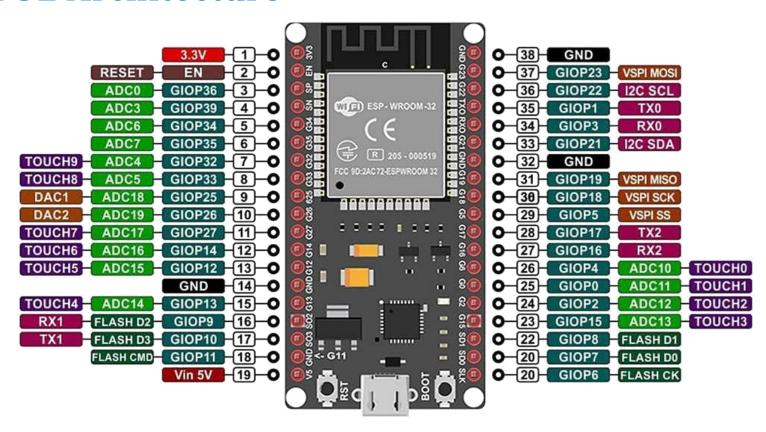
Uscode installation & connection to SQL database

Mars Rover 2022

Adam Bouchaala Teaching Fellow Imperial College London

VS code installation guide

ESP32 Architecture



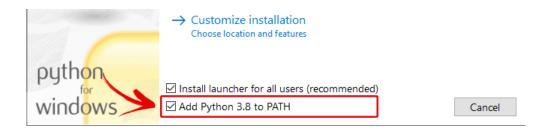
VS Code and PlatformIO IDE for ESP32

- The Arduino IDE works great for small applications.
- However, for advanced projects with more than 200 lines of code, multiple files, and other advanced features like auto completion and error checking, VS Code with the PlatformIO IDE extension is the best alternative.
- Go to https://code.visualstudio.com/ and download the stable build for your operating system (Windows, Mac OS X, Linux Ubuntu).

elect the additional tasks you would like Setup to perform while installing Visual Studio Code, then clic ext.
dditional icons:
Create a desktop icon
ther:
Add "Open with Code" action to Windows Explorer file context menu
Add "Open with Code" action to Windows Explorer directory context menu
Register Code as an editor for supported file types
Add to PATH (requires shell restart)

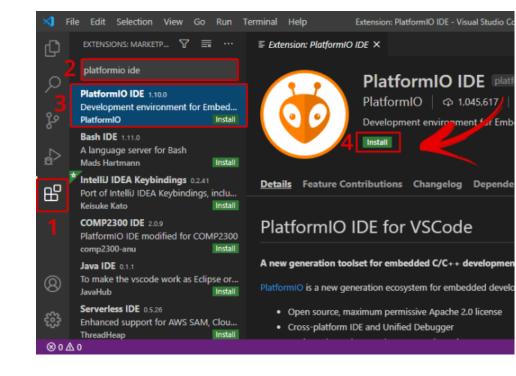
VS Code and PlatformIO IDE for ESP32

- Installing Python on Windows
- To program the ESP32 and ESP8266 boards with PlatformIO IDE you need Python 3.5 or higher installed on your computer. We're using Python 3.8.5.
- Go to python.org/download and download Python 3.8.5 or the newest version.



Installing PlatformIO IDE Extension

- 1. Click on the Extensions icon or press Ctrl+Shift+X to open the Extensions tab
- 2. Search for "PlatformIO IDE"
- 3. Select the first option
- 4. Finally, click the Install button (Note: the installation may take a few minutes)



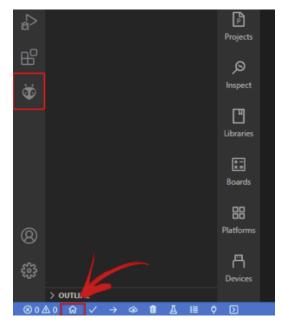
Installing PlatformIO IDE Extension

 After installing, make sure that PlatformIO IDE extension is enabled as shown below.



Installing PlatformIO IDE Extension

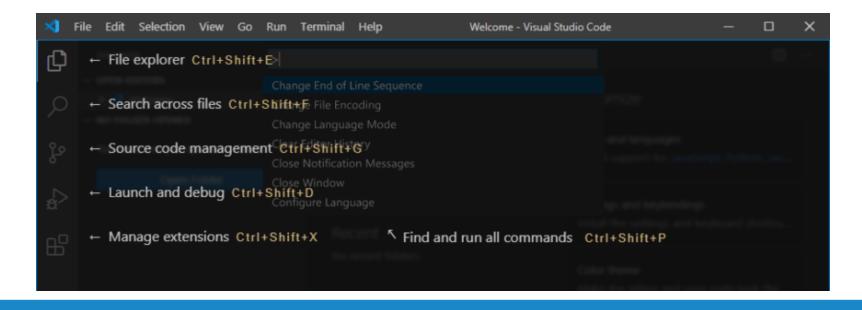
- After that, the PlatformIO icon should show up on the left sidebar as well as a Home icon that redirects you to PlatformIO home.
- If you don't see the PIO icon and the quick tools at the bottom, you may need to restart VS code for the changes to take effect.
- At the bottom, there's a blue bar with PlatformIO commands.

