

Bahria University, Islamabad Department of Software Engineering

Data Structures & Algorithms Lab

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Teacher: RAHEELA AMBRIN

Student : Abdul Rafay

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Comments:

Signature

Code:

All the code files are uploaded on GitHub: https://github.com/CharlieFour/DSA_Lab

You can check out the code on GitHub in Lab_12 folder

Code:

Task_01:

```
#include<iostream>
#include<vector>
#include<queue>
using namespace std;
void DFS(int v, vector<bool>& visited, const vector<vector<int>>&
graph)
{
    visited[v] = true;
    cout << v << " ";
    for(int neighbor : graph[v])
        if(!visited[neighbor])
            DFS (neighbor, visited, graph);
void BSF(int start, const vector<vector<int>>& graph)
    vector<bool> visited(graph.size(), false);
    queue<int> q;
    q.push(start);
    visited[start] = true;
    while(!q.empty())
        int current = q.front();
        q.pop();
        cout << current << " ";</pre>
        for(int neighbor : graph[current])
            if(!visited[neighbor])
                visited[neighbor] = true;
                q.push (neighbor);
```

```
}
   }
int main()
    vector<vector<int>> graph
        {1,
2},
         { 3 } ,
         { 4,
5},
         { },
         { } ,
         { }
    };
    vector<bool> visited(graph.size(), false);
    cout << "Depth First Search Traversal :" << endl;</pre>
    DFS(0, visited, graph);
    cout << "\nBreadth First Search Traversal :" << endl;</pre>
    BSF(0, graph);
    system("pause");
    return 0;
```

Screen Shots:

```
Depth First Search Traversal :
0 1 3 2 4 5
Breadth First Search Traversal :
0 1 2 3 4 5 Press any key to continue . . .
```

Task_02

```
#include <iostream>
#include <vector>
#include <queue>
#include <climits>
using namespace std;
class Node
public:
   int vertexNumber;
    vector<pair<int, int>> children;
   Node(int vertexNumber)
        this->vertexNumber = vertexNumber;
    void add child(int vNumber, int weight)
       children.push back({vNumber, weight});
};
vector<int> dijkstraDist(const vector<Node*>& graph, int source,
vector<int>& path)
    int n = graph.size();
    vector<int> dist(n, INT MAX);
    vector<bool> visited(n, false);
    dist[source] = 0;
    path[source] = -1;
   priority queue<pair<int, int>, vector<pair<int, int>>,
greater<>> pq;
   pq.push({0, source});
    while(!pq.empty())
        int u = pq.top().second;
        pq.pop();
        if (visited[u]) continue;
        visited[u] = true;
        for (auto& child : graph[u] ->children)
            int v = child.first;
            int weight = child.second;
```

```
if(dist[u] + weight < dist[v])</pre>
                 dist[v] = dist[u] + weight;
                path[v] = u;
                pq.push({dist[v], v});
    return dist;
void printPath(const vector<int>& path, int destination)
    if (destination == -1)
       return;
    printPath(path, path[destination]);
    cout << destination << " ";</pre>
}
int main()
    int n = 4;
    vector<Node*> graph;
    for(int i = 0; i < n; i++)
        graph.push back(new Node(i));
    graph[0] \rightarrow add child(1, 1);
    graph[0]->add child(2, 4);
    graph[1]->add child(2, 2);
    graph[1]->add child(3, 6);
    graph[2]->add child(3, 3);
    int source = 0;
    vector<int> path(n);
    vector<int> dist = dijkstraDist(graph, source, path);
    for (int i = 0; i < n; i++)
        if (dist[i] == INT MAX)
           cout << "Vertex " << i << " is not reachable from source</pre>
" << source << ".\n";
        }
        else
```

Screen Shots:

```
Distance from Node 0 to Node 0: 0
Path: 0 0
Distance from Node 0 to Node 1: 1
Path: 0 0 1
Distance from Node 0 to Node 2: 3
Path: 0 0 1 2
Distance from Node 0 to Node 3: 6
Path: 0 0 1 2 3
Press any key to continue . . .
```