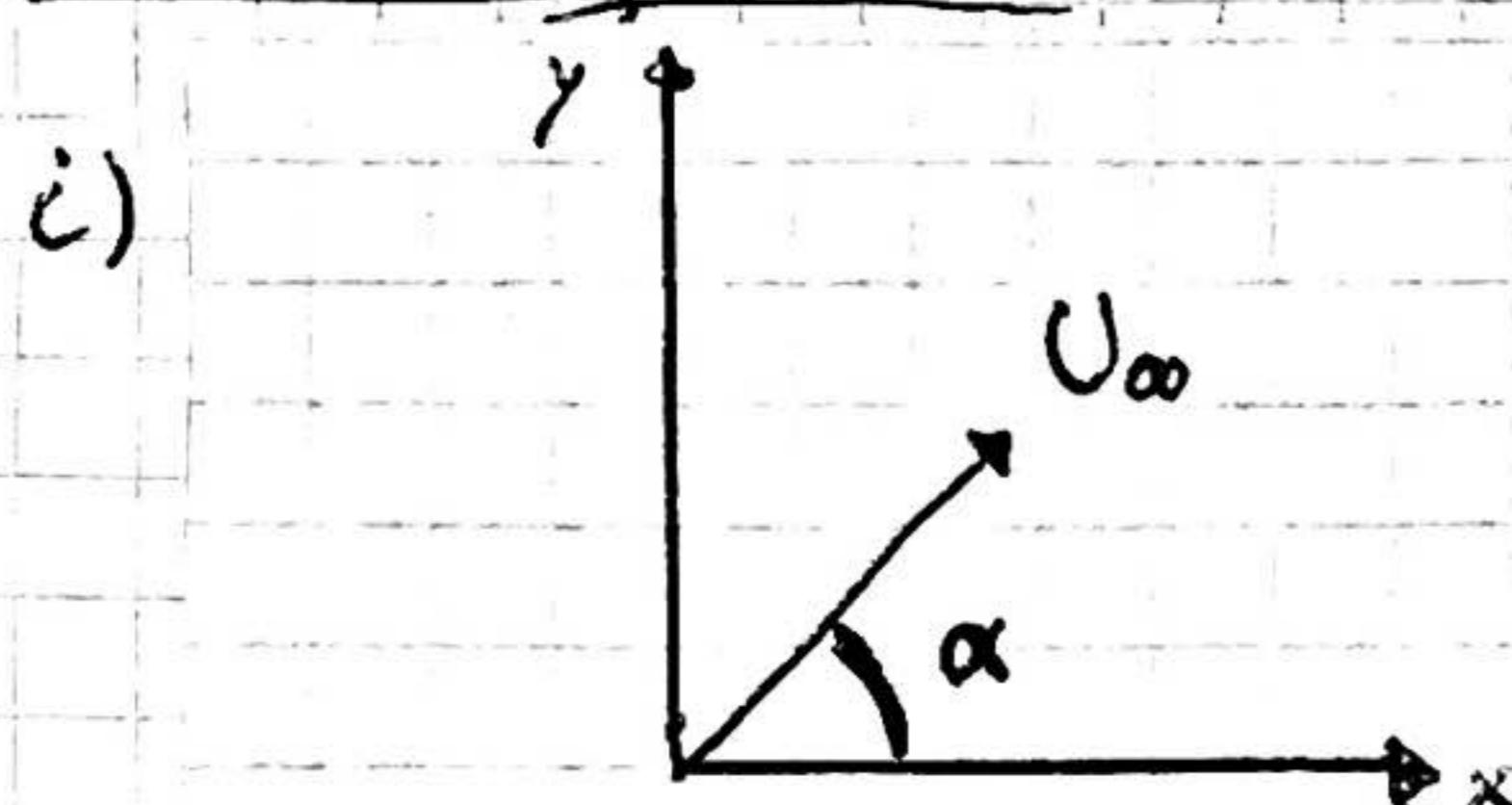


#### 4.1a) Flujos de singularidades elementales

a) campo de velocidades  $\underline{u}(x, y)$

$$b) \underline{w}(x, y) = \nabla \times \underline{u}$$

c) la función de corriente  $\psi(x, y)$  y el gráfico de las líneas de corriente.



$$a) \underline{u} = U_{\infty} \cos(\alpha) \hat{x} + U_{\infty} \sin(\alpha) \hat{y} \quad b) \nabla \times \underline{u} = 0$$

$$\text{incompresible } \frac{\partial p}{\partial t} = 0 \Rightarrow \nabla \cdot \underline{u} = 0$$

$$\text{ideal : no viscosa} \Rightarrow \exists \psi / \nabla \times \underline{\psi} = \underline{u}$$

$$\underline{w} = \nabla \times \underline{u}$$

$$\nabla \times \underline{\psi} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \psi_x & \psi_y & \psi_z \end{vmatrix} = \left( \frac{\partial \psi_z - \partial \psi_y}{\partial y} \right) \hat{x} + \left( \frac{\partial \psi_x - \partial \psi_z}{\partial z} \right) \hat{y}$$

$$\Rightarrow \underline{\psi} = (\psi_x(x, y)) \hat{z}$$

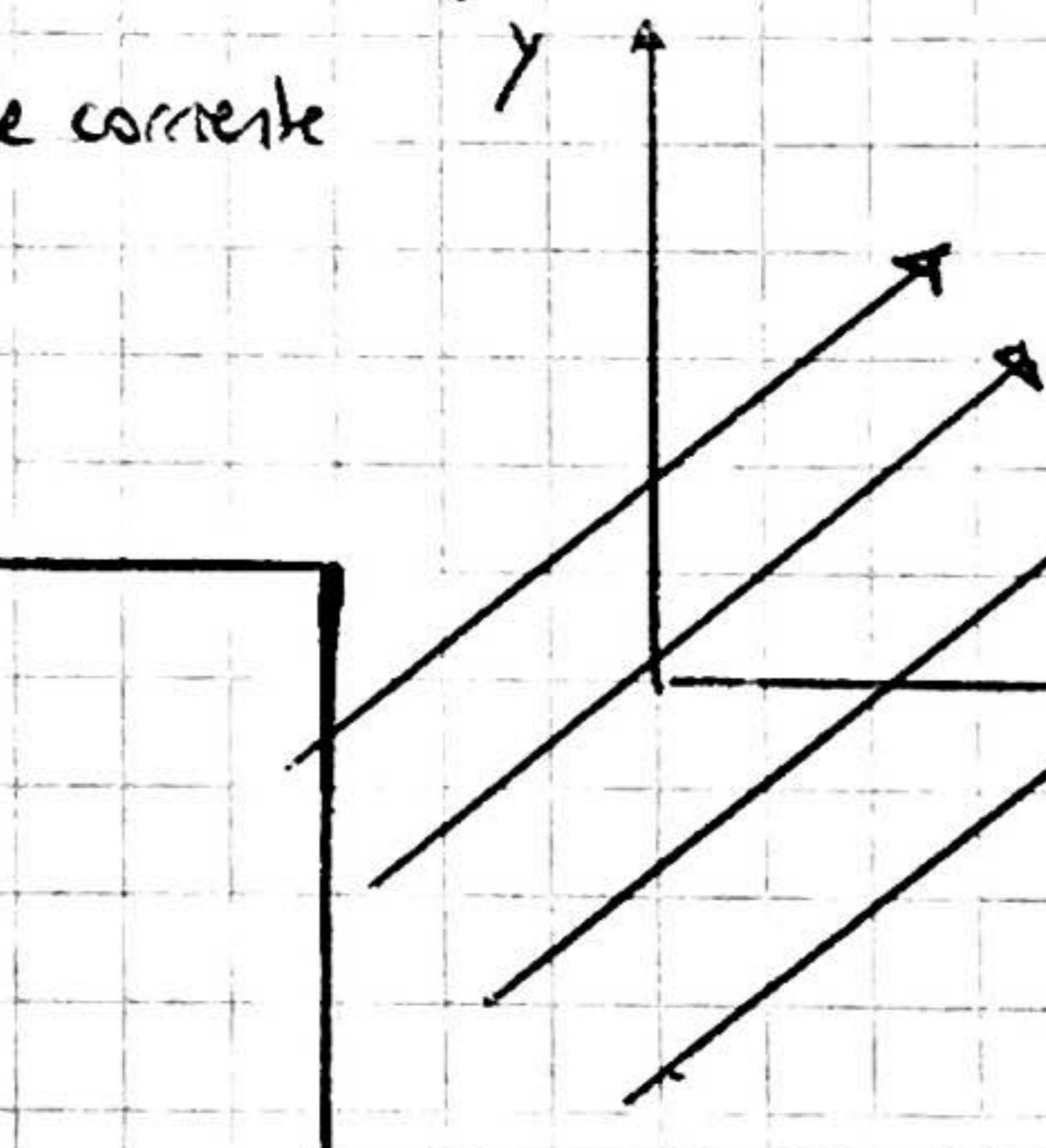
$$\partial_y \psi = U_{\infty} \cos(\alpha) - \partial_x \psi = U_{\infty} \sin(\alpha)$$

c)

$$\Rightarrow \psi(x, y) = U_{\infty} \cos(\alpha)y - U_{\infty} \sin(\alpha)x$$

Si pongo  $\psi(x, y) = \text{cte} \Rightarrow$  despejo las líneas

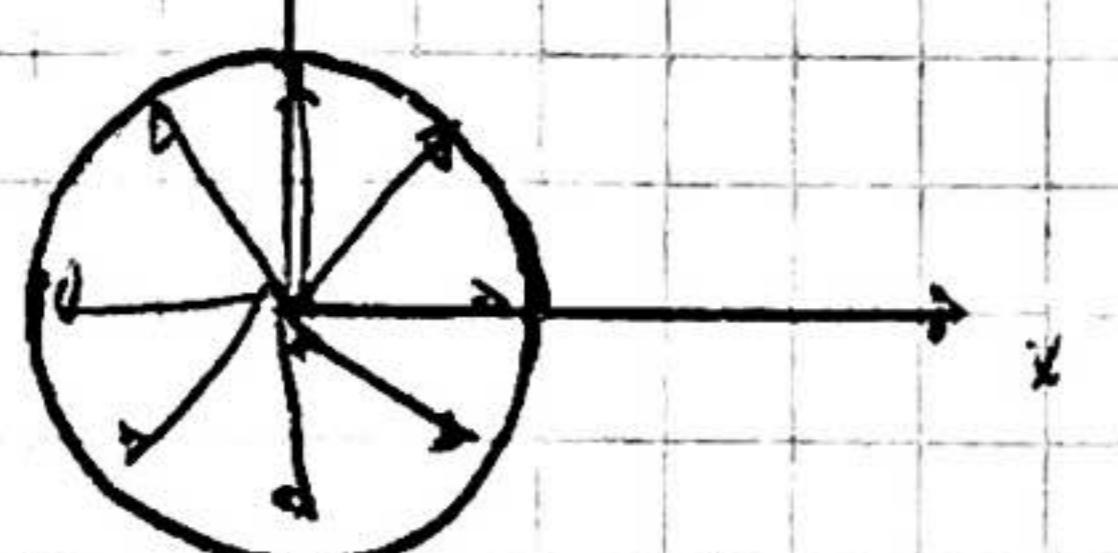
de corriente



$$Q = \int \underline{u} \cdot \hat{n} dl, \quad \hat{n} = \frac{\underline{r}}{|\underline{r}|}, \quad \hat{n} dl = d\underline{l} \times \hat{z} = r dr \hat{r}$$

$$\underline{u} = U_{\infty} \hat{z} \Rightarrow Q = \int u_r r dr \hat{r} = U_{\infty} \frac{r^2}{2} = C'$$

ii)



$$a) \underline{u} = \frac{Q}{2\pi r} \hat{r} \quad u_r = \frac{Q}{2\pi r} \quad u_\theta = 0$$

$$\nabla \times (\psi \hat{z}) = \frac{1}{r} \partial_\theta \psi \hat{r} + \partial_r \psi \hat{\theta} = \underline{u}$$

$$w = \nabla \times \underline{u} = 0$$

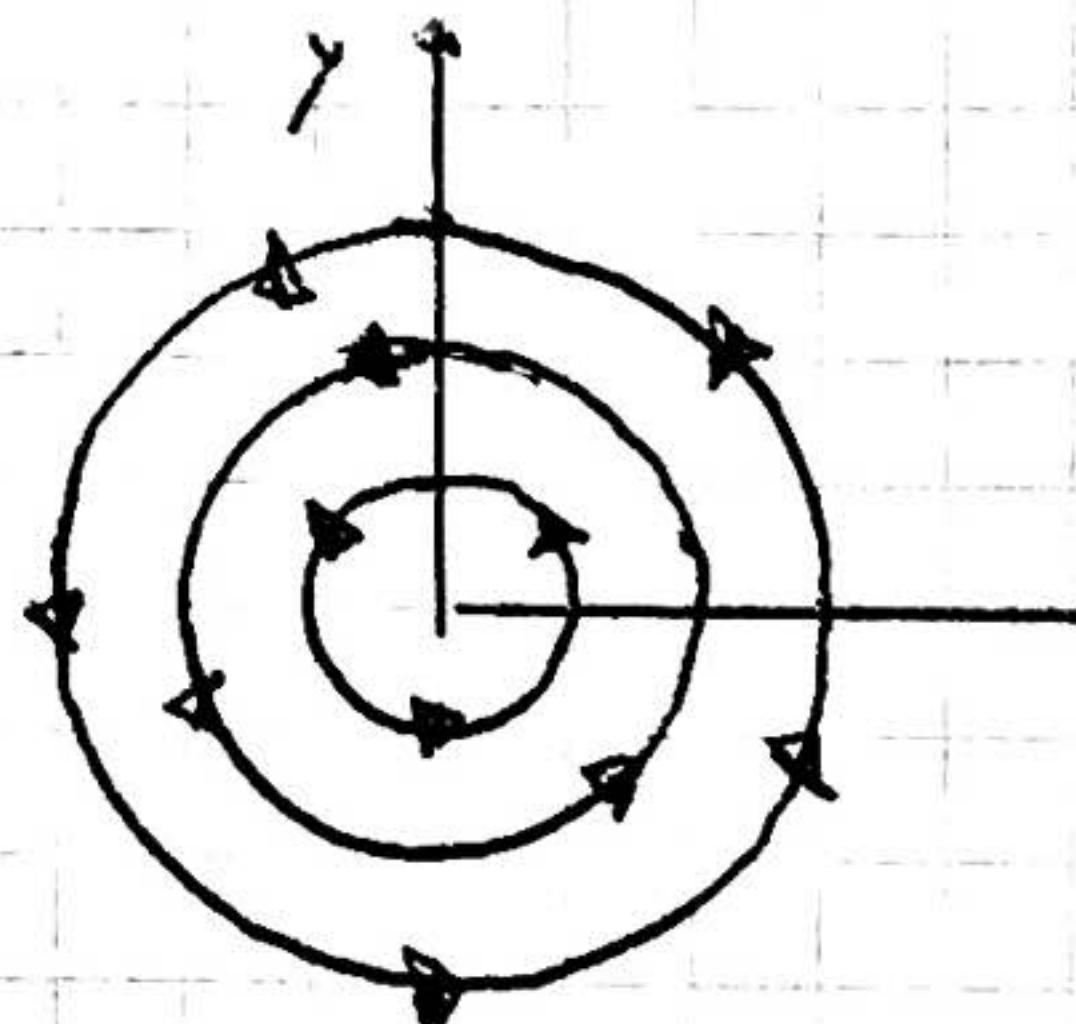
$$\Rightarrow \frac{1}{r} \partial_\theta \psi = \frac{Q}{2\pi r} \Rightarrow \psi = \frac{Q}{2\pi} \theta = \frac{Q}{2\pi} \arctan \left( \frac{y}{x} \right)$$

