

CS3011: Introduction to Artificial Intelligence

Constraint Satisfaction Problems (CSP)

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Definition

- A constraint satisfaction problem (CSP) consists of
 - a set of variables,
 - a domain for each variable, and
 - a set of constraints.
- The aim is to choose a value for each variable so that the resulting possible world satisfies all the constraints.

Constraint Satisfaction Problems

A constraint satisfaction problem consists of three components, X,D, and C:

X is a set of variables, $\{X_1,\ldots,X_n\}$.

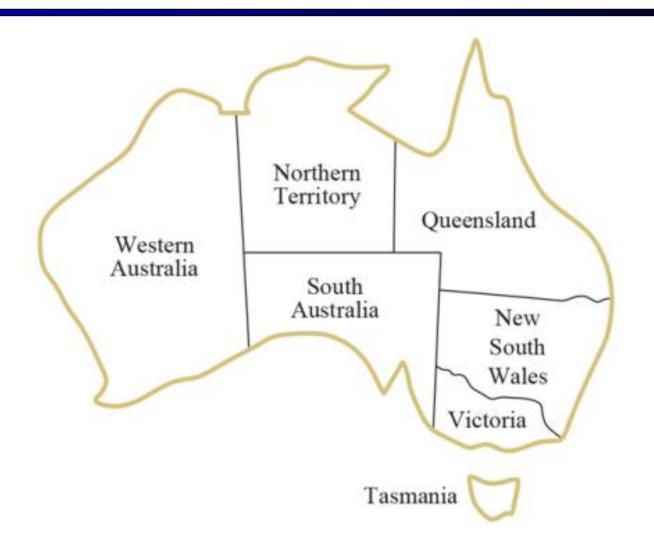
D is a set of domains, $\{D_1, \ldots, D_n\}$, one for each variable.

C is a set of constraints that specify allowable combinations of values.

• A solution is an assignment of a value to each variables X_i such that every constraints satisfied.

CSP Examples: Map Coloring

Map of Australia: We are given the task of coloring each region either red, green, or blue in such a way that no two neighboring regions have the same color.



Example: Map Coloring

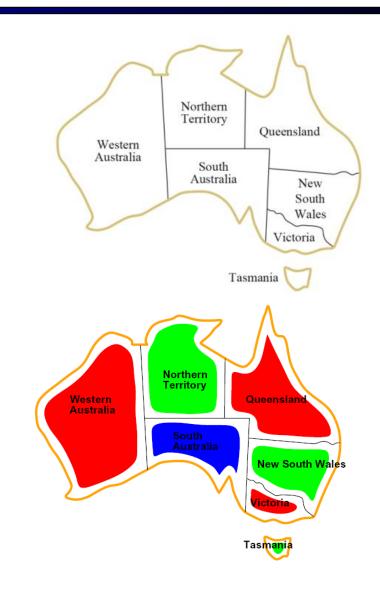
- Variables: WA, NT, Q, NSW, V, SA, T
- Domains: $D = \{red, green, blue\}$
- Constraints: adjacent regions must have different colors

Implicit: $WA \neq NT$

Explicit: $(WA, NT) \in \{(red, green), (red, blue), \ldots\}$

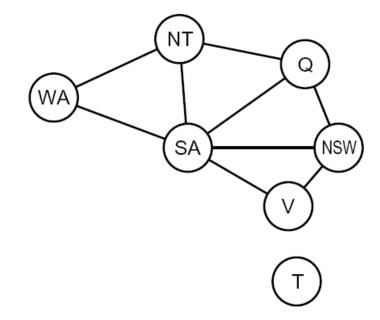
Solutions are assignments satisfying all constraints, e.g.:

```
{WA=red, NT=green, Q=red, NSW=green, V=red, SA=blue, T=green}
```



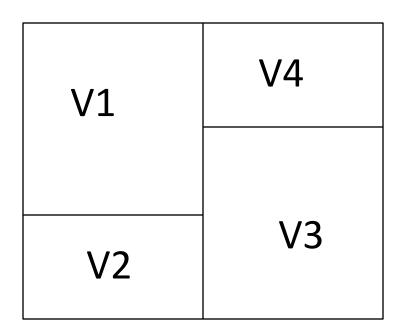
Constraint Graphs

- Binary CSP: each constraint relates (at most) two variables
- Binary constraint graph: nodes are variables, arcs show constraints



