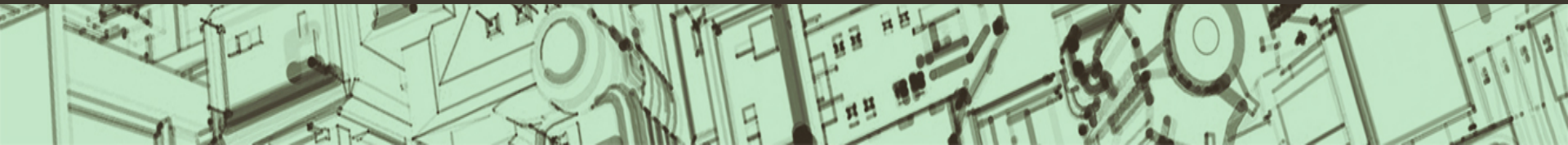


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Traffic simulation

Final Project Report – CIS 667 Fall 2016



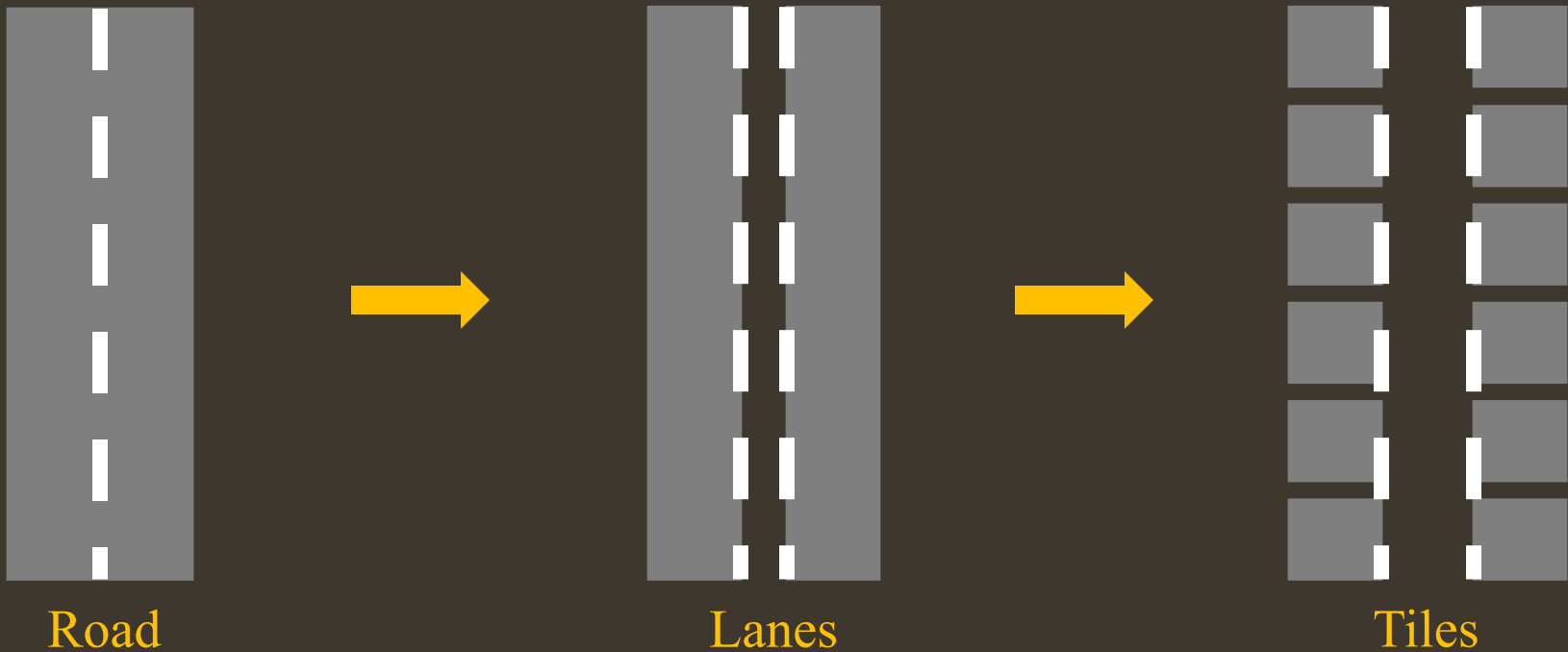
Intuition

- Ultimate goal: simulate the traffic and observe their performance on different road network.

