

CSC 212: Data Structures and Abstractions

Binary search trees

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Trees

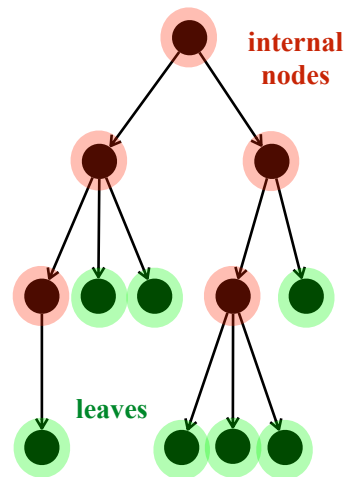
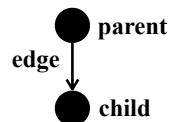
Trees

Definition

- ✓ data structure that consists of **nodes** connected by **edges**
- hierarchical structure, with a single **root** node
- each node can have zero or more **children**

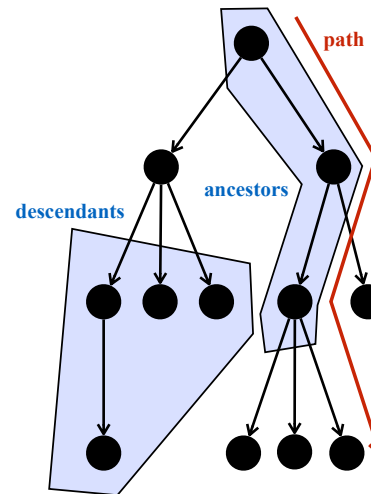
Terminology

- ✓ each node is either a **leaf** or an **internal node**
- leaves are nodes with no children, while internal nodes are nodes with one or more children
- ✓ nodes with the same **parent** are **siblings**



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Paths



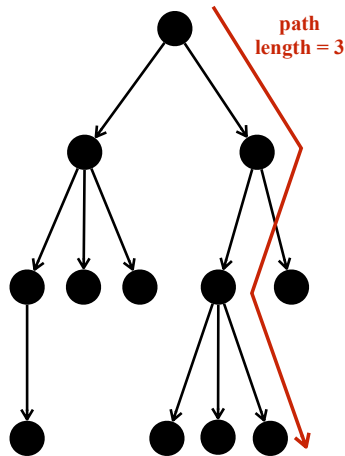
A **path** from node v_0 to v_n is a sequence of nodes v_0, v_1, \dots, v_n , where there is a (directed) edge from one node to the next

The **descendants** of a node v are all nodes reached by a path from node v to the leaf nodes

The **ancestors** of a node v are all nodes found on the path from the root to node v

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Depth and height



The length of a **path** is the number of edges in the path

The **depth** (level) of a node v is the length of the path from the root node to v

The **height** of a node v is the length of the path from v to its deepest descendant

The **depth of the tree** is the depth of deepest node

The **height of the tree** is the height of the root

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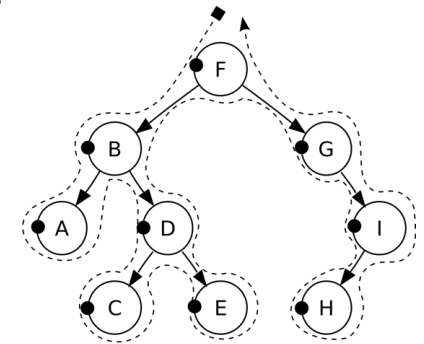
Traversals

Definition

- ✓ a **traversal** is a way of visiting all the nodes in a tree

Types of traversals:

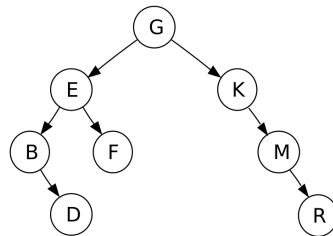
- ✓ **pre-order traversal**: visit the root node first, then recursively visit all subtrees
- ✓ **post-order traversal**: recursively visit all subtrees first, then visit the root node



