



# ON THE APPLICATION OF OPTIMIZATION METHODS FOR SECURED MULTIPARTY COMPUTATIONS

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# Motivation – Why Privacy/Security ?

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- social networks



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- social networks
- healthcare data



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- social networks
- healthcare data
- e-commerce



# Motivation – Why Privacy/Security ?

- social networks



- healthcare data



- e-commerce



- banks, and government services



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- real world:
  - different parties, such as persons and organizations **always interact**
  - they collaborate for mutual benefits

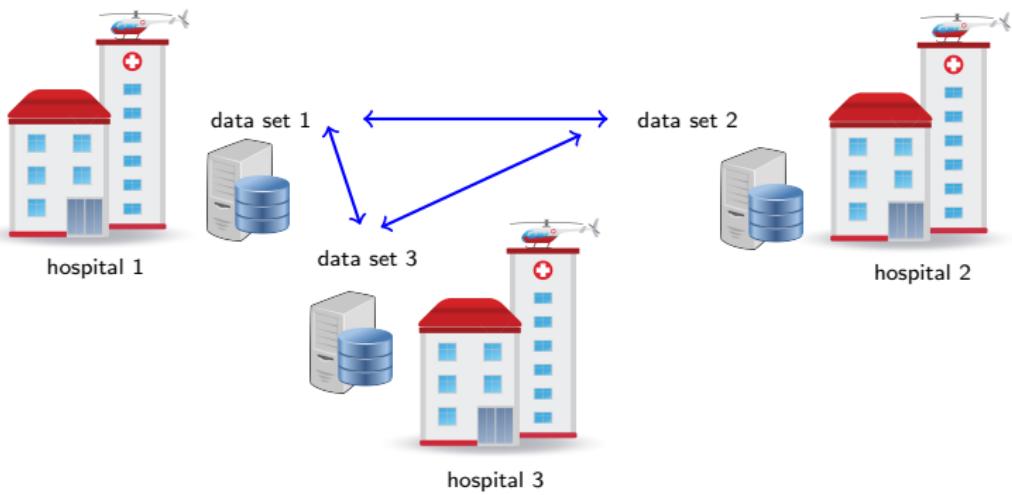
# Motivation – Why Privacy/Security ?

- real world:
  - different parties, such as persons and organizations **always interact**
  - they collaborate for mutual benefits
- collaboration is more appealing **if** security/privacy is guaranteed

# Real World

- **example 1**

- hospitals coordinate  $\Rightarrow$  inference for better diagnosis
- larger data sets  $\Rightarrow$  higher the accuracy of the inference
- **challenge:** neither of the data set should be revealed



# Real World

- **example 2**

- cloud customers outsource their problems to the cloud
- **challenge:** problem data shouldn't be revealed to the cloud



## Real World

- **example 3**
    - secured e-voting systems
    - **challenge:** neither of the vote should be revealed



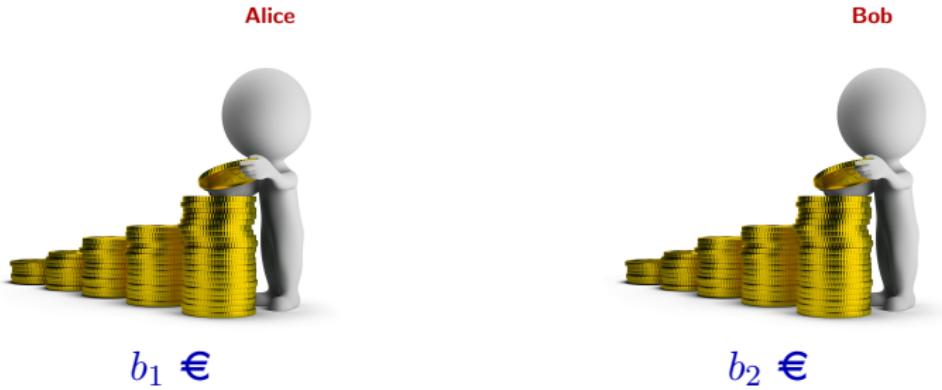
X	X					X	X
		X	X	X			

vote 1      vote 2      ······      vote N

# Real World

- **example 4**

- millionaires' problem [Yao82], i.e., check  $b_1 \leq b_2$
- **challenge:** neither  $b_1$  nor  $b_2$  should be revealed



# Secured Multiparty Computation

- solve, **in a secured manner**, the  $n$ -party problem of the form:

$$f(\mathbf{A}_1, \dots, \mathbf{A}_n) = \inf_{\mathbf{x} \in \{\mathbf{x} | g(\mathbf{x}, \mathbf{A}_1, \dots, \mathbf{A}_n) \leq 0\}} f_0(\mathbf{x}_1, \dots, \mathbf{x}_n, \mathbf{A}_1, \dots, \mathbf{A}_n)$$

- $\mathbf{A}_i$  is the private data belonging to party  $i$
- $\mathbf{x} = (\mathbf{x}_1, \dots, \mathbf{x}_n)$  is the decision variable
- $f_0(\cdot)$  is the global objective function
- $g(\cdot)$  is the vector-valued constraint function
- $f(\cdot)$  is the desired optimal value

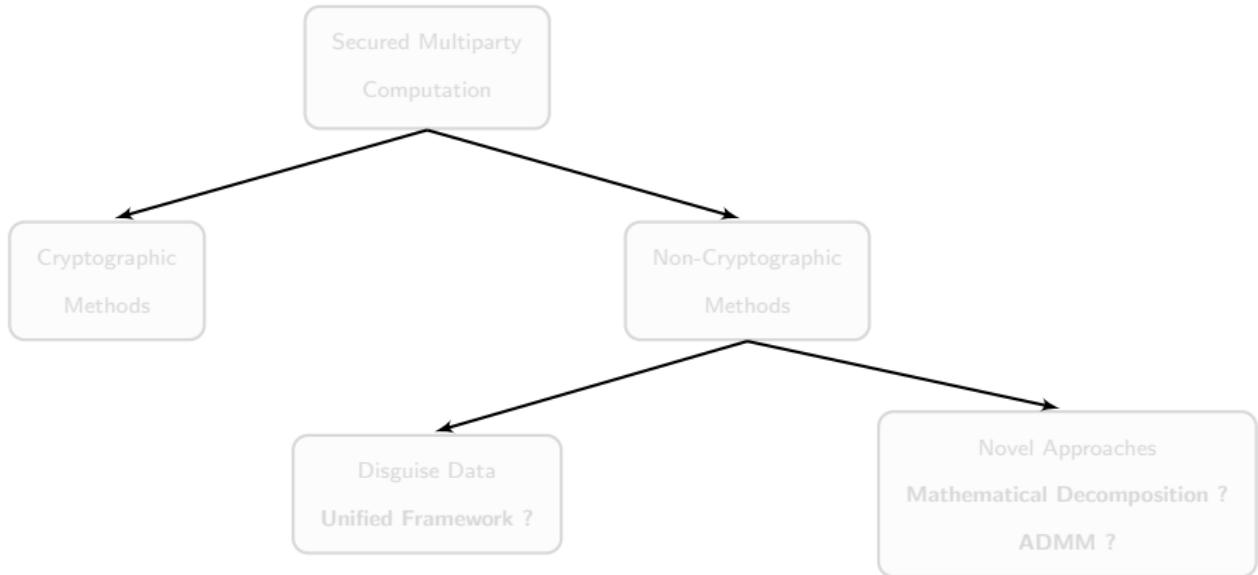
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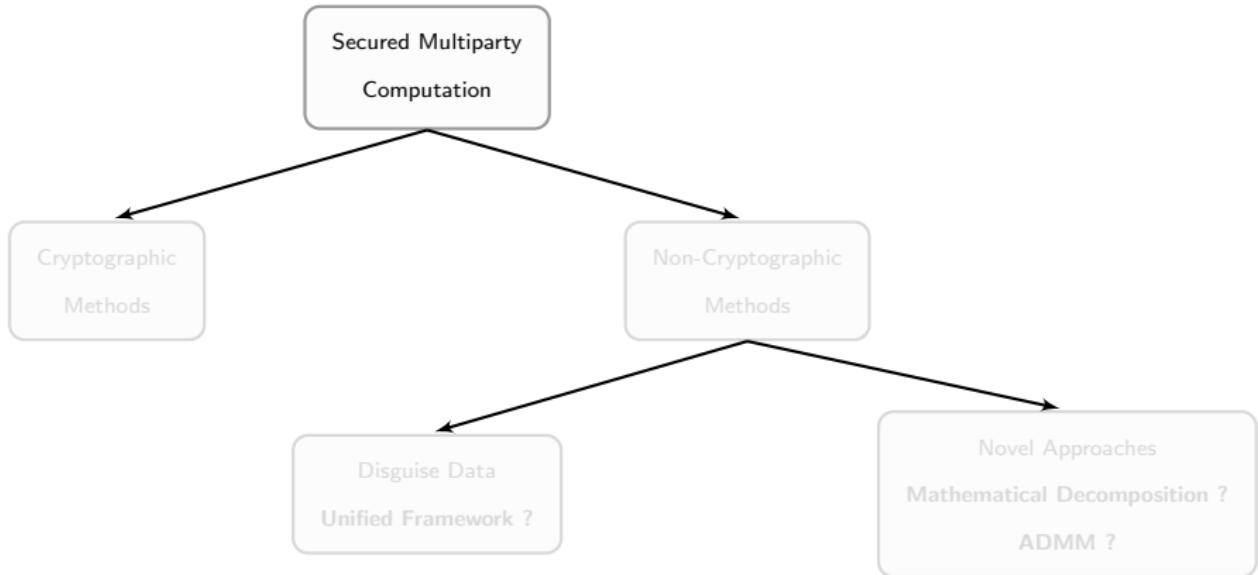
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- can we perform such computations with “acceptable” privacy guarantees ?

