

$$a) \bar{B}(r, \theta, t) = B_\theta \quad ; \quad \bar{B}(r, \theta, t) = B_\varphi \quad ; \quad B_r = B_\varphi = B_\theta = 0 \quad (1)$$

$$\bar{s}(r, \theta, t) = \frac{l}{\mu_0} \bar{B}(r, \theta, t) \times \bar{B}(r, \theta, t) = \frac{l}{\mu_0} B_\theta B_\varphi \hat{\theta} \times \hat{\varphi} =$$

$$= -\frac{l}{\mu_0} \left(\frac{\mu_0 \rho_0 w^2 \sin \theta}{4\pi} \frac{\sin \theta}{r} \cos \left(\omega(t + \frac{r}{c}) \right) \right)^2 \frac{l}{c} \hat{\theta} \times \hat{\varphi}$$

$$= -\frac{l}{\mu_0} \frac{\mu_0^2 \rho_0^2 w^4}{16\pi^2} \frac{\sin^2 \theta}{r^2} \cos^2 \left(\omega(t + \frac{r}{c}) \right) \frac{l}{c} \hat{r} \quad \hat{\theta} \times \hat{\varphi} = -\hat{r}$$

$$= \frac{\mu_0}{c} \frac{\rho_0^2 w^4}{16\pi^2} \frac{\sin^2 \theta}{r^2} \cos^2 \left(\omega(t + \frac{r}{c}) \right) \hat{r}$$

$$b) \langle \bar{s}(r, \theta, t) \rangle = \frac{l}{2} \frac{\mu_0}{c} \frac{\rho_0^2 w^4}{16\pi^2} \frac{\sin^2 \theta}{r^2} = \frac{\mu_0}{c} \frac{\rho_0^2 w^4}{32\pi^2} \frac{\sin^2 \theta}{r^2}$$

$$c) P = \frac{\mu_0}{c} \frac{\rho_0^2 w^4}{32\pi^2} \int_{\theta=0}^{\pi} \frac{\sin^2 \theta}{r^2} \times \sin \theta d\theta \int_{\varphi=0}^{2\pi} d\varphi$$

$$= \frac{\mu_0}{c} \frac{\rho_0^2 w^4}{32\pi^2} \int_{\theta=0}^{\pi} \sin^3 \theta d\theta \left[\varphi \right]_0^{2\pi}$$

$$= \frac{\mu_0}{c} \frac{\rho_0^2 w^4}{32\pi^2} \frac{2\pi}{3} \left[\left(\frac{\cos 3\theta}{12} - \frac{3}{4} \cos \theta \right) \right]_0^{\pi}$$

$$= \frac{\mu_0}{c} \frac{\rho_0^2 w^4}{16\pi} \left[\frac{\cos 3\pi}{12} - \frac{3}{4} \cos \pi - \left(\frac{\cos 0}{12} - \frac{3}{4} \cos 0 \right) \right]$$

$$= \frac{\mu_0}{c} \frac{\rho_0^2 w^4}{16\pi} \left[-\frac{1}{12} - \frac{3}{4}(-1) - \left(\frac{1}{12} - \frac{3}{4} \right) \right]$$

$$= \frac{\mu_0}{c} \frac{\rho_0^2 w^4}{16\pi} \left[-\frac{2}{12} + \frac{6}{4} \right] = \frac{\mu_0}{c} \frac{\rho_0^2 w^4}{16\pi} \left[\frac{-2+18}{12} \right] = \frac{\mu_0}{c} \frac{\rho_0^2 w^4}{16\pi} \frac{16}{12} =$$

$$= \frac{\mu_0}{c} \cdot \frac{P_0^2 w^4}{4\pi} \quad (2)$$

d) $\mu_0 = \frac{1}{\epsilon_0 c^2}; w = 2\pi\nu; \nu = \frac{1}{\tau}; c = \lambda\nu$

$$P = \frac{\mu_0}{c} \cdot \frac{P_0^2 w^4}{4\pi} = \frac{1}{\epsilon_0 c^2} \frac{1}{\tau} \cdot \frac{P_0^2 (2\pi\nu)^4}{4\pi} = \frac{1}{\epsilon_0} \frac{1}{\lambda^3 \nu^3} \frac{P_0^2 (2\pi)^4 \nu^4}{4\pi} =$$

$$= \frac{P_0^2 (2\pi)^4 \nu^4}{\epsilon_0 2\pi 6 \lambda^3 \nu^3} = \frac{P_0^2 (2\pi)^3 \nu}{6 \epsilon_0 \lambda^3} = \frac{(2\pi)^3}{6} \frac{P_0^2}{\epsilon_0} \frac{1}{\lambda^3 \tau}$$

e) $[P] = \frac{C \text{ m}^2}{\text{ s}} \text{ Volt} \cdot \frac{1}{\text{ A}^2 \text{ s}} = \frac{CV}{S} = \frac{J}{s} = \text{Watt}$

Einheit
Watt
= Joule / Sekunde

Linac - Bremsstrahlung

Jet radio synchrotron