Overview

- Road network representation
- Traffic simulation
- Visualization
- Traffic performance on different road network

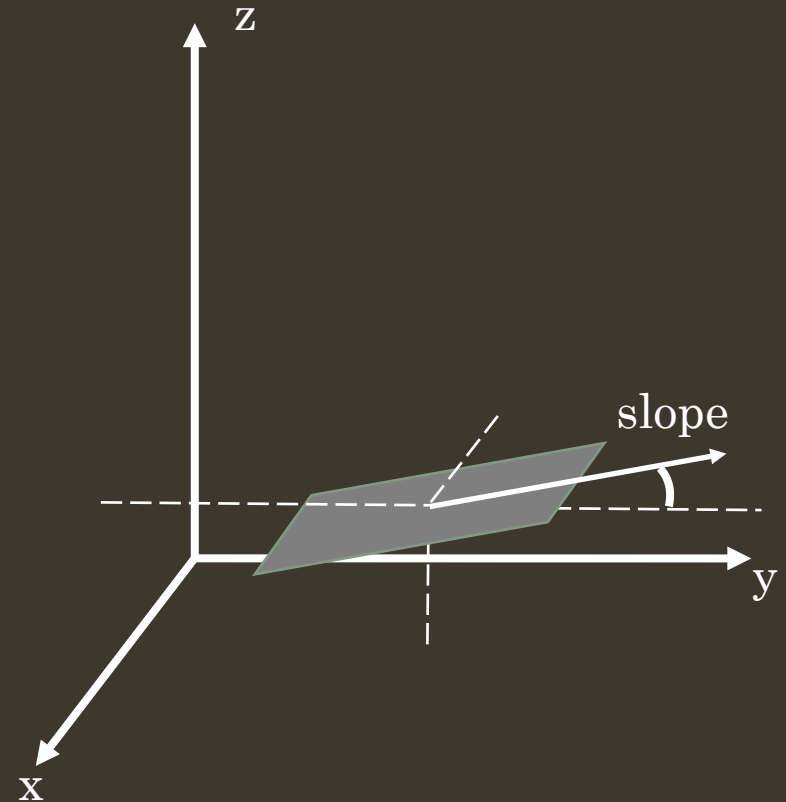
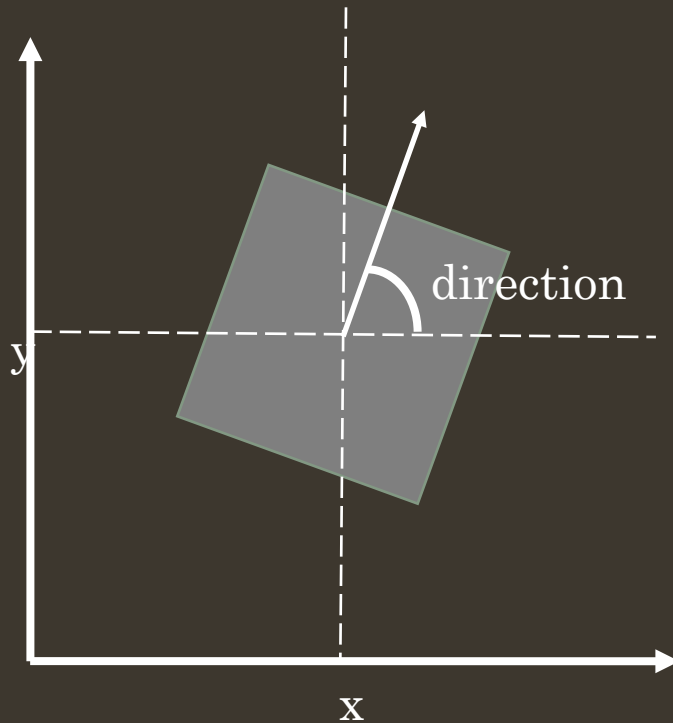
Road Network Representation – Part/Tile based