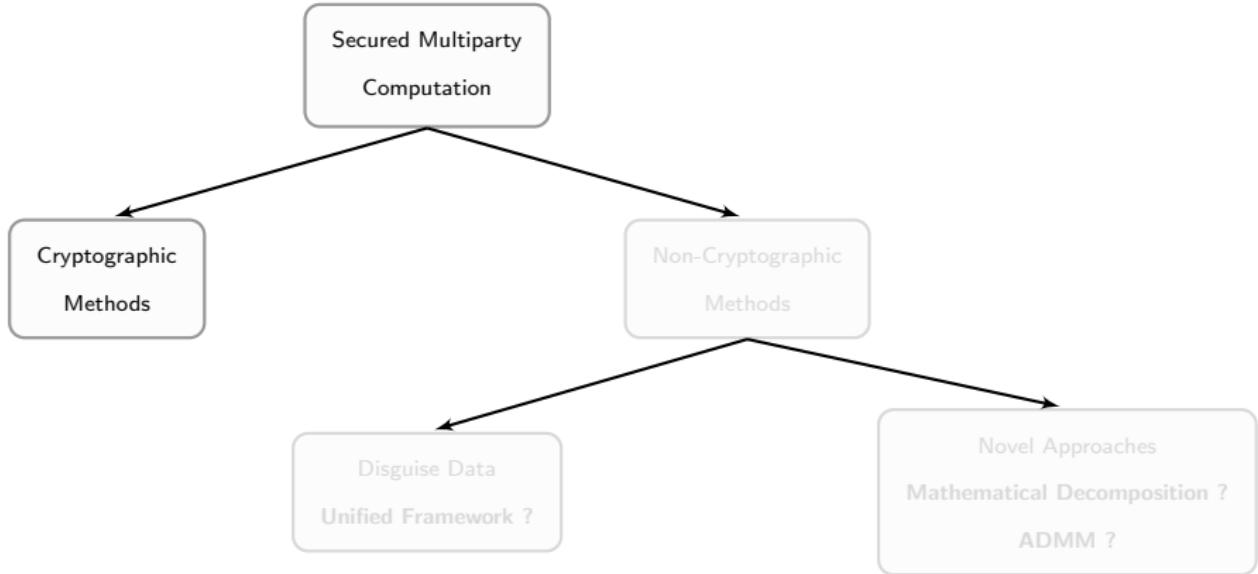
# Overview



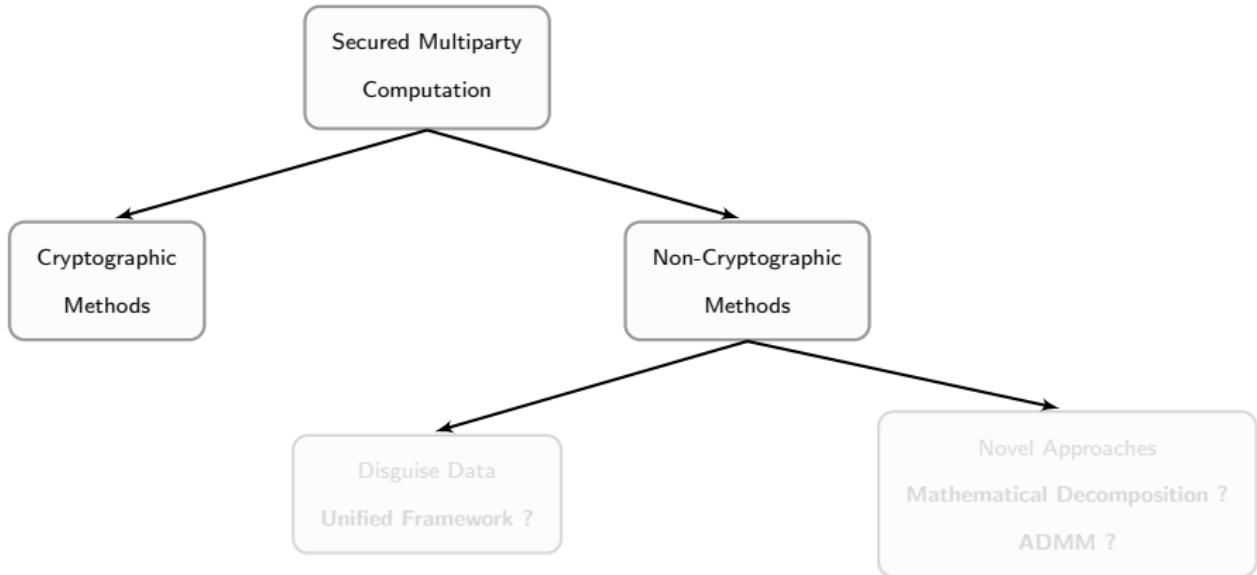
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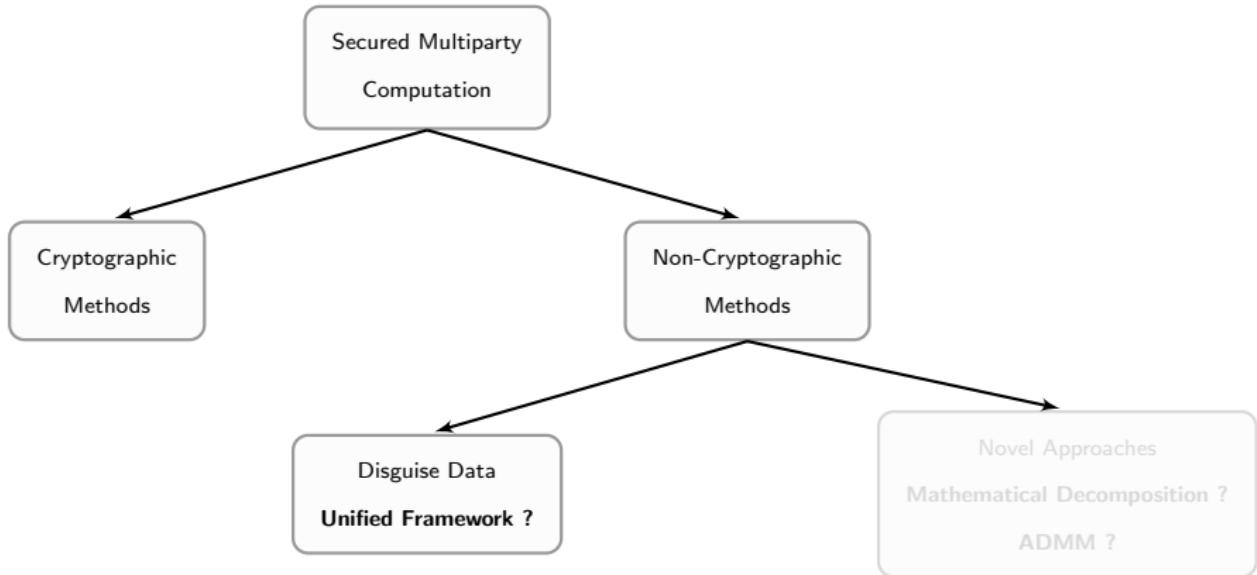
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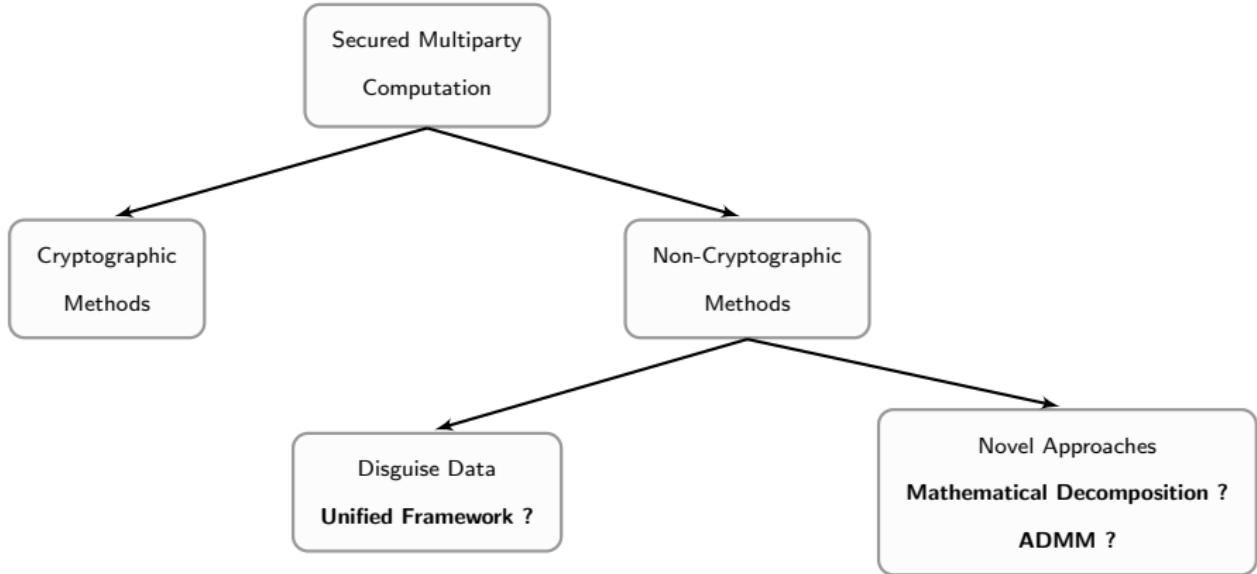
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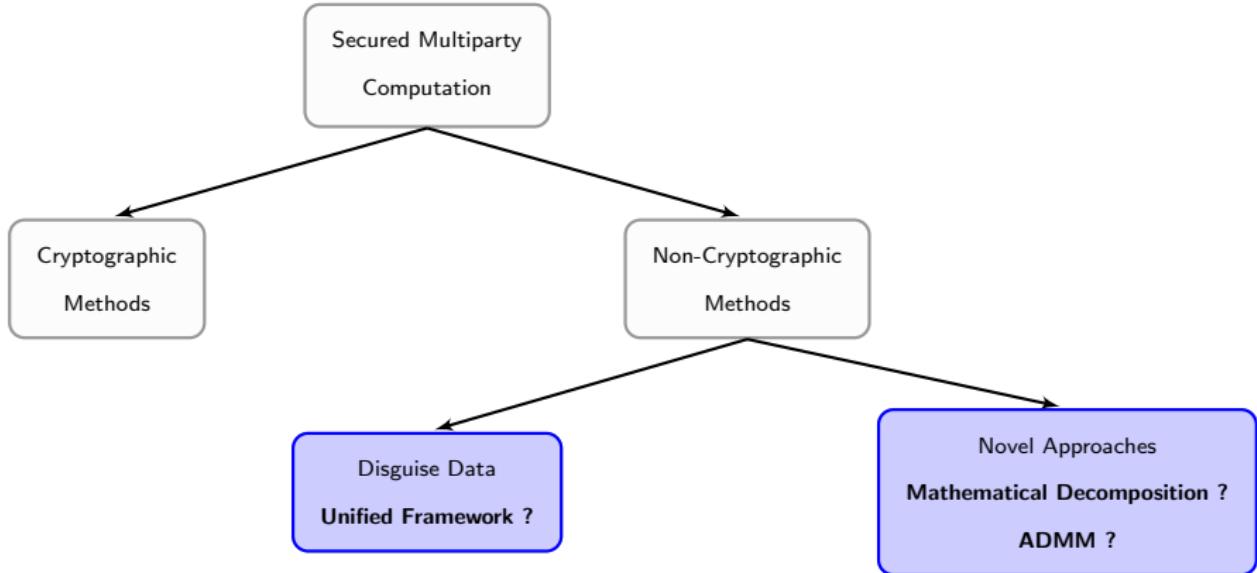
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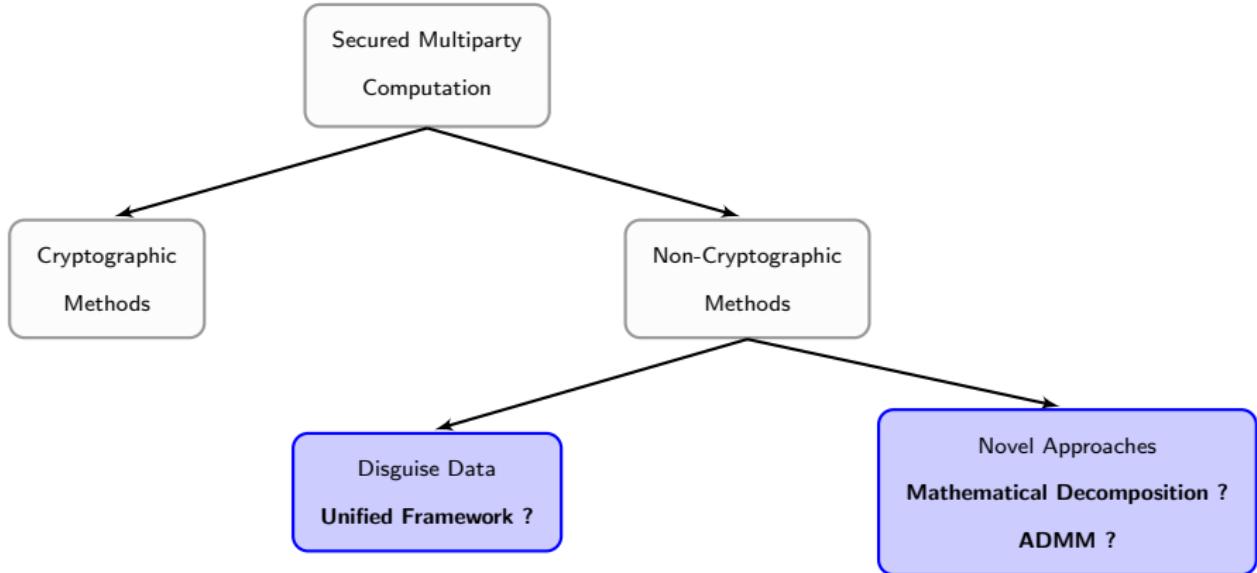
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# Overview



