Before we start

- Reminder: Fill out partner evaluations for all Projects
- Remember to sign up for demonstrations of Project 1
 - Essential for getting a grade for this project!
- In IA:-
 - Tools > Demonstration Scheduling
 - Select an entry marked "OPEN" at a mutually convenient time

Before we start (continued)

...

Project 2 checkpoint is SUNDAY, January 28, at 11:59 PM

- Don't delay
 - No room in calendar for extensions

Questions?

Application Design in a Concurrent World

Professor Hugh C. Lauer CS-3013 — Operating Systems

(Slides include copyright materials from *Operating Systems: Three Easy Step*, by Remzi and Andrea Arpaci-Dusseau, from *Modern Operating Systems*, by Andrew S. Tanenbaum, 3rd edition, and from other sources)

Reading Assignment

Lampson, B.W., and Redell, D. D., "Experience with Processes and Monitors in Mesa," Communications of ACM, vol. 23, pp. 105-117, Feb. 1980. (.pdf)

OSTEP, Part II (§25-34)

- A broad view of concurrency, locks, monitors, and condition variable
- Some of their uses
- Different order from traditional textbooks

Challenge

In a modern world with many processors, how should multi-threaded applications be designed?

Not in OS textbooks

- Focus on process and synchronization mechanisms
- Not on so much how they are used
- Hardly at all about how they should be used!
- See OSTEP, §25-34

Reference

- Kleiman, Shah, and Smaalders, Programming with Threads,
 SunSoft Press (Prentice Hall), 1996
- Out of print!

Three traditional models (plus one new one)

- Data parallelism
- Task parallelism
- Pipelining

■ Google-style massive parallelism

Other Applications

- Some concurrent applications don't fit any of these models
- Some may fit more than one model at the same time.
 - E.g., Microsoft Word

Three traditional models (plus one new one)

- Data parallelism
- Task parallelism
- Pipelining

Google-style massive parallelism

Data Parallel Applications

Single problem with large data

Matrices, arrays, etc.

Divide up the data into subsets

- E.g., Divide a big matrix into quadrants or sub-matrices
- Generally in an orderly way

Assign separate thread (or process) to each subset

- Threads execute same program
- E.g., matrix operation on separate quadrant
- Separate coordination & synchronization required



Data Parallelism (continued)

■ Imagine multiplying two n × n matrices

- Result is n² elements
- Each element is n-member dot product —
 i.e., n multiply-and-add operations
- Total n³ operations (multiplications and additions)
- If $n = 10^5$, matrix multiply takes 10^{15} operations (i.e., ½ week on a 3 GHz Pentium!)

Matrix Multiply (continued)

$\int A_{1,1}$	$A_{1,2}$	$A_{1,3}$	$A_{1,4}^{-}$		$igl[B_{1,1}igr]$	$B_{1,2}$	$B_{1,3}$	$B_{1,4}$
						$B_{2,2}$		
$A_{3,1}$	$A_{3.2}$	$A_{3,3}$	$A_{3,4}$	^	$B_{3,1}$	$B_{3.2}$	$B_{3,3}$	$B_{3,4}$
$A_{4,1}$	$A_{4,2}$	$A_{4,3}$	$A_{4,4}$		$oxedsymbol{B}_{4,1}$	$B_{4,2}$	$B_{4,3}$	$B_{4,4}$

Matrix Multiply (continued)

$$\begin{bmatrix} A_{1,1} & A_{1,2} & A_{1,3} & A_{1,4} \\ A_{2,1} & A_{2,2} & A_{2,3} & A_{2,4} \\ A_{3,1} & A_{3,2} & A_{3,3} & A_{3,4} \\ A_{4,1} & A_{4,2} & A_{4,3} & A_{4,4} \end{bmatrix} \times \begin{bmatrix} B_{1,1} & B_{1,2} & B_{1,3} & B_{1,4} \\ B_{2,1} & B_{2,2} & B_{2,3} & B_{2,4} \\ B_{3,1} & B_{3,2} & B_{3,3} & B_{3,4} \\ B_{4,1} & B_{4,2} & B_{4,3} & B_{4,4} \end{bmatrix}$$