$$\partial_r \psi = 0 \quad \therefore \psi = \psi(r)$$

$$\underline{U} = \frac{Q}{2\pi r} \frac{\hat{r}}{r} = \frac{Q(x\hat{x} + y\hat{y})}{2\pi(x^2+y^2)} = \underline{U} = \frac{Qz}{2\pi r^2} \quad U^* = \frac{Qz^*}{2\pi r^{*2}} = \frac{Q}{2\pi z}$$

iii) vórtice de circulación  $\Gamma$

$$\underline{u} = \frac{\Gamma}{2\pi r} \hat{\theta}$$



$$\underline{w} = 0$$

$$\therefore \psi = \psi(r) = -\frac{\Gamma}{2\pi} \ln(r)$$

$$w \neq 0$$

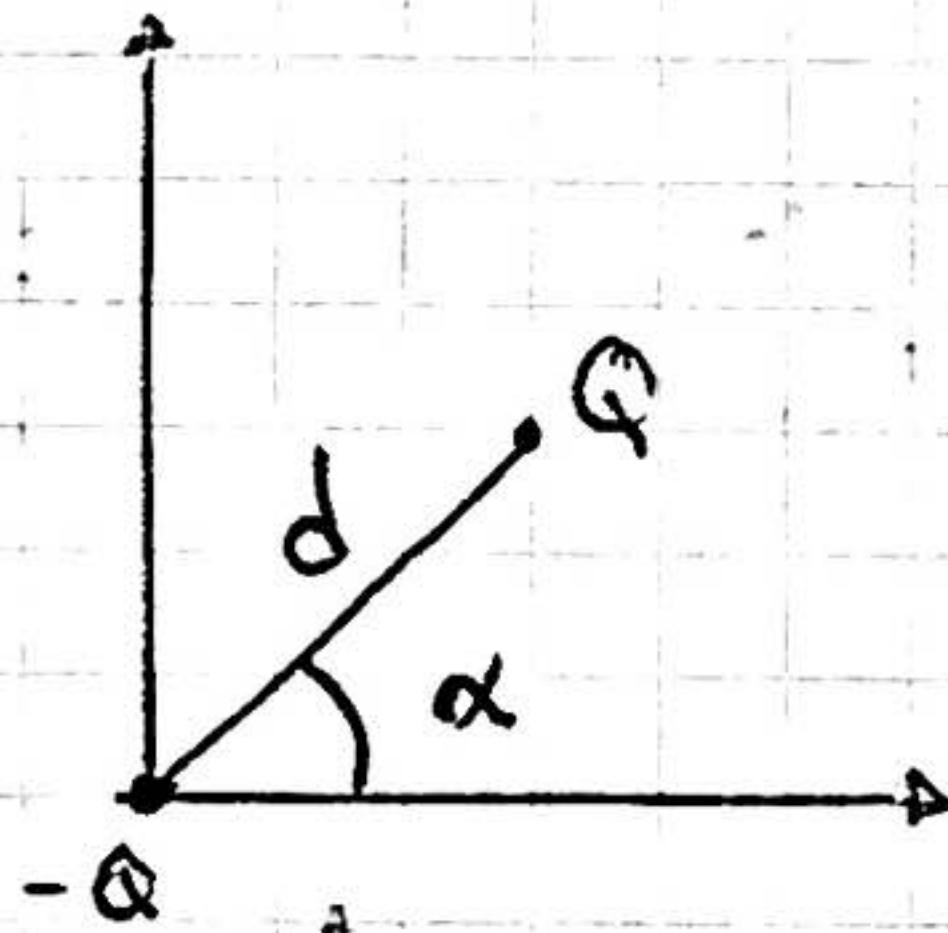
$$\underline{u} = u\hat{e}_r \quad C = \int_0^{2\pi} u\hat{e}_r r d\theta \hat{e}^* = u 2\pi r$$

$$\underline{u} = \nabla \times (\psi \hat{e})$$

$$\rightarrow \frac{1}{r} \partial_r (\psi \hat{r}) = 0 \hat{r}$$

$$-\partial_r \psi \hat{e} = \frac{\Gamma}{2\pi r} \hat{e}$$

iv)



$$\underline{u}_{-Q} = -\frac{Q}{2\pi r} \hat{r} \quad \underline{u}_Q = \frac{Q}{2\pi r} \hat{r} \quad \text{si estuvieran en el origen}$$

$$\underline{u} = \frac{Q}{2\pi} \left( -\frac{\hat{r}}{r} + \frac{\hat{r} - d(\cos\alpha)\hat{x} + d(\sin\alpha)\hat{y}}{(x - d\cos\alpha)^2 + (y - d\sin\alpha)^2} \right) = \frac{Q}{2\pi} \left[ -\frac{(x, y)}{x^2 + y^2} + \frac{(x - d\cos\alpha, y - d\sin\alpha)}{(x - d\cos\alpha)^2 + (y - d\sin\alpha)^2} \right]$$

inmóvil

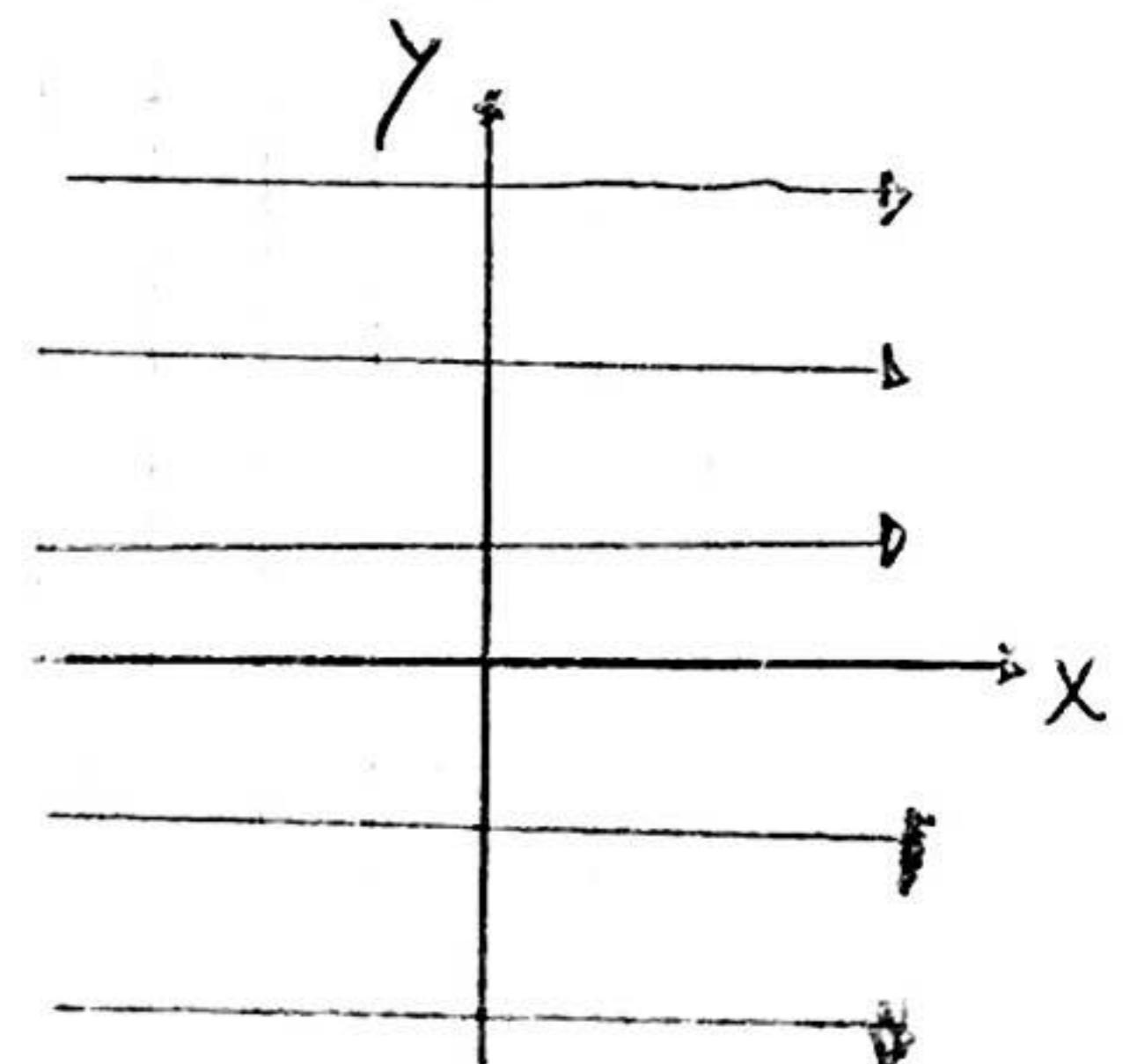
b) Calcule a)  $\underline{u}(x, y)$ ; b) puntos de estancamiento osea  $\underline{u}(x, y) = 0$

c)  $\underline{w} = \nabla \times \underline{u}$ , d) graficar líneas de corriente

$$\text{i)} \psi(x, y) = \alpha y \quad -\partial_x \psi = u_y \Rightarrow \underline{u} = \alpha \hat{x}$$

$$\partial_y \psi = u_x \quad \text{p.d.e} = \phi$$

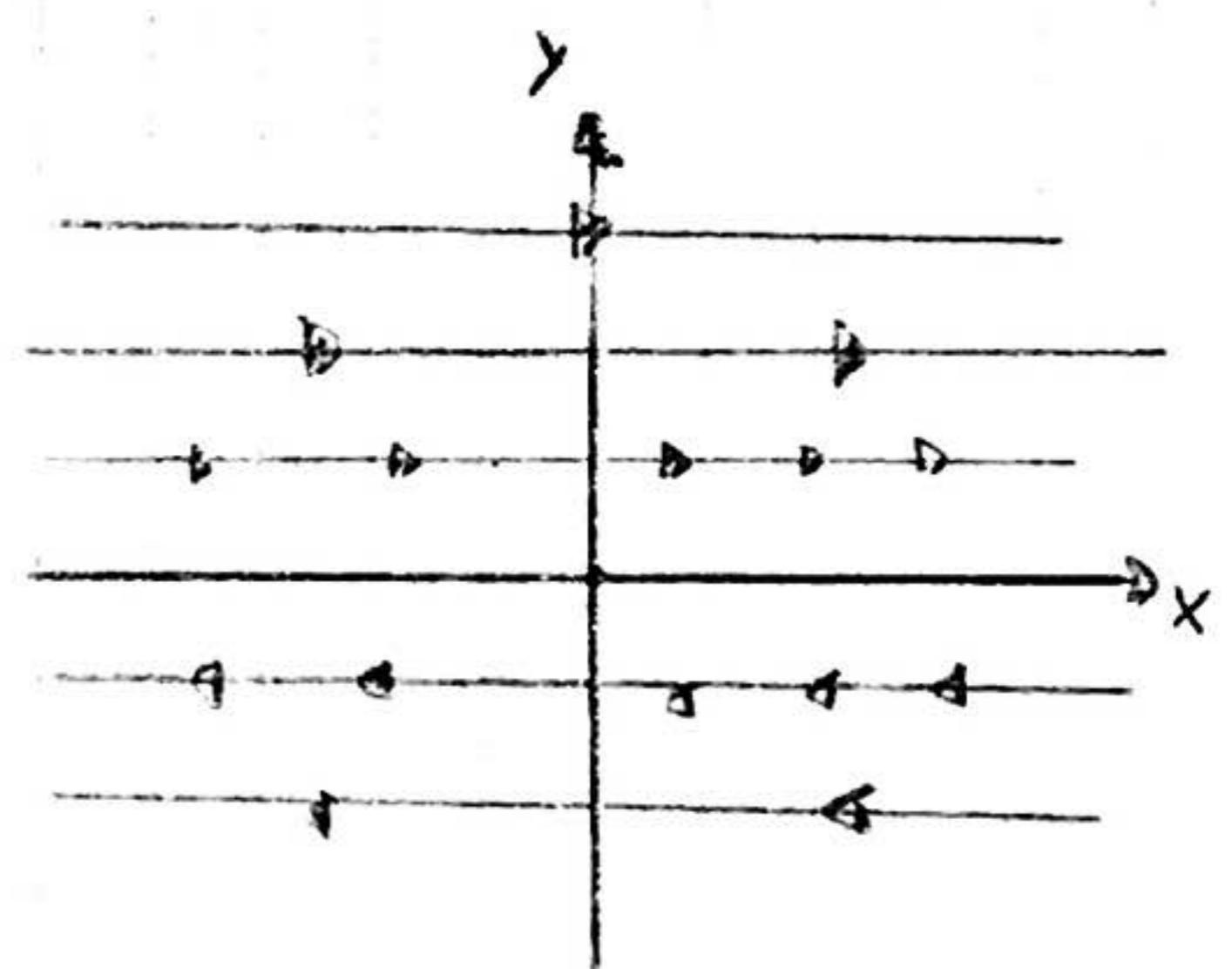
$$\underline{w} = 0$$



$$\text{ii)} \psi(x, y) = b y^2 \Rightarrow u_x = 2 b y \wedge \underline{u} = 2 b y \hat{x}$$