# Our Contributions



# Our Contributions

- **unified framework** for existing methods for disguising private data
  - absence of a systematic approach reduces the scope of applicability
  - unintended mistakes (e.g., [Du01, Vai09])
  - standard proof techniques for privacy guaranties.
- **maneuvering decomposition methods, ADMM**
- **general definition** for privacy  $\Rightarrow$  quantify the privacy
- **a number of examples**
- **comparison:** efficiency, scalability, and many others
- for details, see [WAJ<sup>+</sup>13]

[WAJ<sup>+</sup>13] P. C. Weeraddana, G. Athanasiou, M. Jakobsson, C. Fischione, and J. S. Baras. Per-se privacy preserving distributed optimization

# General Formulation

we pose the design or decision making problem

$$\begin{aligned}
 & \text{minimize} && f_0(\mathbf{x}) \\
 & \text{subject to} && f_i(\mathbf{x}) \leq 0, \quad i = 1, \dots, q \\
 & && \mathbf{C}\mathbf{x} - \mathbf{d} = \mathbf{0},
 \end{aligned} \tag{1}$$

- optimization variable is  $\mathbf{x} = (x_1, \dots, x_n) \in \mathbb{R}^n$ .
- $f_i, i = 0, \dots, q$  are *convex*
- $\mathbf{C} \in \mathbb{R}^{p \times n}$  with  $\text{rank}(\mathbf{C}) = p$
- $\mathbf{d} \in \mathbb{R}^p$
  
  
  
  
  
  
  
  
- **we would like to solve the problem in a privacy preserving manner**

# Unification, Disguising Private Data for SMC

## Proposition (change of variables)

- $\phi : \mathbb{R}^m \rightarrow \mathbb{R}^n$  be a function, with image covering the problem domain  $\mathcal{D}$
- change of variables:

$$\mathbf{x} = \phi(\mathbf{z}) . \quad (2)$$

- resulting problem:

$$\begin{aligned} & \text{minimize} && f_0(\phi(\mathbf{z})) \\ & \text{subject to} && f_i(\phi(\mathbf{z})) \leq 0, \quad i = 1, \dots, q \\ & && \mathbf{C}\phi(\mathbf{z}) - \mathbf{d} = \mathbf{0} \end{aligned} \quad (3)$$

- $\mathbf{x}^*$  solves problem (1)  $\Rightarrow \mathbf{z}^* = \phi^{-1}(\mathbf{x}^*)$  solves problem (3)
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privacy is via the function compositions:

$$\hat{f}_i(\mathbf{z}) = f_i(\phi(\mathbf{z})) , \quad \text{dom } \hat{f}_i = \{\mathbf{z} \in \text{dom } \phi \mid \phi(\mathbf{z}) \in \text{dom } f_i\}$$

$$\hat{h}_i(\mathbf{z}) = \mathbf{C}\phi(\mathbf{z}) - \mathbf{d} , \quad \text{dom } \hat{h}_i = \{\mathbf{z} \in \text{dom } \phi \mid \phi(\mathbf{z}) \in \mathbb{R}^n\}$$

# Example of Change of Variables

- **affine transformation:**  $x = \phi(z) = Bz - a$ ,  $B \in \mathbb{R}^{n \times p}$ ,  
 $\text{rank}(B) = n$ ,  $a \in \mathbb{R}^n$ .