- Multiply 4 sub-matrices in parallel (4 threads)
 - UL×UL, UR×LL, LL×UR, LR×LR
- Multiply 4 other sub-matrices together (4 threads)
 - UL×UR, UR×LR, LL×UL, LR×LL
- Add results together



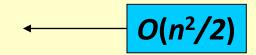
Observation

- Multiplication of sub-matrices can be done in parallel in separate threads
 - No data conflict
- Results must be added together after all four multiplications are finished.
 - Somewhat parallelizable
 - Only $O(n^2/2)$ additions

Matrix Multiply (continued)

$$\begin{bmatrix} A_{1,1} & A_{1,2} & A_{1,3} & A_{1,4} \\ A_{2,1} & A_{2,2} & A_{2,3} & A_{2,4} \\ A_{3,1} & A_{3,2} & A_{3,3} & A_{3,4} \\ A_{4,1} & A_{4,2} & A_{4,3} & A_{4,4} \end{bmatrix} \times \begin{bmatrix} B_{1,1} & B_{1,2} & B_{1,3} & B_{1,4} \\ B_{2,1} & B_{2,2} & B_{2,3} & B_{2,4} \\ B_{3,1} & B_{3,2} & B_{3,3} & B_{3,4} \\ B_{4,1} & B_{4,2} & B_{4,3} \end{bmatrix}$$

- Multiply 4 sub-matrices in parallel (4 thread olin 2)
 - UL×UL, UR×LL, LL×UR, LR×LR
- Multiply 4 other sub-matrices together (4 threads)
 - UL×UR, UR×LR, LL×UL, LR×LL
- Add results together





Amdahl's Law

- Let *P* be ratio of time in parallelizable portion of algorithm to total time of algorithm
- I.e.,

$$P = \frac{Exec \ time \ of \ parallelizable \ part}{Total \ execution \ time}$$

Amdahl's Law (continued)

If T_s is execution time in serial environmental then

$$T_P = T_S \times \left((1 - P) + \frac{P}{N} \right)$$

is execution time on N processors

• I.e., speedup factor is

$$S = \frac{T_S}{T_P} = \frac{1}{(1-P) + \frac{P}{N}}$$
 Diminishing returns in N

More on Data Parallelism

Primary focus – big number crunching

 Weather forecasting, weapons simulations, gene modeling, drug discovery, finite element analysis, etc.

Typical synchronization primitive – barrier synchronization

I.e., wait until all threads reach a common point

Many tools and techniques

- E.g., OpenMP a set of tools for parallelizing loops based on compiler directives
- See <u>www.openmp.org</u>



Definition — Barrier Synchronization

- A synchronization mechanism in which each thread waits at a barrier until all n have arrived.
- pthread_barrier_init
- pthread barrier wait
- **...**
- A fundamental tool in data parallelism

Questions?

Three traditional models (plus one new one)

- Data parallelism
- Task parallelism
- Pipelining

Google-style massive parallelism

Task Parallel Applications

Many independent tasks

- Usually very small
- E.g., airline reservation request

Shared database or resource

E.g., the common airline reservation database

Each task assigned to separate thread

- No direct interaction among tasks (or very little!)
- Tasks share access to common data objects

Task Parallelism (continued)

- Each task is small, independent
 - Too small for parallelization within itself
 - Great opportunity to parallelize separate tasks
- Challenge access to common resources
 - Access to independent objects in parallel
 - Serialize accesses to shared objects
- A "mega" critical section problem

Semaphores and Task Parallelism

Semaphores can theoretically solve critical section issues of many parallel tasks with a lot of parallel data ...

■ BUT:

- No direct relationship to the data being controlled
- Very difficult to use correctly; easily misused
 - Global variables
 - Proper usage requires superhuman attention to detail

Need another approach

Preferably one with programming language support

Solution – *Monitors*

- Programming language construct that supports controlled access to shared data
 - Compiler adds synchronization automatically
 - Enforced at runtime
- Encapsulates
 - Shared data structures
 - Procedures/functions that operate on the data
 - Synchronization between threads calling those procedures
- Only one thread active inside a monitor at any instant
 - All functions are part of one critical section

