Leader Arm: SERVO_DRIVER_BOARD 5V— PWR GND MOTOR_CABLE DYNAMIXELXL330-M077-T DYNAMIXELXL330-M077-T DYNAMIXELXL330-M077-T DATA DATA 5V GND Plug 1 Plug 1 Plug 1 Plug 2 Plug 2 Robot Cable-X3P 180mm Plug 2 DYNAMIXELXL330-M077-T DYNAMIXELXL330-M077-T 902-0162-000 902-0162-000 902-0162-000 DYNAMIXELXL330-M077-T Plug 1 Plug 1 Connect To Computer — Plug 1 Plug 2 Plug 2 BOCTMM4LWK 902-0162-000 902-0162-000 902-0162-000 Follower Arm: VOLTAGE_REDUCER 12V GND SERVO_DRIVER_BOARD DYNAMIXELXL330-M288-T DYNAMIXELXL330-M288-T DYNAMIXELXL330-M288-T DATA V 12V G GND 12V—— PWR 5V Plug 1 Plug 1 Plug 1 Plug 1 GND EP-JY-DC5 Plug 2 Plug 2 Plug 2 Plug 2 902-0163-000 902-0163-000 902-0163-000 902-0163-000 GND MOTOR_CABLE DYNAMIXELXL430-W250-T DYNAMIXELXL430-W250-T Connect To Computer — USB Plug 1 Plug 1 Robot Cable-X3P 180mm BOCTMM4LWK Plug 2 Plug 2 902-0135-000 902-0135-000 TITLE: REV: 1.0 Alexander Koch Robot Arm Wiring Diagram V1.1 Company: Hugging Face Sheet: 1/1 **EasyEDA**

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Drawn By: Jess Moss