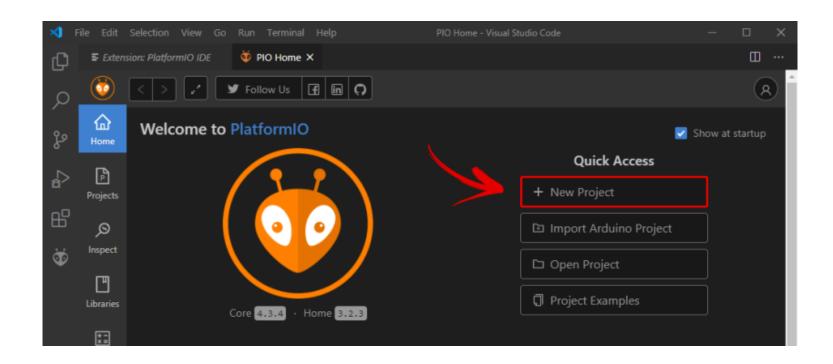


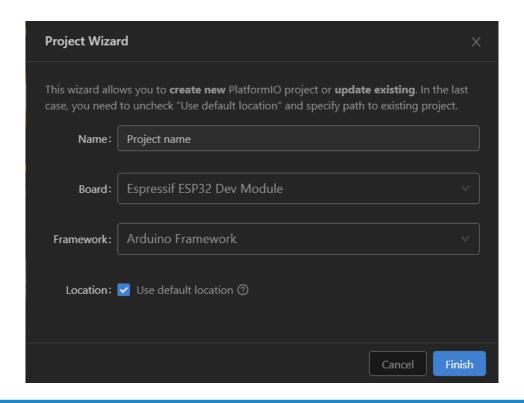


Installing PlatformIO IDE Extension

You can press Ctrl+Shift+X or go to View > Command Palette... to show all the available commands. If you're searching for command and you don't know where it is or its shortcut, you just need to go to the Command Palette and search for it.

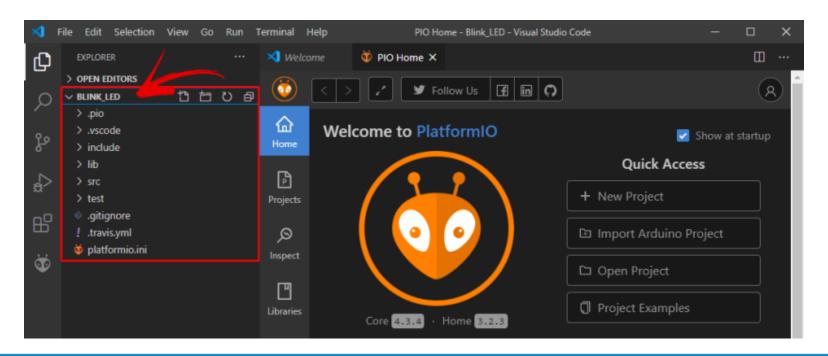




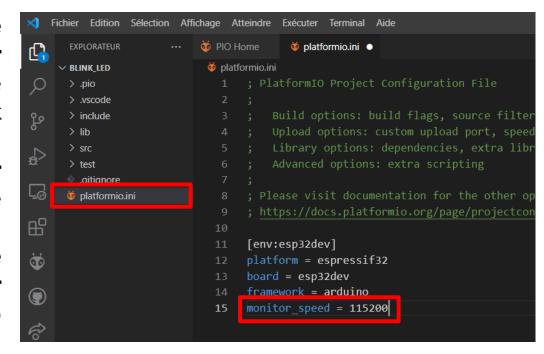


Create a New Project (blink Led)

The Blink_LED project should be accessible from the Explorer tab.