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$$\begin{aligned} & \text{minimize} && c^T x \\ & \text{subject to} && Ax \geq b \end{aligned}$$

- variable is  $x \in \mathbb{R}^n$
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- **equivalent problem:**

$$\begin{aligned} & \text{minimize} && \hat{c}^T z \\ & \text{subject to} && \hat{A}z \geq \hat{b} \end{aligned}$$

- variable is  $z \in \mathbb{R}^p$
- data:  $\hat{c} = B^T c \in \mathbb{R}^p$ ,  $\hat{A} = AB \in \mathbb{R}^{m \times p}$ ,  $\hat{b} = b - Aa \in \mathbb{R}^m$

# Unification, Disguising Private Data for SMC

## Proposition (transformation of objective and constraint functions)

- $\psi_0 : \mathbb{D}_0 \subseteq \mathbb{R} \rightarrow \mathbb{R}$  is monotonically increasing and  $\mathbb{D}_0 \supseteq \text{image } f_0$
- $\psi_i : \mathbb{D}_i \subseteq \mathbb{R} \rightarrow \mathbb{R}$ , with  $\mathbb{D}_i \supseteq \text{image } f_i$  and  $\psi_i(z) \leq 0 \Leftrightarrow z \leq 0$
- $\psi : \mathbb{R}^p \rightarrow \mathbb{R}^m$  satisfies  $\psi(\mathbf{z}) = \mathbf{0} \Leftrightarrow \mathbf{z} = \mathbf{0}$
- if  $\mathbf{x}^*$  solves

$$\begin{aligned} & \underset{\mathbf{x}}{\text{minimize}} && \psi_0(f_0(\mathbf{x})) \\ & \text{subject to} && \psi_i(f_i(\mathbf{x})) \leq 0, \quad i = 1, \dots, q \\ & && \psi(\mathbf{Cx} - \mathbf{d}) = \mathbf{0}, \end{aligned} \tag{4}$$

then solution  $\mathbf{x}^*$  problem (1)

- the optimal value of problem (1),  $p^*$ , and that of problem (4),  $q^*$ , are related by

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$$\bar{h}_i(\mathbf{x}) = \psi(\mathbf{Cx} - \mathbf{d}) \quad \text{dom } \bar{h}_i = \mathbb{R}^n$$

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# Quantify Privacy

## Definition (Attacker model, Passive adversary)

- an entity involved in solving the global problem
- it obtain messages exchanged during different stages of the solution method
- keeps a record of all information it receives
- try to learn and to discover others' private data

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## Definition (Adversarial knowledge)

- the set  $\mathcal{K}$  of information that an adversary might exploit to discover private data
- set  $\mathcal{K}$  can encompass
  - *real-valued components*:  $\mathcal{K}_{\text{real}}$
  - transformed variants of private data
  - statements

# Quantify Privacy

Definition (Privacy index,  $(\xi, \eta) \in [0, 1] \times \mathbb{N}$ )

- private data  $c \in \mathcal{C}$  is related to some adversarial knowledge  $\mathbf{k} \in \mathcal{K}_{\text{real}} \subseteq \mathcal{K}$  by a vector values function  $f_c : \mathcal{C} \times \mathcal{K}_{\text{real}} \rightarrow \mathbb{R}^m$ , such that  $f_c(c, \mathbf{k}) \leq \mathbf{0}$
- consider the uncertainty set

$$\mathcal{U} = \{c \mid f_c(c, \mathbf{k}) \leq \mathbf{0}, \text{ } f_c \text{ is arbitrary, } \mathcal{K}\} \quad (6)$$

- then

$$\xi = 1 - 1/N_{\mathcal{K}}, \quad N_{\mathcal{K}} \text{ is the cardinality of } \mathcal{U} \quad (7)$$

$$\eta = \text{affine dimension of } \mathcal{U} \quad (8)$$

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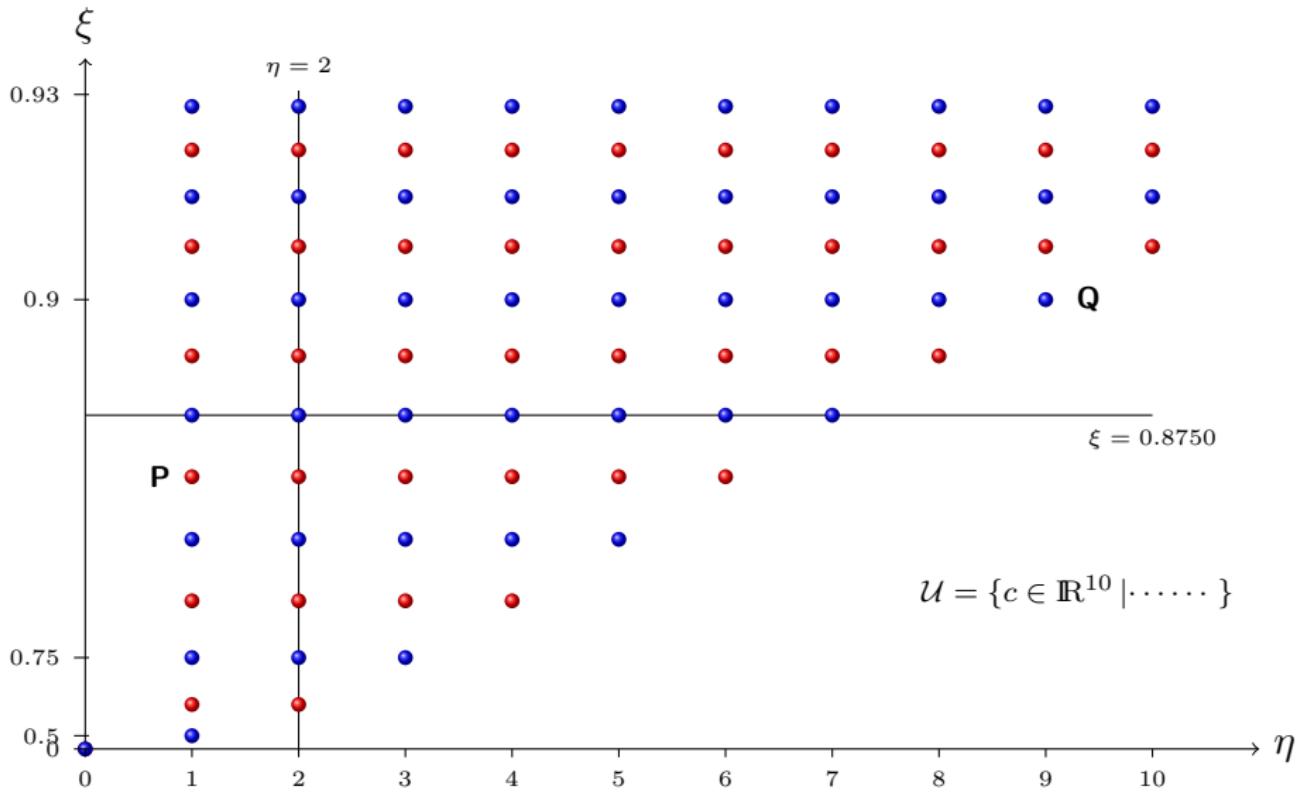
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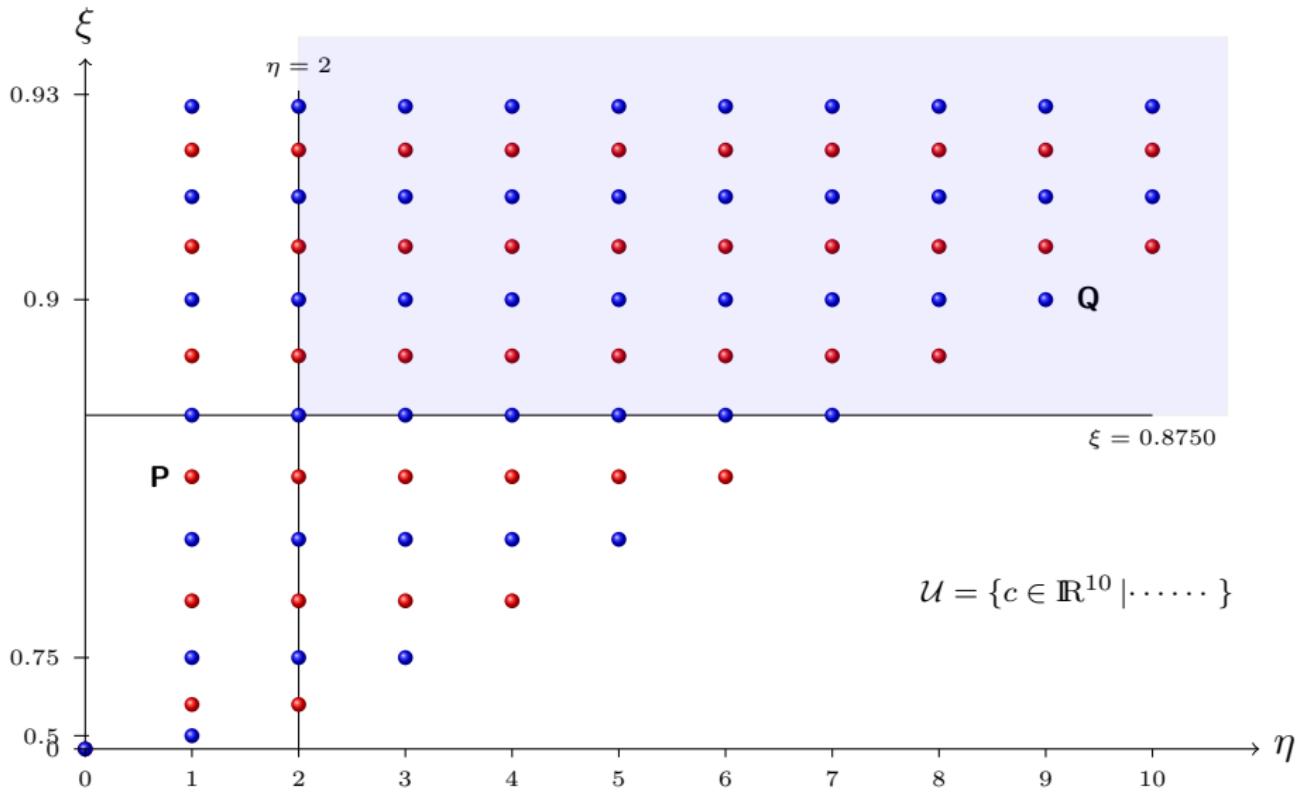
$\xi$  : a measure of probability that the adversary guesses wrong

