



MA2x5x FLIC Camera Application Note

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Revision History

Revision	Description	Author
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Table of Contents

1 Introduction5

1.1 Related documents and resources5

1.2 Abbreviations5

2 FLIC Camera Application6

2.1 Constructing a Camera Application with FLIC7

2.2 Common Types used in Plugins9

3 Building & Running the Camera Application on MV021211

3.1 Dependencies11

3.2 Building & Running the Camera Application11

1 Introduction

This application note describes how to build a basic streaming camera application using the FLIC framework.

This application processes raw pixel data is captured from the IMX208 sensor and processed line-by-line through the SIPP Image Signal Processing (ISP) engine, the processed YUV is then sent over a UVC class USB3 interface. The resulting YUV stream can be viewed on Linux using standard USB UVC class viewers such a cheese or guvcview.

1.1 Related documents and resources

Related MDK documentation can be obtained from <http://www.movidius.org>. If you do not have access to the documents below, you can request them. Relevant documents include:

1. Movidius MDK release (download from www.movidius.org).
2. FLIC Programmers Guide and API.
3. MA2x5x SIPP User Guide.

1.2 Abbreviations

Term	Definition
3A	Auto-White-Balance, Auto-Exposure, and Auto-Focus.
HDMI	High Definition TV interface.
ISP	Image Signal Processing.
UVC	USB Video Class.
YUV	Video format.

2 FLIC Camera Application

A basic streaming examples, `mdk/common/components/flic/examples/arch/ma2x5x/flic06LiveCam` has been added to demonstrate how to use the FLIC framework to create a simple single sensor, camera application. This is a basic camera as it does not have any 3A algorithms or camera control, these will be added in future releases.

NOTE: This pipeline should NOT be used for image quality evaluation. The pipeline uses a static set of parameters. There are no 3A (Auto-White-Balance, Auto-Exposure, Auto-Focus) algorithms integrated which are required to dynamically generate new parameters based on light conditions.

Raw pixel data is captured from the Sony IMX208 sensor and processed line-by-line through the SIPP Image Signal Processing (ISP) engine, and the processed YUV is then sent over HDMI interface to view on TV or HDMI capable monitor.


```

        icSourceSetup srcSet;

        OpipeReset(); // reset the SIPP ISP Opipe component

        //Create plugins
        RgnAlloc.Create(RgnBuff, DEF_POOL_SZ);
        plgIspCtrl = PlgIspCtrl::instance();
        plgIspCtrl->Create();
        plgSrc.Create(IC_SOURCE_0);
        plgSrc.outFmt = SIPP_FMT_16BIT; // Two byte per pixel
        plgIsp.Create(IC_SOURCE_0);

        if(0 == getSrcSzLimits(IC_SOURCE_0, &srcSet)) {
            icSourceSetup* srcLimits = &srcSet;
            srcLimits->maxBpp = 16;

            plgPoolSrc.Create(&RgnAlloc,
                            N_POOL_FRMS,
                            ((srcLimits->maxPixels * srcLimits->maxBpp) >> 3); //RAW

            plgPoolIsp.Create(&RgnAlloc,
                            N_POOL_FRMS,
                            (srcLimits->maxPixels * 3)>>1); //YUV420
        }
        else {
            // not define max size for initialized camera
            assert(0);
        }

        plgOut.Create();

        // add plugins to pipeline
        p.Add(plgIspCtrl);
        p.Add(&plgOut);
        p.Add(&plgSrc);
        p.Add(&plgIsp);
        p.Add(&plgPoolSrc);
        p.Add(&plgPoolIsp);

        // Link the plugins to create a path through the pipeline
        plgPoolSrc.out.Link(&plgSrc.in0);
        plgSrc.outCommand.Link(&plgIspCtrl->inCtrlResponse);
        plgIspCtrl->outSrcCommand[IC_SOURCE_0].Link(&plgSrc.inCommand);

        plgPoolIsp.out.Link(&plgIsp.in0);
        plgSrc.out.Link(&plgIsp.inI);
        plgIsp.outF.Link(&plgOut.in );
        plgIsp.outE.Link(&plgIspCtrl->inCtrlResponse);
        plgOut.outCmd.Link(&plgIspCtrl->inCtrlResponse);
        plgIspCtrl->outOutCmd.Link(&plgOut.inCmd);

        // Start the pipeline
        p.Start();
    }

```

When raw pixels arrive from the sensor, they are streamed directly into DDR from the PlgSrc plugin (the MipiRx hardware has dedicated DMA to DDR). Start-of-Frame events are generated for each new frame by

PlgSrc.