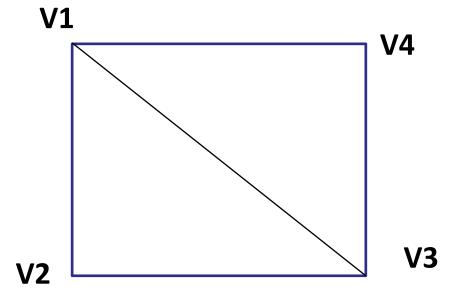
Example: Map Colouring

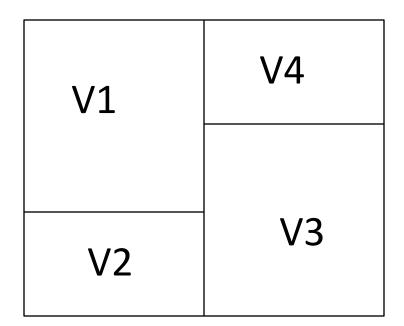
 Can we colour all 4 regions with 3 colours (Red, Green, Blue)so that no two adjacent regions are the same colour?



Example: Map Colouring as CSP

- X= { V1, V2, V3, V4}
- Di = { Red, Green, Blue}
- Constraints: adjacent regions must have different colors
- Solution?

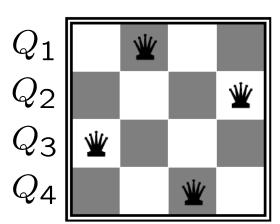




Example: N-Queens

Formulation:

- Variables: Q_k
- Domains: $\{1, 2, 3, ... N\}$



Constraints:

Implicit: $\forall i, j \text{ non-threatening}(Q_i, Q_j)$

Explicit: $(Q_1, Q_2) \in \{(1,3), (1,4), \ldots\}$

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Example: Cryptarithmetic

Variables:

FTUWRO
$$C_1$$
 C_2 C_3

Domains:

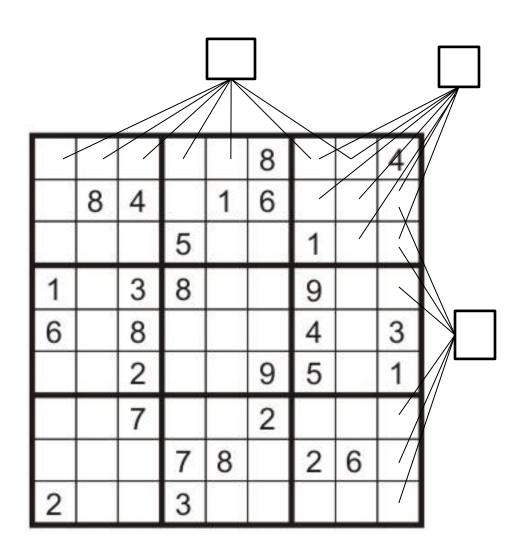
$$\{0, 1, 2, 3, 4, 5, 6, 7, 8, 9\}$$

Constraints:

$$egin{aligned} & ext{alldiff}(F,T,U,W,R,O) \ & O+O=R+10\cdot C_1 \ & C_1+W+W=U+10\cdot C_2 \ & C_2+T+T=O+10\cdot C_3 \ & C_3=F \ , \end{aligned}$$

A cryptarithmetic problem: Each letter stands for a distinct digit; the aim is to find a substitution of digits for letters such that the resulting sum is arithmetically correct, with the added restriction that no leading zeroes are allowed.

Example: Sudoku



- Variables:
 - Each (open) square
- Domains:
 - **1**,2,...,9
- Constraints:

9-way alldiff for each column

9-way alldiff for each row

9-way alldiff for each region

Varieties of Constraints

Unary constraints involve a single variable (equivalent to reducing domains), e.g.:

$$SA \neq green$$

■ Binary constraints involve pairs of variables, e.g.:

$$SA \neq WA$$

■ **Higher-order constraints** involve 3 or more variables:

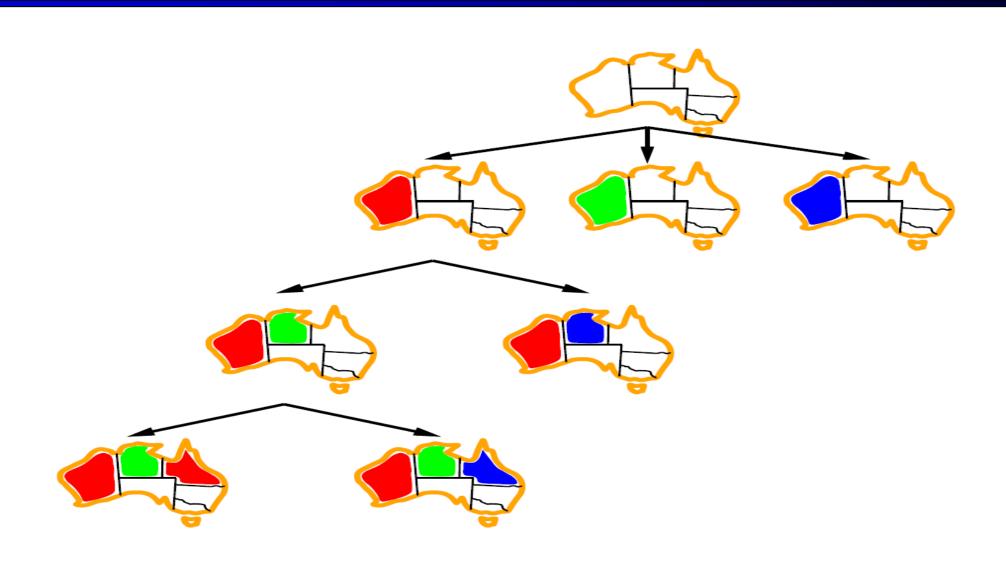
e.g., cryptarithmetic column constraints