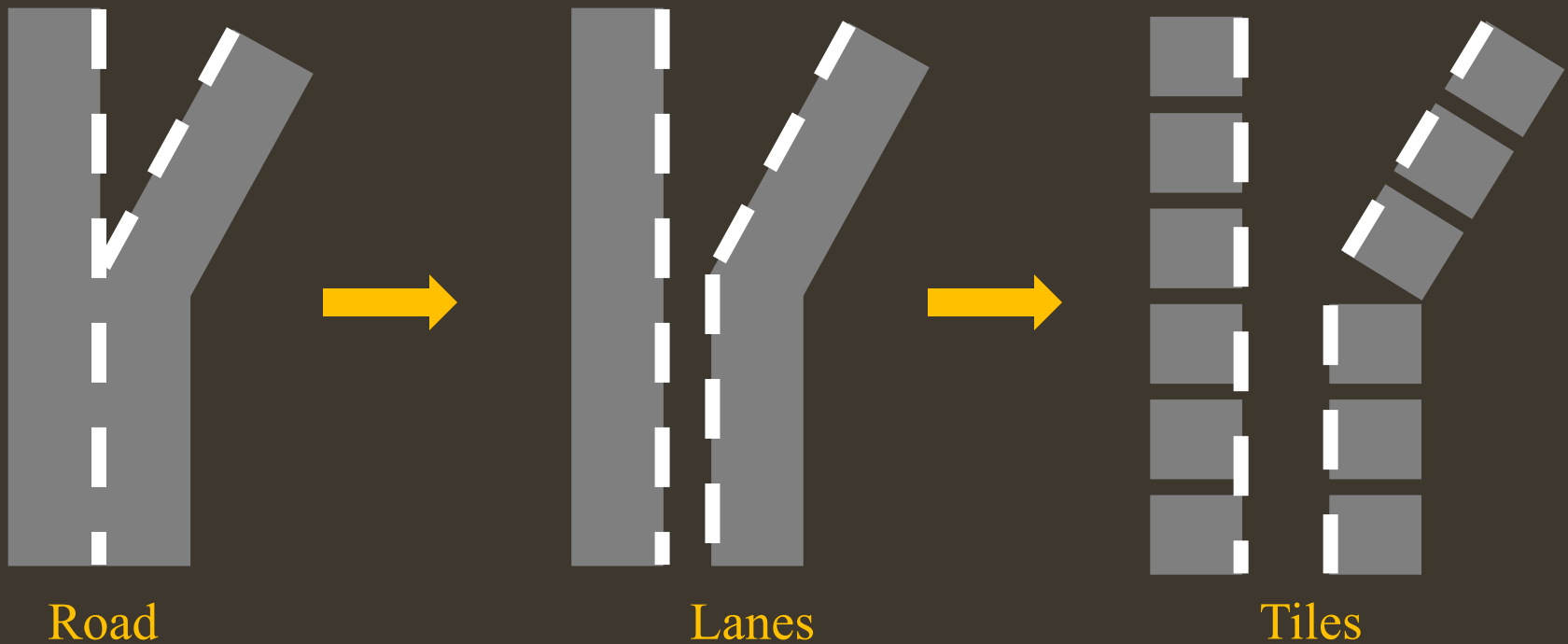
Reference: Daniel Topfer, Jens Spehr, Jan Effertz and Christoph Stiller, Efficient Scene Understanding for Intelligent Vehicles Using a Part-Based Road Representation (ITSC 2013)

