

Purpose: Make the robot scan the entire area, and find the correct block

Steps:

1. Place the robot on the starting place.
2. Robot moves two inches from the starting point
3. Robot rotates 90 degrees clockwise and move towards one side of the arena
4. Scan every block on the side
5. Robot rotates towards second side
6. Robot scans every block in the second side
7. Robot rotates towards the third side
8. Robot scans every block in the third side
9. Robot reports that it has found the specified block