Solving CSPs

Standard Search Formulation

- States defined by the values assigned so far (partial assignments)
 - Initial state: the empty assignment, {}
 - Successor function: assign a value to an unassigned variable
 - Goal test: the current assignment is complete and satisfies all constraints
- We'll start with the straightforward, naïve approach, then improve it
 - Depth-first search for CSPs with single-variable assignments is called backtracking search
 - Backtracking search is the basic uninformed algorithm for CSPs

Backtracking Example



Improving Backtracking

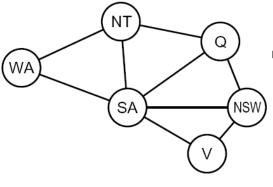
- Really important how to choose the next variable
 - Minimum Remaining Values (MRV) heuristic
 - Degree heuristic(involved in most constraints)
 - Least-constraining-value heuristic

- Propagating information through constraints
 - Forward Checking
 - Arc consistency

Minimum Remaining Values Heuristic

- Minimum remaining values (MRV):
 - Choose the variable with the fewest legal left values in its domain

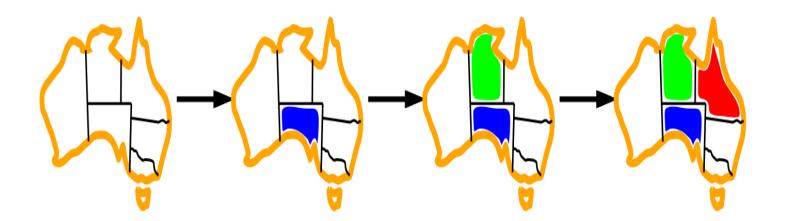


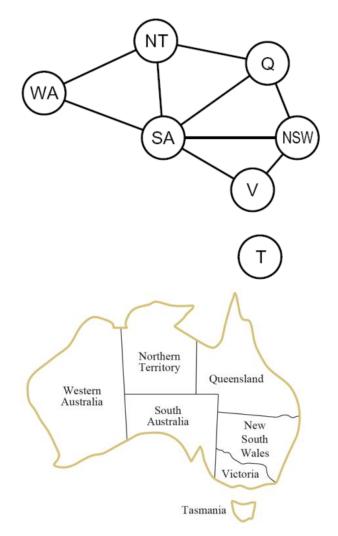


Degree heuristic

Degree heuristic:

 choose the variable that is involved in the largest number of constraints on other unassigned variables



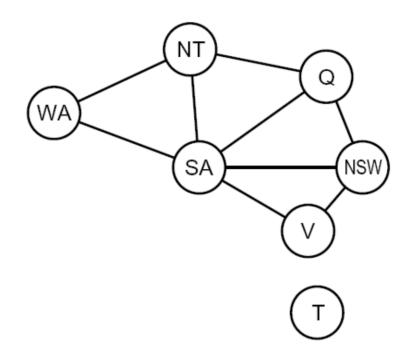


Least-constraining-value (LCV) heuristic

 Given a choice variable, choose the least constraining value i.e., the one that rules out the fewest values in the remaining variables

Example:

- The partial assignment with WA =Red and NT= green and that our next choice is for Q.
- Blue would be a bad choice because it eliminates the last legal value left for Q's neighbour, SA.
- The least-constraining value heuristic therefore prefers red to blue.

