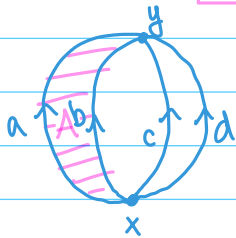


$$C_*(X): 0 \leftarrow C_0(X) \leftarrow C_1(X) \leftarrow C_2(X) \leftarrow \dots$$

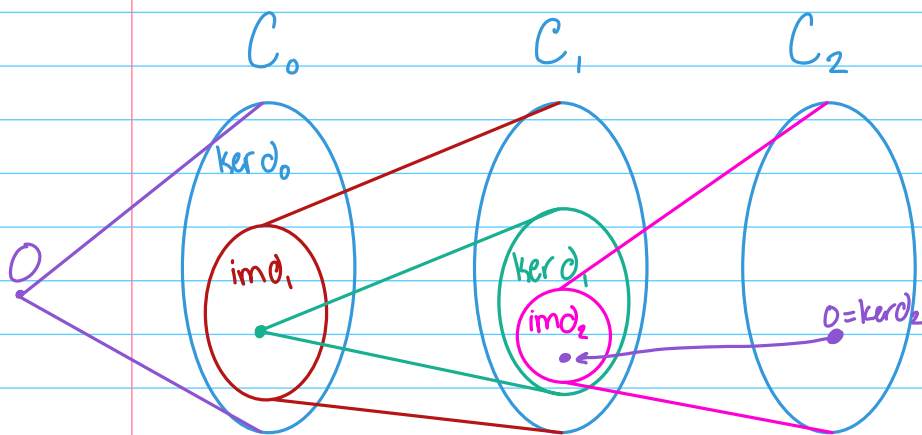
$$C_*(X_1): 0 \leftarrow \overset{x,y}{\mathbb{R}^2} \leftarrow \overset{a,b,c,d}{\mathbb{R}^4} \leftarrow 0$$

$$X_2: \text{add in } \boxed{2\text{-cell } A}. \quad C_*(X_2): 0 \leftarrow \overset{x,y}{\mathbb{R}^2} \leftarrow \overset{a,b,c,d}{\mathbb{R}^4} \leftarrow \overset{A}{\mathbb{R}}$$



for X_2 , $d_1 = \begin{bmatrix} 1 & -1 & -1 & -1 \\ -1 & 1 & 1 & 1 \end{bmatrix}$ same as X_1
But we now have $d_2: C_2 \rightarrow C_1$

$$d_2(A) = a - b \quad d_2 = \begin{bmatrix} 1 \\ -1 \\ 0 \\ 0 \end{bmatrix}$$



$$\ker d_0 = \mathbb{R}^2$$

$$\operatorname{im} d_1 = \mathbb{R}^4$$

$$\ker d_1 = \mathbb{R}^3$$

$$\operatorname{im} d_2 = \mathbb{R}^1$$

$$\ker d_2 = 0$$

$$\operatorname{im} d_3 = 0$$

$$\frac{\ker d_0}{\operatorname{im} d_1} = \mathbb{R}$$

$$\frac{\ker d_1}{\operatorname{im} d_2} = \mathbb{R}^2$$

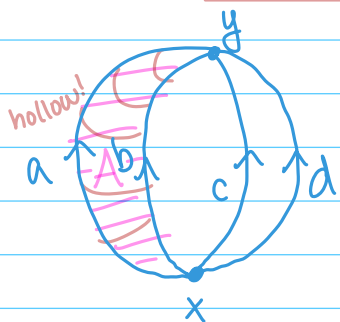
$$\frac{\ker d_2}{\operatorname{im} d_3} = 0$$

$$H_0(X_2) \cong \mathbb{R} \quad H_1(X_2) \cong \mathbb{R}^2 \begin{matrix} b-c \\ c-d \end{matrix} \quad H_2(X_2) = 0$$

Compare:

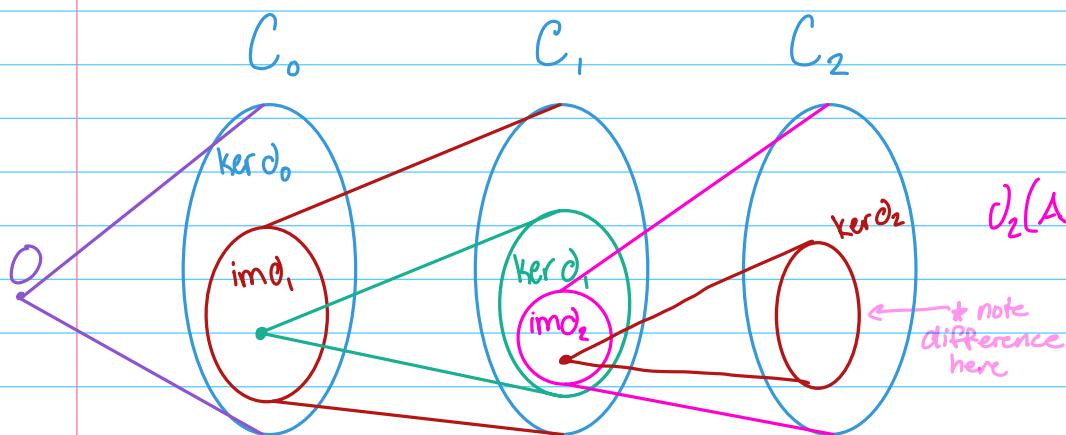
$$H_0(X_1) = \mathbb{R} \quad H_1(X_1) = \mathbb{R}^3 \begin{matrix} a-b \\ b-c \\ c-a \end{matrix}$$