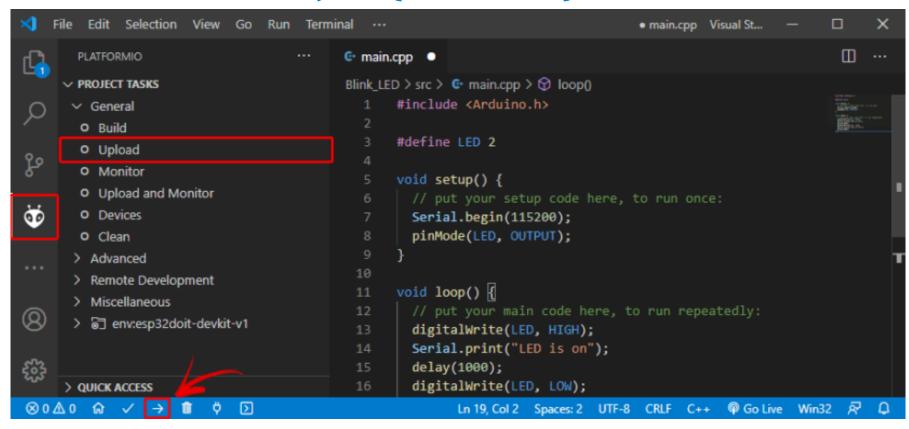
- The platformio.ini file is the PlatformIO Configuration File for your project. It shows the platform, board, and framework for your project.
- You can also add other configurations like libraries to be included, and upload options.
- With the ESP32, if you want to use a baud rate of 115200 in your Serial Monitor, you just need to add monitor_speed = 115200.



- The src folder is your working folder. Under the src folder, there's a main.cpp file. That's where you write your code. Click on that file. The structure of an Arduino program should open with the setup() and loop() functions.
- In PlatformIO, all your Arduino sketches should start with the #include <Arduino.h>.

```
#include <Arduino.h>
#define LED 2
void setup() {
    Serial.begin(115200);
    pinMode(LED, OUTPUT);
}
```

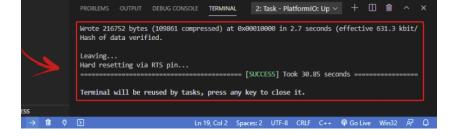
```
void loop() {
    digitalWrite(LED, HIGH);
    Serial.println("LED is on");
    delay(1000);
    digitalWrite(LED, LOW);
    Serial.println("LED is off");
    delay(1000);
}
```



Create a New Project (blink Led)

Now, click on the Serial Monitor icon and you should see it printing the current

LED state.

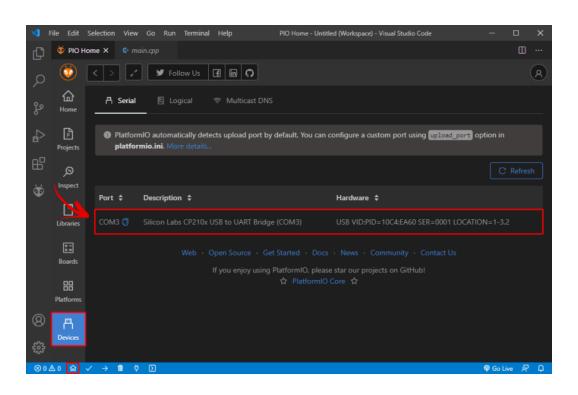


If the code is successfully uploaded, you should get the following

message.



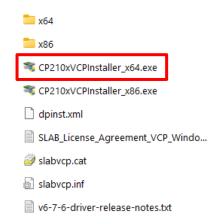
Detect COM Port



PlatformIO will automatically detect the port your board is connected to. To check the connected devices, you can go to the PIO Home and click the Devices icon.

if no device is detected, install the esp32 driver in the shared folder.

Detect COM Port



If PlatformIO cannot detect the port, try restarting VS Code.

PlatformIO will automatically detect the port your board is connected to. To check the connected devices, you can go to the PIO Home and click the Devices icon.

if no device is detected, install the esp32 driver in the shared folder.

ESP32 Read Digital Inputs

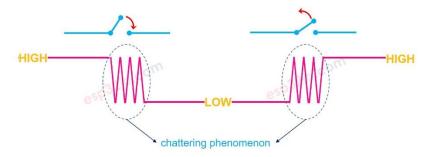
read digital inputs like a button switch:

- Set the GPIO you want to control as an INPUT by using the pinMode() function as follows: pinMode(GPIO, INPUT);
- To read a digital input, like a button, use the digitalRead() function, that accepts as argument, the GPIO (int number) you are referring to. digitalRead(GPIO);

All ESP32 GPIOs can be used as inputs, except GPIOs 6 to 11 (connected to the integrated SPI flash).

Debounce on a Pushbutton

When a button is pressed/released or when a switch is toggled between ON and OFF, its state is changed from LOW to HGH (or HIGH to LOW) once. Is this correct?



Pushbuttons often generate spurious open/close transitions when pressed, due to mechanical and physical issues: these transitions may be read as multiple presses in a very short time fooling the program.