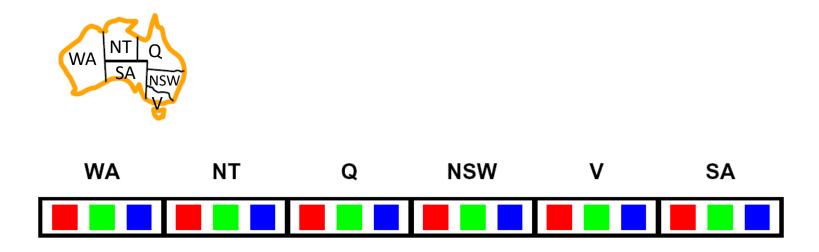


Propagating information through constraints

- Forward Checking
- Arc consistency

Forward Checking

- Idea: Keep track of remaining legal values for unassigned variables.
- Terminate search when any variable has no legal values



Forward Checking

 Forward checking propagates information from assigned to unassigned variables, but doesn't provide early detection for all failures:



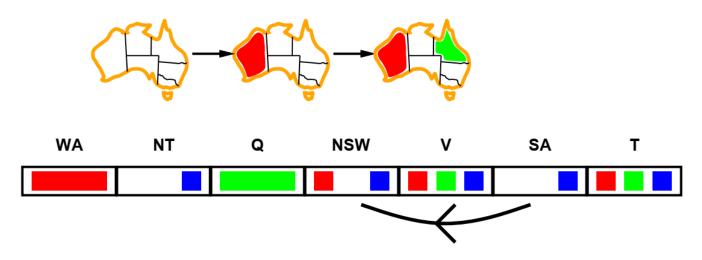


NT and SA cannot both be blue!

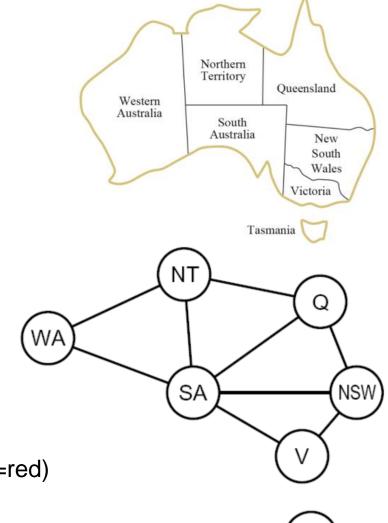
Arc consistency

- Simplest form of propagation makes each arc consistent
 - $X \rightarrow Y$ is consistent iff

for every value x of X there is some allowed y



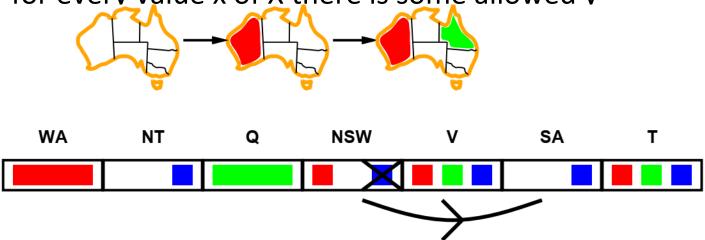
The current domain of SA and NSW are {blue} and {red, blue}. For SA=blue, there is a consistent assignment for NSW (i.e., NSW=red) Therefore, arc from SA to NSW is consistent.

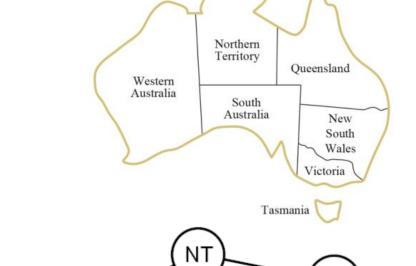


Arc consistency

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SA

- The reverse arc from NSW to SA is not consistent: for NSW ={blue}, there is no consistent assignment for SA.
- The arc can me made consistent by deleting the value blue from the domain of NSW
- Arc consistency detects failure earlier than forward checking



AC -3 Algorithm

- The most popular algorithm for enforcing arc consistency is called AC-3.
- To make every variable arc-consistent, the AC-3 algorithm maintains a queue of arcs to consider.
 - Initially, the queue contains all the arcs in the CSP.
 - Each binary constraint becomes two arcs, one in each direction
- If revised down to nothing, then we know the whole CSP has no consistent solution, and AC-3 can immediately return failure.
- Otherwise, we keep checking, trying to remove values from the domains of variables until no more arcs are in the queue.
 - At that point, we are left with a CSP that is equivalent to the original CSP—they both have the same solutions—but the arc-consistent CSP will be faster to search because its variables have smaller domains.

AC -3 Algorithm

```
function AC-3(csp) returns false if an inconsistency is found and true otherwise
  queue \leftarrow a queue of arcs, initially all the arcs in csp
  while queue is not empty do
     (X_i, X_j) \leftarrow POP(queue)
     if REVISE(csp, X_i, X_j) then
        if size of D_i = 0 then return false
        for each X_k in X_i. NEIGHBORS - \{X_j\} do
          add (X_k, X_i) to queue
  return true
function REVISE(csp, X_i, X_j) returns true iff we revise the domain of X_i
  revised \leftarrow false
  for each x in D_i do
     if no value y in D_i allows (x,y) to satisfy the constraint between X_i and X_i then
        delete x from D_i
        revised \leftarrow true
  return revised
```