$\eta$  : indicates how effective the transformation disguises the private data

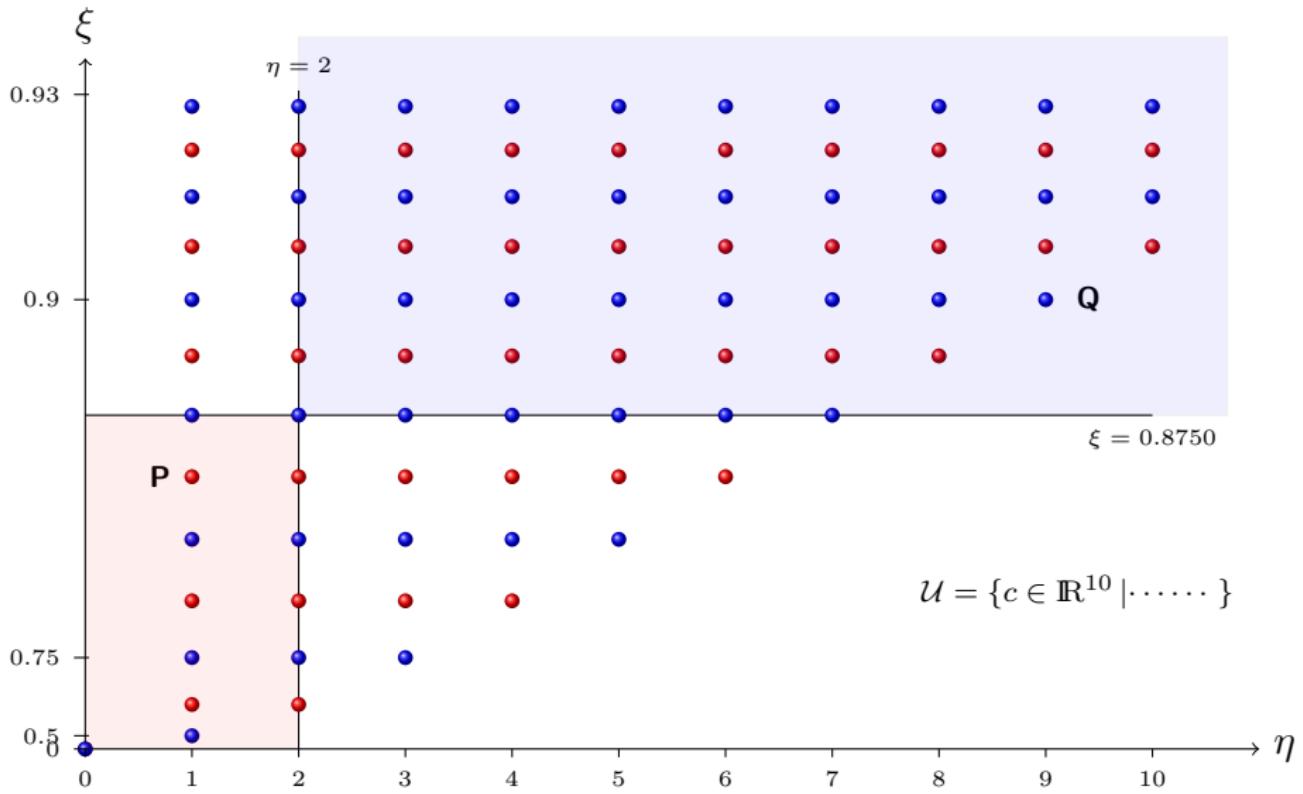
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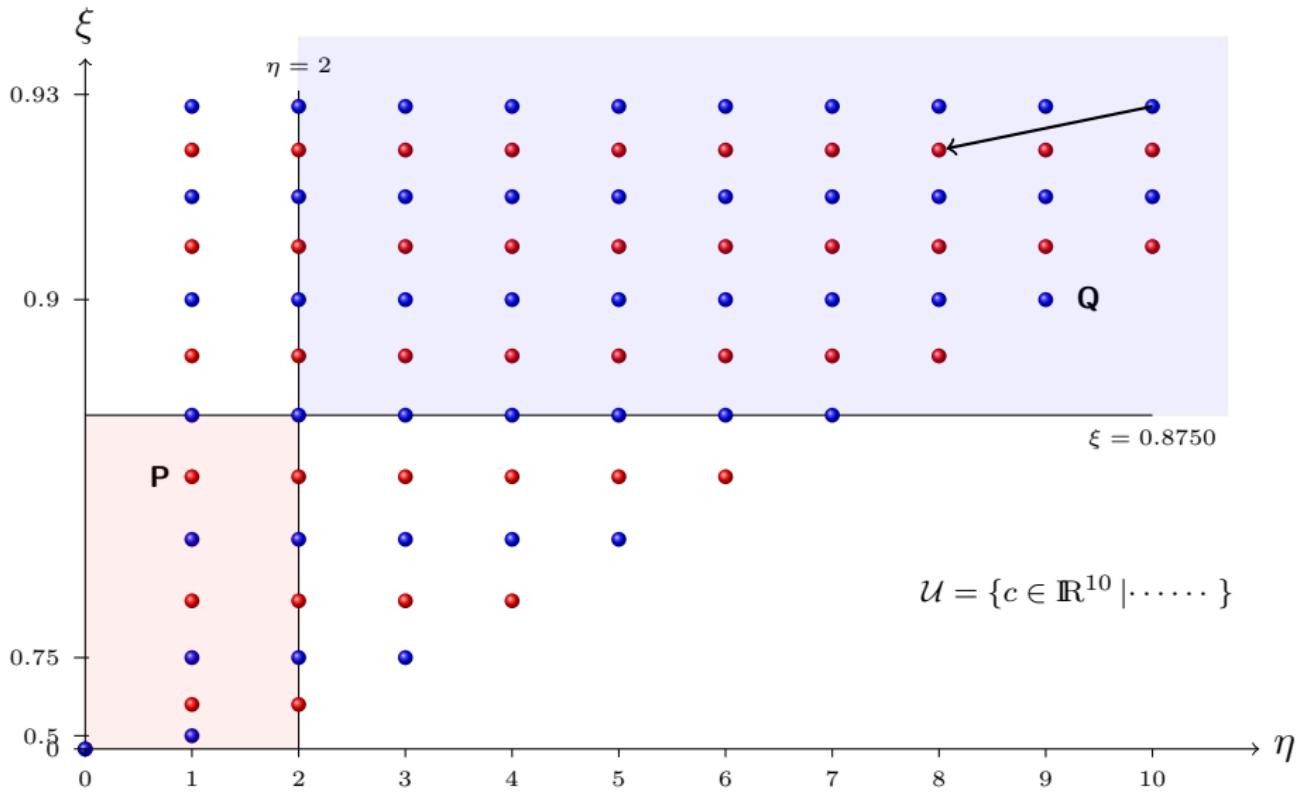
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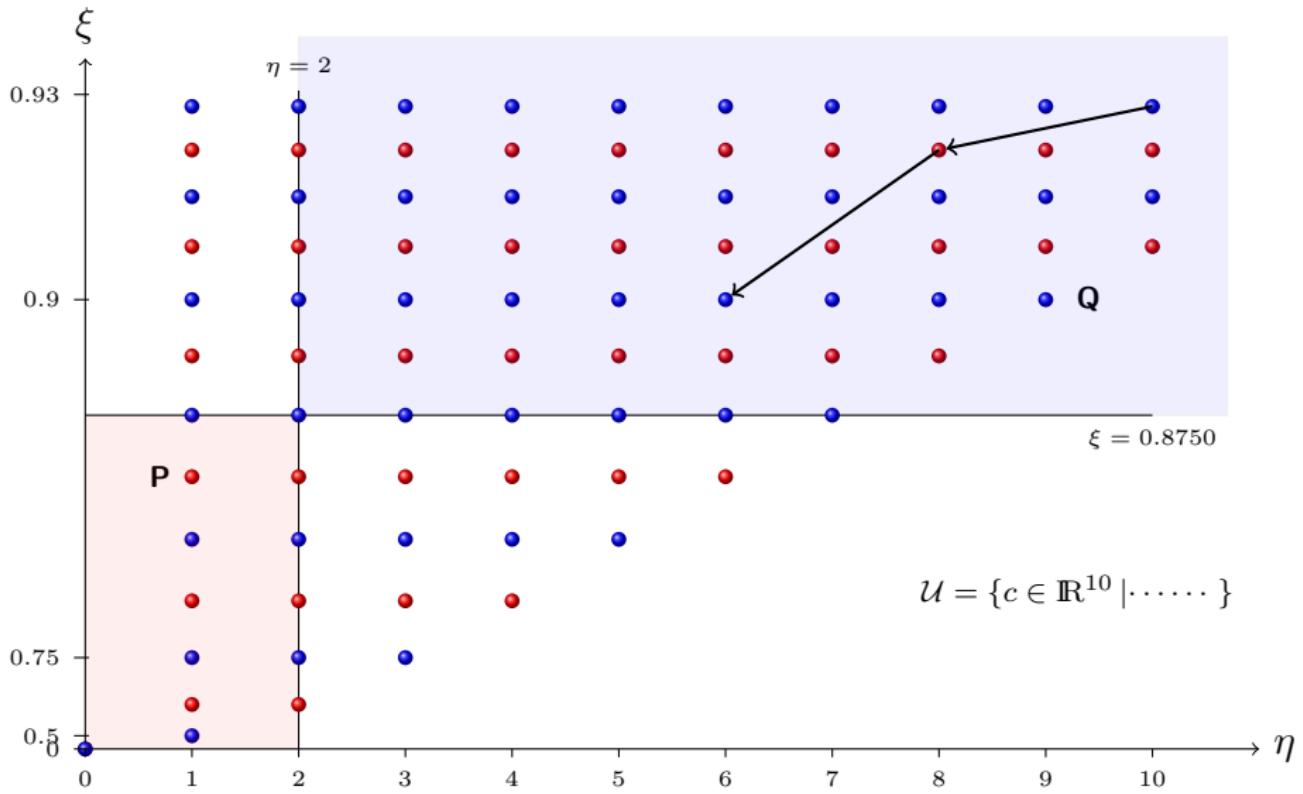
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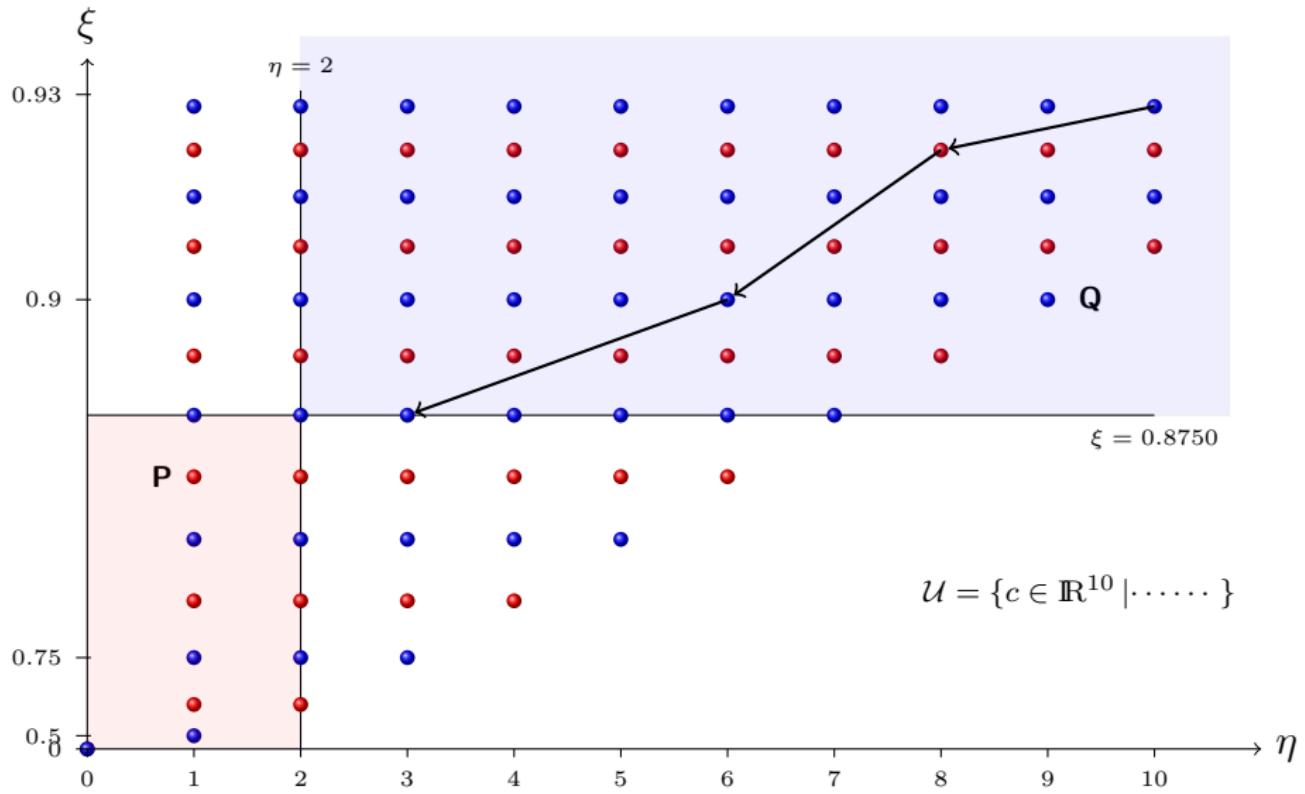