Road Network Representation

- Basic Element: Road Tile



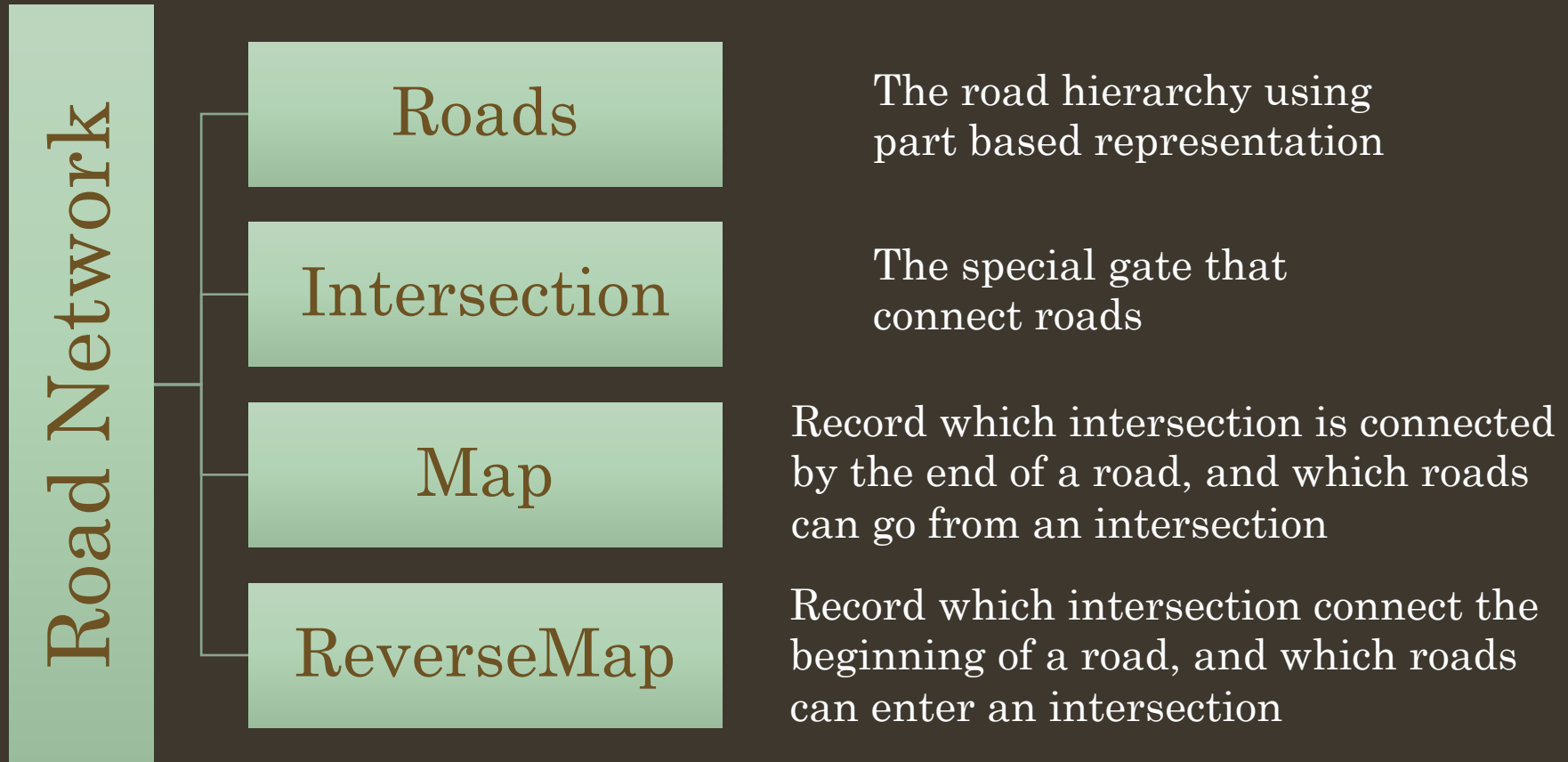
Road Network Representation – Part/Tile based made flexible



Advantage: using simple hierarchical structure to represent sophisticated road network.

Almost any shape can be represented if the tile length is chosen correctly.

Road Network Representation - Hierarchy Component



Roads and Intersections are only geo-structures.
Map and ReverseMap provide connections and they are used for route search.

Road Network Representation

- Features

- All road network elements (including intersections, roads, lanes, and tiles) share same feature:
 - *Geo-location*
- Super class RNLocation
- Class family tree:
 - RNLocation: (x,y,z)
 - -RNGate (entry, exit)
 - -RNElement (width, length)
 - --RNRoadTile (slope, direction)
 - --RNLane: consists Array<RNRoadTile>
 - --RNRoad: consists Array<RNLane>
 - --RNIntersection (entries, exits)

Traffic Simulation – Car Representation

- Car as an agent:
 - Each car take a move based on its road network observed and its current situation recorded.
- Two type of car:
 - A car with a start point and a destination
 - Path search agent
 - Shortest path or least traffic
 - A car takes random walk
 - Local search agent
 - Random walk or least traffic

Traffic Simulation

– Intelligent Driver Model(IDM)

- Capture the driver's control of speed by quantify the tendency of accelerate and brake. The driver tends to keep the same speed with the previous car and keep the minimum distance that it can follow.
 - $\Delta v = a_{max} * (tendency\ of\ acceleration - tendency\ of\ deceleration)$
 - $tendency\ of\ acceleration = 1 - \left(\frac{v_{previous}}{v_{me}}\right)^{power\ of\ acceleration}$
 - $tendency\ of\ deceleration = 1 - \left(\frac{desired\ min\ gap}{actual\ distance\ to\ previous\ car}\right)^{power\ of\ deceleration}$
 - $desired\ minimum\ gap(simplified) = \frac{(approaching\ rate * v_{me})}{2 * a_{max}}$
- Parameters I chosed:
 - $a_{max} = 1$
 - Power of acceleration = 1
 - Power of deceleration = 2

