1 The doughnut experiment

We simulate data in a 2D doughnut shape. There are 2 quantitive features (x_1, x_2) and a binary outcome. A 2D doughnut has two circles. Observations with (x_1, x_2) falling between the circles have a high probability to be in class 1, and those falling inside the inner circle or outside the outer circle have a high probability to be in class 0. We also generate additional noise features x_3, \dots, x_{10} . We compare the performance of various prediction models on this data.

You could similarly generate a high-dimensional doughnut data, although it would be difficult to visualize.

```
library(class)
                       ## knn()
library(splines)
                       ## ns()
library(gam)
                       ## gam() allowing multiple smoothing splines
library(rpart)
                       ## rpart()
                       ## randomForest()
library(randomForest)
library(xgboost)
                       ## xgboost()
library(e1071)
                       ## svm()
                       ## for 3D plots
library(rgl)
```

1.1 Generate data

Set seed and sample size. Define the 2D doughnut region by specifying the inner and outer radii. Assign a high probability to the doughnut region and a low probability outside this region. You may treak these numbers to see how much the performance would change for various methods. To generate the outcome deterministically, set $p_{in} = 1$ and $p_{out} = 0$. To generate the outcome probabilistically, set these probabilities to be between 0 and 1.

```
N = 1000; Ntrain = 800
radius1 = 1; radius2 = 1.5  ## radii that define our doughnut
pin = 0.9; pout = 0.1  ## probabilities of class 1 for inside and outside the doughnut
#N = 5000; Ntrain = 4000
#pin = 1; pout = 0
```

First, generate the features. Then, generate the outcome according to the first two features. Check whether the data are well distributed in their location (inside, on, and outside the doughnut).

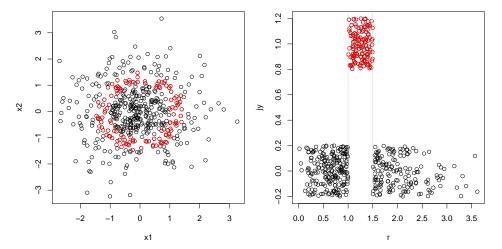
We put all data into a data frame, and then split the data into training and test sets.

```
train = sample(1:N, Ntrain)
mydata = data.frame(x1, x2, x3, x4, x5, x6, x7, x8, x9, x10, y)
mydata.train = mydata[train,]
mydata.test = mydata[-train,]
```

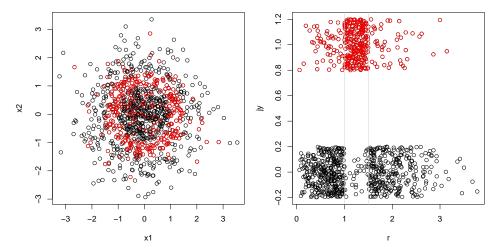
Plot the data.

```
plot(x1, x2); points(x1[y==1], x2[y==1], col=2)
plot(r, jy); points(r[y==1], jy[y==1], col=2); abline(v=c(radius1, radius2), col='lightgrey')
```

This is what I got with $p_{in} = 1$, $p_{out} = 0$, and N = 500:



This is what I got with $p_{in} = 0.9$, $p_{out} = 0.1$, and N = 1000:



For every prediction model, we will make a plot on the test set, and display the model on a grid. We create some relevant functions here.

```
getpred = function(mod, dataset) {
  if (class(mod)[1] %in% c('glm','Gam'))
    ytestpred = predict(mod, dataset, type="response")
  if (class(mod)[1] %in% c('rpart','randomForest.formula'))
    ytestpred = predict(mod, dataset, type="class")
  if (class(mod)[1] %in% c('svm.formula', 'xgb.Booster'))
    ytestpred = predict(mod, dataset)
    ytestpred
}

testseteval = function(mod) {
    ytestpred = getpred(mod, mydata.test)
    table(y[-train], ytestpred)
}

testsetplot = function(mod) {
    ytestpred = getpred(mod, mydata.test)
    testsetplot2(ytestpred)
```

```
testsetplot2 = function(ytestpred) {
  plot(ytestpred, jy[-train], xlab='predicted y', ylab='observed y (jittered)',
       main=paste("cor =", round(cor(as.numeric(ytestpred), y[-train]), 3)))
gridlen = 201
gridx1 = seq(-3, 3, length.out=gridlen)
gridx2 = gridx1
g1 = rep(gridx1, each=gridlen)
g2 = rep(gridx2, gridlen)
## grid to evaluate models on
testgrid = data.frame(x1=g1, x2=g2,
                      x3=rnorm(gridlen^2), x4=rnorm(gridlen^2), x5=rnorm(gridlen^2),
                      x6=rnorm(gridlen^2), x7=rnorm(gridlen^2), x8=rnorm(gridlen^2),
                      x9=rnorm(gridlen^2), x10=rnorm(gridlen^2), r=sqrt(g1^2+g2^2))
## 2D and 3D plots on a grid
gridplots = function(mod) {
  gridpred = matrix(getpred(mod, testgrid), gridlen)
  gridplots2(gridpred)
gridplots2 = function(gridpred) {
  plot(x1, x2); points(x1[y==1], x2[y==1], pch=19)
  contour(gridx1, gridx2, gridpred, add=T, col=1:5, lwd=3, levels=c(0.1,0.3,0.5,0.7,0.9))
  rgl::plot3d(g1, g2, gridpred)
```

1.2 KNN

KNN using only x1 and x2. You may treak the parameter k.

```
table(knn(mydata.train[, 1:2], mydata.test[, 1:2], y[train], k=10), y[-train])
knn1.pred = matrix(knn(mydata.train[, 1:2], testgrid[, 1:2], y[train], k=10), gridlen)
gridplots2(knn1.pred)
```

KNN using all features.

```
table(knn(mydata.train[, 1:10], mydata.test[, 1:10], y[train], k=10), y[-train])
knn2.pred = matrix(knn(mydata.train[, 1:10], testgrid[, 1:10], y[train], k=10), gridlen)
gridplots2(knn2.pred)
```

1.3 Logistic regression

Only linear terms in x1 and x2.

```
mod1 = glm(y ~ x1 + x2, mydata, subset=train, family=binomial)
testsetplot(mod1)
gridplots(mod1)
```

Now add quadratic terms in x1 and x2.

```
mod2 = glm(y \sim x1 + x2 + I(x1^2) + I(x2^2), mydata, subset=train, family=binomial) testsetplot(mod2) gridplots(mod2)
```

Logistic regression or GAM with splines on x1 and x2. You may treak the df parameters.

Using splines on the radius based on the first two features, $r = \sqrt{x_1^2 + x_2^2}$. You may treak the df parameter.

```
mod4 = glm(y[train] ~ ns(r, df=4), data=data.frame(y,r)[train,], family=binomial)
testsetplot2(predict(mod4, data.frame(r=r[-train])))
gridplots(mod4)
```

```
mod5 = glm(y ~ ., mydata, subset=train, family=binomial)
testsetplot(mod5)
gridplots(mod5)
```

1.4 Classification trees

```
tree1 = rpart(factor(y) ~ x1+x2, data=mydata, subset=train, method='class')
testseteval(tree1)
gridplots(tree1)
```

```
tree2 = rpart(factor(y) ~ ., data=mydata, subset=train, method='class')
testseteval(tree2)
gridplots(tree2)
```

1.5 Random forest

RF seems to be worse than a classification tree for a small N but better for a large N.

```
testseteval(rf2)
gridplots(rf2)
```

1.6 XGBoost

1.7 SVM

Only x1 and x2 are considered. You may play with the cost parameter.

This model is great when the sample size is large.

Now add quadratic terms.

1.8 ANN?