Similar, End-of-Frame events triggered by the PlgSrc are sent to PlgIsplCtrl.

A DMA transfer complete IRQ, triggers the PlgISPCtrl to create a combined message, containing the raw frame and ISP configuration parameters (typically generated by 3A algorithms).

This combined message is sent to the PlgIspl, that will convert the raw pixels to processed YUV image.

The YUV image is transferred to PlgOut plugin for transmission over HDMI.

2.2 Common Types used in Plugins

A key design consideration for pipelines designed using the FLIC framework is to agree and use common (or application level) data types in the pipeline.

For raw and processed frames typically used in Camera or Computer Vision applications processing pixel data, the FLIC has pre-defined a number of useful Types common to these type of applications. These are defined in:

- `flic/common/commonTypes/leon/FrameTypes.h`
- `flic/common/commonTypes/leon/ImgTypes.h`

```
typedef struct {
    uint32_t    w; // Width
    uint32_t    h; // Height
} ImgSize;

typedef struct {
    int32_t     x1;
    int32_t     y1;
    int32_t     x2;
    int32_t     y2;
} ImgRect; // Rectangle coordinates

// MsgBuf data description structure
typedef struct FrameS {
    ImgFrmFmt    fmt; // raw, YUV, ..
    ImgFrmType   type; //
    void *       fbPtr [IMG_MAX_PLANES];
    uint32_t     stride[IMG_MAX_PLANES];
    uint32_t     width [IMG_MAX_PLANES];
    uint32_t     height[IMG_MAX_PLANES];
    uint32_t     tSize [IMG_MAX_PLANES];
    uint32_t     nPlanes;
    uint64_t     ts      [IMG_MAX_TS];
    uint32_t     tsEvent[IMG_MAX_TS]; // app specific events associated
                                         // with timestamps

    uint32_t     tsNr;
    uint32_t     seqNo; // index for the frame
    void *       *userData; // associated app specific information
                                         // with this frame
    uint32_t     instId; // instance associated with this frame
} FrameT;
```

```
class IspInputMsg
{
public:
    icIspConfig*   ispCfg; // SIPP ISP kernel parameters
    ImgFramePtr    img;    // Input frame pointer
};

// mipiRx, receiver Configuration structure
typedef struct {
    IcMipiRxCtrlNoT    controllerNo;
    uint32_t           noLanes;
    uint32_t           laneRateMbps;
    IcMipiRxDataTypeT  dataType;
    uint32_t           dataMode;
    IcMipiRxCtrlRecNoT recNrl;
} icMipiConfig;

typedef struct {
    ImgSize           cameraOutputSize;
    ImgRect           cropWindow;

    /*
     * Bayer Format - Raw, Demosaic and LSC blocks should be
    programmed
     * to match the Bayer order specified here.
     */
    icBayerFormat     bayerFormat;
    uint32_t           bitsPerPixel;

    /* mipi RX data configuration */
    icMipiConfig       mipiRxData;
    // used just for pc run version, and contain input file name
    const char *inFileName;
} icSourceConfig;
```

3 Building & Running the Camera Application on MV0212

3.1 Dependencies

The following items are required to run the Streaming Camera Application:

1. MV0212 development kit with MV0200 camera daughter card (Sony IMX208 sensor).
2. MDK release 17.11 or later.
3. Olimex JTAG connector and USB cable.
4. PC Linux.
5. HDMI cable and HDMI capable monitor or TV.

3.2 Building & Running the Camera Application

To Build and run the application on the MV0235:

1. `cd mdk/common/components/flic/examples/arch/ma2x5x/flic06LiveCam`
2. `make clean all -j4`
3. `make debug`

To view the ISP processed YUV frames transmitted over HDMI to TV or monitor from the HDMI interface on the Myriad development board.