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Pre-order traversal

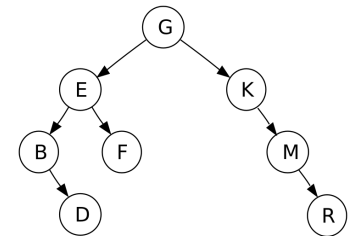
```
algorithm preorder(p) {
    visit(p)
    for each child c of p {
        preorder(c)
    }
}
```



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Post-order traversal

```
algorithm postorder(p) {
    for each child c of p {
        postorder(c)
    }
    visit(p)
}
```



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Binary trees

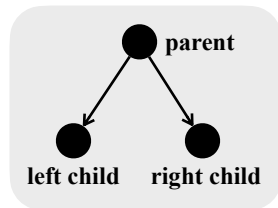
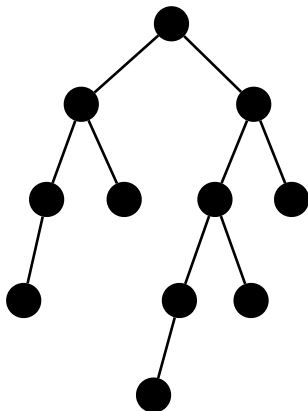
k-ary trees

- k-ary tree
 - ✓ every node has between 0 and k children
- Full k-ary tree
 - ✓ every node has exactly 0 or k children
- Complete k-ary tree
 - ✓ every level is entirely filled
 - ✓ except possibly the deepest, where all nodes are as far left as possible
- Perfect k-ary tree
 - ✓ every leaf has the same depth and the tree is full

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Binary trees

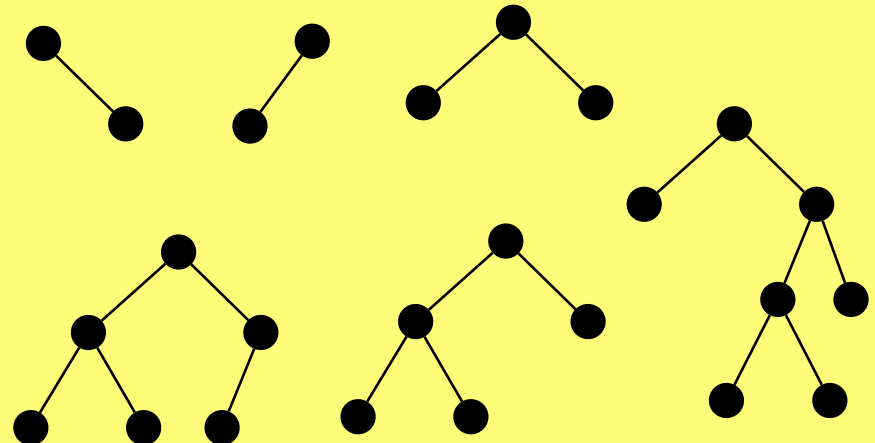
- Definition
 - ✓ a special case of a k-ary tree, where $k = 2$