$$\text{p.d.e: } \{y=0\}$$

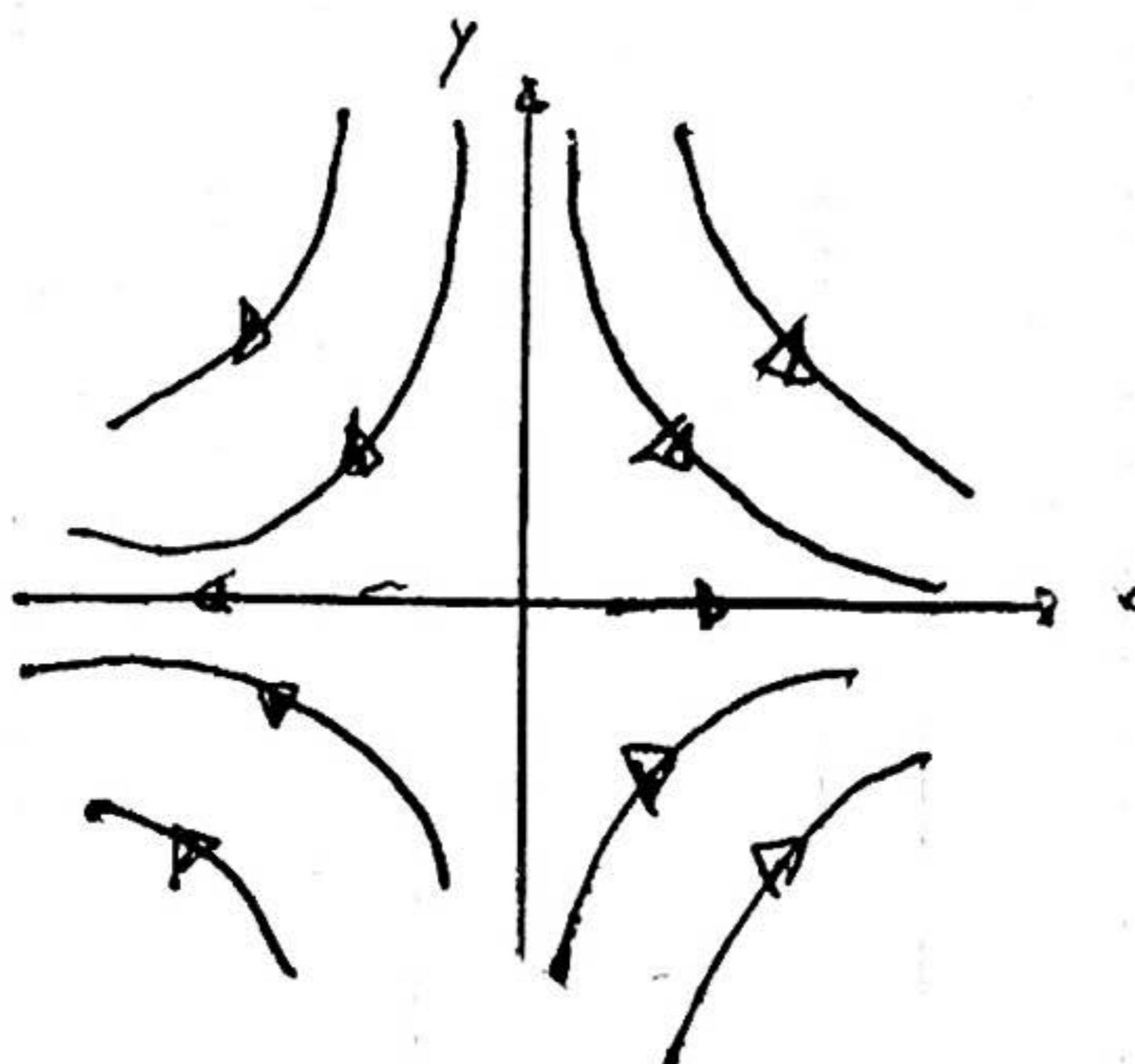
$$\underline{w} = -2 b \hat{z}$$



$$\text{iii)} \psi(x, y) = cxy \quad u_y = -\partial_x \psi = -cy \quad \Rightarrow \underline{u} = cx \hat{x} - cy \hat{y}$$

$$u_x = \partial_y \psi = cx$$

$$\text{p.d.e: } \{(x, y) = (0, 0)\} \quad \nabla \times \underline{u} = (\partial_x, \partial_y, \partial_z) \times (cx, -cy, 0) = (0, 0, 0)$$



$$\psi(x, y) = \text{cte} \Rightarrow y = \frac{C}{x}$$

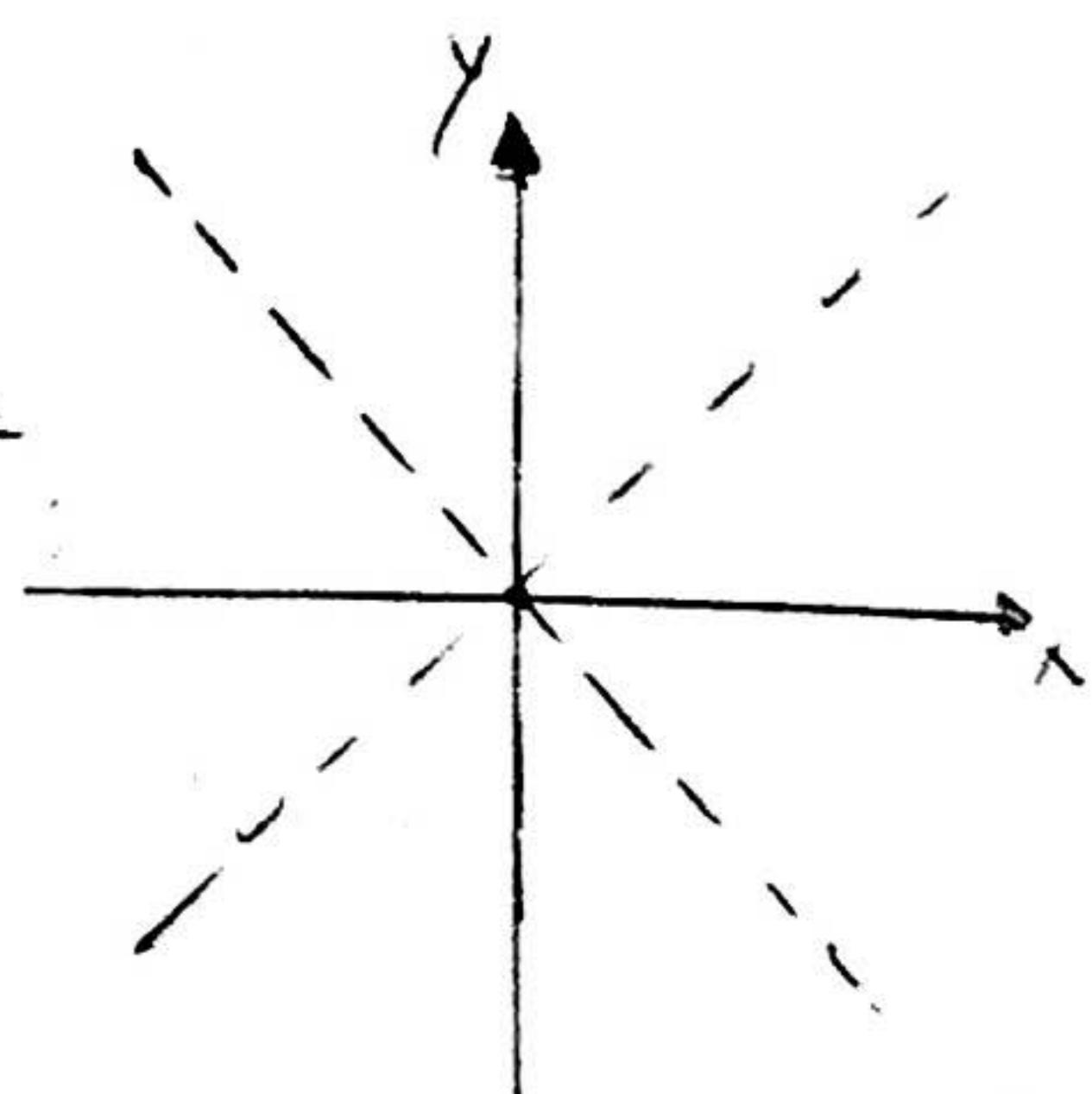
$$\text{iv)} \psi(x, y) = d(3x^2y - y^3)$$

$$\Rightarrow \underline{u} = 3d(x^2 - y^2) \hat{x} - 6dxy \hat{y}$$

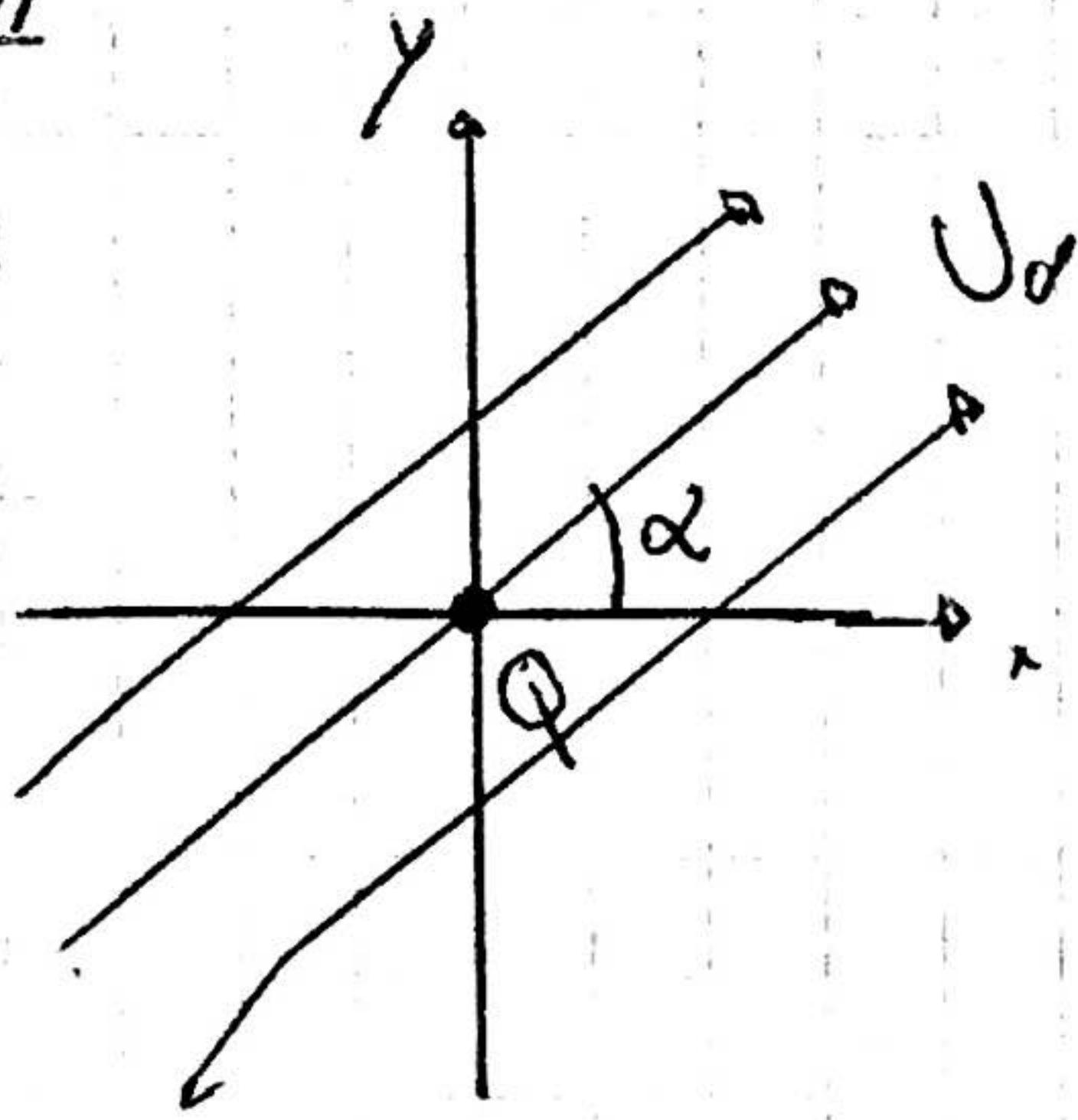
$$\text{p.d.e: } \begin{cases} x^2 = y^2 \Leftrightarrow x, y = 0 \\ x, y = 0 \end{cases}$$

$$u_y = -\partial_x \psi = -6dxy$$

$$u_x = \partial_y \psi = 3dx^2 - 3dy^2$$



6.2)



$$\psi = \psi_{U_0} + \psi_U$$

$$U_Q = \frac{Q}{2\pi r} \hat{r} \Rightarrow \frac{1}{r} \partial_r \psi \hat{r} - \partial_\theta \psi \hat{\theta} = \underline{u}$$

$$\Rightarrow \psi = \frac{Q}{2\pi} \theta$$

$$U_0 = U_{0x} \cos(\alpha) \hat{x} + U_{0y} \sin(\alpha) \hat{y}$$

$$\begin{aligned} \partial_y \psi &= u_x \\ -\partial_x \psi &= u_y \end{aligned} \Rightarrow \psi = U_{0x} \cos(\alpha) y - U_{0y} \sin(\alpha) x$$

$$\therefore \boxed{\psi = U_{0x} \cos(\alpha) y - U_{0y} \sin(\alpha) x + \frac{Q}{2\pi} \operatorname{arctg} \left( \frac{y}{x} \right)}$$

p.d.e.  $\underline{u} = \frac{Q}{2\pi(x^2+y^2)} (\hat{x} + \hat{y}) + U_{0x} \cos(\alpha) \hat{x} + U_{0y} \sin(\alpha) \hat{y}$

$$\underline{u} = 0 \Rightarrow \frac{Q}{2\pi(x^2+y^2)} x + U_{0x} \cos(\alpha) = 0 \Rightarrow \frac{Q}{2\pi(x^2+y^2)} x = -U_{0x} \cos(\alpha)$$

$$\frac{Q}{2\pi(x^2+y^2)} y + U_{0y} \sin(\alpha) = 0 \quad \frac{Q}{2\pi(x^2+y^2)} y = -U_{0y} \sin(\alpha)$$

$$\Rightarrow \frac{y}{x} = t \tan(\alpha) \quad \text{p.d.e. } \begin{cases} (x,y) \in \mathbb{R}^2 / y = t \tan(\alpha) x \\ (x,y) \neq (0,0) \end{cases}$$

$$6. \text{ i) } \underline{u} = U_0 \cos(\alpha) \hat{x} + U_0 \sin(\alpha) \hat{y}$$

$$\psi = U_0 \cos(\alpha) y - U_0 \sin(\alpha) x$$

$$\nabla \times \underline{u} = 0 \Rightarrow \exists \phi \quad \underline{u} = \nabla \phi$$

$$\phi = U_0 \cos(\alpha) \hat{x} + U_0 \sin(\alpha) \hat{y}$$

$$\rightarrow W(z) = \phi + i\psi = U_0 \cos(\alpha)(x+iy) + U_0 \sin(\alpha)(y-ix)$$

$$= U_0 \cos(\alpha)z - iU_0 \sin(\alpha)(x+iy) \Rightarrow W(z) = U_0 \cos(\alpha)z - iU_0 \sin(\alpha)z$$

$$\rightarrow W = U_0 e^{-i\alpha} z$$

$$\text{ii) } \underline{u} = \frac{\Omega}{2\pi r} \hat{r}$$

$$\psi = \frac{\Omega}{2\pi} \phi = \frac{\Omega}{2\pi} \arctg \left( \frac{y}{x} \right)$$

$$\nabla \times \underline{u} = 0 \Rightarrow \underline{u} = \nabla \phi$$

$$\Delta \phi = \frac{\partial \phi}{\partial r} + \frac{1}{r} \frac{\partial \phi}{\partial \theta}$$

$$\Rightarrow \frac{\Omega}{2\pi r} = \frac{\partial \phi}{\partial r} \Rightarrow \phi = \frac{\Omega}{2\pi} h(r)$$

$$\frac{\partial \phi}{\partial \theta} = 0 \Rightarrow \phi = \phi(r) \quad \therefore W = \phi + i\psi = \frac{\Omega}{2\pi} h(r) + i \frac{\Omega}{2\pi} \phi$$