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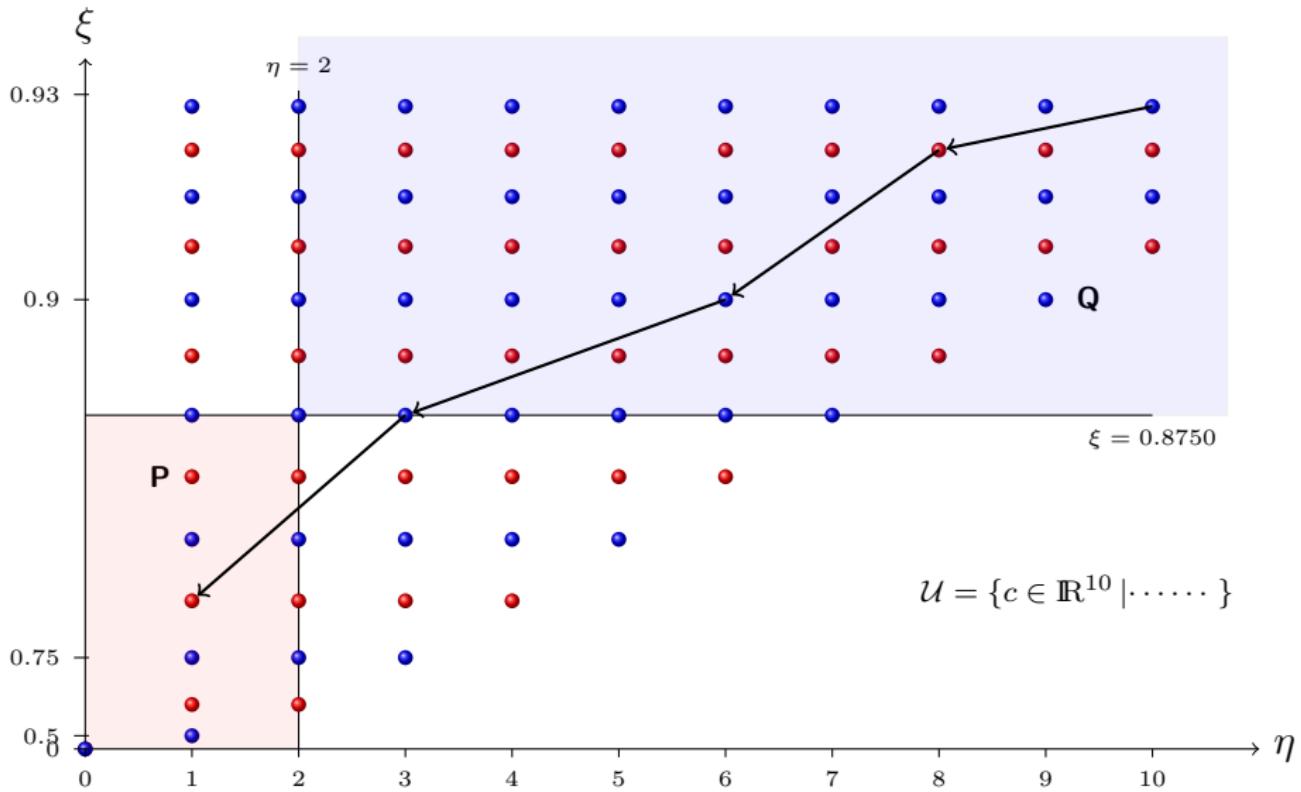
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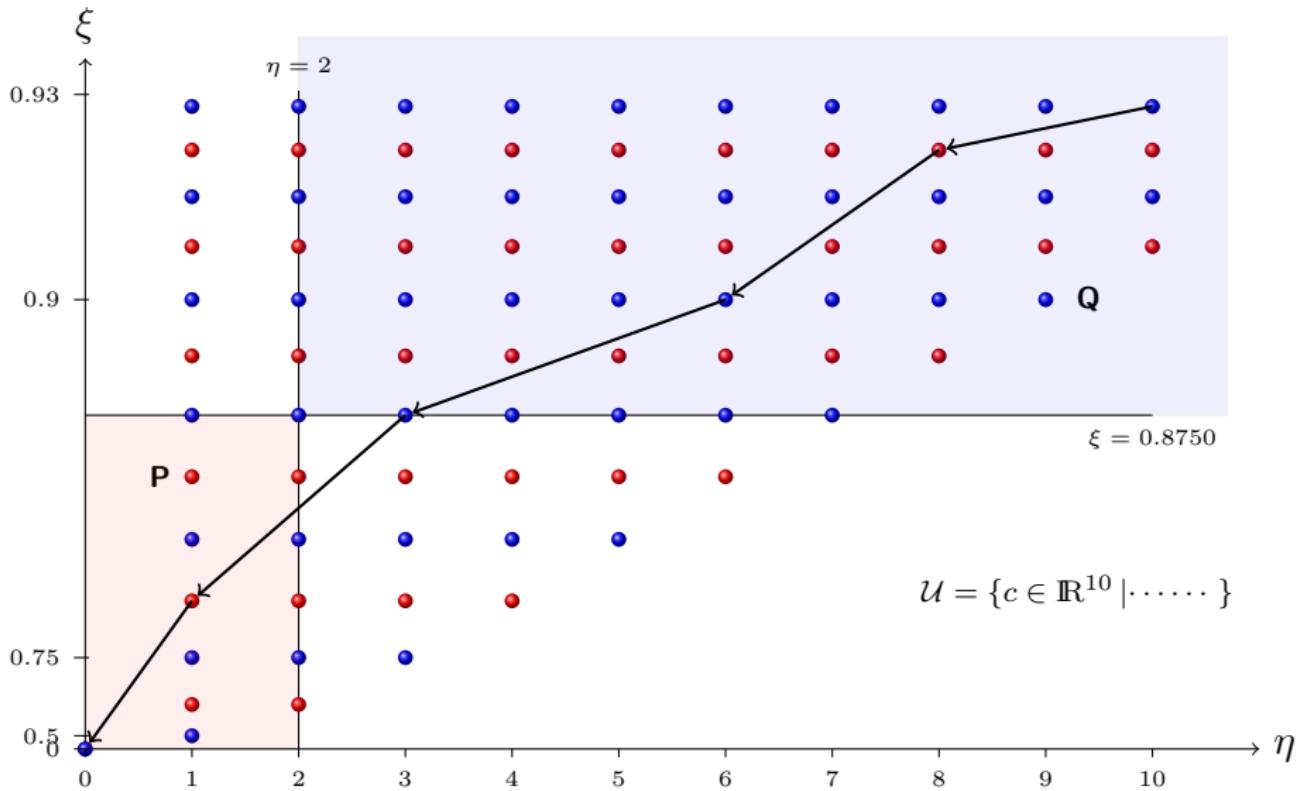
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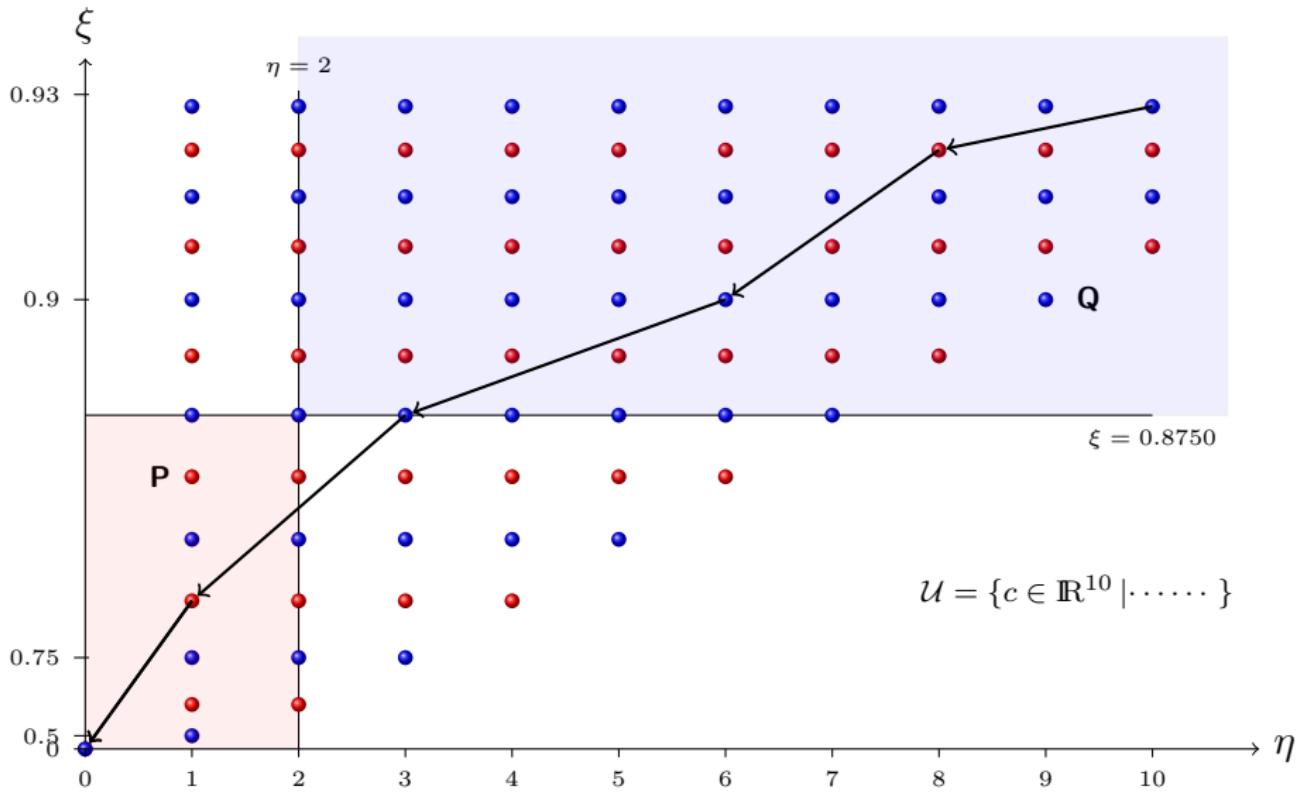
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# Privacy Index in a Least-Squares Problem