X_3 : add in 2-cell B (along a, b just like A)



$$C_*(X_3): 0 \leftarrow \overset{x, y}{\mathbb{R}^2} \leftarrow \overset{a, b, c, d}{\mathbb{R}^4} \leftarrow \overset{A, B}{\mathbb{R}^2}$$

$$d_2(B) = a - b \quad d_2 = \begin{bmatrix} 1 & -1 \\ 0 & 0 \end{bmatrix}$$



$$d_2(A - B) = (a - b) - (a - b) = 0$$

* note difference here

$$\ker d_0 = \mathbb{R}^2$$

$$\text{im } d_1 = \mathbb{R}^4$$

$$\ker d_1 = \mathbb{R}^3$$

$$\text{im } d_2 = \mathbb{R}^1$$

$$\ker d_2 = \cancel{\mathbb{R}^1}$$

$$\text{im } d_3 = 0$$

$$\frac{\ker d_0}{\text{im } d_1} = \mathbb{R}$$

$$\frac{\ker d_1}{\text{im } d_2} = \mathbb{R}^2$$

$$\frac{\ker d_2}{\text{im } d_3} = 0$$

$$H_0(X_2) \cong \mathbb{R} \quad H_1(X_2) \cong \mathbb{R}^2 \begin{matrix} b-c \\ c-d \end{matrix} \quad H_2(X_2) = 0 \quad H_3(X_3) \cong \mathbb{R}^1$$

Compare:

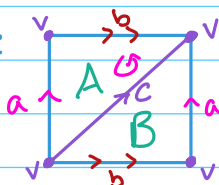
$$H_0(X_1) = \mathbb{R} \quad H_1(X_1) = \mathbb{R}^3 \begin{matrix} a-b \\ b-c \\ c-a \end{matrix}$$

Ex

$$H_n(S^n) \cong \mathbb{R} \quad (\text{what about lower dim? TBC'd})$$

Ex

Torus:



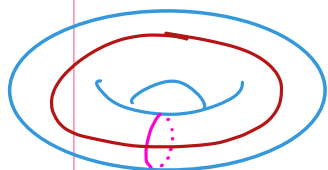
$$d_2(A) = -a + c - b$$

$$C_*(T): 0 \leftarrow C_0(T) \leftarrow C_1(T) \leftarrow C_2(T) \leftarrow 0$$

$$0 \leftarrow \mathbb{R} \xleftarrow{d_1} \mathbb{R}^3 \xleftarrow{d_2} \mathbb{R}^2 \leftarrow 0$$

$$d_1: [0 \ 0 \ 0]$$

$$d_2: \begin{matrix} a \\ b \\ c \end{matrix} \begin{bmatrix} A & B \\ -1 & 1 \\ 1 & -1 \end{bmatrix}$$



$$\begin{array}{lll} \ker d_0 = \mathbb{R} & \ker d_1 = \mathbb{R}^3 & \ker d_2 = \mathbb{R} \\ \text{im } d_1 = 0 & \text{im } d_2 = \mathbb{R} & \text{im } d_3 = 0 \\ H_0(T) = \mathbb{R} & H_1(T) = \mathbb{R}^2 & H_2(T) = \mathbb{R} \end{array}$$

Def: A chain complex of vector spaces is

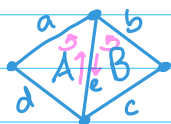
$$\dots \leftarrow C_{n-1} \xleftarrow{d_n} C_n \xleftarrow{d_{n+1}} C_{n+1} \leftarrow \dots$$

such that

$$d^2 = 0 \quad (d_n \circ d_{n+1} = 0 \quad \forall n)$$

Note: This means $\text{im } d_{n+1} \subseteq \ker d_n$

The homology of a chain complex is \ker / im



Intuitively, $d(A+B)$ ought to be $a+b+c+d$.
But $d(A) = a+e+d$
 $d(B) = b+e+c$
and we want d to be linear.

But then we'd get
 $d(A+B) = a+b+c+d+2e$

Sol'n: introduce "orientation"
(or order) in a way
that makes e 's cancel

Def: A singular n -simplex of a space X is a map $\Delta^n \rightarrow X$

$$(\Delta^n = \{(t_0, \dots, t_n) \mid \sum t_i = 1, t_i \geq 0, \forall i\})$$

Ex: $\Delta^0 = \{1\}$, so any
function $\Delta^0 \rightarrow X$ just
picks a point out in X .

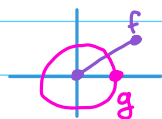
So, the set of singular 0-simplices of X
is basically just X .

Ex: $\Delta^1 = \{(t, 1-t) \mid 0 \leq t \leq 1\} \subseteq \mathbb{R}^2$

A 1-simplex in X is a curve,
that is, Δ^1 is basically just $[0, 1]$ and $f: [0, 1] \rightarrow X$ is
a curve.

Ex: $f: \Delta^1 \rightarrow \mathbb{R}^2$
 $(t, 1-t) \mapsto (t, t)$

$$g(t, 1-t) = (\cos(2\pi t), \sin(2\pi t))$$



Def: The n -singular chain group of X are the (really ∞ -dimensional) vector spaces whose basis is the n -simplices of X .

(Note: in our examples so far, the simplicial chain group is a finite-dimensional subspace of the singular chain gp)