# Digital Signal Processing

## Mannem Charan AI21BTECH11019

### **CONTENTS**

Abstract—This document provides the solution of Assignment 1.

# Question 3.6.e: Determine

- 1) the inverse z-transform using both the methodspartial fraction expansion and power series expansion. In addition, indicate whether the Fourier transform exists or not.
- 2) And then consider the result from inverse ztransform as the impulse response of the a system (h(n)), check whether that system is causal or not and stable or not.

$$X(z) = \frac{1 - az^{-1}}{z^{-1} - a}, \ |z| > \left| \frac{1}{a} \right| \tag{1}$$

**Solution:** Given z-transform of a signal x(n) as,

$$X(z) = \frac{1 - az^{-1}}{z^{-1} - a}, \ |z| > \left| \frac{1}{a} \right|$$
 (2)

- 1) Now to find inverse z-transform of eq (2), we will use following two methods,
  - a) Using partial fractions
  - b) Using power series expansion

# Using partial fractions:

$$X(z) = \frac{1 - az^{-1}}{z^{-1} - a}, \ |z| > \left| \frac{1}{a} \right|$$
 (3)

$$=\frac{z^1(z-a)}{z^1(1-az^1)}$$
 (4)

From the region of convergence i.e., ROC x(n)is a right-sided sequence and since M = N = 1and pole is first order, we can write X(z) as,

$$X(z) = b_0 + \frac{A_1}{1 - rz^{-1}} \tag{5}$$

Now

$$X(z) = \frac{1 - az^{-1}}{-a\left(1 - \frac{z^{-1}}{a}\right)} \tag{6}$$

Comparing eqs (5) and (6), we will get  $r = \frac{1}{a}$ , and

$$b_0 r = -1 \tag{7}$$

$$\implies b_0 = -a \text{ and } (8)$$

$$b_0 + A_1 = \frac{-1}{a} \tag{9}$$

$$\implies A_1 = \frac{-1}{a} + a \tag{10}$$

So X(z) will be,

$$X(z) = -a - \frac{\frac{1}{a} - a}{1 - \frac{z^{-1}}{a}} \tag{11}$$

Since ROC  $|z| > \left| \frac{1}{a} \right|$ ,

$$-a \stackrel{\mathcal{Z}}{\rightleftharpoons} -a\delta(n) \tag{12}$$

$$\frac{\frac{1}{a} - a}{1 - \frac{z^{-1}}{a}} \stackrel{\mathcal{Z}}{\rightleftharpoons} \left(\frac{1}{a} - a\right) \left(\frac{1}{a}\right)^n u(n) \tag{13}$$

(14)

From the linearity of z-transform,

$$x(n) = -a\delta(n) - (1 - a^2)a^{-(n+1)}u(n)$$
 (15)

Using power series expansion Here we will try to find the power series itself which results in z-transform. And compare it with the below expression to get x(n),

$$X(z) = \sum_{n=-\infty}^{\infty} x(n)z^{-n}$$
 (16)

We will do that using long division method,
$$z^{-1} - a = \frac{-\frac{1}{a} - \frac{1}{a} (\frac{1}{a} - a) z^{-1} - \frac{1}{a^2} (\frac{1}{a} - a) z^{-2} \dots}{1 - a z^{-1}}$$

$$\frac{1 - \frac{z^{-1}}{a}}{\frac{z^{-1}}{a} - a z^{-1}}$$

$$\frac{(\frac{1}{a} - a) z^{-1} - \frac{1}{a} (\frac{1}{a} - a) z^{-2}}{\frac{1}{a} (\frac{1}{a} - a) z^{-2}}$$

The power series will be

$$X(z) = -\frac{1}{a} + -\left(\frac{1}{a} - a\right) \sum_{n=1}^{\infty} \left(\frac{1}{a}\right)^n z^{-n}$$
 (17)

Comparing with (16),

$$x(n) = -a\delta(n) - \left(\frac{1}{a} - a\right)\left(\frac{1}{a}\right)^n u(n)$$
 (18)

$$= -a\delta(n) - (1 - a^2)a^{-(n+1)}u(n)$$
 (19)

And for x(n), fourier transform exists when ROC contains the unit circle (|z| = 1),this will happen when

$$\left|\frac{1}{a}\right| < 1\tag{20}$$

$$\implies |a| > 1$$
 (21)

 $\therefore$  For |a| > 1, given signal x(n) has Fourier transform.

2) Consider a system whose impulse response is given by,

$$h(n) = -a\delta(n) - (1 - a^2)a^{-(n+1)}u(n)$$
 (22)

We can say that the system is stable when,

$$\sum_{n=-\infty}^{\infty} h(n) < \infty \tag{23}$$

It is possible when ROC contains the unit circle,

$$\left|\frac{1}{a}\right| < 1\tag{24}$$

$$|a| > 1 \tag{25}$$

 $\therefore$  The system is stable if |a| > 1.

To check whether the system is causal or not we need to check whether the ROC for H(z) is outside the outermost pole. Since the ROC here is,

$$|z| > \left| \frac{1}{a} \right| \tag{26}$$

It is clearly outside the outer most pole  $(|z| = \frac{1}{a})$ . Hence the given system is causal.