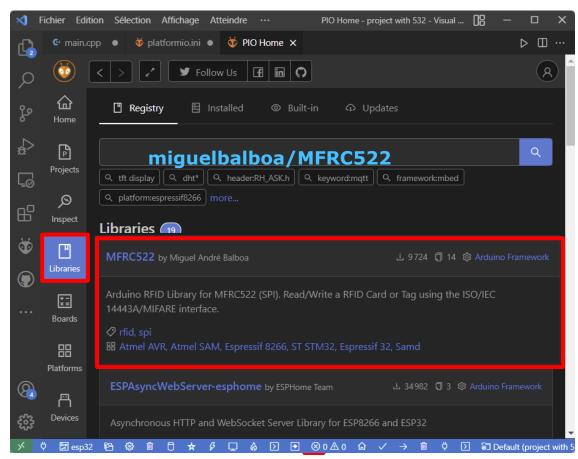
Debounce on a Pushbutton

```
const int buttonPin1 = 34;
int buttonState, B1_state;
int lastButtonState = LOW;
unsigned long lastDebounceTime = 0;
unsigned long debounceDelay = 40;
```

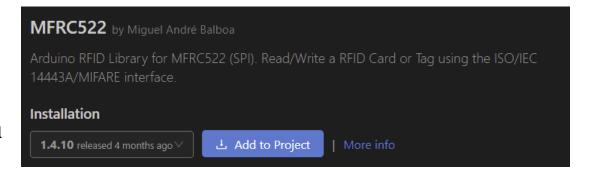
```
void setup()
{
    Serial.begin(115200);
    pinMode(buttonPin1, INPUT);
}
void loop()
{
    B1_state = read_state_Button(buttonPin1);
    if (B1_state == HIGH){
        | Serial.println("Button pushed");
        | }
}
```

```
int read state Button(int buttonPin)
 buttonState = 0;
 int reading = digitalRead(buttonPin);
  if (reading != lastButtonState)
    lastDebounceTime = millis();
 delay(debounceDelay + 1);
 if ((millis() - lastDebounceTime) > debounceDelay)
    if (reading != buttonState)
     buttonState = reading;
  lastButtonState = reading;
  return buttonState;
```

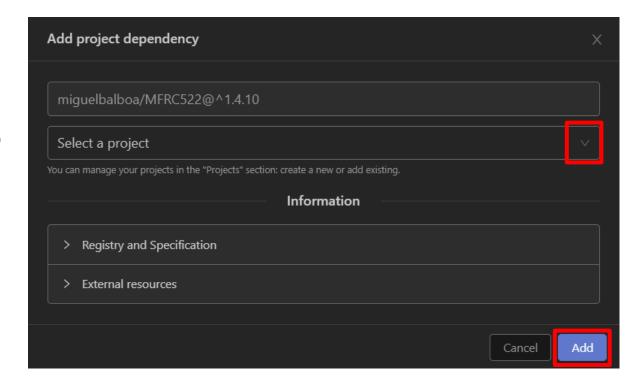
- Click the Home icon to go to PlatformIO Home.
- Click on the Libraries icon on the left sidebar.
- Search for the library you want to install.
- For example, RFID 522 library:
- miguelbalboa/MFRC522



- Click on the library you want to include in your project. Then, click Add to Project.
- Select the project where you want to use the library.

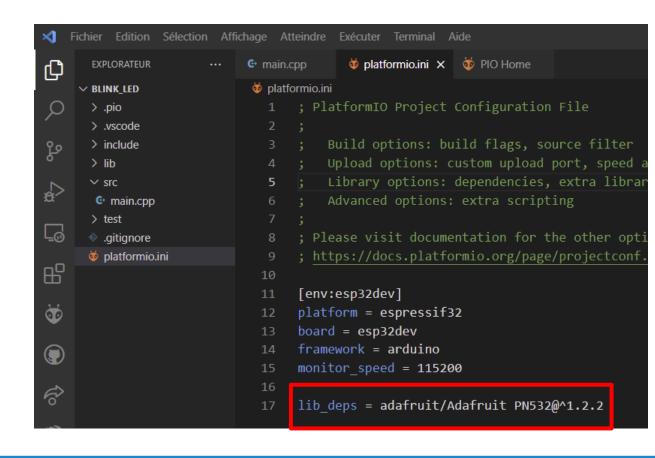


- Click on the library you want to include in your project. Then, click Add to Project.
- Select the project where you want to use the library.



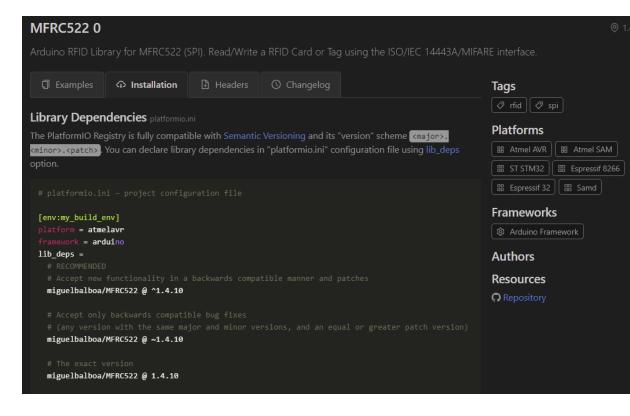
Installing ESP32 Libraries

This will add the library identifier using the lid_deps directive on the platformio.ini file.



