

# 振动

external force:  $F(t)$

$$m\ddot{x} + c\dot{x} + kx = F(t) \quad kx(t): \text{shear force} \quad \text{viscous damping force: } c\dot{x}(t)$$

地位移  $x_0(t)$ . 则  $m\ddot{x}(t) = -k(x(t) - x_0(t)) - c(\dot{x}(t) - \dot{x}_0(t))$

$$y(t) = x(t) - x_0(t)$$

$$\therefore m\ddot{y}(t) + c\dot{y}(t) + ky(t) = -m\ddot{x}_0(t) \quad \text{ground acceleration } -m\ddot{x}_0(t) = F(t)$$

$$m\ddot{x} + c\dot{x} + kx = F(t)$$

$$\frac{k}{m} = \omega_0^2, \quad \frac{c}{m} = 2\varepsilon\omega_0$$

$$\therefore \ddot{x} + 2\varepsilon\omega_0\dot{x} + \omega_0^2 x = \frac{F(t)}{m}$$

$$x(t) = x_c(t) + x_p(t) \quad \text{root } \lambda_{1,2} = \omega_0(-\varepsilon \pm \sqrt{\varepsilon^2 - 1})$$

① underdamped system  $\lambda_{1,2} = \omega_0(-\varepsilon \pm \sqrt{\varepsilon^2 - 1}) = -\varepsilon\omega_0 \pm i\omega_d$

$$\omega_d = \omega_0\sqrt{1 - \varepsilon^2} \quad (\text{damped natural circular frequency})$$

$$x_c = e^{-\varepsilon\omega_0 t} (A \cos \omega_d t + B \sin \omega_d t)$$

determine A, B with i.c.  $x(0) = x_0, \dot{x}(0) = V_0$

$$\Rightarrow x_c(t) = e^{-\varepsilon\omega_0 t} \left( x_0 \cos \omega_d t + \frac{V_0 + \varepsilon\omega_0 x_0}{\omega_d} \sin \omega_d t \right), \quad 0 < \varepsilon < 1.$$

[special case]  $\varepsilon = 0$ ,  $x_c = a \cos(\omega_0 t - \varphi)$   $a = \sqrt{x_0^2 + (\frac{V_0}{\omega_0})^2}$ ,  $\varphi = \tan^{-1}(\frac{V_0}{\omega_0 x_0})$

受阻振动 damped free vibration  $x_c(t) = a e^{-\varepsilon\omega_0 t} \cos(\omega_d t - \varphi)$

$$a = \sqrt{x_0^2 + (\frac{V_0 + \varepsilon\omega_0 x_0}{\omega_d})^2}, \quad \varphi = \tan^{-1}(\frac{V_0 + \varepsilon\omega_0 x_0}{\omega_d x_0})$$

② 临界阻尼

critically damped system

$$\varepsilon = 1. \quad x_c(t) = e^{-\omega_0 t} (C_0 + C_1 t) \quad \text{with i.c. } x(0) = x_0, \dot{x}(0) = V_0$$

$$\Rightarrow x_c(t) = e^{-\omega_0 t} (x_0 + (V_0 + \omega_0 x_0)t)$$

过阻尼

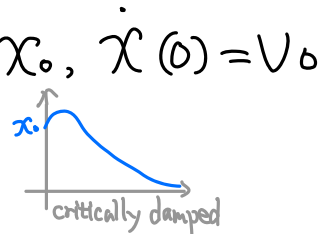
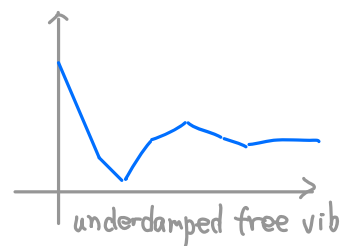
③ over damped  $\varepsilon > 1.$

$$x_c(t) = C_1 e^{-\omega_0(\varepsilon - \sqrt{\varepsilon^2 - 1})t} + C_2 e^{-\omega_0(\varepsilon + \sqrt{\varepsilon^2 - 1})t}$$

• Forced Vibration

$$F(t) = F_0 \sin \Omega t$$

$$x_p(t) = \frac{F_0}{m} \frac{1}{\sqrt{(\omega_0^2 - \Omega^2)^2 + (2\varepsilon\omega_0\Omega)^2}} \sin(\Omega t - \varphi)$$



$$\text{where, } \cos \varphi = \frac{\omega_0^2 - \Omega^2}{\sqrt{(\omega_0^2 - \Omega^2)^2 + (2\varepsilon\omega_0\Omega)^2}}$$

$$\sin \varphi = \frac{2\varepsilon\omega_0\Omega}{\sqrt{(\omega_0^2 - \Omega^2)^2 + (2\varepsilon\omega_0\Omega)^2}}$$

$$r = \frac{\Omega}{\omega_0} = \text{frequency ratio.}$$

$$k = m\omega_0^2, \quad |x_p(t)| = \frac{F_0}{k} \frac{1}{\sqrt{(1-r^2)^2 + (2\varepsilon r)^2}}$$

• Resonance

$$\varepsilon = 0. \quad \Omega = \omega_0.$$

$$\ddot{x}_p + \omega_0^2 x_p = \frac{F_0}{m} \sin \omega_0 t$$

$$\Rightarrow x_p = -\frac{F_0 t}{2m\omega_0} \cos \omega_0 t$$