Reference: Martin Treiber, Ansgar Hennecke, and Dirk Helbing, Congested Traffic States in Empirical Observations and Microscopic Simulations (March 18, 2014)

Traffic Simulation

– Integration and Views

Traffic Simulator

Traffic
representation

Road
Network

Car
Agent

Views

Road
as
line

Crossing
as
node

Car
as
point

Stats

Average
speed

Traffic Simulation

– User Interaction

- User operation:
 - Drag a line:
 - Create a road, if the road connect with other roads, create an intersection to connect them
 - Draw thousands of shapes
 - Double click:
 - Start traffic simulation
 - In the code:
 - Change experimental parameters
 - Extend the code:
 - Automatically create road network of complicated shapes and traffic of various densities.

Traffic Simulation

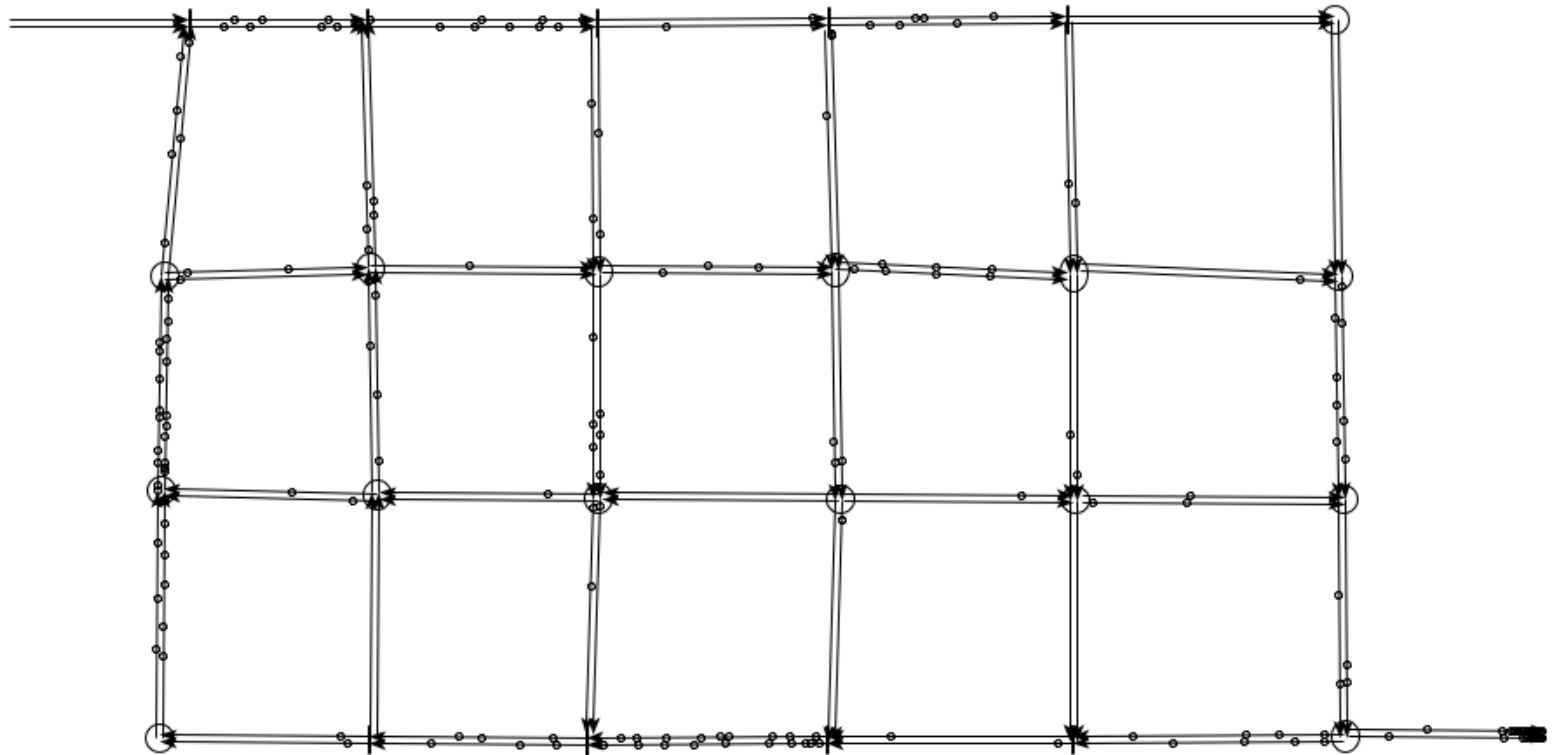
– Detailed Process Example

- Car agent working:
 - >Get percept from the road network and traffic situation
 - Current road, next road, destination, previous car
 - >Update its status using the percept
 - Traveling or reached destination or dead end
 - >Generate an action
 - Start moving, keep moving on the current lane; Passing an intersection; Reached destination; IDM to keep distance to other cars.
 - >The traffic simulator decide if the action works
 - Currently all of them works
 - >Do this update process 25 times a second.