Installing ESP32 Libraries

Alternatively, on the library window, if you select the Installation tab and scroll a bit, you'll see the identifier for the library. You can choose any of those identifiers depending on the options you want to use.



Installing ESP32 Libraries

Alternatively, on the library window, if you select the Installation tab and scroll a bit, you'll see the identifier for the library. You can choose any of those identifiers depending on the options you want to use.

https://registry.platformio.org/

https://registry.platformio.org/libraries/mig uelbalboa/MFRC522

- If you need multiple libraries, you can separate their name by a coma or put them on different lines.
- After installing the MFRC532 library, go to Examples;

```
; Please visit documentation for the other options and examples
; https://docs.platformio.org/page/projectconf.html

[env:esp32dev]
platform = espressif32
board = esp32dev
framework = arduino
monitor_speed = 115200
lib_deps =

marcoschwartz/LiquidCrystal_I2C @ ^1.1.4
adafruit/Adafruit PN532@^1.2.2
```

Libraries / SPI communication

- The code starts by including the needed libraries
- As we're going to use SPI communication you need to change the pin definition to use the ESP32 GPIOs.

```
#include <SPI.h>
#include <Wire.h>
#include <MFRC522.h>

#define SCK 18
#define MISO 19
#define MOSI 23
#define CS 5

#define RST_PIN 4
#define SS_PIN 2

MFRC522 mfrc522(SS_PIN, RST_PIN);
```

SPI	MOSI	MISO	CLK	cs
HSPI	GPIO 13	GPIO 12	GPIO 14	GPIO 15
VSPI	GPIO 23	GPIO 19	GPIO 18	GPIO 5

ESP 32 Wi-Fi connection

• In the setup() you add the sensor initialization:

```
SPI.begin(); // Init SPI bus
mfrc522.PCD_Init(); // Init MFRC522
```

In the loop() you add the following code:

```
if (mfrc522.PICC_IsNewCardPresent()) // RFID read here
{
   if (mfrc522.PICC_ReadCardSerial())
   {
      idcard = "";
      for (byte i = 0; i < mfrc522.uid.size; i++) {
        idcard +=(mfrc522.uid.uidByte[i] < 0x10 ? "0" : "")
        + String(mfrc522.uid.uidByte[i], HEX);
    }
      Serial.println("tag rfid :" + idcard);
      mfrc522.PICC_HaltA();
      mfrc522.PCD_StopCrypto1();
   }
}</pre>
```

ESP 32 Wi-Fi connection

• The first thing you need to do to use the ESP32 Wi-Fi functionalities is to include the WiFi.h library in your code, as follows:

#include <WiFi.h>

- This library is automatically "installed" when you start a new project with an ESP32 board in VS Code + PlatformIO.
- The ESP32 board can act as Wi-Fi Station, Access Point or both. To set the Wi-Fi mode, use WiFi.mode() and set the desired mode as an argument:

WiFi.mode(WIFI_STA)	station mode: the ESP32 connects to an access point
WiFi.mode(WIFI_AP)	access point mode: stations can connect to the ESP32
WiFi.mode(WIFI_STA_AP)	access point and a station connected to another access point

ESP 32 Wi-Fi connection

ESP32

(STATION)

- When the ESP32 is set as a Wi-Fi station, it can connect to other networks (like your router).
- In this scenario, the router assigns a unique IP address to your ESP board.
- You can communicate with the ESP using other devices (stations) that are also connected to the same network by referring to the ESP unique IP address.

Router (ACCESS POINT) Wi-Fi Client (STATION)

Wi-Fi Client

(STATION)

ESP 32 Wi-Fi connection

- To connect the ESP32 to a specific Wi-Fi network, you must know its SSID and password.
- Additionally, that network must be within the ESP32 Wi-Fi range.
- You can use the following function to connect the ESP32 to a Wi-Fi network.

```
1 void initWiFi() {
2  WiFi.mode(WIFI_STA);
3  WiFi.begin(ssid, password);
4  Serial.print("Connecting to WiFi ..");
5  while (WiFi.status() != WL_CONNECTED) {
6   Serial.print('.');
7   delay(1000);
8  }
9  Serial.println(WiFi.localIP());
10 }
```

Set a Static ESP32 IP Address

- Instead of getting a randomly assigned IP address, you can set an available IP address of your preference to the ESP32 using WiFi.config().
- Outside the setup() and loop() functions, define the following variables with your own static IP address and corresponding gateway IP address.
- By default, the following code assigns the IP address 192.168.1.184 that works in the gateway 192.168.1.1.

```
// Set your Static IP address
IPAddress local_IP(192, 168, 1, 184);
// Set your Gateway IP address
IPAddress gateway(192, 168, 1, 1);

IPAddress subnet(255, 255, 0, 0);
IPAddress primaryDNS(8, 8, 8, 8); // optional
IPAddress secondaryDNS(8, 8, 4, 4); // optional
```

