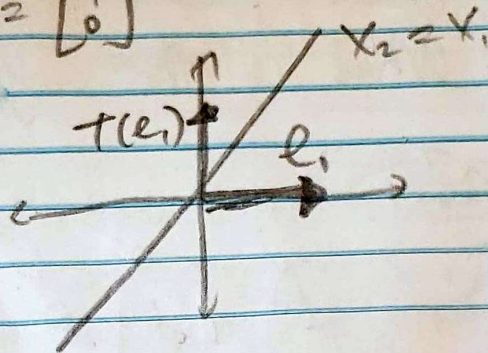


Written Homework 1.9
Charles Liu

1. Let $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ first reflect points through the horizontal x_1 -axis and then reflect points through the line $x_2 = x_1$.

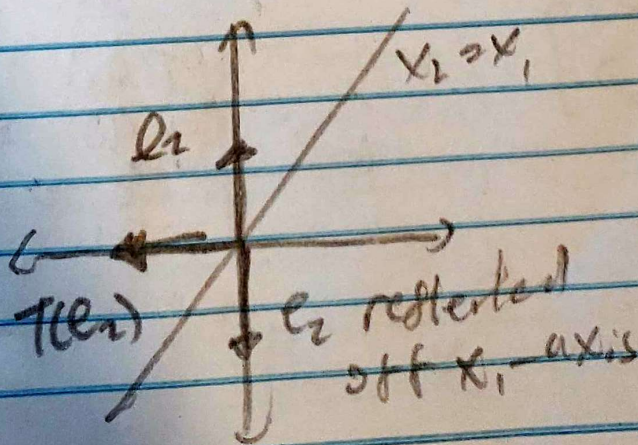
a) What is the standard matrix of T ?

$$e_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$



$$T(e_1) = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$e_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$



$$T(e_2) = \begin{bmatrix} -1 \\ 0 \end{bmatrix}$$

$$A = [T(e_1) \ T(e_2)] = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

standard matrix
of T

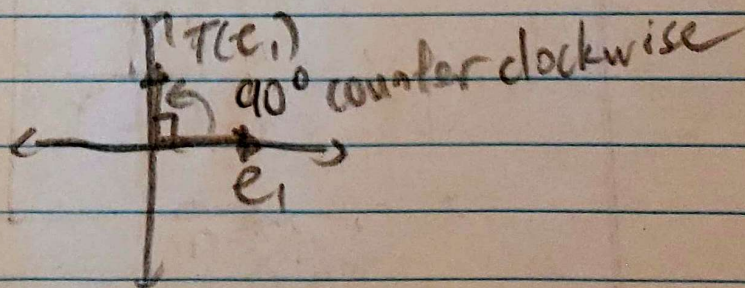
b) Show that the transformation, T ,
is merely a rotation about the
origin. What is the angle of that
rotation?

$$T(x) = Ax \quad A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

As proved before, $T(e_1) = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$,
which is a 90° (or $\frac{\pi}{2}$) rotation

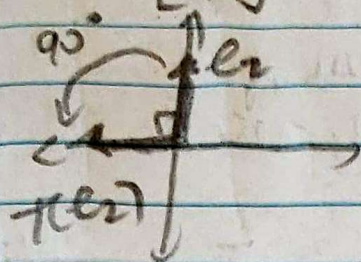
counterclockwise about the origin, of

$$e_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$



$T(e_2) = \begin{bmatrix} -1 \\ 0 \end{bmatrix}$ is also a 90° (or $\frac{\pi}{2}$) rotation counter-clockwise of

$$e_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$



Since every linear transformation of $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ $= T\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}\right)$ can be written as

$$T\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}\right) = T\left(x_1 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} 0 \\ 1 \end{bmatrix}\right)$$

$$= T(x_1 e_1 + x_2 e_2)$$

$$= \underline{x_1 T(e_1) + x_2 T(e_2)}$$

Since T is a linear transformation,
and thus x_1 and x_2 are both
rotated by the same 90° counter-clockwise
and T is merely a rotation about the origin,

The angle of that rotation is
 90° counter-clockwise.

Rotational Matrix:

$$\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

$$-\sin \theta = -1 \quad \theta = 90^\circ \checkmark$$

$$\sin \theta = 1$$

$$\cos \theta = 0$$

2. Let $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear transformation

a) If T maps \mathbb{R}^n onto \mathbb{R}^m , decide which of m and n is greater than or equal to the other. Justify your answer.

n is greater than or equal to m .

If the transformation T maps \mathbb{R}^n onto \mathbb{R}^m , then its standard matrix must have a pivot in every row, and be a $m \times n$ matrix.

If $n < m$, there will not be enough columns for the standard matrix to have a pivot in every row, so

$$n \geq m.$$

- b) If T is one-to-one, decide which of m or n is greater than or equal to the other. Justify your answer
- m is greater than or equal to n . If the transformation $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is one-to-one, the standard matrix of the transformation is an $m \times n$ matrix and has a pivot in each column.

If there is not enough rows for there to be a pivot in every column ($m < n$), then T is not one-to-one, so $m \geq n$.

c) If T is one-to-one and onto, what can you say about the relationship between m and n ?

m and n must be equal, since each row and column of the $m \times n$ matrix of the transformation T must have pivots. This means the amount of pivots = amount of pivot = amount of pivots columns = amount of rows = amount of columns = $(m = n)$