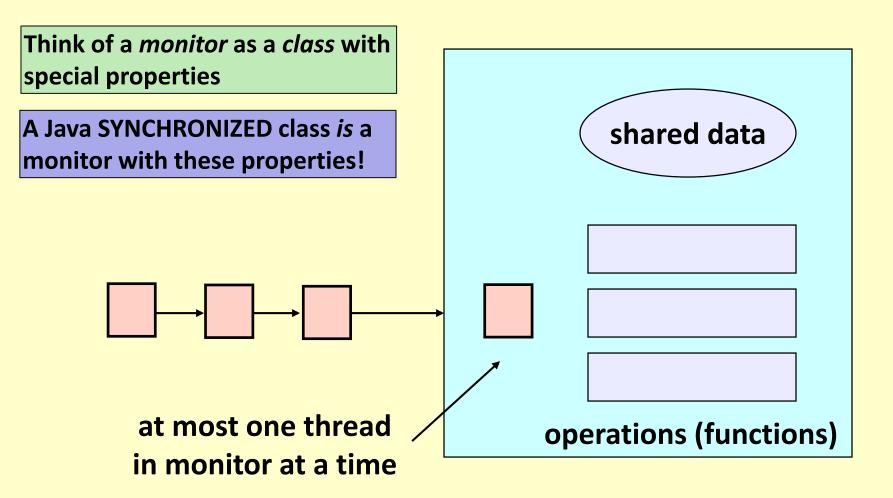
Hoare, C.A.R., "Monitors: An Operating System Structuring Concept," *Communications of ACM*, vol. 17, pp. 549-557, Oct. 1974 (<a href="https://px.ncbi.nlm.n

Monitors

High-level synchronization allowing safe sharing of an abstract data type among concurrent threads.

```
monitor monitor-name
{
    monitor data declarations (shared among
       functions)
    function body F1 (...) {
    function body F2 (...) {
    function body Fn (...) {
       initialization & finalization code
```

Monitors



Synchronization with Monitors

Mutual exclusion

Essentially a semaphore with values limited to zero and one

- Each monitor has a built-in mutual exclusion lock
- Only one thread can be executing inside at any time
- If another thread tries to enter a monitor procedure, it blocks until the first relinquishes the monitor
- Once inside a monitor, thread may discover it is not able to continue
 - Due to some condition or external event that must happen
- condition variables provided within monitor

Does not resemble a semaphore at all!

- Threads can wait for something to happen i.e., an Event!
- Threads can signal others that something has happened
- Condition variable can only be accessed from inside monitor.
- wait'ing thread relinquishes monitor lock temporaril

Cannot even be implemented with semaphores!

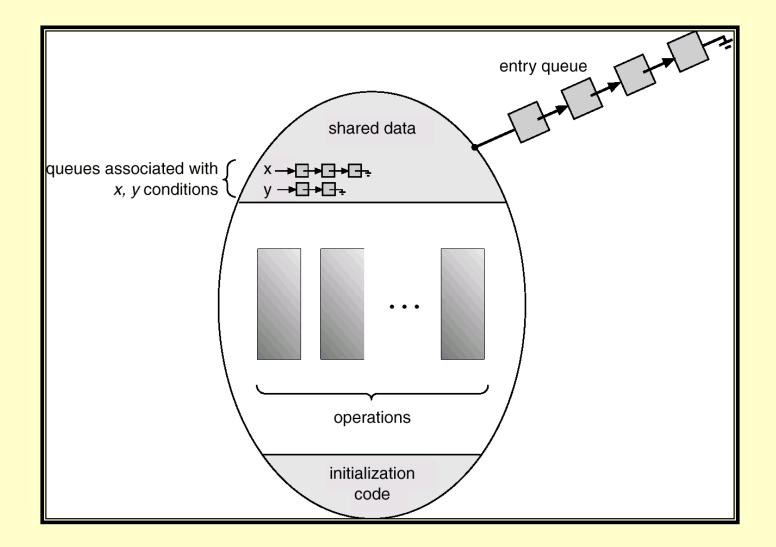
Waiting within a Monitor

■ To allow a thread to wait within the monitor, a condition variable must be declared, as

```
condition x;
```

- Condition variable a queue of waiting threads inside the monitor
- Can only be used with the operations wait and signal
 - Operation wait(x) means that thread invoking this operation is suspended until another thread invokes signal(x)
 - The signal operation resumes exactly one suspended thread. If no thread is suspended, then the signal operation has no effect.

