \alpha}, \quad (3b)$$

16 and

$$A = (R - z); B = (R - \zeta); B' = (R - \zeta') \quad (4)$$

17 Below, the displacement fields of different dislocation types are listed without
18 derivation.

19 *1.1. Dislocation in the y-z plane: screw component b_s*

The displacement field $\mathbf{u} = [u_x, u_y, u_z]$ of the screw component of an inclined dislocation with magnitude of Burgers vector b_s in the y - z plane at any point (x, y, z) is shown below. These equations also apply to the case of a pure screw dislocation when the Burgers vector is along the dislocation line, i.e., along the $-\zeta'$ direction.

$$u_x = \{xm_s + \frac{2\eta \cos^2 \alpha}{B} + 2(1 - 2\nu) \cot \alpha [-1 + \cos \alpha + \cos \alpha \log A - \frac{y \sin \alpha}{A} - \log B] - \sin 2\alpha\} / (2SG), \quad (5)$$

$$u_y = \{ym_s - \frac{2x \cos \alpha}{B} - \sin \alpha (\omega' - \omega) + 2(1 - 2\nu) \cot \alpha [x \sin \alpha / A - \omega \cos \alpha]\} / (2SG), \quad (6)$$

$$u_z = \{zm_s + \cos \alpha (\omega' - \omega) - 2(1 - 2\nu) \omega \cos \alpha\} / (2SG), \quad (7)$$

20 where

$$m_s = \frac{x \sin 2\alpha}{RB}; S = \left(\frac{Gb_s}{2\pi}\right)^{-1} \quad (8)$$

21 and G is the shear modulus and ν the Poisson ratio.

22 1.2. Dislocation in the y - z plane: edge component b_e

The displacement field $\mathbf{u} = [u_x, u_y, u_z]$ of the edge component of an inclined dislocation with magnitude of Burgers vector b_e in the y - z plane at any point (x, y, z) is given by:

$$u_x = \{xm_e + \lambda + 2\frac{\cos \alpha}{B}(z + 2(1 - \nu)\eta \sin \alpha) - 4(1 - \nu) \sin^2 \alpha + k[1 - \cos \alpha - \cos \alpha \log A + \frac{y \sin \alpha}{A} + \log B]\}/(2D_e G), \quad (9)$$

$$u_y = \{ym_e + q_e \sin \alpha + \theta \cos \alpha + k[-\frac{x \sin \alpha}{A} + \omega \cos \alpha]\}/(2D_e G), \quad (10)$$

$$u_z = [zm_e + q_e \cos \alpha + \theta \sin \alpha - 2x \cos \alpha(\frac{1}{B'} + \frac{1 - 2\nu}{B}) + k\omega \sin \alpha]/(2D_e G), \quad (11)$$

where:

$$q_e = x[\frac{1}{B'} - \frac{1}{B} + \frac{2z \cos \alpha}{B^2}], \quad (12a)$$

$$m_e = -\frac{q_e}{R} - \frac{4(1 - \nu)x \cos^2 \alpha}{RB}, \quad (12b)$$

$$D_e = [\frac{Gb_e}{4\pi(1 - \nu)}]^{-1}, \quad (12c)$$

$$\lambda = (1 - 2\nu) \log(\frac{B'}{B}), \quad (12d)$$

$$\theta = 2(1 - \nu)(\omega' - \omega), \quad (12e)$$

$$k = 4(1 - \nu)(1 - 2\nu) \cot^2 \alpha, \quad (12f)$$

23 *1.3. Pure Edge dislocation in the x - z plane: $|\mathbf{b}| = b_x$*

In this case, the Burgers vector of the edge dislocation is perpendicular to the y - z plane for all angles α , i.e., a pure edge dislocation.

$$u_x = \{xm_x + \theta + k[\frac{x \tan \alpha}{A} - \omega]\}/(2D_x G), \quad (13)$$

$$u_y = \{ym_x + q_x \sin \alpha - \lambda \cos \alpha - \frac{2 \cos \alpha}{B}[z \cos \alpha + (1 - 2\nu)y \sin \alpha] \\ + k[-1 + \cos \alpha - \log A + \frac{y \tan \alpha}{A} + \cos \alpha \log B]\}/(2D_x G), \quad (14)$$

$$u_z = \{zm_x + q_x \cos \alpha - \lambda \sin \alpha - \frac{2\eta' \cos \alpha}{B'} + \frac{4 \cos \alpha}{B}[(1 - \nu)y \cos \alpha \\ - (1 - 2\nu)z \sin \alpha] + k \tan \alpha(\cos \alpha - \log A + \cos \alpha \log B) \\ + 4(1 - \nu) \cos \alpha \cot \alpha\}/(2D_x G) \quad (15)$$

where:

$$q_x = \frac{\eta'}{B'} - \frac{\eta}{B} - \frac{2z\eta \cos \alpha}{B^2}, \quad (16a)$$

$$m_x = -\frac{q_x}{R} + \frac{2(1 - 2\nu)y \cos \alpha}{RB}, \quad (16b)$$

$$D_x = (\frac{Gb_x}{4\pi(1 - \nu)})^{-1}, \quad (16c)$$

$$\lambda = (1 - 2\nu) \log(\frac{B'}{B}), \quad (16d)$$

$$\theta = 2(1 - \nu)(\omega' - \omega), \quad (16e)$$

$$k = 4(1 - \nu)(1 - 2\nu) \cot^2 \alpha, \quad (16f)$$

24 **References**

- 25 [1] E. H. Yoffe, A dislocation at a free surface, Philosophical Magazine 6
26 (1961) 1147–1155.
- 27 [2] S. J. Shaibani, P. M. Hazzledine, The displacement and stress fields of
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29 sophical Magazine A 44 (1981) 657–665.