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## Binary Classification:

May 14, 2021

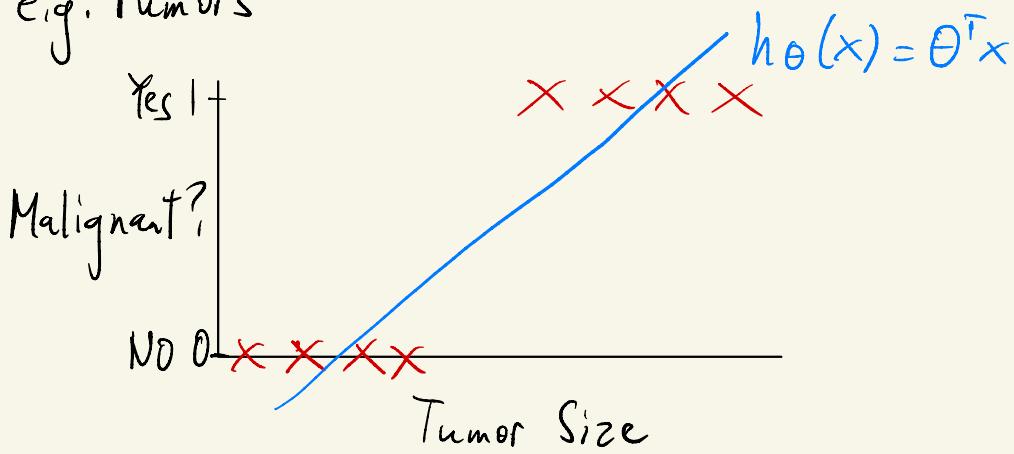
In binary classification, the predicted value  $y$  can only take on two discrete values: 0 or 1.

i.e.  $y \in \{0, 1\}$

$\rightarrow 0$  is the negative class

$\rightarrow 1$  is the positive class

e.g. Tumors

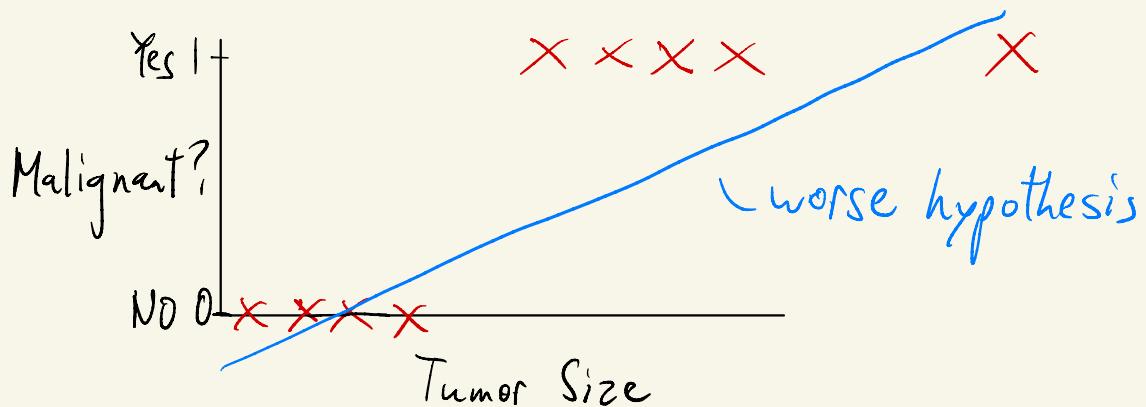


Threshold Classifier Output  $h_{\theta}(x)$  at 0.5;

$\rightarrow$  If  $h_{\theta}(x) \geq 0.5, y=1 \quad \} \text{predicted}$

$\rightarrow$  If  $h_{\theta}(x) < 0.5, y=0 \quad \} \text{predicted}$

But data can skew linear regression!



∴ Using linear regression for a classification problem usually isn't a good idea.

\* Also, if you are using linear regression, the output can be  $<0$  or  $>1$ , even if all the training examples only have 0 or 1.

↳ Hence we use the logistic regression algorithm, which makes  $h_\theta(x) \in [0, 1]$   
i.e.,  $0 \leq h_\theta(x) \leq 1$

## Logistic Regression Model:

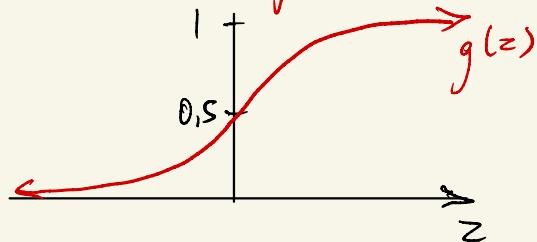
We want  $0 \leq h_\theta(x) \leq 1$ .

Let  $h_\theta(x) = g(\theta^T x) = g(z)$ , where;

$$g(z) = \frac{1}{1 + e^{-z}}$$

↳ this is the logistic function, or sigmoid function.

$$\therefore h_\theta(x) = \frac{1}{1 + e^{-\theta^T x}}$$



## Interpretation of Hypothesis Output:

$h_\theta(x)$  is the estimated probability that  $y=1$  on input  $x$ .

e.g.  $x = \begin{bmatrix} x_0 \\ x_1 \end{bmatrix} = \begin{bmatrix} 1 \\ \text{tumorSize} \end{bmatrix}$

$h_\theta(x) = 0.7$ , let's say

↳ Tumor has a 70% chance of being malignant.

$$\therefore h_{\theta}(x) = P(y=1|x; \theta)$$

↳ the probability that  $y=1$  given  $x$  parameterized by  $\theta$

e.g. If  $P(y=1|x; \theta) = 0.7$ ,

then  $P(y=0|x; \theta) = 0.3$ .