- original problem:

$$\text{minimize } \|\mathbf{a}x - \mathbf{b}\|_2$$

- variable is  $x \in \mathbb{R}$
- private data:  $\mathbf{a} = (\mathbf{a}_1, \mathbf{a}_2) \in \mathbb{R}^6$ ,  $\mathbf{b} = (\mathbf{b}_1, \mathbf{b}_2) \in \mathbb{R}^6$
- 2-parties: party  $i$  owns  $\mathbf{a}_i, \mathbf{b}_i$ ,  $i = 1, 2$

- equivalent problem:

$$\text{minimize } \|\mathbf{a}x - \mathbf{b}\|_2^2 - \mathbf{b}^\top \mathbf{b} = (\textcolor{blue}{r}_1 + r_2)x^2 - 2(\textcolor{blue}{s}_1 + s_2)x$$

- variable is  $x \in \mathbb{R}$
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# Privacy Index in a Least-Squares Problem

- party 2 is the adversary and wants to discover  $\mathbf{a}_1$

- knowledge of party 2

$$\mathcal{K} = \left\{ r_1, s_1, \{r_1 = \mathbf{a}_1^\top \mathbf{a}_1\}, \{s_1 = \mathbf{b}_1^\top \mathbf{a}_1\} \right\}$$

- the uncertainty set of  $\mathbf{a}_1$ :

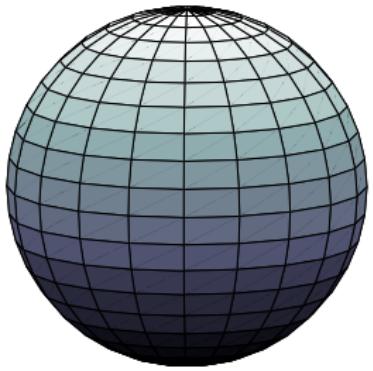
$$\mathcal{U} = \left\{ \mathbf{a}_1 \mid r_1 = \mathbf{a}_1^\top \mathbf{a}_1, s_1 = \mathbf{b}_1^\top \mathbf{a}_1, \mathbf{b}_1 \in \mathbb{R}^3 \right\}$$

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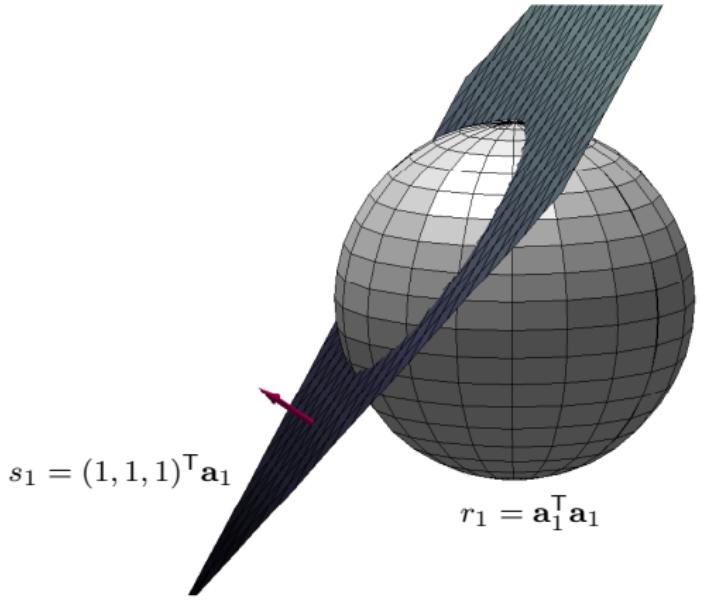


$$r_1 = \mathbf{a}_1^\top \mathbf{a}_1$$

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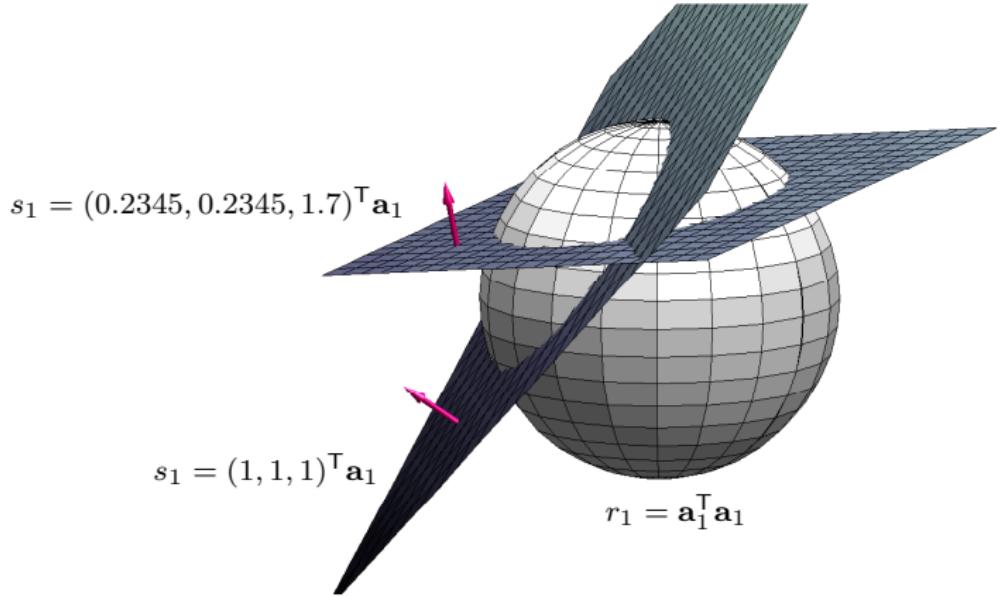
# Privacy Index in a Least-Squares Problem