$$h(z) = h(|z|) + i\phi$$

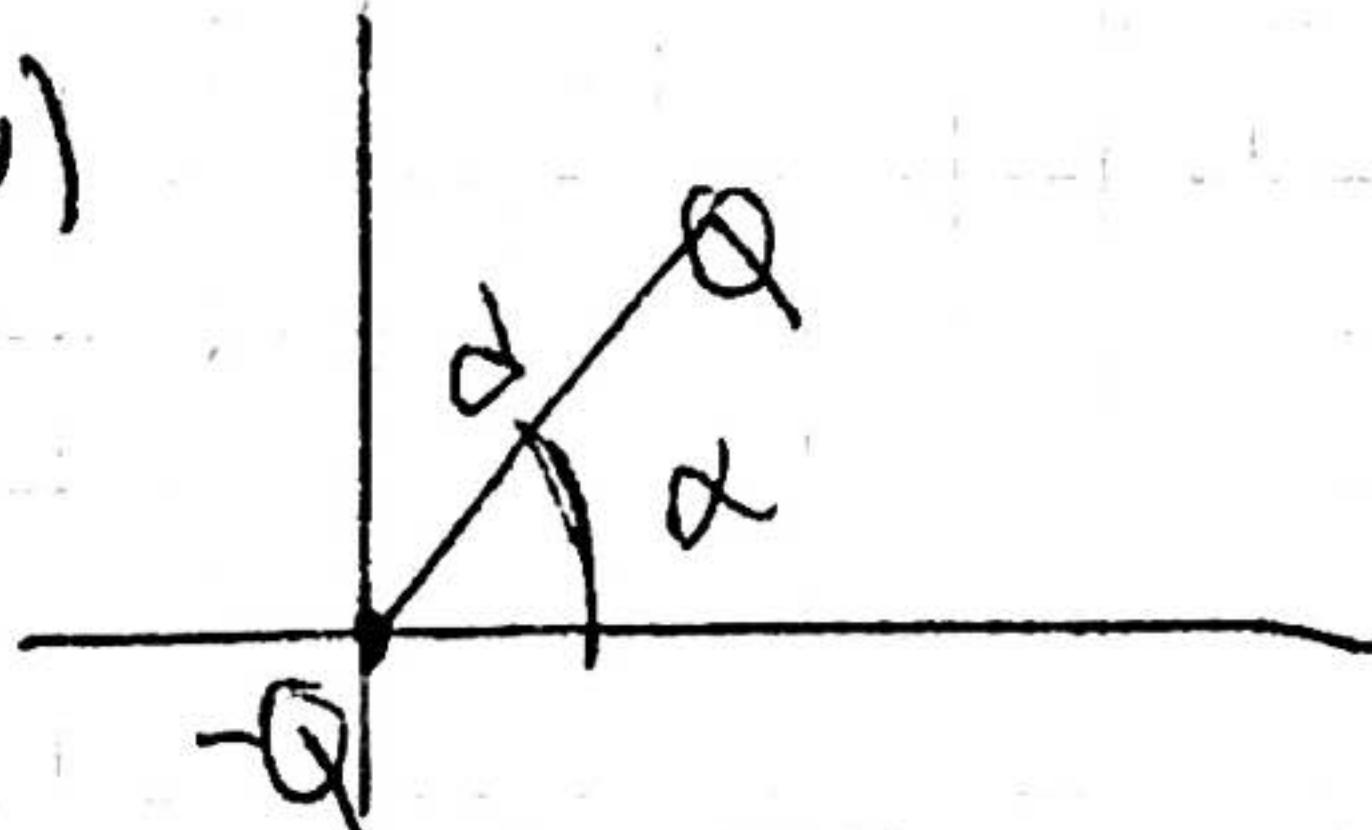
$$z = x+iy \quad r = \sqrt{x^2+y^2} = |z| \quad \Rightarrow W(z) = \frac{\Omega}{2\pi} h(z)$$

$$\text{iii) } \underline{u} = \frac{\Gamma}{2\pi r} \hat{\theta} \quad \psi = -\frac{\Gamma}{2\pi r} b(r)$$

$$\phi / \Delta \phi = \underline{u} \Rightarrow \frac{\partial \phi}{\partial r} + \frac{1}{r} \frac{\partial \phi}{\partial \theta} = \frac{\Gamma}{2\pi r} \hat{\theta} \Rightarrow \phi = \frac{\Gamma}{2\pi} \theta$$

$$\therefore W = \frac{\Gamma}{2\pi} \theta - i \frac{\Gamma}{2\pi} h(r) = i \frac{\Gamma}{2\pi} \theta + \frac{\Gamma}{2\pi i} h(r) = \frac{\Gamma}{2\pi i} h(z) = W(z)$$

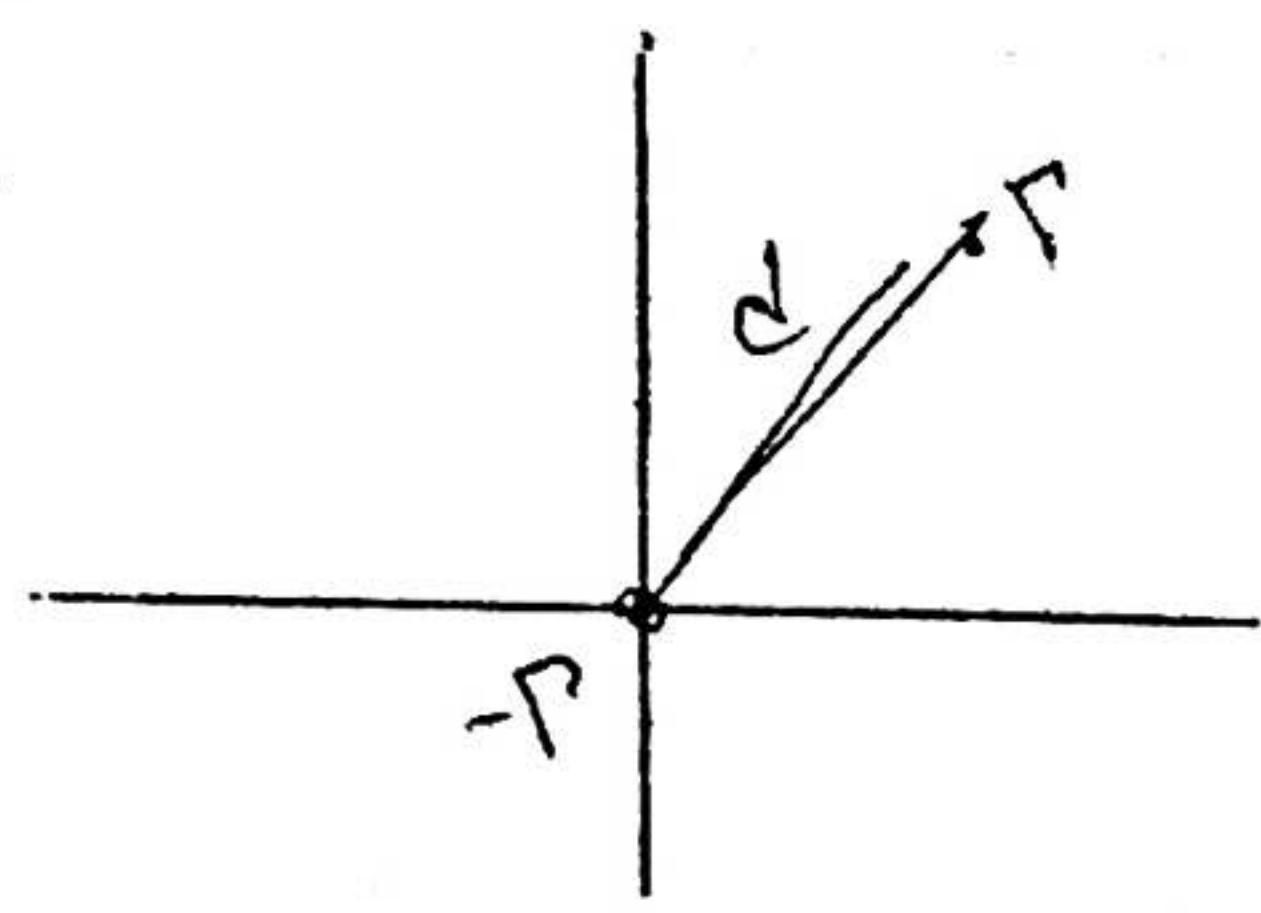
iv)



$$\lim_{\delta \rightarrow 0} \frac{\Omega d}{Q} = \mu_Q$$

$$W(z) = -\frac{\mu_Q}{2\pi z}$$

V)

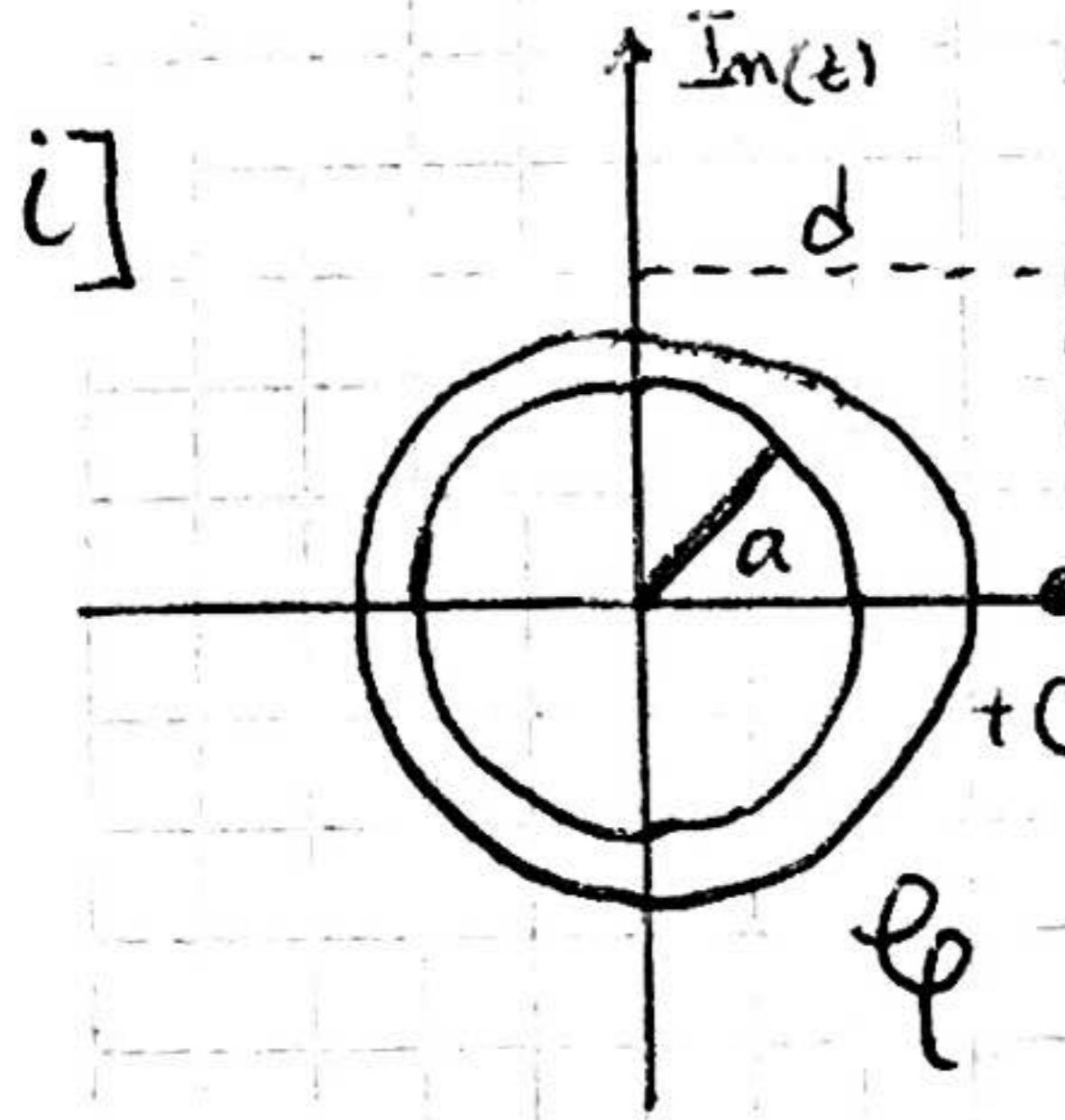


$$\lim_{\substack{d \rightarrow 0 \\ r \rightarrow \infty}} \oint d = \mu_p$$

$$W = -\frac{\mu_p}{2\pi i z} e^{iz}$$

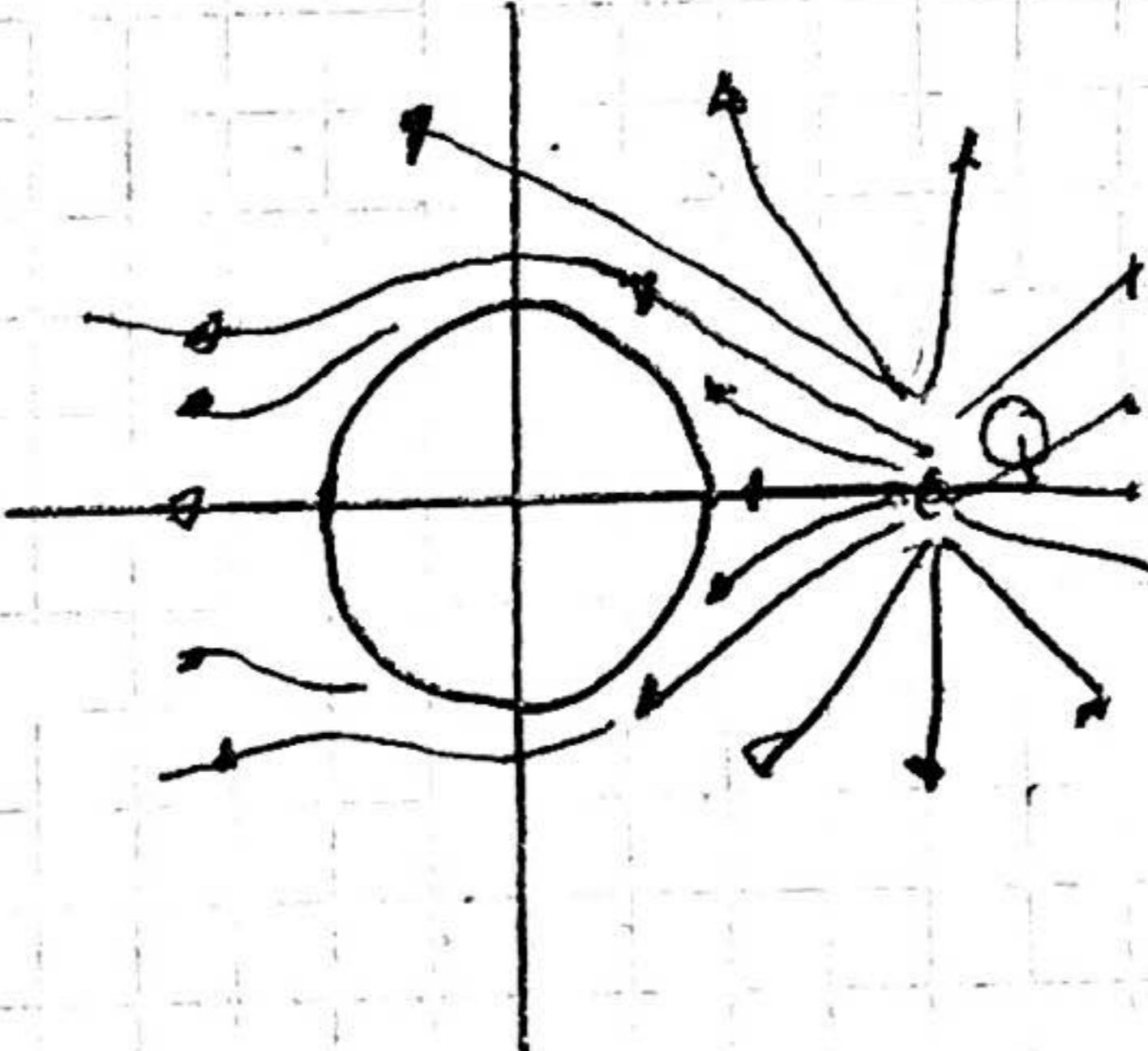
### 6.7) fluidos ideales, incompresibles, irrotacionales