Since  $P(y=1|x; \theta) + P(y=0|x; \theta) = 1$ .

### Decision Boundary:

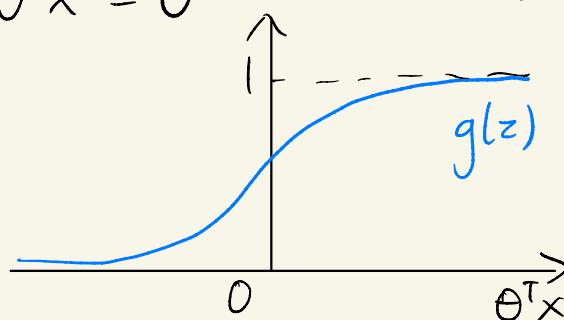
The decision boundary is the line that separates the area where  $y=0$  and  $y=1$ . It is created by  $h_{\theta}(x)$ .

e.g.

Predict  $y=1$  if  $h_{\theta}(x) \geq 0.5$  and  $y=0$  if  $h_{\theta}(x) < 0.5$ .

↳  $h_{\theta}(x) \geq 0.5$   
when  $\theta^T x \geq 0$

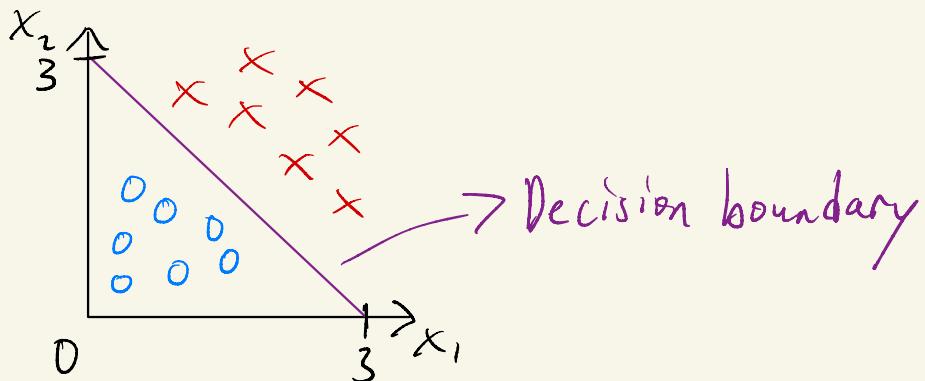
↳  $h_{\theta}(x) < 0.5$   
when  $\theta^T x < 0$



$$\text{e.g. } h_{\theta}(x) = g(\theta_0 + \theta_1 x_1 + \theta_2 x_2)$$

and let  $\theta = \begin{bmatrix} -3 \\ 1 \\ 1 \end{bmatrix} \rightarrow \begin{array}{l} \theta_0 = -3 \\ \theta_1 = 1 \\ \theta_2 = 1 \end{array}$

Predict  $y=1$  if  $-3 + x_1 + x_2 \geq 0$ .



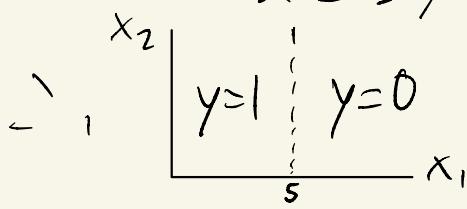
$\therefore x_1 + x_2 = 3$  is the decision boundary  
 ↳ i.e., like  $h_{\theta}(x) = 0.5$

e.g.  $\theta_0 = 5, \theta_1 = -1, \theta_2 = 0, h_{\theta}(x) = g(5 - x_1)$

↳  $y=1$  if  $5 - x_1 \geq 0$

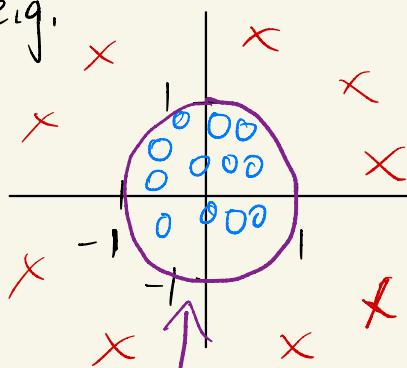
$$5 \geq x_1$$

$x \leq 5$ , then  $y=1$



## Non-Linear Decision Boundaries!

e.g.



$$h(\mathbf{x}) = g(\theta_0 + \theta_1 x_1 + \theta_2 x_2 + \theta_3 x_1^2 + \theta_4 x_2^2)$$

$$\text{let } \boldsymbol{\theta} = \begin{bmatrix} -1 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

Predict  $y=1$  if  $-1 + x_1^2 + x_2^2 \geq 0$

$$\Leftrightarrow x_1^2 + x_2^2 \geq 1, \text{ circle}$$

You can also have higher-order polynomial decision boundaries.

e.g.