Set a Static ESP32 IP Address

- Then, in the setup() you need to call the WiFi.config() method to assign the configurations to your ESP32.
- The primaryDNS and secondaryDNS parameters are optional and you can remove them.

```
// Configures static IP address
if (!WiFi.config(local_IP, gateway, subnet, primaryDNS, secondaryDNS)) {
   Serial.println("STA Failed to configure");
}
```

Reconnect to Wi-Fi Network: After Losing Connection

- To reconnect to Wi-Fi after a connection is lost, we can use WiFi.reconnect() to try to reconnect to the previously connected access point:
- Or, we can call WiFi.disconnect() followed by WiFi.begin(ssid,password).
- In the loop() we can check once in a while if the board is connected.

```
unsigned Long currentMillis = millis();
// if WiFi is down, try reconnecting
if ((WiFi.status() != WL_CONNECTED) && (currentMillis - previousMillis >=interval)) {
    Serial.print(millis());
    Serial.println("Reconnecting to WiFi...");
    WiFi.disconnect();
    WiFi.reconnect();
    previousMillis = currentMillis;
    unsigned Long previousMillis = 0;
    unsigned Long interval = 30000;
}
```

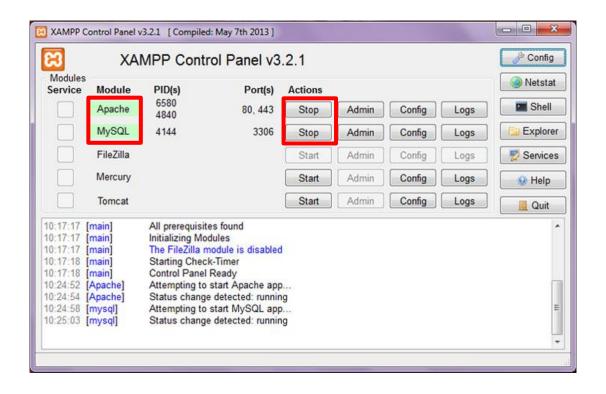
Connection to database

- In this tutorial, we will build an ESP32 client that sends an HTTP POST request to a PHP script to insert data (sensor readings) into a MySQL database.
- You'll also have a web page that displays the sensor readings, timestamps and other information from the database. You can visualize your data from anywhere in the world by accessing your own server.
- As an example, we will use an RFID reader connected to an ESP card.
 You can change the code provided to send readings from another sensor or use multiple cards.
- In order to create and build this project, you'll use these technologies:
 - ✓ ESP32 programmed with PlatformIO / Arduino IDE / etc ...
 - ✓ Hosting server and domain name
 - ✓ PHP script to insert data into MySQL and display it on a web page
 - **✓** MySQL database to store readings

ESP 32 connection to database

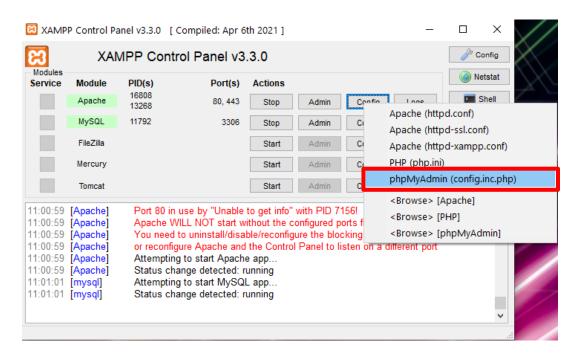
XAMPP server installation

- Uncheck the Learn more about bitnami option and click Next button.
- Choose the root directory path to set up the htdocs folder for our applications. For example, 'C:\xampp'.
- Click the Allow access button to allow the XAMPP modules from the Windows firewall.
- After the installation process, click the Finish button of the XAMPP Setup wizard.
- Now the XAMPP icon is clearly visible on the right side of start menu. Show or Hide can be set by using the control panel by clicking on the icon.
- To start Apache and MySql, just click on the Start button on the control panel.