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Practice

- Mark the following binary trees ($k=2$) as full/complete/perfect



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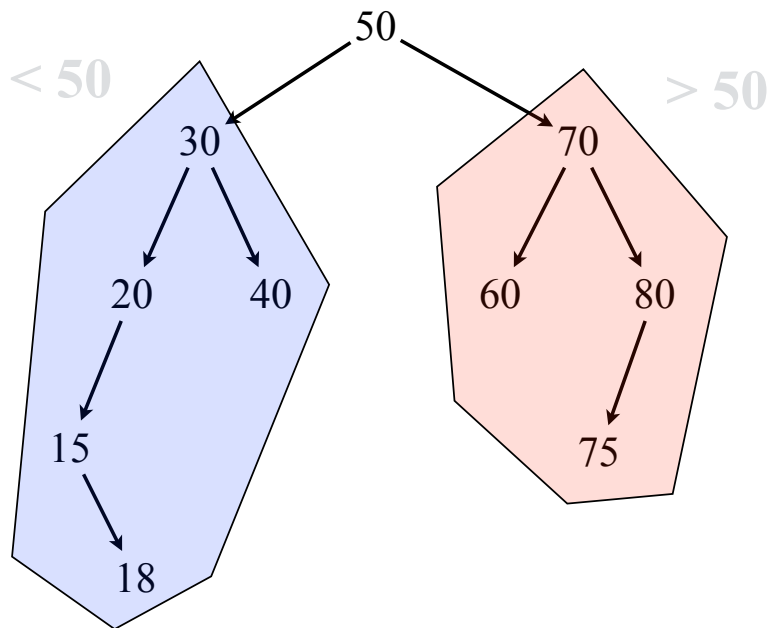
Binary search trees

Binary search tree

- A binary search tree (BST) is a **binary tree**
- A BST has **symmetric order**
 - ✓ each node x in a BST has a key denoted by $key(x)$
 - ✓ for all nodes y in the left subtree of x , $key(y) < key(x)$ **
 - ✓ for all nodes y in the right subtree of x , $key(y) > key(x)$ **

(**) assume that the keys of a BST are pairwise distinct

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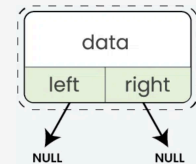


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Representing a node

```
template <typename T>
struct BSTNode {
    T data;
    BSTNode<T> *left, *right;

    BSTNode(const T& value) {
        data = value;
        left = right = nullptr;
    }
};
```



The implementation of a **binary tree node** requires a structure that can accommodate connections to two child nodes

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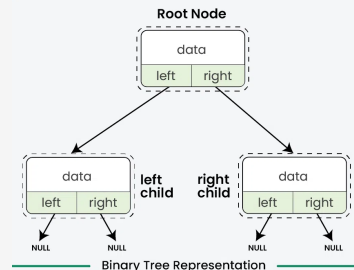
Representing a binary search tree

```
template <typename T>
class BST {
private:
    struct Node {
        T data;
        Node *left, *right;
        Node(const T& value) {
            data = value;
            left = right = nullptr;
        }
    };

    Node *root;
    size_t size;

public:
    BST() : root(nullptr), size(0) {}
    ~BST() { clear(); }
    size_t getSize() const { return size; }
    bool empty() const { return size == 0; }

    void insert(const T& value);
    void remove(const T& value);
    bool contains(const T& value) const;
    void clear();
};
```



<https://www.geeksforgeeks.org/binary-tree-representation/>

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Insert

Algorithm

- ✓ if tree is empty, create a new node as root, done
- ✓ starting node p at the root, repeat:
 - compare the key to insert with the key of p, if equal, done
 - if the new key is less than the key of p, set p to the left subtree
 - if p is empty, create new node here, done
 - else continue
 - if the new key is greater than the key of p, set p to the right subtree
 - if p is empty, create new node here, done
 - else continue

Time complexity

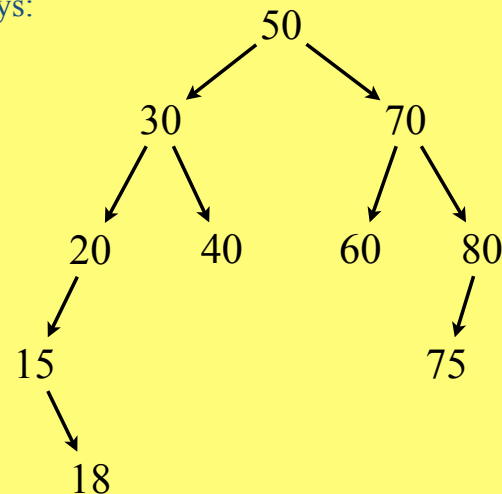
- ✓ $O(h)$, where h is the height of the tree

