Charles Wszalek EGR 310

## **PYTHON CODE**

```
import numpy as np
import matplotlib.pyplot as plt
import scipy.optimize
from lib.Header import *
points = [[-1000, 0],
      [-137, 837],
      [725, 1349],
      [1588, 1853],
      [2451, 1969],
      [3313, 1998],
      [4176, 1820],
      [5039, 1468],
      [5901, 799],
      [6764, 0]]
[[x1, b1],
[x2, b2],
[x3, b3]] = [[725, 1349],
         [1588, 1853],
         [2451, 1969]]
xrange = np.linspace(-1000,8000,8000)
def L1(x):
  return ((x-x2) * (x-x3)) / ((x1-x2) * (x1-x3))
def L2(x):
  return ((x-x1) * (x-x3)) / ((x2-x1) * (x2-x3))
def L3(x):
  return ((x-x1) * (x-x2)) / ((x3-x1) * (x3-x2))
def ylag(x):
  return L1(x) * b1 + L2(x) * b2 + L3(x) * b3
plt.figure()
plt.plot(xrange, ylag(xrange))
plt.plot([coord[0] for coord in points], [coord[1] for coord in points], '.')
SAVE(1)
plt.show()
# scipy.optimize.curve_fit allows you to put in a fit function and adjusts parameters
def fitfn(x, a, b, c):
  return a*x**2 + b*x + c
```

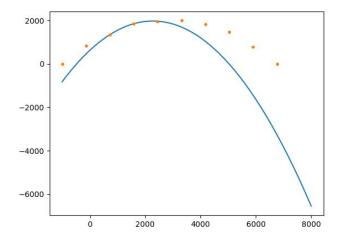
```
[[AA, BB, CC], covar] = scipy.optimize.curve_fit(fitfn, [coord[0] for coord in points], [coord[1] for coord in points], params = np.polyfit([coord[0] for coord in points], [coord[1] for coord in points], 2)

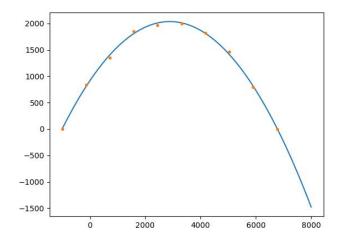
plt.figure()
# plt.plot(xrange, fitfn(xrange, AA, BB, CC))
plt.plot(xrange, np.polyval(params, xrange))
plt.plot([coord[0] for coord in points], [coord[1] for coord in points], '.')
SAVE(2)
plt.show()

PDF("Radar_Tracking.py", "Radar_Tracking.pdf")
```

## OUTPUT

## Plots





## **Prints**