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**Plexiglass** 

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Game begins

**Balls are** released

**Players** activate controls **Controls** activate flippers

Goal is scored

Tally is displayed

Ball returned to field

Goal threshold is reached

Game ends

## Introduction

**Aim:** To build an accessible four-player pinball-type game for children with disabilities at John Chilton School.

# **User Requirements**

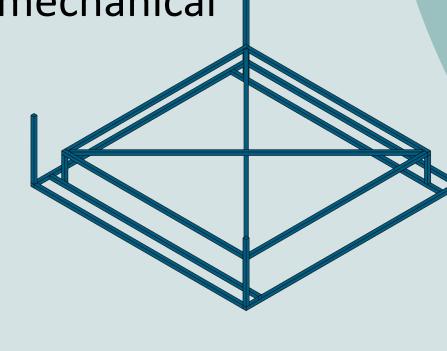
- Functional Game Design
- 2 Variety of Control Technologies
- Audio-visual feedback
- Autonomous Game (CPU)
- 5 Safety and Security
- Suitable size for a player on a wheelchair: 700 mm x 700 mm
- Light-weight
- Contrasting colours for visually impaired players

# 1 Functional Game Design

## A. The Chassis

 Made of hollow stainless steel and aluminium tubes

 Provides mechanical support



## B. Ball Return Mechanism

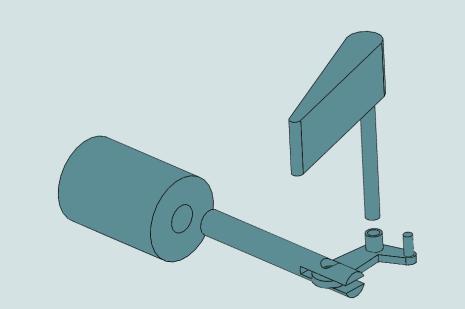
- Ball rolls down the ramp into one compartment of the wheel
- The wheel is controlled by a timing belt connected to a pulley rotated by a motor
- When the container with the ball reaches the top position, the ball rolls back due to the inner inclined planes of the wheel

## C. The Goal Counting Mechanism

- Consists of an infrared light emitting diode and a photodiode
- When a ball obstructs the infrared beam, the counter increments

## D. Flipper Mechanism

A 50V coil pulls a cylindrical steel plunger which swings the flipper bat.



1 USB Port per side

(for plugging in 1 control)

# **2** Variety of Control Technologies

## **Control 1: Eyebrow control**

An Arduino Nano is processing the data from:

- MMG: Microphone placed on the player's forehead converting the sound of muscle contractions into an electrical signal
- An IMU unit sensing the head movement to cancel out false activation

D. Flipper

Mechanism

#### **Control 2: Button**

 Pressing the button sends an impulse to the CPU



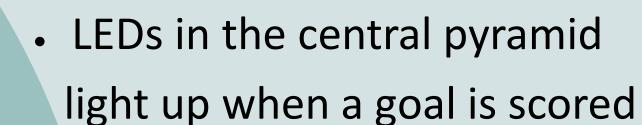
## **Control 3: Voice Recognition**

• The keyword 'Go' is recognised using the 'Snowboy' software and sends an impulse to the CPU



# **Audio-visual Feedback**

 4 sounds respectively indicate the game starting, ending, flippers moving and scoring goals





# **Central Processing Unit**

- Triggers flippers upon activation of the control on the same side using parallel processing
- Tracks scores
- Runs ball return motor
- Provides audio-visual feedback

# **Safety and Security**

 Power distributed from an external power supply connected to mains, equipped with fuses

Plexiglass top prevents injuries from components

**Results and Evaluation** 

# Flipper activation delay Delay(m) 500 300 300 100 Voice **Eyebrow Control** Button **Control Activation Success Rate**

C. The goal

counting sensor

**B. Ball Return** 

Mechanism

Fig. 1: Bar Chart showing the delay between the action of the player and the reaction of the flipper. A logic analyser was used to record the waves at input and output

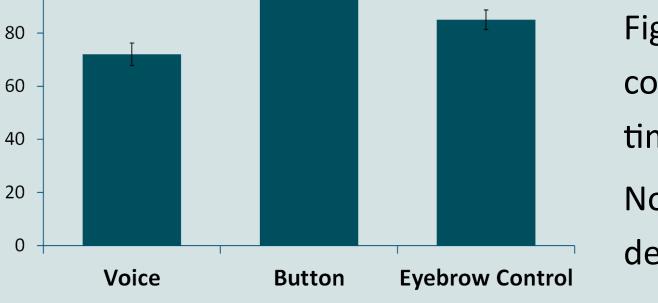


Fig. 2: Bar Chart showing the success rate of each control. Ten participants tested each control 20 times

Note: Error bars in both charts show the standard deviation of the mean

The delays introduced by each control are negligible for the user experience, but can be corrected at the processing stage. The success rate is acceptable for playing the game.

# **Further Improvements**

- Lighter materials can be used to increase the portability of the game
- More bumpers can be added to the playfield to make it more fun
- The success rate can be increased for MMG and voice recognition with better signal processing for both and further training of the model for the latter

## Conclusion

The final board game is a fully functional assistive technology game which allows disabled students to play independently.

## Acknowledgements

Thank you to: Dr. Ian Radcliff, Paschal Egan, Dr. Ravi Vaidyanathan, Dan Nardini, Niraj Kanabar, John Chilton School, Snowboy and ICRS