Monitors – Condition Variables



wait and signal (continued)

The thread invoking wait automatically relinquishes monitor lock to allow other threads in.

- When a thread invokes signal, any resumed thread must reacquire monitor lock before proceeding
 - Program counter is still inside the monitor
 - Resumed thread cannot proceed until it actually acquires the monitor lock

Signal Semantics

- signal(c) means
 - Waiting thread is made ready, but signaler continues
 - Waiting thread competes for monitor lock whenever signaler leaves monitor or executes wait itself
 - condition not necessarily true when waiting thread runs again
 - being signaled is only a hint of something changed
 - must recheck conditional case

pthread_cond_signal and Java Notify() method use these semantics!

Called Mesa Semantics in OSTEP

Monitor Example*

```
monitor FIFOMessageQueue {
                                      /* function implementations */
 struct qItem {
                                      FIFOMessageQueue(void) {
    struct qItem *next,*prev;
                                      /* constructor*/
   msg t msg;
                                        head = tail = NULL;
  };
                                      };
 /* internal data of queue*/
                                      void addMsg(msg t newMsg) {
struct altem *head *tail.
  conditi Only one thread allowed
                                      qItem *new = malloc(qItem);
 /* fun inside monitor at a time!
                                        new \rightarrow prev = tail;
                                        new \rightarrow next = NULL;
void addMsg(msg t newMsg);
                                        if (tail==NULL) head = new;
  msg t removeMsg(void);
                                        else tail\rightarrownext = new;
/* constructor/destructor */
                                      tail = new;
Let any waiting threads know that
                                      signal nonEmpty;
 message queue is non-empty!
                                      };
```

^{*} Adapted from Kleiman, Shah, and Smaalders

Monitor Example (continued)

```
/* function implementations
                                         /* function implementations
        continued*/
                                             concluded*/
msq t removeMsg(void) {
                                    Even after returning from wait,
 while (head == NULL)
                                    we are not 100% sure queue
    wait(nonEmpty);
                                    non-empty — Why?
  struct gItem *old = head;
                                                                      ead:
                                             head = top \rightarrow next;
  if (old \rightarrow next == NULL)
                                             free (top);
    tail = NULL; /*last
  element*/
                                         };
  else
    old→next→prev = NULL;
                                         /* what is missing here? */
  head = old \rightarrow next;
                                         /* answer:- need to unblock
                                         waiting threads in destructor!
  msg t msg = old \rightarrow msg;
                                         */
  free (old);
  return (msq);
};
```

Invariants

Monitors lend themselves naturally to programming invariants

- I.e., logical statements or assertions about what is true when no thread holds the monitor lock
- Similar to loop invariant in sequential programming
- All monitor operations must preserve invariants
- All functions must restore invariants before waiting

Easier to explain & document

Especially during code reviews with co-workers

Invariants of Example

- Element are stored in order of arrival!
- head points to first element
 - or NULL if no elements
- tail points to last element
 - or NULL if no elements)
- Each element except head has a non-null prev
 - Points to element insert just prior to this one
- Each element except tail has a non-null next
 - Points to element insert just after to this one
- head has a null prev; tail has a null next

Personal Experience

- During design of *Pilot* operating system ...
- Prior to introduction of monitors, it took an advanced degree in CS and a lot of work to design and debug critical sections
- Afterward, a new team member with BS and ordinary programming skills could design and debug monitor as first project
 - And get it right the first time!

Modern world

- More advanced techniques available and appropriate
- Many monitor implementations involve system calls
 - Expensive in time and performance!
- Wait-free implementations for simple shared data structures
 - Java
- Comprehensive text on theory and practice:—

The Art of Multiprocessor Programming, by Maurice Herlihy & Nir Shavit, Morgan Kaufman, 2012

Monitors – Summary

- Much easier to use than semaphores
 - Especially to get it right
 - Helps to have language support
- Available in Java SYNCHRONIZED CLASS
- Can be simulated in C or C++ using
 - pthreads, conditions, mutexes, etc.
- Highly adaptable to object-oriented programming
 - Each separate object can be its own monitor!
- Monitors may have their own threads inside!