- the uncertainty set of  $\mathbf{a}_1$ :

$$\mathcal{U} = \left\{ \mathbf{a}_1 \mid r_1 = \mathbf{a}_1^T \mathbf{a}_1, s_1 = \mathbf{b}_1^T \mathbf{a}_1, \mathbf{b}_1 \in \mathbb{R}^3 \right\}$$

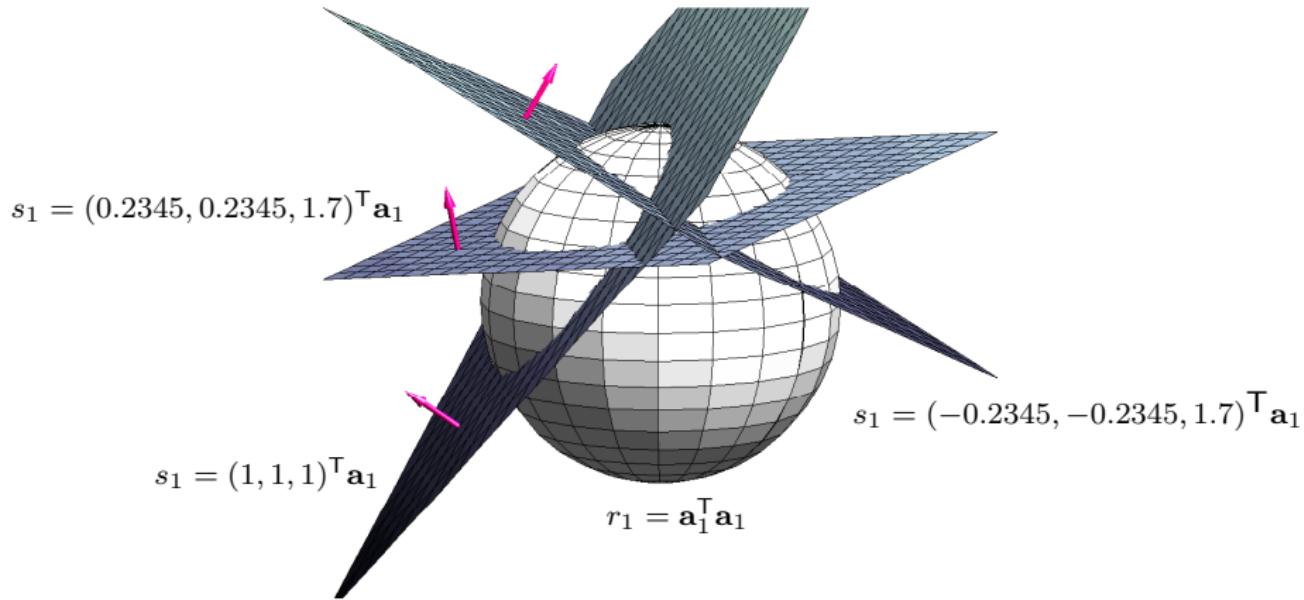
# Privacy Index in a Least-Squares Problem



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$$\mathcal{U} = \left\{ \mathbf{a}_1 \mid r_1 = \mathbf{a}_1^T \mathbf{a}_1, s_1 = \mathbf{b}_1^T \mathbf{a}_1, \mathbf{b}_1 \in \mathbb{R}^3 \right\}$$

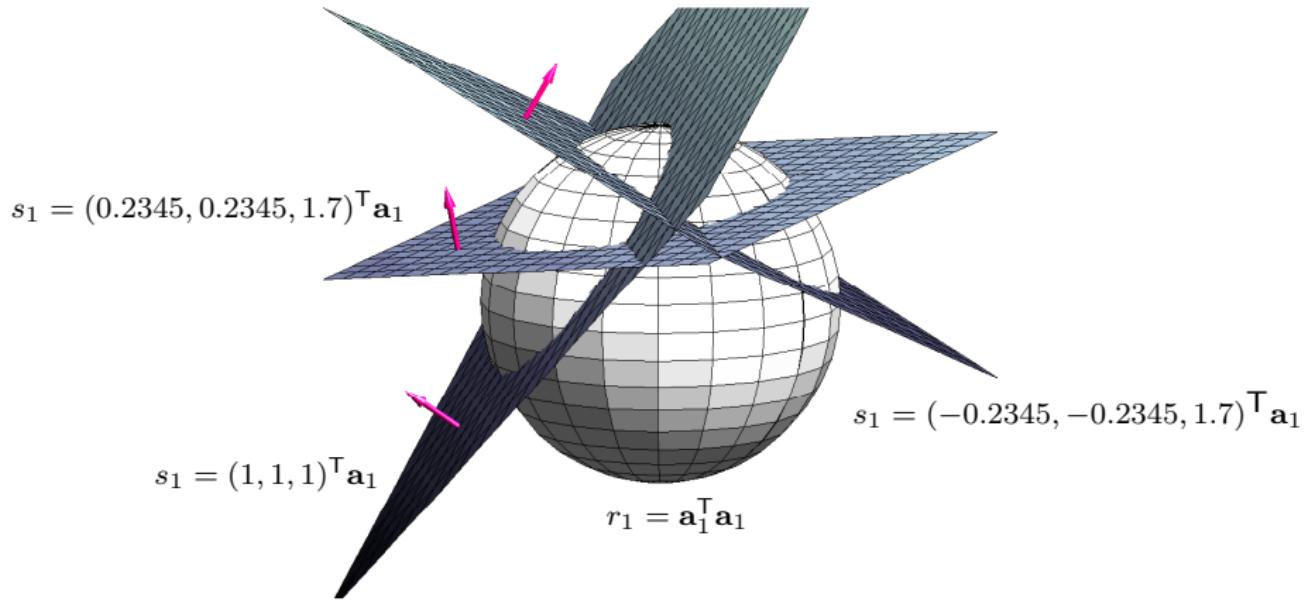
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$\mathbf{b}_1$  is known:  $(\xi, \eta) = (1, 2)$

$\mathbf{b}_1$  is arbitrary:  $(\xi, \eta) = (1, 3)$

# Cryptographic vs Non-Cryptographic Methods

Cryptographic methods	Non-Cryptographic methods
<ul style="list-style-type: none"><li>• large circuit representations (1000s of bits) to compute <math>f(\mathbf{A}_1, \dots, \mathbf{A}_n)</math></li></ul>	no such restrictions
<ul style="list-style-type: none"><li>• not scalable</li></ul>	scalable
<ul style="list-style-type: none"><li>• finite field restriction for <math>\mathbf{A}_i</math></li></ul>	no such restrictions
<ul style="list-style-type: none"><li>• hardly handle non-integer valued <math>\mathbf{A}_i</math> (overflow, underflow, round-off, and truncations errors)</li></ul>	no such restrictions HQ implementations (LAPACK,BLAS)
<ul style="list-style-type: none"><li>• <math>f_0</math> and <math>\mathbf{g}</math> are often restricted</li></ul>	no hard restrictions
<ul style="list-style-type: none"><li>• mechanism influences the algorithm iterations</li></ul>	mechanism is transparent to the solver
<ul style="list-style-type: none"><li>• theory for general <math>f_0</math> and <math>\mathbf{g}</math> are not promising</li></ul>	there exist a rich and a promising theory, e.g., convex optimization
<ul style="list-style-type: none"><li>• privacy guarantees for <math>\mathbf{A}_i</math> are broadly studied</li></ul>	to be investigated

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# Cryptographic Vs Non-Cryptographic Methods

encrypting simplex algorithm iterations...a quote from Toft [Tof09]

- start with **32-bit numbers**
- **after ten iterations** these have grown to **32 thousand bits**
- **after twenty iterations** they have increased to **32 million**
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INEFFICIENT

# Conclusions

If you think cryptography is  
the answer to your problem,  
then you dont know what  
your problem is.

-PETER G. NUMANN  
Principal Scientist, SRI International  
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- cryptography is **inefficient**
- **alternatives** for cryptographic approaches: **less investigated**
- we believe that **substantial research is required**

# THANK YOU



# ON THE APPLICATION OF OPTIMIZATION METHODS FOR SECURED MULTIPARTY COMPUTATIONS

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