Demo

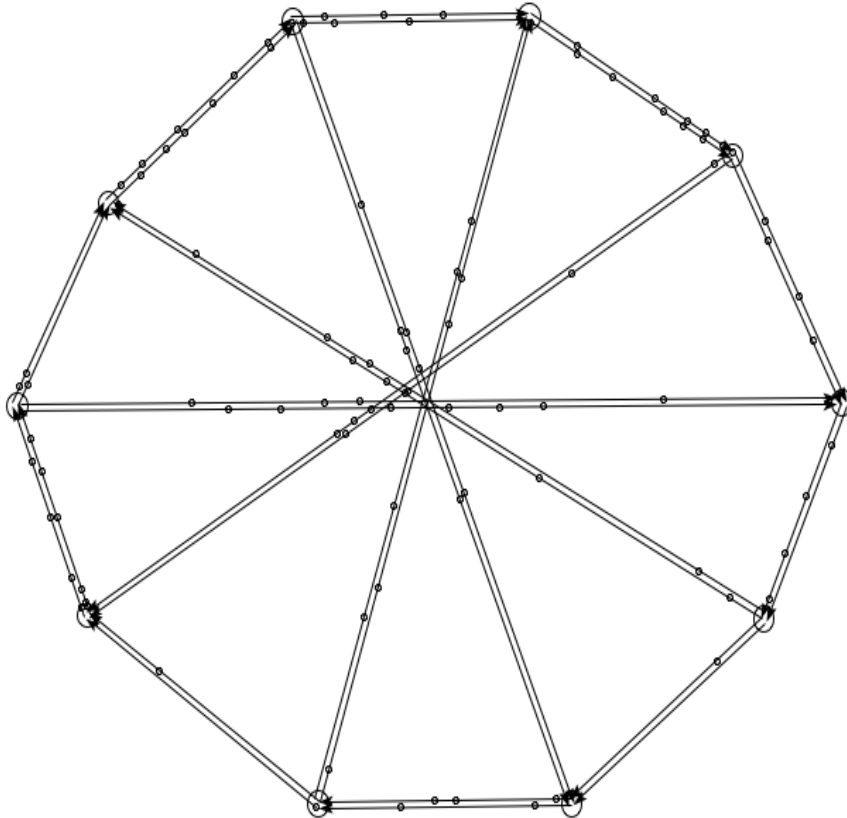
Conclusion

-Flexible Road Network Construction



Conclusion

-Showing statistic results



Average velocity: 11.780943185
Average velocity: 12.1491750911
Average velocity: 12.1996256992
Average velocity: 12.6535442763
Average velocity: 12.8273275439
Average velocity: 13.0985182758
Average velocity: 13.309480945
Average velocity: 13.3896965142
Average velocity: 13.2446515059
Average velocity: 13.1305300143
Average velocity: 12.660524964
Average velocity: 12.2499370979
Average velocity: 11.6125054514
Average velocity: 11.705816954
Average velocity: 12.0884384987
Average velocity: 12.182057507
Average velocity: 12.175055828
Average velocity: 12.5060114004
Average velocity: 12.2902255362
Average velocity: 12.618645447
Average velocity: 12.4966642066
Average velocity: 12.4085321838
Average velocity: 12.5678053634

Conclusion

-Observation based on stats

- Traffic average speed:
 - Slower when higher car density
 - For a certain traffic density, it has an optimal average speed. Traffic will slow down if they are faster, and will speed up if they are slower.
 - Even when traffic density is relatively low, some specific part of the traffic is significantly slower than others. This shows “Traffic jam come out of nowhere”.
 - If speed limit is infinite, it will reach this optimal speed eventually, but it fluctuate.
 - If speed limit is lower than the optimal average speed, all cars will reach a stable speed of the speed limit at the end.