

Bitonic Tour Problem

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In the **euclidean traveling-salesman problem**, we are given a set of n points in the plane, and we wish to find the shortest closed tour that connects all n points. Figure 15.11(a) shows the solution to a 7-point problem. The general problem is NP-hard, and its solution is therefore believed to require more than polynomial time (see Chapter 34).

J. L. Bentley has suggested that we simplify the problem by restricting our attention to **bitonic tours**, that is, tours that start at the leftmost point, go strictly rightward to the rightmost point, and then go strictly leftward back to the starting point. Figure 15.11(b) shows the shortest bitonic tour of the same 7 points. In this case, a polynomial-time algorithm is possible.

Describe an $O(n^2)$ -time algorithm for determining an optimal bitonic tour. You may assume that no two points have the same x-coordinate and that all operations on real numbers take unit time. (*Hint: Scan left to right, maintaining optimal possibilities for the two parts of the tour.*)

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Restricting our attention to **bitonic tours**

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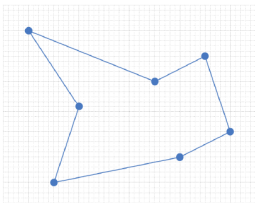


Figure: Tour

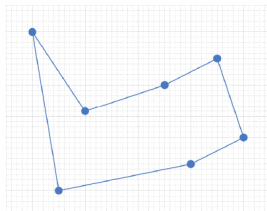


Figure: Bitonic Tour

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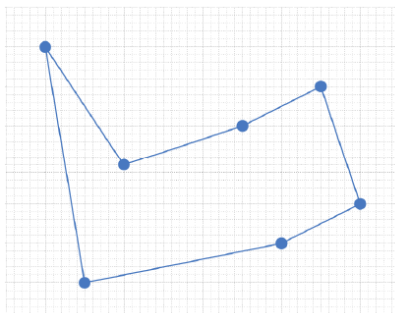
Bitonic

(computing theory, of a sequence) Having the property $x_0 \leq \cdots \leq x_k \geq \cdots \geq x_{n-1}$ for some $k, 0 \leq k < n$, or being a circular shift of such a sequence.

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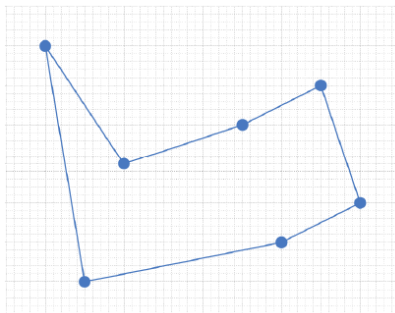
The shortest bitonic path $P_{i,j}$, where $i \leq j$, includes all points p_1, p_2, \dots, p_j ; it starts at some point p_i , goes strictly left to point p_1 , and then goes strictly right to point p_j .



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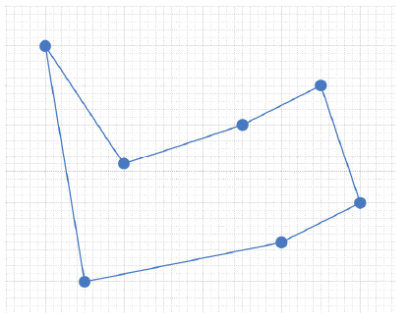
$$P_{n,n}$$



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$$P_{n,n} = P_{n-1,n} + I_{n-1,n}$$

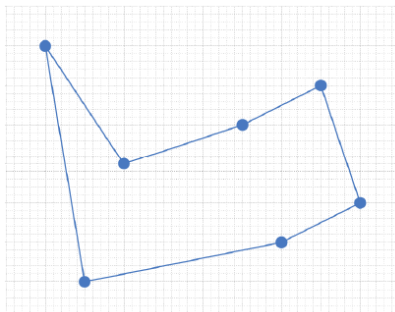


Optimal Substructure

$P_{i,j}(i < j)$ is the shortest bitonic tour.

(1). $i < j - 1$, remove the line $p_{j-1}p_j$, it becomes $P_{i,j-1}$.

(2). $i = j - 1$. let k be the predecessor of p_j . Remove $p_k p_j$ and it becomes $P_{k,j-1}$.