- a) líneas de corriente    b)  $W$     c) p.d.e    d)  $p(z)$  presión del contorno sólido



$$W = W_0 + \overline{W_0 \left( \frac{a^2}{z} \right)}$$

por el C w<sub>0</sub>  
sig. otra fren  
del circuito



$$W_0 = \frac{Q}{2\pi} \ln(z-d) + \frac{Q}{2\pi} \ln\left(\frac{a^2}{z}-d\right)$$

$$\frac{a^2-dz}{z} = \frac{d}{z} \left( \frac{a^2}{d} - z \right)$$

$$\Rightarrow W = \frac{Q}{2\pi} \ln(z-d) + \frac{Q}{2\pi} \left[ \ln\left(\frac{a^2}{d}\right) - \ln(z) + \ln\left(\frac{a^2}{d} + z\right) \right]$$

$$W = \frac{Q}{2\pi} \ln(z-d) + \frac{Q}{2\pi} \ln\left(z+\frac{a^2}{d}\right) + \frac{Q}{2\pi} \left[ \ln\left(\frac{a^2}{d}\right) - \ln(z) \right]$$

c) p.d.e  $\frac{dw}{dz} = 0 \Rightarrow \frac{dw}{dz} = \frac{Q}{2\pi(z-d)} + \frac{Q}{2\pi(z-a^2/d)} - \frac{Q}{2\pi z} = 0$

$$\frac{(z-a^2/d)+(z-d)}{(z-d)(z-a^2/d)} - \frac{1}{z} = 2z^2 - z(a^2/d - d)$$

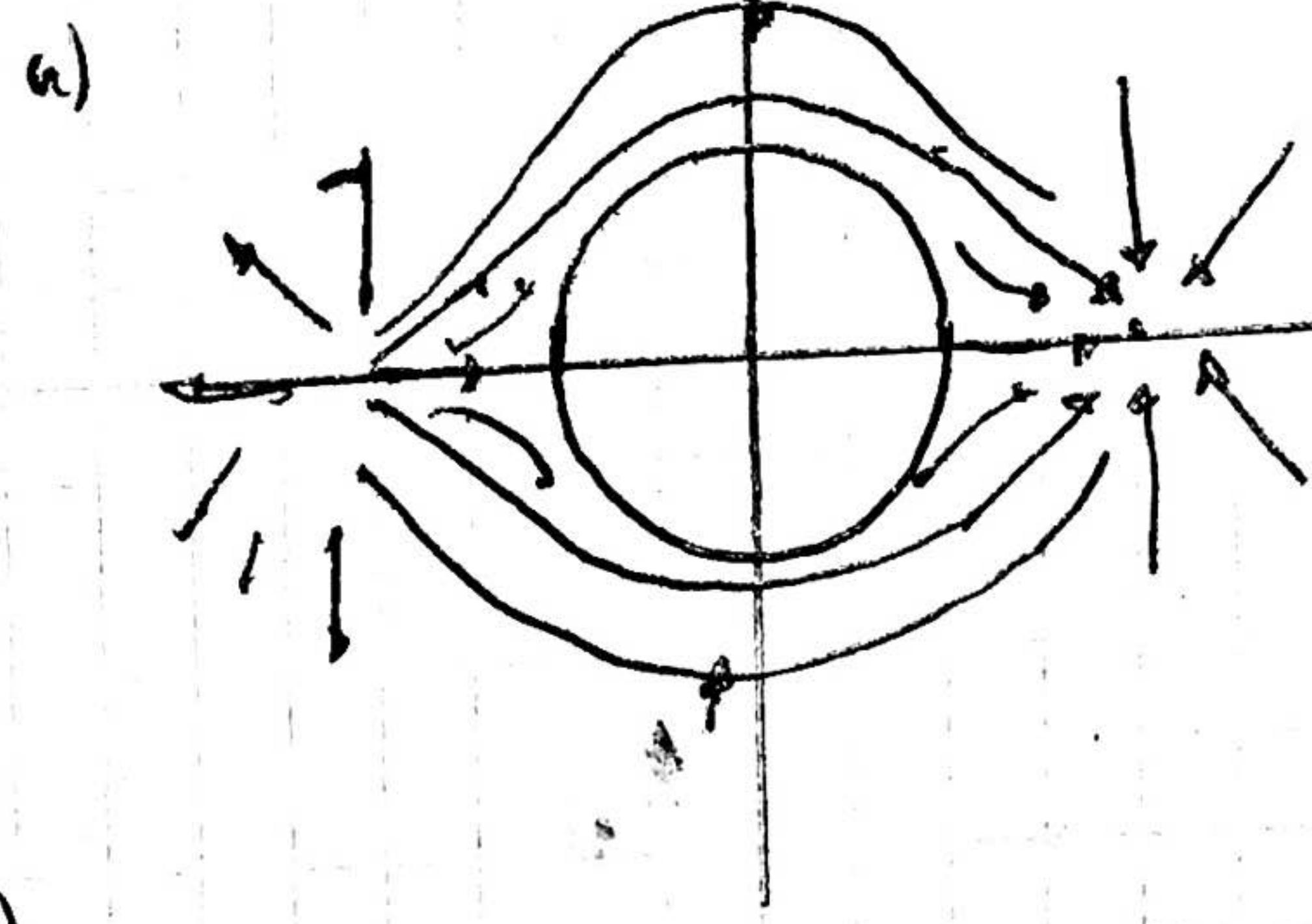
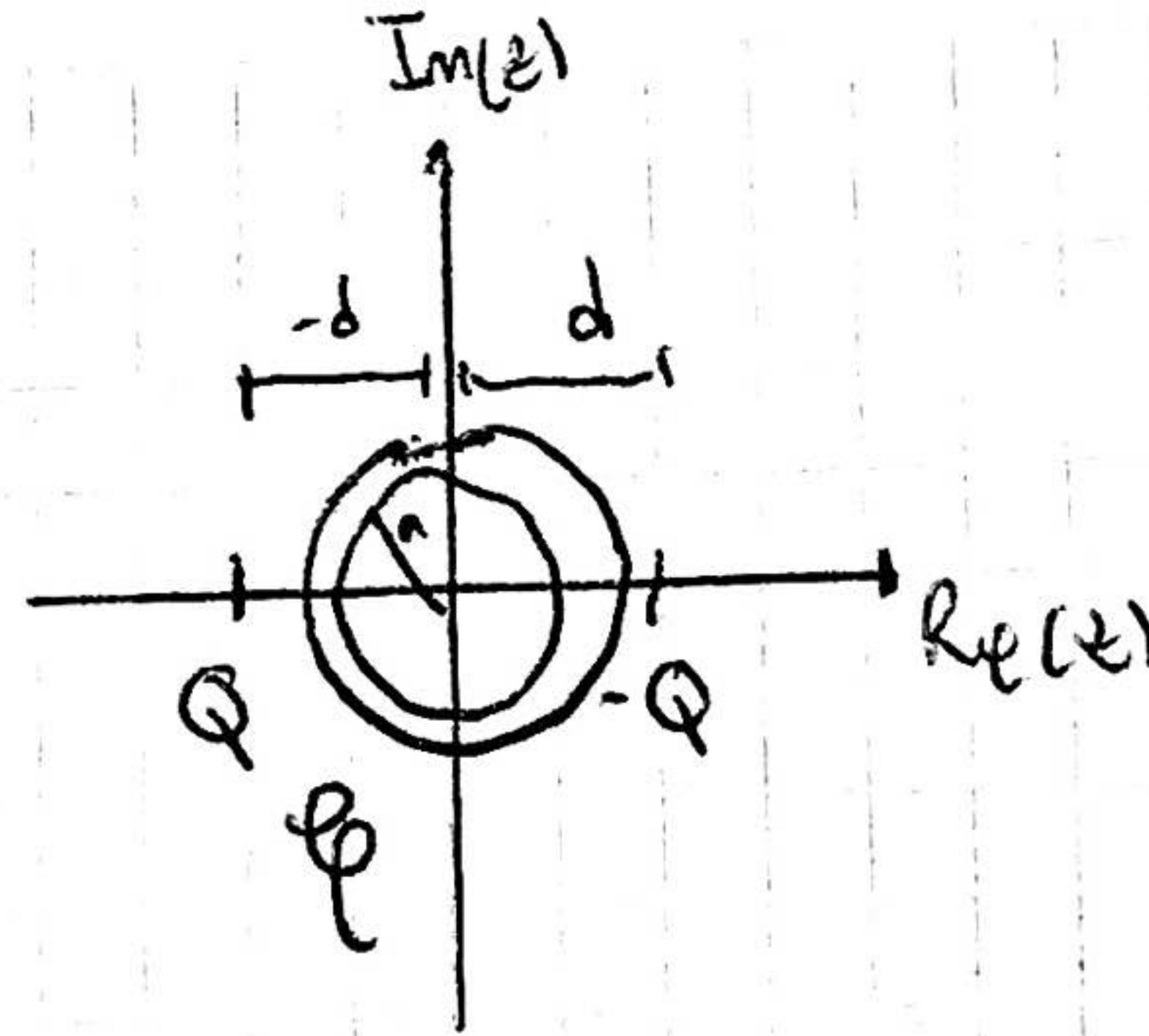
Wolfram dice  $z=a$ ,  $z=-a$

d)  $p = -\int \frac{v^2}{2} + C = -\int \frac{1}{2} \left| \frac{dw}{dz} \right|^2 + K$  en el contorno sólido  $z = ae^{i\theta}$   $\theta \in [0, \pi]$

$$\Rightarrow p = -\frac{\rho Q^2}{2 \cdot 4\pi^2} \left[ \frac{1}{ae^{i\theta}-d} + \frac{1}{ae^{i\theta}-a^2/d} - \frac{1}{ae^{i\theta}} \right]^2 + K$$

Gratificar con wolfram...

ii)



$$\text{b)} \quad W(z) = \frac{Q}{2\pi} \ln(z+d) - \frac{Q}{2\pi} \ln(z-d) + \frac{Q}{2\pi} \ln\left(\frac{a^2}{z}+d\right) - \frac{Q}{2\pi} \ln\left(\frac{a^2}{z}-d\right)$$

$$\begin{aligned}\frac{a^2+d}{z} &= \frac{a^2+dz}{z} = \frac{d}{z} \left( \frac{a^2}{d} + z \right) \\ \frac{a^2-d}{z} &= \frac{d}{z} \left( z + \frac{a^2}{d} \right)\end{aligned}$$

$$\Rightarrow W(z) = \frac{Q}{2\pi} \left[ \ln(z+d) - \ln(z-d) \right] + \frac{Q}{2\pi} \left[ \ln(d) - \ln(z) + \ln\left(z + \frac{a^2}{d}\right) \right] - \frac{Q}{2\pi} \left[ \ln(d) - \ln(z) + \ln\left(z + \frac{a^2}{d}\right) \right]$$

$$\Rightarrow W(z) = \frac{Q}{2\pi} \left[ \ln(z+d) - \ln(z-d) \right] + \frac{Q}{2\pi} \left[ \ln\left(z + \frac{a^2}{d}\right) - \ln\left(\frac{a^2}{d} - z\right) \right]$$

p.d.e.  $\frac{\partial W}{\partial z} = 0 = \frac{Q}{2\pi} \left[ \frac{1}{z+d} - \frac{1}{z-d} \right] + \frac{Q}{2\pi} \left[ \frac{1}{z + \frac{a^2}{d}} - \frac{1}{z - \frac{a^2}{d}} \right] = 0$

$$\Leftrightarrow \frac{z-d-(z+d)}{(z^2-d^2)} + \frac{z-\frac{a^2}{d}-(z+\frac{a^2}{d})}{(z^2-\frac{a^4}{d^2})} = 0$$

$$\Leftrightarrow \frac{-2d}{(z^2-d^2)} - \frac{2a^2/d}{(z^2-a^4/d^2)} = 0 \quad \Leftrightarrow d^2(z^2-a^4/d^2) = -a^2(z^2-d^2)$$

$$\Leftrightarrow z^2(d^2+a^2) = a^2d^2 + a^4$$

$$\Leftrightarrow z^2 = \frac{a^2d^2 + a^4}{d^2 + a^2} = \frac{(d^2 + a^2)a^2}{d^2 + a^2}$$

$$\Leftrightarrow z = \pm a$$

$$P = -f \left| \frac{\partial W}{\partial z} \right|^2 + K$$

Pero obviamente los únicos con significado físico para este problema serán

$$z=a, z=-a$$

1d)

$$P = -\rho \frac{v^2}{2} + K = -\rho \frac{|v|^2}{2} + K; \text{ pero evaluado en } z = a e^{i\theta}$$

$$\left. \frac{dv}{dz} \right|_{z=a e^{i\theta}} = \frac{Q}{2\pi} \left[ \frac{ae^{-i\theta}-d}{|ae^{i\theta}-d|^2} + \frac{ae^{-i\theta}-az/d}{|ae^{i\theta}-az/d|^2} - \frac{ae^{-i\theta}}{a^2} \right]$$

$$(\cos \theta - \#)^2 + \sin^2 \theta$$

$$1 - 2\# \cos \theta + \#^2$$

$$\left( \frac{\frac{(e^{-i\theta}-d/a)}{a(1-2dcos\theta+\frac{d^2}{a^2})}}{a(d(a-2cos\theta+\frac{d}{a}))} + \frac{\frac{e^{-i\theta}-a/d}{a(1-2\frac{a}{d}cos\theta+\frac{a^2}{d^2})}}{a(\frac{a}{d}(d-a-2cos\theta+\frac{a}{d}))} - \frac{e^{-i\theta}}{a} \right)$$

$$\frac{\frac{de^{-i\theta}}{d\theta} - \frac{1}{a}}{a} + \frac{\frac{de^{-i\theta}}{d\theta} - \frac{a}{d}}{a} - \frac{e^{-i\theta}}{a} + 2\cos \theta \cdot e^{-i\theta} - \frac{1}{a} e^{-i\theta}$$

$$\frac{-2\left(\frac{a-2\cos\theta+\frac{d}{a}}{a}\right)a}{-2\left(1-\cos\theta \cdot e^{-i\theta}\right)} = \frac{-2\left(1-\cos^2\theta+i\cos\theta \cdot \sin\theta\right)}{a\left(\frac{a}{d}-2\cos\theta+\frac{d}{a}\right)} = \frac{\frac{-\cos(2\theta)}{\left(1-2\cos^2\theta+\cos^2\theta+\cos^2\theta \cdot \sin^2\theta\right)}}{\left|\frac{a}{d}\right|^2}$$