ESP 32 connection to database

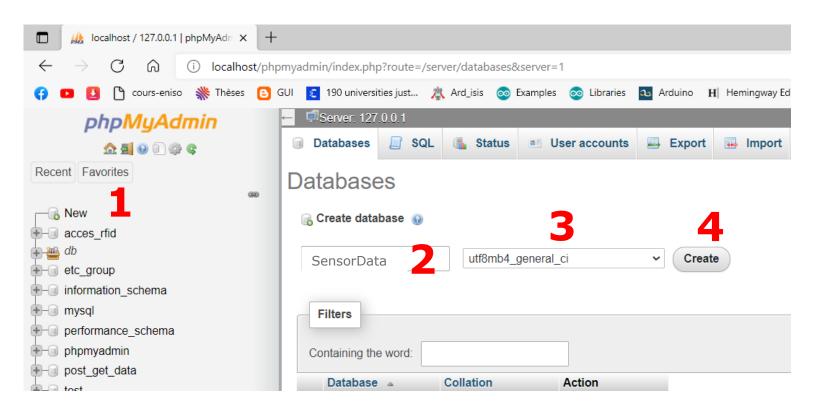
change password



```
/* Authentication type and info */
$cfg['Servers'][$i]['auth_type'] = 'config';
$cfg['Servers'][$i]['user'] = 'ESP32';
$cfg['Servers'][$i]['password'] = 'esp32io.com';
$cfg['Servers'][$i]['extension'] = 'mysqli';
$cfg['Servers'][$i]['AllowNoPassword'] = true;
$cfg['Lang'] = '';
/* Bind to the localhost ipv4 address and tcp */
$cfg['Servers'][$i]['host'] = '127.0.0.1';
$cfg['Servers'][$i]['connect type'] = 'tcp';
/* User for advanced features */
$cfg['Servers'][$i]['controluser'] = 'ESP32';
$cfg['Servers'][$i]['controlpass'] = 'esp32io.com';
/* Advanced phpMyAdmin features */
$cfg['Servers'][$i]['pmadb'] = 'phpmyadmin';
$cfg['Servers'][$i]['bookmarktable'] = 'pma bookmark';
$cfg['Servers'][$i]['relation'] = 'pma relation';
```

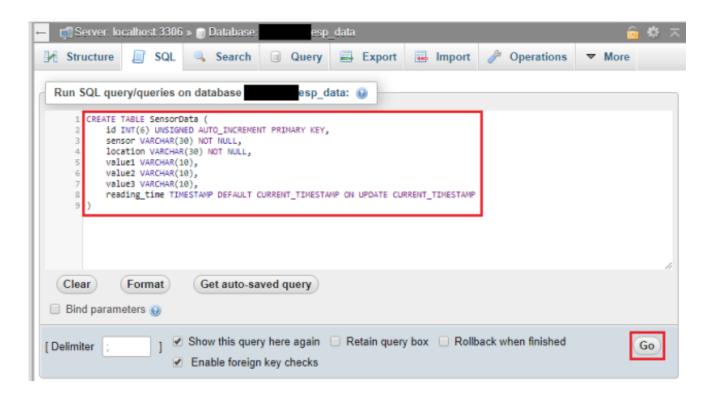
ESP 32 connection to database

Create a new data base



ESP 32 connection to database

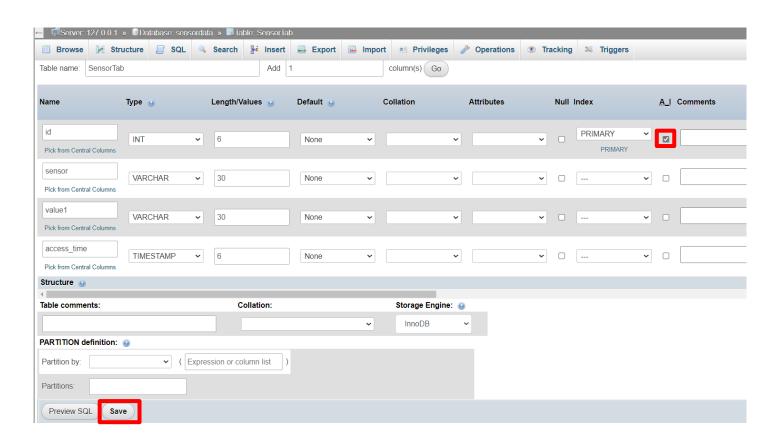
Create Table Procedure 1:

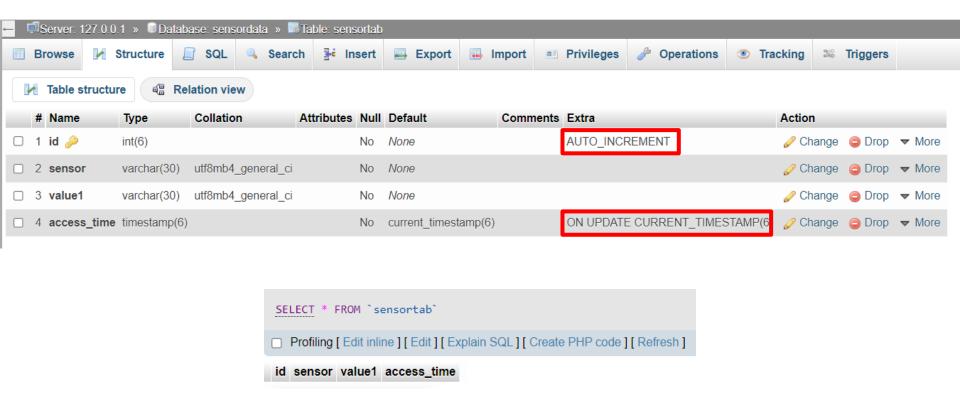


ESP 32 connection to database

Create Table Procedure 2:

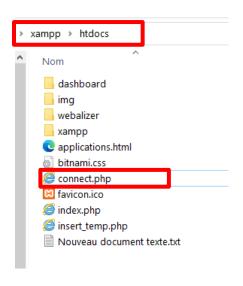






ESP 32 connection to database

Save php file in htdoc Folder



```
class Database {
    private static $dbName = 'db sensor' ;
    private static $dbHost = 'localhost' ;
    private static $dbUsername = 'root';
    private static $dbUserPassword = '';
    private static $cont = null;
   public function construct() {
        die('Init function is not allowed');
    public static function connect() {
         // One connection through whole application
       if ( null == self::$cont ) {
                    self::$cont = new PDO( "mysql:host=".self::$dbHost.";"."dbname=".self::$dbName,
                         self::$dbUsername, self::$dbUserPassword);
                catch(PDOException $e) {
                    die($e->getMessage());
       return self::$cont;
    public static function disconnect() {
        self::$cont = null;
```

ESP 32 connection to database

 Create a new file in xampp/htdoc with this exact name and extension: post_sensor_data.php

- Now we return to the Vs code.
- we need to add some libraries to connect to the wifi and make http requests to access the database. we can use separate files to lighten the main code.
 - ➤ Add #include "main_function.h"
- In the main_fuction file, we find these libraries

```
#include <WiFiClient.h>
#include <HTTPClient.h>
#include <WiFiUdp.h>
#include <NTPClient.h> //https://github.com/taranais/NTPClient
```

- Download the NTPClient library from the given link.
- Extract it and put it in your_project/lib folder.
- Make sure that the library that you download contain the .h file in first folder which corresponds to #include <NTPClient.h> (VsCode rule).

ESP 32 connection to database

In the main.cpp file, make sure that all these libraries are included.

```
#include <Arduino.h> #include <string.h> #include <WiFi.h> #include <WiFi.h> #include <Wire.h> #include <MFRC522.h> #include "main_function.h"
```

Define the host variable in which you put your ip address

```
const char *host = "http://your-ip-adress/";
```

Sockets problem

If there is a socket problem, follow the steps in this link

https://windowsreport.com/windows-sockets-registry-entries-required-for-network-connectivity-are-missing/#2

- OTA (Over-the-Air) update using the AsyncElegantOTA library is the process of loading new firmware to the ESP32 board using a Wi-Fi connection rather than a serial communication.
- This functionality is extremely useful in case of no physical access to the ESP32 board.
- The Async Elegant OTA library creates a web server that allows the update of new firmware (a new sketch) to the ESP32 board without the need to make a serial connection between the ESP32 and the computer.
- Additionally, with this library, we can also upload new files to the ESP32 filesystem (SPIFFS).
- The files you upload should be in .bin format.

ESP32 OTA (Over-the-Air) Updates

To add OTA capabilities to your projects using the AsyncElegantOTA library, follow these steps:

1. Iclude

the <u>AsyncElegantOTA</u>, <u>AsyncTCP</u> and <u>ESPAsyncWebServer</u> libraries in the platformio.ini file of your project;

lib_deps = ESP Async WebServer ayushsharma82/AsyncElegantOTA @ ^2.2.5

ESP32 OTA (Over-the-Air) Updates

2. Include AsyncElegantOTA library at the top of the code:

```
#include <AsyncTCP.h>
#include <ESPAsyncWebServer.h>
#include <AsyncElegantOTA.h>
AsyncWebServer server(80);
```

3. Add this line

AsyncElegantOTA.begin(&server); before server.begin();

- The first sketch should be uploaded via the serial port.
- This sketch should contain the code to create the OTA Web Updater so that you are able to upload the code later using your browser.
- The OTA Web Updater sketch creates a web server you can access to upload a new sketch via a web browser.
- Then, you need to implement OTA routines in every sketch you upload, so that you're able to do the next updates/uploads over-the-air.
- If you upload a code without an OTA routine, you'll no longer be able to access the web server and upload a new sketch over-the-air.

- In the local network, open the browser and type the ESP32 IP address.
- We should get access the root (/) web page with some text displayed.



- 4. Open the browser and go to http://<IPAddress>/update, where <IPAddress> is the ESP32 IP address.
 - The following web page should load.
 - VS Code automatically generates the .bin file for the project every code compilation.
 - The file is called firmware.bin and it is saved in this root.
 - .pio/build/esp32doit-devkitv1/firmware.bin

