MAXIMUM A POSTERIORI PRINCIPLE (MAP)

- BAYESIAN IN NATURE
- GOAL IS TO ESTIMATE PARAMETER & OF A DISTRIBUTION
 P(0) FROM A SET OF DATA POINTS &.
- PMAP = ARG MAX P(Old)
- P(0/00) = POSTERIOR BELIEF, GIVEN OBSERVATIONS
- OMAP = ARG MAX P(& O) P(O)

WHERE P(0) = PRIOR BELIEF.

DOSERVATION
$$G_{MAP} = ARG_{MAX} P(G|G)P(G)$$

PROOF: $G_{MAP} = ARG_{MAX} P(G|G)P(G)$

$$= ARG_{MAX} P(G|G)P(G)$$

$$G_{MAP} = ARG_{MAX} P(G|G)P(G)$$

IF COSERVATIONS ARE INDEPENDENT, THEM

$$P(G_{MAP}, G_{MAX}, G_{MAX$$

EXAMPLE

BERNOULLI DISTRIBUTION: bx (x; b) = p(1-p); p>0; x=0,1

BETA DISTRIBUTION:

TBETA (P; a, b) = 1 B(a, b) pa-1 (1-p) ; 0 0

 $B(a,b) = \frac{\Gamma(a)\Gamma(b)}{\Gamma(a+b)} = BETA FUNCTION$

T(t) = Soctol = doc; Re(t) >0; = GAMMA FUNCTION

(m) = (m-1)! ; m = TD TP = {1,2,3, -.. }

= SET OF POSITIVE INTEGERS

TC) FUNCTION IS A GENERALIZATION OF FACTORIAL FUNCTION FOR POSITIVE REAL NUMBERS

D = {21, 22, -.. , 2 = DATA SET

P(xi | b) = pxi (1-p) - xi

P(b) = 1 B(a,b) pa-1 (1-p)6-1

P (| ω) α P (ω | p) P (p)

2 PROPORTIONAL

THAT IS, P(| ω) α { π | p α (1-p) | p | (1-p) | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1 | 1-1

PMAP = ARG MAX { = (2: lup + (1-2:) lu (1-b))

+ (a-1) lup + (b-1) lu (1- p) }

$$\frac{\partial x}{\partial y} = \frac{x_i}{\sum_{i=1}^{n} \left(\frac{x_i}{p} + \frac{(1-x_i)(-1)}{(1-p)}\right)} + \frac{(a-1)}{p} + \frac{(b-1)(-1)}{(1-p)} = 0$$

$$\frac{s}{p} = \frac{(m-s)}{(1-p)} + \frac{(a-1)}{p} + \frac{(b-1)}{(1-p)} = 0$$

$$b = \frac{s+a-1}{n+a+b-2}$$

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PRIOR DISTRIBUTION: THIS DISTRIBUTION IS ALSO NORMAL:

THIS IS EQUIVALENT TO MINIMIZING THE FOLLOWING FUNCTION OF M.

$$g'(\mu) = \frac{2}{\beta^2} (\mu - \nu) + \frac{2}{\sigma^2} \sum_{i=1}^{M} (x_i - \mu) (-i) = 0$$

$$\Rightarrow \hat{\mu}_{MAP} = \frac{3^2 \sum_{i=1}^{m} x_i + 5^2}{n \beta^2 + 5^2}$$