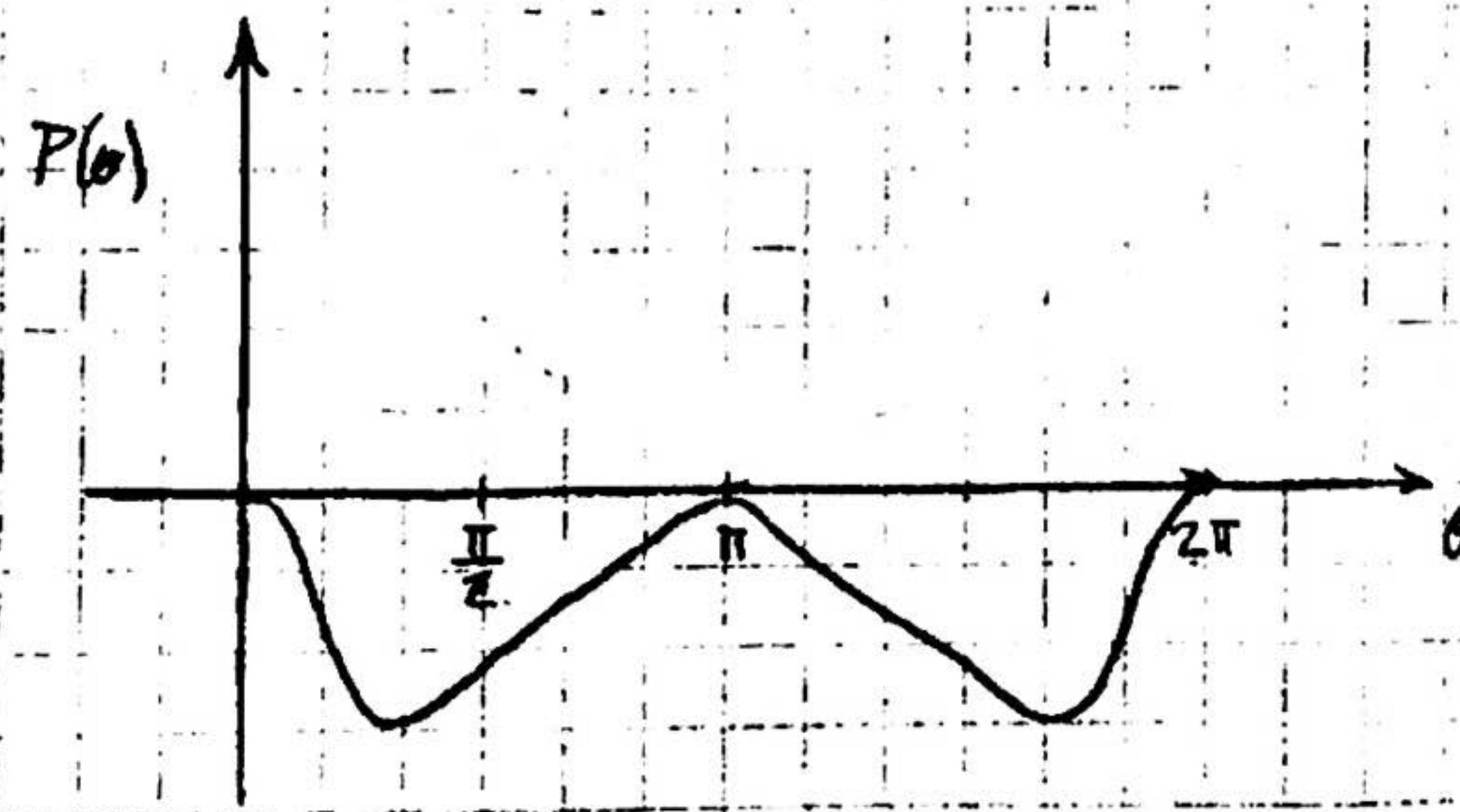
$$\left. \frac{dv}{dz} \right|_{z=a e^{i\theta}}^2 = \frac{\frac{Q^2}{4} \left( \frac{a}{d} - 2\cos\theta + \frac{d}{a} \right)^2}{\left( \frac{a}{d} - 2\cos\theta + \frac{d}{a} \right) a} = \left| \frac{2/a}{\left( \frac{a}{d} - 2\cos\theta + \frac{d}{a} \right)} \cdot (-\sin\theta - i \cdot \sin\theta \cdot \cos\theta) \right|^2$$

$$\left( \frac{2/a \cdot \sin\theta}{\left( \frac{a}{d} - 2\cos\theta + \frac{d}{a} \right)} \right)^2 \underbrace{\left[ 1 + i \cdot \cos\theta \right]^2}_{(1+\cos^2\theta)}$$

$$\frac{(4/a^2) \cdot \sin^2\theta \cdot (1+\cos^2\theta)}{\left( \frac{a}{d} + \frac{d}{a} - 2\cos\theta \right)^2}$$

Presión sobre el  
contorno sólido

$$P(\theta) = -\frac{\rho}{2} \cdot \frac{4}{a^2} \cdot \frac{\sin^2\theta \cdot (1+\cos^2\theta)}{\left( \frac{a}{d} + \frac{d}{a} - 2\cos\theta \right)^2} + K$$



Podríamos  
hacer  $P(\theta)$  positiva  
sumándole la  
constante  $K$

$$z^2 dz - a^2 = -z^2 a^2 + a^2 dz$$

$$z^2 (dz + a^2) = z^2 a^2 + a^2$$

$$\frac{z^2}{z^2} = \frac{a^2 (dz + a^2)}{a^2 + dz} \rightarrow z^2 = a^2$$

$$z = a \cdot e^{i\pi} \quad k=0,1 \rightarrow$$

Puntos de estancamiento,  $\boxed{z = \pm a}$

2d)

$$P = -\frac{\rho}{z} \left| \frac{dw}{dz} \right|^2 + K \quad \text{evaluando en } z = a \cdot e^{i\theta}$$

$$P(\theta) = -\frac{\rho}{z} \left| \frac{Q}{2\pi} \left( \frac{-2d}{a^2 e^{i2\theta} - d^2} + \frac{-2a^2/d}{a^2 e^{i2\theta} - a^2} \right) \right|^2$$

$$-\frac{\rho}{z} \frac{Q^2}{\pi^2} \left| \frac{-d}{a^2 (e^{i2\theta} - \frac{d^2}{a^2})} - \frac{a^2/d}{a^2 (e^{i2\theta} - \frac{a^2}{d^2})} \right|^2$$

$$P(\theta) = -\frac{\rho}{z} \frac{Q^2}{\pi^2} \left( \frac{1}{a^2} \right)^2 \left| -\frac{d}{(e^{i2\theta} + \frac{d^2}{a^2})} - \frac{a^2}{d(e^{i2\theta} - \frac{a^2}{d^2})} \right|^2$$

$$U = -\frac{d(e^{i2\theta} - d^2/a^2)}{\left| e^{i2\theta} - \frac{d^2}{a^2} \right|^2} - \frac{a^2(e^{i2\theta} - a^2/d^2)}{d \left| e^{i2\theta} - \frac{a^2}{d^2} \right|^2} = -\left( \frac{d \left( \frac{a^2}{d^2} - 2\cos(2\theta) + \frac{d^2}{a^2} \right)}{d^2 \left( \frac{a^2}{d^2} - 2\cos(2\theta) + \frac{a^2}{d^2} \right)} + \frac{a^2 \left( \frac{d^2}{a^2} - 2\cos(2\theta) + \frac{a^2}{d^2} \right)}{d^2 \left( \frac{d^2}{a^2} - 2\cos(2\theta) + \frac{a^2}{d^2} \right)} \right)$$

$$\begin{aligned} & \left. \begin{aligned} & \left( \cos(2\theta) - \frac{d^2}{a^2} \right)^2 + \sin^2(2\theta) \\ & 1 - 2 \frac{d^2}{a^2} \cos(2\theta) + \frac{d^4}{a^4} \end{aligned} \right) \\ & = -\frac{\frac{d^2 a^2}{d^4} (e^{i2\theta} - d^2/a^2) + \frac{d^2 d^2}{d^4 a^2} (e^{-i2\theta} - a^2/d^2)}{\left( \frac{a^2}{d^2} - 2\cos(2\theta) + \frac{d^2}{a^2} \right)} \\ & = -\frac{\frac{a^2}{d^2} e^{-i2\theta} - d + d \cdot e^{-i2\theta} - \frac{a^2}{d}}{\left( \frac{a^2}{d^2} - 2\cos(2\theta) + \frac{d^2}{a^2} \right)} \end{aligned}$$

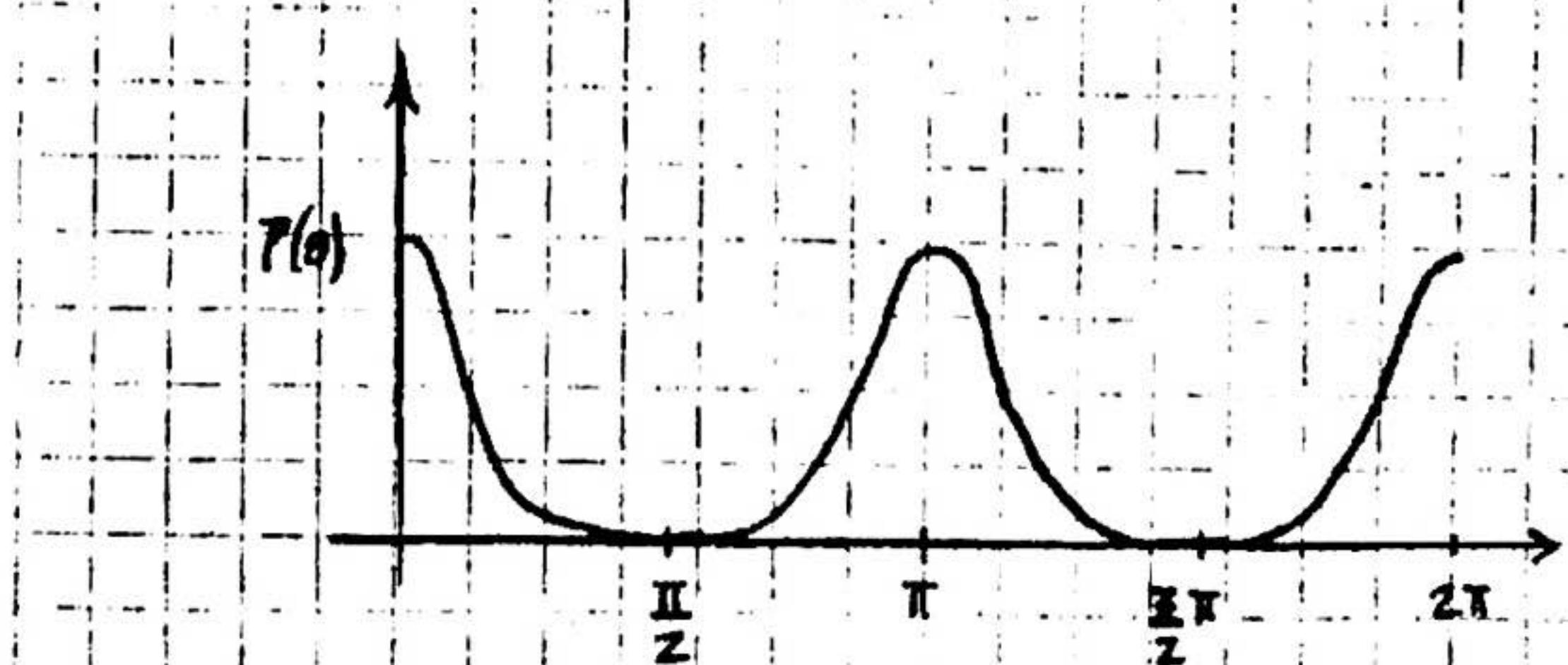
$$= \frac{(e^{-i2\theta} - 1) \left( \frac{a^2}{d} - d \right)}{\left( \frac{a^2}{d^2} - 2\cos(2\theta) + \frac{d^2}{a^2} \right)} \rightarrow \cos^2(2\theta) + \sin^2(2\theta) + 2\cos(2\theta) + 1$$

$$P(\theta) = -\frac{\rho}{z} \frac{Q^2}{\pi^2 a^4} \frac{(a^2 - d^2)^2}{d^2 \left( \frac{a^2}{d^2} - 2\cos(2\theta) + \frac{d^2}{a^2} \right)^2} \cdot \left( (\cos(2\theta) + 1)^2 + \sin^2(2\theta) \right)$$

$$P(\theta) = -\frac{\rho}{z} \frac{Q^2}{\pi^2} (a^2)$$

$$P(\theta) = -\frac{\rho Q^2}{\pi^2}$$

Podemos graficar esta función



6.10)

$$c) \quad W = \frac{Q}{2\pi} h(z-d) + \frac{Q}{2\pi} h(-z+a^2/d) + \frac{Q}{2\pi} [h(d) - h(z)]$$

$$F_x - iF_y = \frac{1}{2} \oint_C \left( \frac{\partial w}{\partial z} \right)^2 dz = \sum_i \frac{p_i(z_i)}{2} \sum_k \operatorname{Res} \left\{ \left( \frac{\partial w}{\partial z} \right)^2, z_k \right\}$$

interior a  $\oint_C$

$$\frac{\partial U}{\partial z} = \frac{Q}{2\pi} \left[ \frac{1}{z-d} + \frac{1}{z-a\gamma_d} - \frac{1}{z} \right]$$

2nd order

$\alpha_d \approx 0.1$

$$\Rightarrow \left( \frac{\partial W}{\partial z} \right)^c = \frac{Q^2}{4\pi^2} \left[ \underbrace{\frac{1}{(z-d)^2}}_{\text{exten, polo de orden 2}} + \underbrace{\frac{1}{(z-a_1^*)^2}}_{\text{res=0 per = análogo orden 1 en } z=a_1^*} + \frac{1}{z^2} - \underbrace{\frac{2}{(z-d)^2}}_{\text{polo de orden 1 en } z=d} - \underbrace{\frac{2}{(z-a_1^*)^2}}_{\text{polo de orden 1 en } z=a_1^*} + \frac{72}{(z-d)(z-a_1^*)} \right]$$

$$\Rightarrow \operatorname{Res}\left(\left(\frac{\partial w}{\partial z}\right)^2, z_0\right)_{\text{int}} = \left[ \operatorname{Res}\left(\frac{-2}{(z-d_1)^2}, 0\right) + \operatorname{Res}\left(\frac{-2}{(z-a_{j_1}^2)^2}, 0, \frac{a_{j_1}^2}{d}\right) + \operatorname{Res}\left(\frac{-2}{(z-d)(z-a_{j_2}^2)}, \frac{a_{j_2}^2}{d}\right) \right]$$

\*  $\frac{Q^2}{4\pi^2}$

"  $a_{j_1}^2$

$\frac{2}{d}$

$a_{j_2}^2$

$\frac{2d}{a^2}$

$- \frac{2d}{a^2}$

$\frac{-2}{a^2 - d}$

$$\Rightarrow F_x - iF_y = -\pi \rho \frac{a^2}{4\pi^2} \left[ \frac{2}{d} + \frac{2d}{a^2} - \frac{2d}{a^2 + d^2} \right]$$