Monitors in C

- Must be programmed in "long-hand"
 - No language support!
- Monitor data implemented as a struct
 - Include one pthread_mutex_t object
 - I.e., the "monitor lock"
 - One or more pthread_cond_t objects
 - I.e., the condition variables (representing events or conditions to wait for)

■ Many implementations available in C++

Monitors in C or C++ (continued)

Initialization & destruction of mutexes:—

```
    pthread_mutex_init(lock) /*dynamic*/
    pthread_mutex_t lock = /*static*/
        PTHREAD_MUTEX_INITIALIZER;
    pthread mutex destroy(lock)
```

Conditions variables:—

```
pthread_cond_init(event) /*dynamic*/
pthread_cont_t event = /*static*/
PTHREAD_COND_INITIALIZER;
pthread cond destroy(event)
```

Monitors in C or C++ (continued)

- For protecting monitor data, every function must be surrounded by:
 - pthread_mutex_lock(lock) or pthread_mutex_trylock(lock)
 - pthread_mutex_unlock(lock)

Only the thread holding the lock can unlock it

- For conditions and events:
 - pthread_cond_wait(event, lock)
 - Same here!
 - pthread cond signal (event)
 - pthread cond broadcast(event)

Monitors – References

OSTEP, Part II (§25-34)

See also

- Lampson, B.W., and Redell, D. D., "Experience with Processes and Monitors in Mesa," *Communications of ACM*, vol. 23, pp. 105-117, Feb. 1980. (<u>.pdf</u>)
- Redell, D. D. et al. "Pilot: An Operating System for a Personal Computer," Communications of ACM, vol. 23, pp. 81-91, Feb. 1980. (.pdf)

■ We will use or simulate monitors in Project 3

Message-oriented Design (Another variant of Task Parallelism)

- Shared resources managed by separate processes
 - Typically in separate address spaces
- Independent task threads send messages requesting service
 - Task state encoded in message and responses
- Manager does work and sends reply messages to tasks
- Synchronization & critical sections
 - Inherent in message queues and process main loop
 - Explicit queues for internal waiting

Message-Oriented Design (continued)

- Message-oriented and monitor-based designs are equivalent!
 - Including structure of source code
 - Performance
 - Parallelizability
 - Shades of Remote Procedure Call (RPC)!
 - However, not so amenable to object-oriented design

See

Lauer, H.C. and Needham, R.M., "On the Duality of Operating System Structures," Operating Systems Review, vol 13, #2, April 1979, pp. 3-19. (.pdf)

Questions?

Three traditional models (plus one new one)

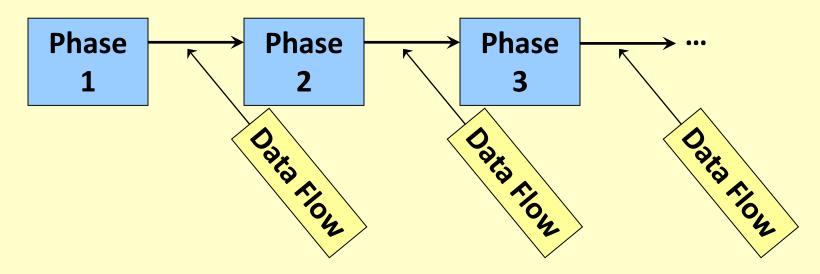
- Data parallelism
- Task parallelism
- Pipelining

Google-style massive parallelism

Pipelined Applications

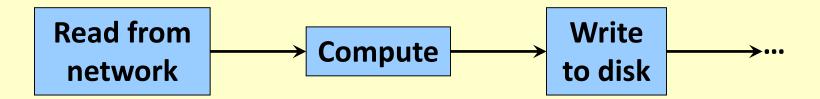
- Application can be partitioned into phases
 - Output of each phase is input to next
- Separate threads or processes assigned to separate phases
 - Data flows through phases from start to finish, pipeline style
- Buffering and synchronization needed to
 - Keep phases from getting ahead of adjacent phases
 - Keep buffers from overflowing or underflowing

Pipelined Parallelism



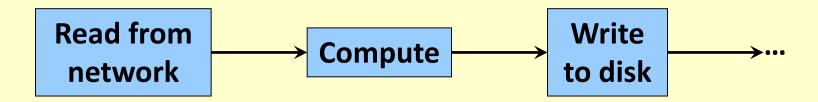
- Assume phases do not share resources
 - Except data flow between them
- Phases can execute in separate threads in parallel
 - I.e., Phase 1 works on item i, which Phase 2 works on item i-1, while Phase 3 works on item i-2, etc.