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Practice

Insert the following keys:

- ✓ 65, 27, 90, 11, 51



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Remove

Approach

- ✓ find node to be removed, then apply one of the cases below
- ✓ **case 1**: node is a leaf
 - trivial, delete node and set parent's pointer to nullptr
- ✓ **case 2**: node has 1 child
 - set parent's pointer to the only child and delete node
- ✓ **case 3**: node has 2 children
 - find successor (smallest node in the right subtree)
 - copy successor's data to node
 - delete successor

can also use predecessor

Time complexity

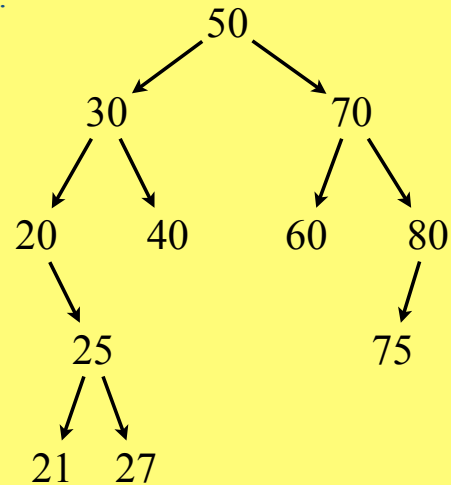
- ✓ $O(h)$, where h is the height of the tree

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Practice

Remove the following keys:

✓ 27, 40, 80, 20, 30, 50



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Contains

Algorithm

- ✓ start at root node
- ✓ if the search key matches the current node's key then found
- ✓ if search key is greater than current node's key
 - search on right child
- ✓ if search key is less than current node's
 - search on left child
- ✓ stop when current node is nullptr (not found)

Time complexity

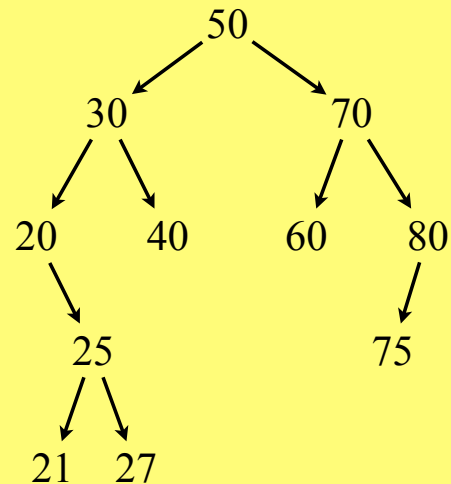
- ✓ $O(h)$, where h is the height of the tree

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Practice

Search the following keys:

✓ 25, 77, 18, 40, 75



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Analysis

Practice

- Starting from an empty BST, insert the following keys in the order given
 - 20 10 30 5 15 25 35
 - 10 20 5 15 30 35 25
 - 5 10 15 20 25 30 35
- How is the order of insertion related to the shape of the tree?
- How is the height of the tree related to the number of nodes?

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Practice

- Complete the following table with rates of growth
 - as a function of the number of nodes

Operation	Best case	Average case	Worst case
Insert			
Remove			
Search			

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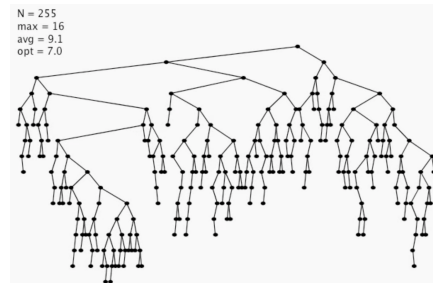
Average case

Proposition

- if n distinct keys are randomly inserted into a BST, the expected number of compares is $\sim c \log n$
- can be formally justified through probabilistic analysis (not covered in this class)

Implications

- even without explicit balancing mechanisms, randomly built BSTs provide reasonably efficient operations



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