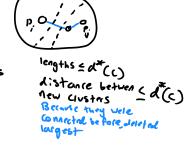
Stacing di is length of last deleted edge

P; E ('s, P; E C' + C's)





<u> Proof</u>

If you can delete an edge then it's a cylle Goetet G'

MST(G')=MST(G) Edge has largest weight -> Campt be post of MST 4 MSTCG1)=MST(G)

efficiency: Each deletion legules O(VIE) amount of work # deletical E -> V-1 E-x= v-1

X=E-V+1

Lecture - Shortest Path

Single-Source Shortest Paths: Input: directed weighted graph G=CV,E)

W:E>R weight of Path:

P = V1, V2, ... VK

W(P)= EW(V, V; H) = Sum of edge weights Shortest Path weight:

S (u,v)= {min {wcp}: u ~v} { 00 if there is no path

Varian +S Weight Copie Sents:

· Cost accumulates along path (1) Single-source ·what to minimize (2) Oll pairs

3) Single pair Generalizes BFS 4) Single destination

negative weights

Answerd so long as no hegative weight cycles

Subpath of shortest parts is a shortest Path Proof (ut and post

P;s Shortest path

Optimal substructure

S(u,v)=w(Pux)+w(Pxy)+w(Pyv) is minimal Suppose 3 another Pry With WCP' j < W(Pry)

Contradiction! Mesuit shortest

Cycles Cannot Contain Cycles! - neg weight out

- Zero weight cycle ok ... Rule out!

All algorithms use some setup: Initialize-single-Source (G, w)

lack oner nen

V.J= 00 V.TI= NIL

2) VIT = prodecossor in tree

Output of algorithm

VVEV 1) V.d= S(5V)

initialize to oo v.d 2 S(S,V) during algorithm (shortest path estimate)

· IT induces shortest path tree