Example



- Reading from network involves long waits for each item
- Computing is non-trivial
- Writing to disk involves waiting for disk arm, rotational delay, etc.

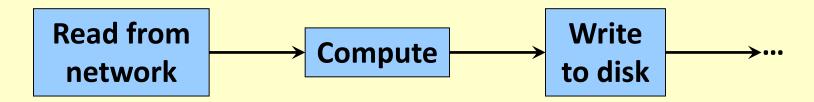
Example Time Line



Single threaded

Jingle tilledded									
	wait and read	compute	write and wait	wait and read	compute	write and wait	•••		

Example Time Line



Single threaded

om grown outside							
wait and read	compute	write and wait	wait and read	compute	write and wait	•••	

Multi-threaded pipeline

wait and read	wait and read		wait and read		wait and read			•••
	compute		compute		compute		compute	
		write	e and wait write		and wait write		and wait	write and wait



Example

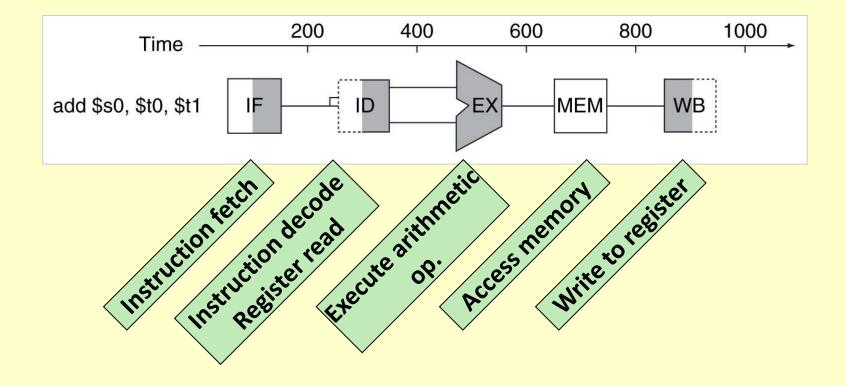
- Unix/Linux/Windows pipes
 - read xx | compute yy | write zz
- Execute in separate processes
 - Data flow passed between them via OS pipe abstraction
 - I.e., stdout of one process becomes stdin of next process

Another Example

PowerPoint presentations

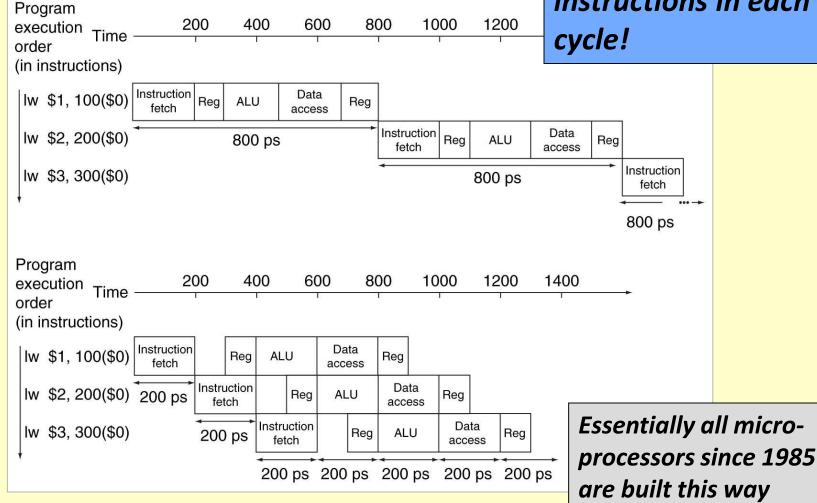
- One thread manages display of current slide
- A separate thread "reads ahead" and formats the next slide
- Instantaneous progression from one slide to the next

Third Example – Pipelined Processor



Pipelined Processor (continued)

Modern processors have 12-30 pipeline stages and issue 4+ instructions in each cycle!



