

MECH3750

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Tutorial - Focus on numerical theory.

Quizzes - Friday Contacts W3,5,7,9,11

Resources > Black board, Cithab

Taylor Expansions.

· Making approximations for a function near to a known point.

 $f(x) = f(a) + \frac{5'(a)}{1!} (x-a) + \frac{5'(a)}{2!} (x-a)^2 + \dots + \frac{5'(a)}{n!} (x-a)^n$

know point = a some point × near to a.

Rn = 5(2) (x-9) (x-9)

O((x-a)³) } Describe extra terms beyond expansion 08 interest.



$$\begin{aligned}
f(x,y) &= f(a,b) + f_{x}(a,b)(x-a) + f_{y}(a,b)(y-b) \\
&+ f_{z}(f_{xx}(a,b)(x-a)^{2} + 2f_{xy}(a,b)(x-a)(y-b) \\
&+ f_{yy}(a,b)(y-b)^{2}) + H.O.T.
\end{aligned}$$

$$f(x) = f(x) + \nabla f(x-x) + \frac{1}{2}(x-x)H(x-x)$$

$$H = \left(\frac{5}{5} \times x + \frac{5}{5} \times y \right)$$

$$f(x_0) + f'(x_0)h. + \left(\frac{5}{5} \times x + \frac{5}{5} \times y \right)$$

Newton's Method. > &(x) = 0

Sor soh=0
$$\Rightarrow h = -f(x_0)$$

 $\int_{0}^{\infty} f(x_0)$

$$x_1 = x_0 + h = x_0 - \frac{\varsigma(x_0)}{\varsigma(x_0)}$$

$$x^{n+k} = x^{n} - \left(\int (x^{n}) \right)^{-1} \int (x_{n})^{n}$$

Stop iterating when $f(x^{n+1}) < \xi = small$ $\begin{pmatrix} a & b \\ c & d \end{pmatrix}^{-1} \rightarrow \frac{1}{ad-bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}.$

f(x,y) = S(a,b) +

 $+O(h^3)$

Error ~ h3

h= (x,y) - (9,6) h= J(x-9)2+(9-6)2

Newton's Method.

key; write yourse equation s.t. f(x)=0

Least Squares.

Principle - house some data > Sit a known equation to it

- Minimise sum of errors.

F

$$y(x) = q_0 + q_1 \times E = \sum_{i=1}^{\infty} (q_0 + q_1 \times i - s_i)^2$$

Minimize E > derive & set =0

$$\frac{\partial E}{\partial a_0} = \mathcal{E}_i \mathcal{Q} \left(q_0 + a_i x_i - S_i \right) = 0$$

$$\frac{\partial E}{\partial a_i} = \underbrace{2i 2xi (a_0 + a_1 xi - Si)} = 0$$

$$\sum_{i} 1(q_{0} + q_{i} \times i) = \sum_{i} 1 \cdot S_{i}$$

$$P\begin{pmatrix} a_0 + a_1 \times_1 \\ a_0 + a_1 \times_2 \\ a_6 + a_1 \times_3 \end{pmatrix} = \begin{pmatrix} 1 & 1 & 1 & 1 \\ \times_1 \times_2 & \cdots & \times_n \end{pmatrix} \xrightarrow{f}$$

$$P\left(\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}\begin{pmatrix} a_0 \\ a_1 \end{pmatrix} = Pf \Rightarrow PPa = Pf$$

a=(PPT)PS