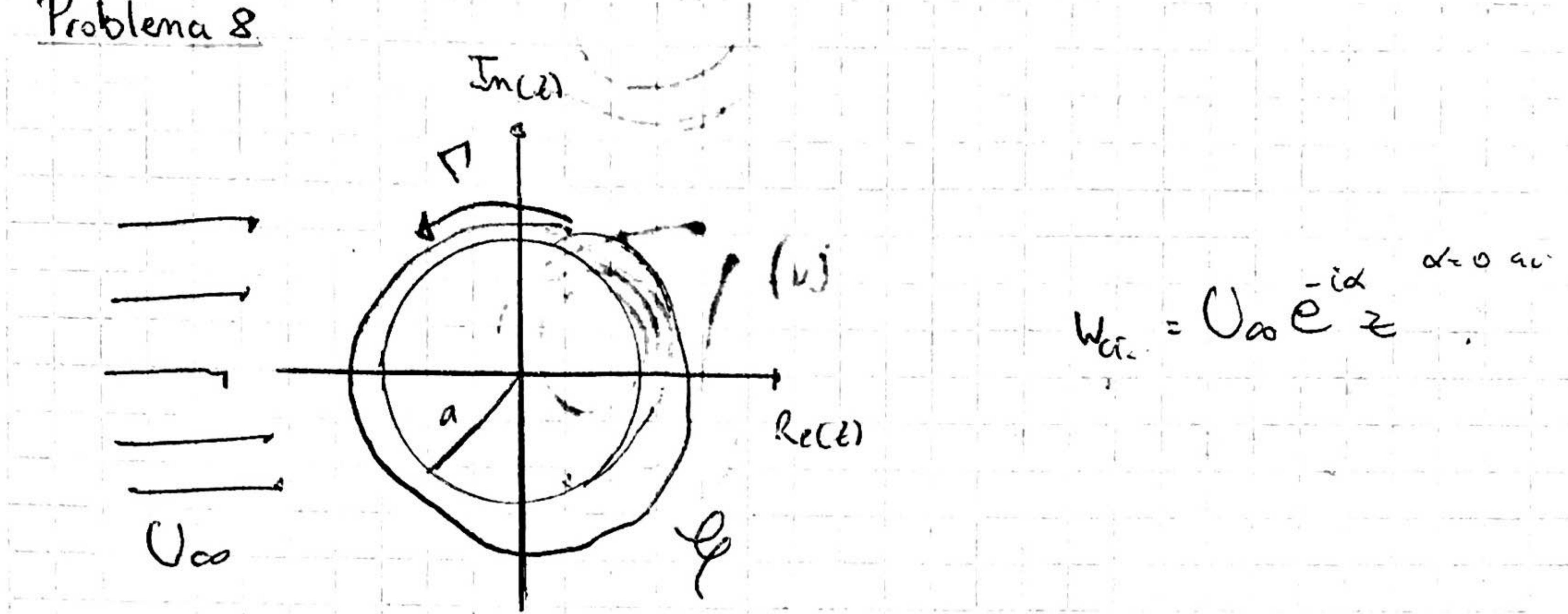
$$\Rightarrow F_x = -\frac{\rho Q^2}{4\pi} \cdot \frac{2(a^2 + d^2) + 2d^2}{d(a^2 - d^2)} = \frac{-\rho Q^2 a^2}{2\pi d(a^2 - d^2)} = F_x$$

$$\text{ii) } W = \frac{Q}{2\pi} [h(z+d) - h(z-d)] + \frac{Q}{2\pi} [h(z+a^2) - h(a^2 - z)]$$

$$\frac{\partial W}{\partial z} = \frac{Q}{2\pi} \left[ \frac{1}{z+d} - \frac{1}{z-d} + \frac{1}{z+a_{1d}^e} + \frac{1}{z-a_{1d}^e} \right]$$

fiaca ...

### Problema 8



$$\Rightarrow W(z) = W_{\text{circ}}(z) + \overline{W_{\text{circ}}(\alpha^2)} + W_p$$

$$= U_{\infty} z + \frac{U_{\infty} a^2}{z} - \frac{i\Gamma}{2\pi} \ln(z)$$

$$\Rightarrow W(z) = U_{\infty} \left(1 + \frac{a^2}{z^2}\right) - \frac{i\Gamma}{2\pi} \ln(z)$$

$$\text{p.d.e. } \frac{dW}{dz} = U_{\infty} - \frac{U_{\infty} a^2}{z^2} - \frac{i\Gamma}{2\pi z} = 0$$

$$\Leftrightarrow U_{\infty} z^2 - \frac{i\Gamma}{2\pi} z - U_{\infty} a^2 = 0$$

$$z = \frac{i\Gamma}{2\pi} \pm \frac{\sqrt{-\Gamma^2 + 4U_{\infty} a^2}}{2U_{\infty}}$$

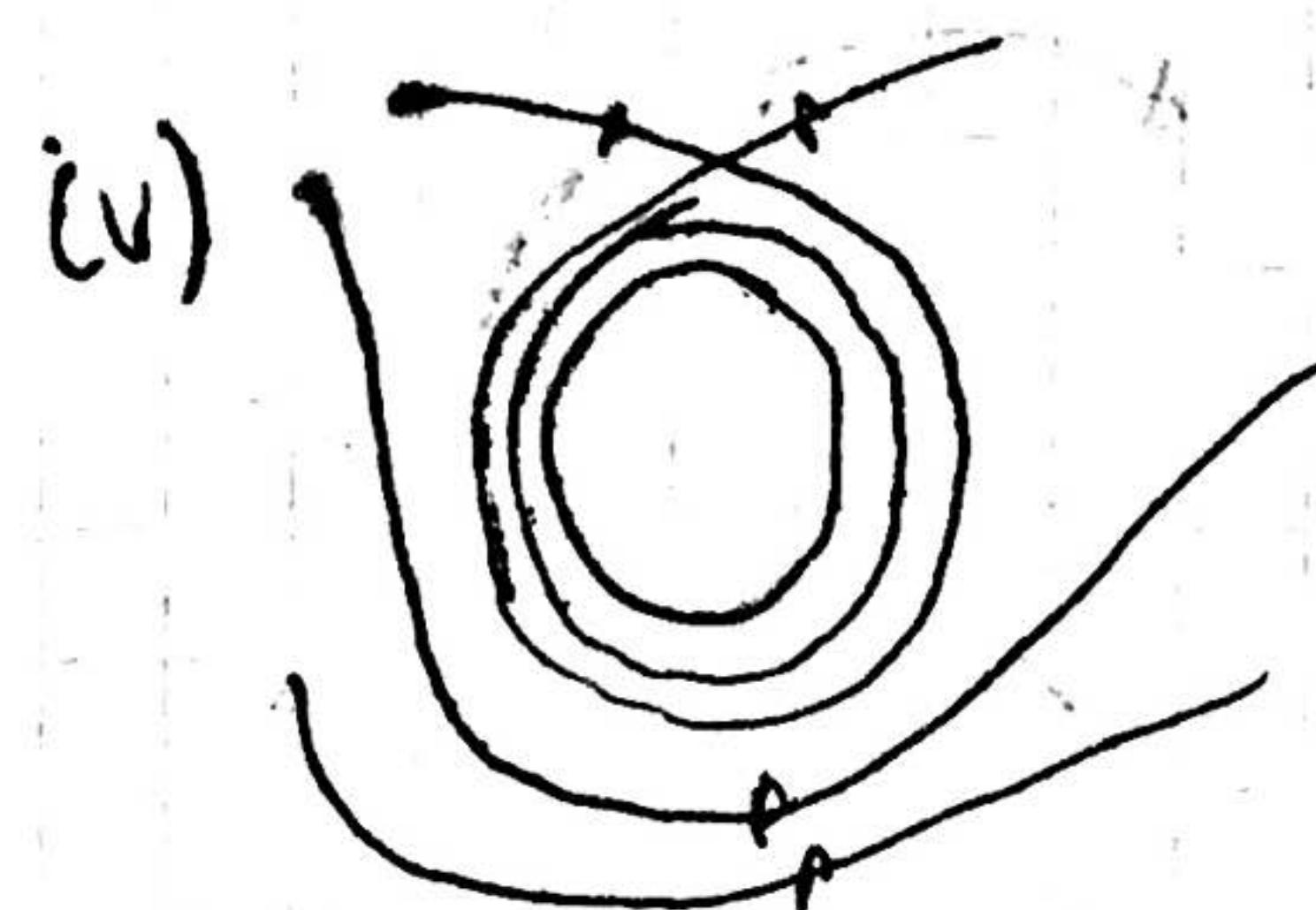
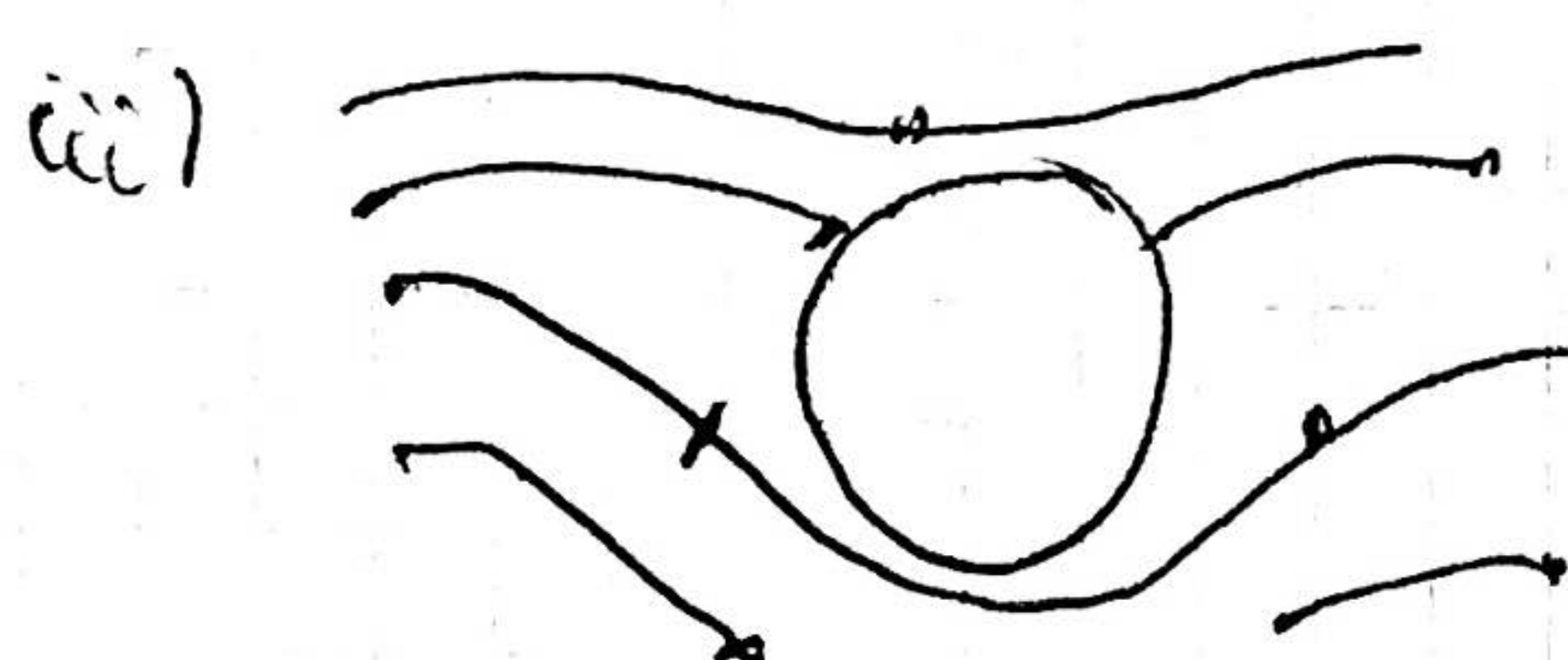
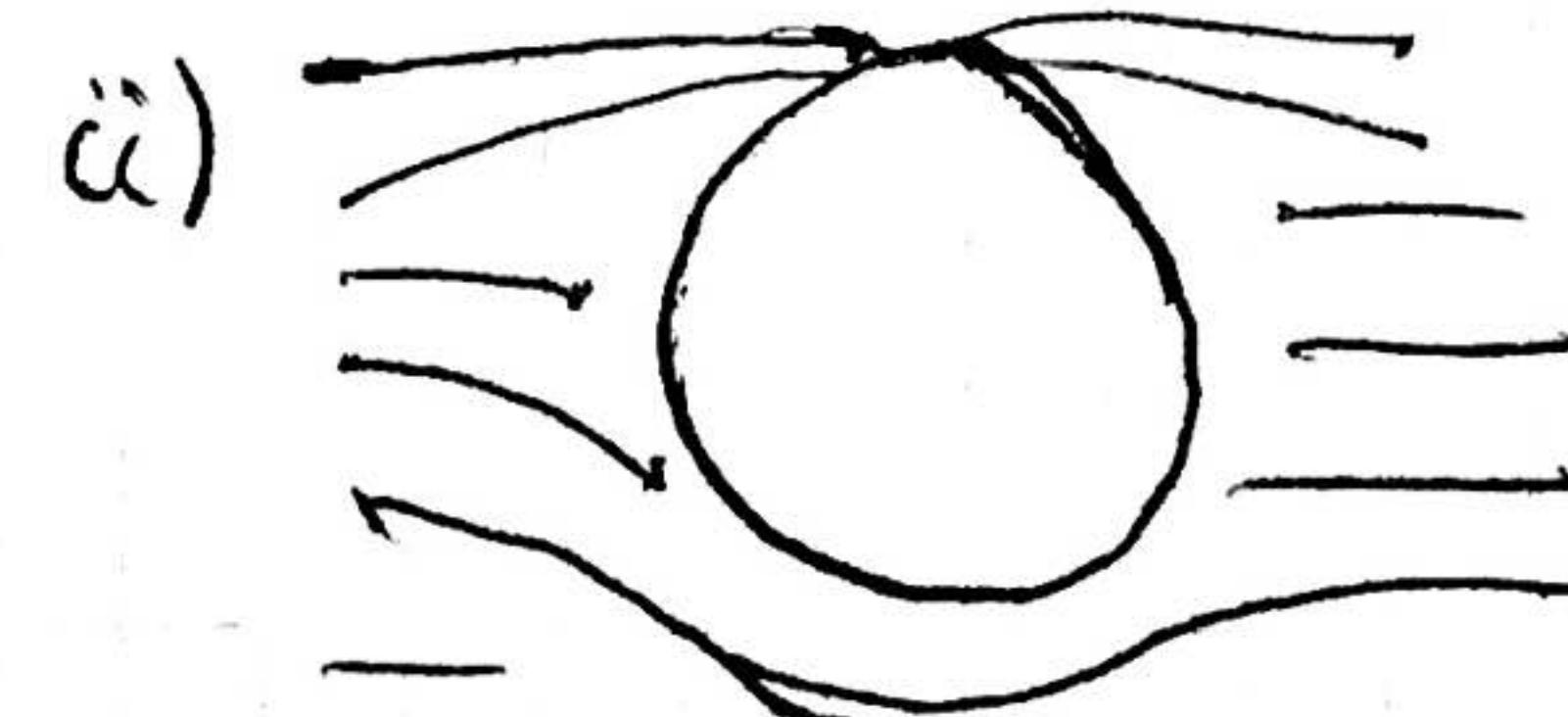
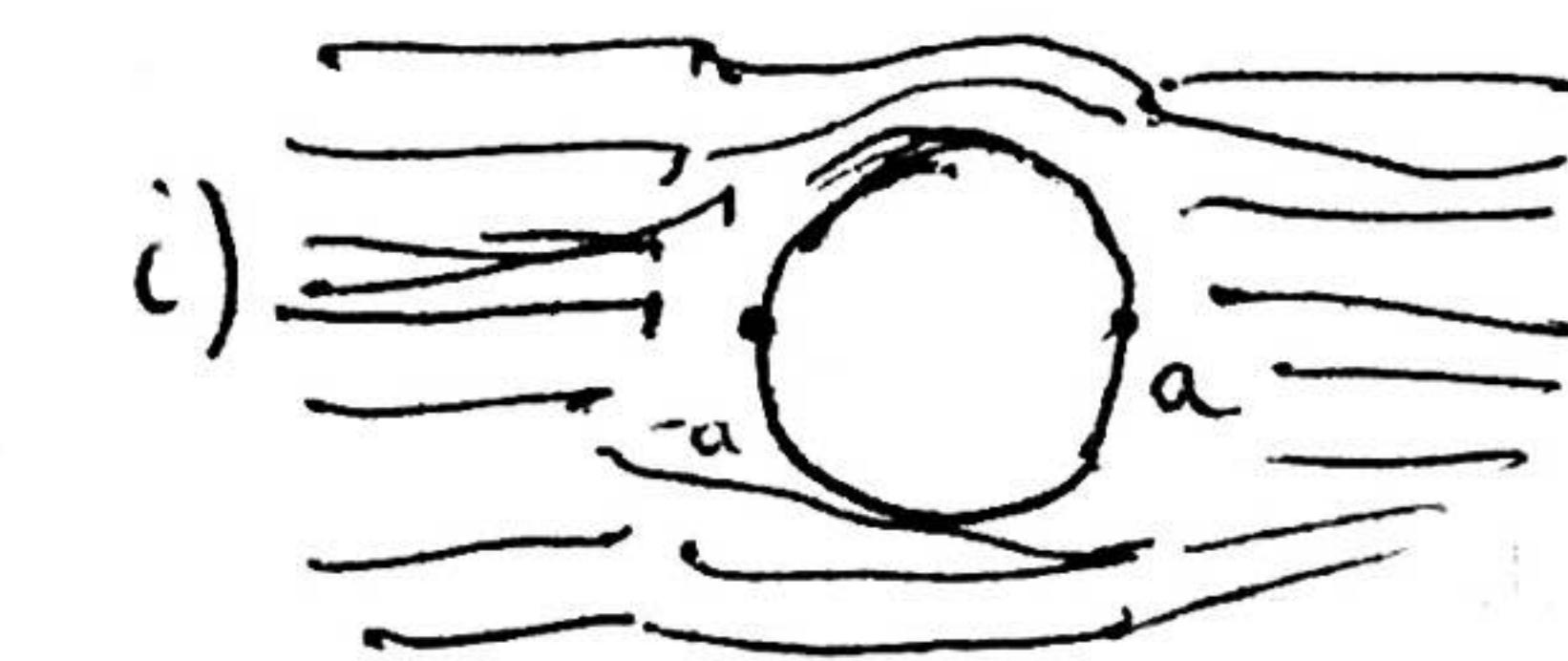
$$\Rightarrow z = \frac{i\Gamma}{4\pi U_{\infty}} \pm \sqrt{\frac{-\Gamma^2}{16\pi^2 U_{\infty}^2} + a^2}$$