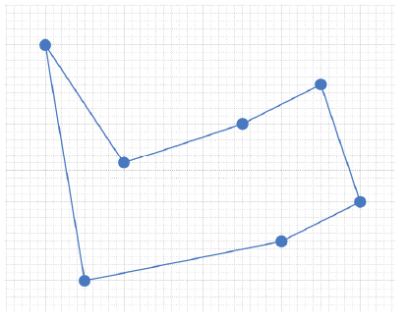


└ What is the optimal-substructure?

└ Case 1: $i < j - 1$

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$i < j - 1$. But $P_{i,j}$ includes all points p_1, \dots, p_{j-1}, p_j . p_{j-1} is the predecessor of p_j .
cut-and-paste

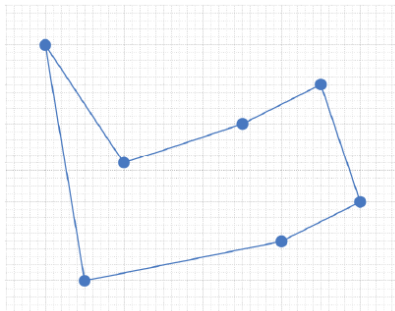


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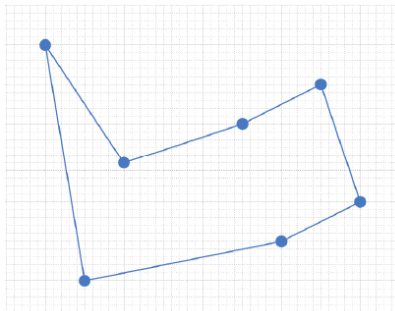
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$i = j - 1$. p_j must have a predecessor $p_k (1 \leq k \leq j - 2)$.

cut-and-paste

Why $P_{k,j-1}$? Why not $P_{j-1,k}$?



$$P[i, j] = \begin{cases} I[1, 2] & i = 1 \text{ and } j = 2 \\ P[i, j - 1] + I[j - 1, j] & i < j - 1 \\ \min_{1 \leq k \leq j-2} P[k, j - 1] + I[k, j] & i = j - 1 \end{cases}$$

- What is the **optimal-substructure**?

- Recursive formula

$$P[i, j] = \begin{cases} I[1, 2] & i = 1 \text{ and } j = 2 \\ P[i, j-1] + I[j-1, j] & i < j-1 \\ \min_{1 \leq k \leq j-2} P[k, j-1] + I[k, j] & i = j-1 \end{cases}$$

$$P[1, j] = \sum_{k=2}^j P[k-1, k]?$$

EUCLIDEAN-TSP(p)

```
1  SORT( $p$ )
2  let  $b[1..n, 2..n]$  and  $r[1..n - 2, 3..n]$  be new arrays
3   $b[1, 2] = \text{LEN}(p[1], p[2])$ 
4  for  $j = 3$  to  $n$ 
5      for  $i = 1$  to  $j - 2$ 
6           $b[i, j] = b[i, j - 1] + \text{LEN}(p_{j-1}, p_j)$ 
7           $r[i, j] = j - 1$ 
8       $b[j - 1, i] = \infty$ 
9      for  $k = 1$  to  $j - 2$ 
10          $q = b[k, j - 1] + \text{LEN}(p_k, p_j)$ 
11         if  $q < b[j, j - 1]$ 
12              $b[j - 1, j] = q$ 
13              $r[j - 1, j] = k$ 
14   $b[n, n] = b[n - 1, n] + \text{LEN}(p_{n-1}, p_n)$ 
15  return  $b$  and  $r$ 
```

```

PRINT-
TOUR( $R, N$ )
1  print  $p[n]$ 
2  print  $p[n - 1]$ 
3   $k = r[n - 1, n]$ 
4  PRINT-PATH
5  ( $r, k, n - 1$ )
6  print  $p[k]$ 

```

PRINT-PATH(r, i, j)

```

1  if  $i < j$ 
2       $k = r[i, j]$ 
3      if  $k \neq i$ 
4          print  $p[k]$ 
5      if  $k > 1$ 
6          PRINT-PATH( $r, i, k$ )
7  else
8       $k = r[j, i]$ 
9      if  $k > 1$ 
10         PRINT-PATH( $r, k, j$ )
11         print  $p[k]$ 

```

