

# HW 6

Charles Liu

Linear Optimization - Dr. Tom Asaki

February 21st 2025

---

1. Consider the standard form polyhedron  $P = \{x \in \mathbb{R}^n \mid Ax = b, x \geq 0\}$ , and assume that the rows of matrix  $A$  are linearly independent. Prove that if two different bases correspond to the same basic solution, then this basic solution is degenerate.

**Theorem.** For the standard form polyhedron  $P = \{x \in \mathbb{R}^n \mid Ax = b, x \geq 0\}$  where  $A$  has linearly independent rows, if two different bases correspond to the same basic solution, then that basic solution is degenerate.

*Proof:*

We want to show that the basic solution is degenerate, which is equivalent to showing that at least one variable in  $x$  is zero.

Assume that we have two distinct bases  $B_1$  and  $B_2$  that produce the same basic solution,  $x$ . BWOC, assume that  $x$  has all  $(m)$  nonzero variables. This means all  $m$  variables in  $B_1$  and  $B_2$  are nonzero.

As  $B_1$  and  $B_2$  are distinct, there's at least one variable in  $B_1$  that's not in  $B_2$ .

However, this means there is  $m + 1$  nonzero variables in  $x$ , a contradiction, so  $x$  must be degenerate.

---

2. Consider nonempty polyhedron  $P \subset \mathbb{R}^n$  and suppose that for each variable  $x_i$  we have either the constraint  $x_i \geq 0$  or the constraint  $x_i \leq 0$ . Prove that  $P$  has at least one basic feasible solution.

**Theorem.** For the nonempty polyhedron  $P \subset \mathbb{R}^n$ , if we have that each variable  $x_i$  either satisfies the constraint  $x_i \geq 0$  or  $x_i \leq 0$ , then  $P$  has at least one basic feasible solution.

*Proof:*

Since  $P$  is nonempty, we can take an element  $x$  where  $x \in P$  and  $x$  is feasible. Consider a

line  $S = \{y \in \mathbb{R}^n \mid y = x + \lambda d\}$ , where  $\lambda \in \mathbb{R}$ ,  $d \neq 0$  and  $d \in \mathbb{R}^n$ .

Take some constraint in the polyhedra, where  $i = j$ . Also consider another element in  $d$  which is non-zero,  $d_j$ .

**Case 1:**  $x_j \geq 0$  and  $d_j > 0$ , then  $x_j + \lambda d_j \notin P$  when  $\lambda < -\frac{x_j}{d_j}$ .

**Case 2:**  $x_j \geq 0$  and  $d_j < 0$ , then  $x_j + \lambda d_j \notin P$  when  $\lambda > -\frac{x_j}{d_j}$ .

**Case 3:**  $x_j \leq 0$  and  $d_j > 0$ , then  $x_j + \lambda d_j \notin P$  when  $\lambda < -\frac{x_j}{d_j}$ .

**Case 4:**  $x_j \leq 0$  and  $d_j < 0$ , then  $x_j + \lambda d_j \notin P$  when  $\lambda > -\frac{x_j}{d_j}$ .

Since there can be no line in  $P$ , by [Theorem 2.6](#),  $P$  has an extreme point which by [Theorem 2.3](#) is equivalent to  $P$  having a basic feasible solution.

---