i)  $\bullet \Gamma = 0 \Rightarrow z = \pm a$  puntos de estancamiento

ii)  $\bullet -\frac{\Gamma^2}{16\pi^2 U_{\infty}^2} + a^2 = 0 \Leftrightarrow \Gamma^2 = 16\pi^2 U_{\infty}^2 a^2 \Rightarrow z = ia$  único punto de estancamiento

iii)  $\bullet \frac{\Gamma^2}{16\pi^2 U_{\infty}^2} > a^2 \Rightarrow z = \frac{i\Gamma}{4\pi U_{\infty}} \pm i \sqrt{a^2 + \frac{\Gamma^2}{16\pi^2 U_{\infty}^2}}$  los p.d.e. sobre el eje  $\text{Im}$

iv)  $\bullet \frac{\Gamma^2}{16\pi^2 U_{\infty}^2} < a^2 \Rightarrow z = \frac{i\Gamma}{4\pi U_{\infty}} \pm \sqrt{\frac{a^2 - \frac{\Gamma^2}{16\pi^2 U_{\infty}^2}}{16\pi^2 U_{\infty}^2}}$  los puntos de alrededor del eje  $\text{Im}$



$$c) F_x + iF_y = \frac{ip}{2} \oint \left( \frac{\partial W}{\partial z} \right)^2 dz = \frac{ip}{2} \oint \left[ C_{\infty} - \frac{U_{\infty} a^2}{z^2} - \frac{i\Gamma}{2\pi z} \right]^2 dz$$

$\oint$

$$= \frac{ip}{2} \oint \left[ \underbrace{U_{\infty}^2}_{\text{pole orden 4}} + \underbrace{\frac{U_{\infty}^2 a^4}{z^4}}_{\text{pole orden 4}} - \underbrace{\frac{\Gamma^2}{4\pi^2 z^2}}_{\text{pole orden 2}} + 2 \underbrace{\frac{U_{\infty}^2 a^2}{z^2}}_{\text{pole orden 2}} + 2 \underbrace{\frac{U_{\infty} i\Gamma}{2\pi z}}_{\text{pole orden 1}} - \underbrace{\frac{2 U_{\infty} a^2}{2\pi z^3}}_{\text{pole orden 3}} \right] dz$$

$$= \frac{ip}{2} \cdot (2\pi i) \sum_{k=1}^n \operatorname{Res} \left\{ f(z), z_k \right\} \quad \text{si sing interior al contorno}$$

Residuo

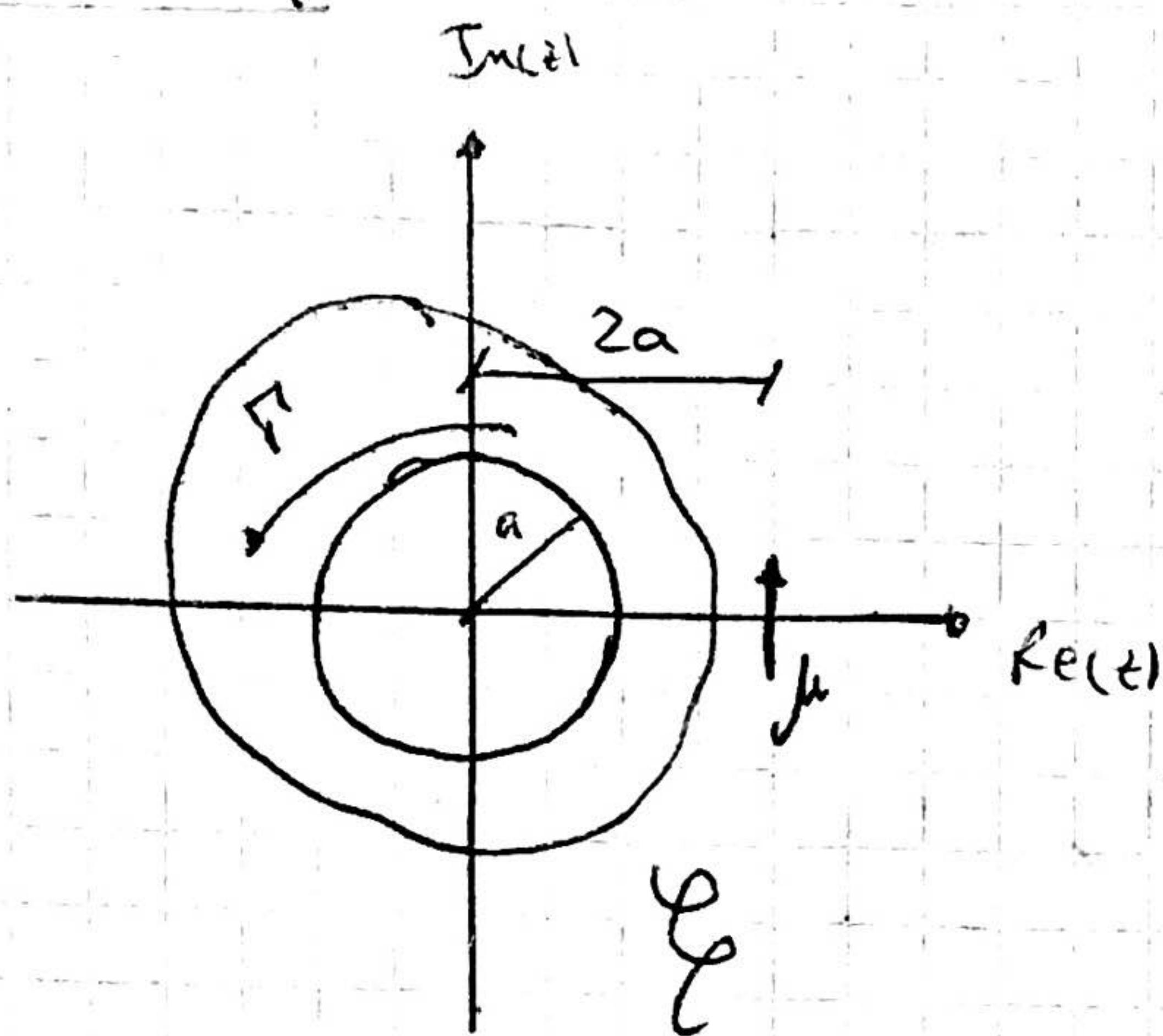
sing  $z=0$  interior al contorno

Solo tengo residuo para el polo de orden 1

$$\text{y vale simplemente } -\frac{2(U_{\infty} i\Gamma)}{\pi} \Rightarrow F_x + iF_y = \frac{ip}{2} 2\pi i \left( -\frac{U_{\infty} i\Gamma}{\pi} \right)$$

$$\Leftrightarrow F_x + iF_y = pi U_{\infty} \Gamma \Rightarrow F_y = -p U_{\infty} \Gamma$$

Problema 6.9



Fluido incompresible irrotacional  
de densidad  $\rho = \rho_0$

Hallar  $\rho_0 / F$  sobre el  $a = \infty$

$$W = \frac{\mu_0 e^{i\alpha}}{2\pi(z-2a)} + \frac{\mu_0 e^{-i\alpha}}{2\pi(a^2/2 - z)} - \frac{i\Gamma}{2\pi} \ln(z) \quad \text{si } \alpha = \frac{\pi}{2}$$

$$\Rightarrow W(z) = \frac{\mu_0 i}{2\pi(z-2a)} - \frac{\mu_0 i}{2\pi(a^2/2 - z)} - \frac{i\Gamma}{2\pi} \ln(z)$$

$$F_x - iF_y = \frac{if}{2} \oint_C \left( \frac{\partial W}{\partial z} \right)^2 dz = \frac{if}{2} (2\pi i) \sum_{n=1}^{\infty} \operatorname{Res} \left\{ \left( \frac{\partial W}{\partial z} \right)^2, z_n \right\} \quad z \text{ sing interior}$$

$$\frac{\partial W}{\partial z} = -\frac{\mu_0 i}{2\pi(z-2a)} - \frac{\mu_0 i}{2\pi(a^2/2 - z)} \frac{a^2}{z^2} - \frac{i\Gamma}{2\pi z}$$

$$A^2 + B^2 + C^2 + 2AB + 2AC + 2BC = (A+B+C)^2$$

$$\Rightarrow F_x - iF_y = \frac{\mu_0 i}{2} \oint_C \left[ \frac{-\mu_0^2}{4\pi^2(z-2a)^4} + \frac{-\mu_0^2}{4\pi^2(a^2/2 - z)^4} \frac{a^4}{z^4} + \frac{\Gamma^2}{4\pi^2 z^2} - \frac{2\mu_0^2 a^2}{4\pi^2 (z-2a)^2 (a^2/2 - z)^2 z^2} \right. \right. \\ \left. \left. - \frac{i\Gamma}{4\pi^2 (z-2a)^2 z} - \frac{\mu_0 a^2 \Gamma}{4\pi^2 (a^2/2 - z)^2 z^3} \right] dz$$

Singularidades

$z = 2a \rightarrow$  exterior

$z = 0 \rightarrow$  interior

$z = a\sqrt{2} \rightarrow$  interior

(1) exterior

(2) polo de orden 4 con residuo nulo pues es su propio desarrollo de Laurent

(3) polo de orden 2 también residuo nulo es su propio desarrollo de Laurent

Entonces quedan  $\text{Res}(t(z), 0)$  polo orden 1

$\text{Res}(g(z), \alpha_2)$  polo orden 2

$\text{Res}(h(z), 0)$  polo orden 1

$\text{Res}(h(z), \alpha_2)$  polo orden 2

$$\text{Res}(t(z), 0) = \lim_{z \rightarrow 0} -\frac{\mu_0 \Gamma}{4\pi^2 (z-2a)^2} = -\frac{\mu_0 \Gamma}{16\pi^2 a^2}$$

$$\text{Res}(g(z), \alpha_2) = \lim_{z \rightarrow \alpha_2} \frac{d}{dz} \left( \frac{-2\mu_0^2 a^2}{4\pi^2 (z-2a)^2 (\alpha_2^2 - 2az)^2} \cdot (z-\alpha_2)^2 \right)$$

$$= \lim_{z \rightarrow \alpha_2} -\frac{2\mu_0^2 a^2}{4\pi^2} \frac{d}{dz} \left[ \frac{1}{(z-2a)^2 4a^2} \right] = \lim_{z \rightarrow \alpha_2} -\frac{\mu_0^2}{8\pi^2 a} \left( \frac{-2}{(z-2a)^3} \right)$$

$$= +\frac{\mu_0^2}{4\pi^2} \frac{8}{27a^3}$$

Los otros dos residuos calculados en la práctica

$$\text{Res}(h(z), 0) = \frac{1}{2} a^2$$

$$\text{Res}(h(z), \alpha_2) = -\frac{1}{2} a^2$$

$$\therefore F_x - iF_y = \frac{\rho i}{2} (2\pi i) \left[ -\frac{\mu_0 \Gamma}{16\pi^2 a^2} + \frac{\mu_0^2 8}{4\pi^2 27a^3} \right]$$

$$F_x = \pi \rho \left[ \frac{\mu_0 \Gamma}{16\pi^2 a^2} - \frac{\mu_0^2 8}{4\pi^2 27a^3} \right] = 0$$

$$\Leftrightarrow \frac{\Gamma}{16} - \frac{\mu_0 8}{4 \cdot 27a} = 0$$

$$\boxed{\mu_0 = \frac{27\Gamma}{32} a}$$