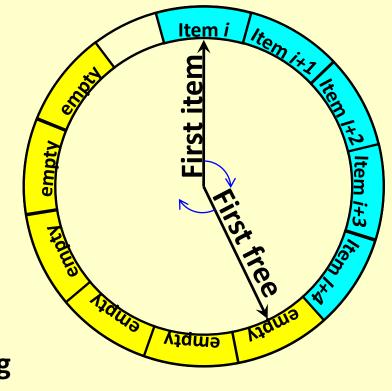
Producer-Consumer

- Fundamental synchronization mechanism for decoupling the flow between parallel phases
- One of the few areas where semaphores are natural tool

Definition — *Producer-Consumer*

- A method by which one process or thread communicates an unbounded stream of data through a finite buffer to another.
- Buffer:— a temporary storage area for data
 - Esp. an area by which two processes (or computational activities) at different speeds can be decoupled from each other

Example – Ring Buffer



Consumer empties items, starting with first full item

Producer fills items, starting with first free slot

Implementation with Semaphores

```
struct Item { ...
};
Item buffer[n];
semaphore empty = n, full = 0;
```

Producer:-

```
int j = 0;
  while (true) {
      wait_s(empty);
      produce(buffer[j]);
      post_s(full);
      j = (j+1) mod n;
}
```

Consumer:-

```
int k = 0;
  while (true) {
     wait_s(full);
     consume(buffer[k]);
     post_s(empty);
        k = (k+1) mod n;
}
```

Implementation with Semaphores

```
struct Item { ...
};
Item buffer[n];
semaphore empty = n, full = 0;
```

Producer:-

```
int j = 0;
while (true) {
    wait_s(empty);
    produce(buffer[j]);
    post_s(full);
    j = (j+1) mod n;
}
```

Consumer:-

```
int k = 0;
while (true) {
    wait_s(full);
    consume(buffer[k]);
    post_s(empty);
    k = (k+1) mod n;
}
```

Note: critical section may be needed to protect buffer!

Real-world example — I/O overlapped with computing

Producer: the input-reading process

- Reads data as fast as device allows
- Waits for physical device to transmit records
- Unblocks and stores data into ring buffer, one record per slot

Consumer

- Computes on each record in turn
- Is freed from the details of waiting and unblocking physical input

Double Buffering

- A *producer-consumer* application with *n=2*
- Widely used for many years
- Most modern operating systems provide this in I/O and file read and write functions

Summary: Producer-Consumer

- Occurs frequently throughout computing
- Needed for decoupling the timing of two activities
- Especially useful in Pipelined parallelism
- Uses whatever synchronization mechanism is available

Questions?

A final note (for all three models)

- Multi-threaded applications require thread safe libraries
 - I.e., so that system library functions may be called concurrently from multiple threads at the same time
 - E.g., malloc(), free() for allocating from heap and returning storage to heap
- Most modern Linux & Windows libraries are thread safe

Thread-safe Libraries

- May implemented as monitors
 - Using pthread_mutex, pthread_cond
- Only one thread in "module" at a time
 - File writes or reads
 - **-** ...
- Some may be implemented by wait-free operations
 - malloc(), free()

Questions?

Three traditional models (plus one new one)

- Data parallelism
- Task parallelism
- Pipelining

Google-style massive parallelism

Google & Massive Parallelism

- Exciting topic of research in recent years
- 1000s, 10000s, or more threads/processes
- Primary function *Map/Reduce*
 - Dispatches 1000s of tasks that search on multiple machines in parallel
 - Collects results together
- Topic for another time/course

Reading Assignment

- OSTEP, Part II (§25-34)
 - More than you can read in one sitting ...
 - ... or even in one week!
- Lampson, B.W., and Redell, D. D., "Experience with Processes and Monitors in Mesa," Communications of ACM, vol. 23, pp. 105-117, Feb. 1980.

http://www.cs.wpi.edu/~cs3013/c14/Papers/LampsonRedell_Monitors.pdf

Questions?