COMPSCI 371D Homework 0 (Prerequisites)

Collaborators

- Chavez Cheong
- Khoo Qi Xuan
- Jake Heller

Part 1: Algebra and Multivariate Calculus

Problem 1.1

$$g =
abla V(x) = egin{bmatrix} (1+k)x_0 - kx_1 \ (1+k)x_1 - kx_0 \end{bmatrix}$$
 $H(x) = egin{bmatrix} k+1 & -k \ -k & k+1 \end{bmatrix}$

Problem 1.2

$$egin{align} \lambda_0 &= 1, u_0 = egin{bmatrix} rac{1}{\sqrt{2}} \ rac{1}{\sqrt{2}} \end{bmatrix} \ \lambda_1 &= 2k+1, u_1 = egin{bmatrix} rac{-1}{\sqrt{2}} \ rac{1}{\sqrt{2}} \end{bmatrix} \end{split}$$

Problem 1.3

We see that $\lambda_0=1>0$ and $\lambda_1=2k+1>1>0$ since k>0, and thus we have that all eigenvalues of H are real and positive. Since H is also a symmetric matrix, H is positive definite.

Problem 1.4

$$U = egin{bmatrix} rac{1}{\sqrt{2}} & -rac{1}{\sqrt{2}} \ rac{1}{\sqrt{2}} & rac{1}{\sqrt{2}} \end{bmatrix}$$

$$\Lambda = egin{bmatrix} 1 & 0 \ 0 & 2k+1 \end{bmatrix}$$

Problem 1.5

As U is an orthogonal matrix, we know that $U^{-1}=U^{T}$.

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Hence,
$$U^{-1}=U^T=egin{bmatrix} rac{1}{\sqrt{2}} & rac{1}{\sqrt{2}} \ -rac{1}{\sqrt{2}} & rac{1}{\sqrt{2}} \end{bmatrix}$$

Problem 1.6

$$HU = U\Lambda$$

Multiplying both sides by U^{-1}

$$HUU^{-1} = U\Lambda U^{-1}$$

$$H = U\Lambda U^{-1}$$

From Problem 1.5, we know that U is an orthonormal vector, hence $U^{-1}=U^{T}$

$$H = U\Lambda U^T$$

Hence:

$$W=U=egin{bmatrix} rac{1}{\sqrt{2}} & -rac{1}{\sqrt{2}} \ rac{1}{\sqrt{2}} & rac{1}{\sqrt{2}} \end{bmatrix}$$

$$D=\Lambda=egin{bmatrix}1&0\0&2k+1\end{bmatrix}$$

Problem 1.7

$$y(t) = a\cos(\omega t + \phi)$$

$$\dot{y}(t) = -a\omega\sin(\omega t + \phi)$$

$$\ddot{y}(t) = -a\omega^2\cos(\omega t + \phi)$$

We have $dy + \ddot{y} = 0$

$$ad\cos(\omega t + \phi) - a\omega^2\cos(\omega t + \phi) = 0$$

$$a(d-\omega^2)\cos(\omega t + \phi) = 0$$

$$\therefore \omega = \sqrt{d}$$

Problem 1.8

$$Dy - \ddot{y} = 0$$

$$egin{bmatrix} 1 & 0 \ 0 & 2k+1 \end{bmatrix} egin{bmatrix} y_0 \ y_1 \end{bmatrix} - egin{bmatrix} \ddot{y}_0 \ \ddot{y}_1 \end{bmatrix} = egin{bmatrix} 0 \ 0 \end{bmatrix}$$

We get the system of equations:

$$y_0 - \ddot{y_0} = 0$$

$$(2k+1)y_1 - \ddot{y}_1 = 0$$

Following Problem 1.7:

$$d_0 = 1$$

$$\omega_0=\sqrt{d_0}=\sqrt{1}=1$$

$$d_1 = 2k + 1$$

$$\omega_1=\sqrt{d_1}=\sqrt{2k+1}$$

Hence, we have:

$$y_0(t) = a_0 \cos(t + \phi_0)$$

$$y_1(t) = a_1 \cos(\sqrt{(2k+1)}t + \phi_1)$$

We know that $y=W^Tx$. From Problem 1.6, we know that W=U, and hence $y=U^Tx$. Multiplying both sides of the equation by U,

$$Uy = UU^Tx$$

Since U is orthonormal, $UU^T = UU^{-1} = I$

$$x = Uy$$

$$\left[egin{array}{c} x_0 \ x_1 \end{array}
ight] = \left[egin{array}{cc} rac{1}{\sqrt{2}} & -rac{1}{\sqrt{2}} \ rac{1}{\sqrt{2}} & rac{1}{\sqrt{2}} \end{array}
ight] \left[egin{array}{c} y_0 \ y_1 \end{array}
ight] = \left[egin{array}{cc} rac{1}{\sqrt{2}}y_0 - rac{1}{\sqrt{2}}y_1 \ rac{1}{\sqrt{2}}y_0 + rac{1}{\sqrt{2}}y_1 \end{array}
ight]$$

Hence, we have

$$x_0(t) = rac{1}{\sqrt{2}} a_0 \cos(t + \phi_0) - rac{1}{\sqrt{2}} a_1 \cos(\sqrt{(2k+1)}t + \phi_1)$$

$$x_1(t) = rac{1}{\sqrt{2}} a_0 \cos(t + \phi_0) + rac{1}{\sqrt{2}} a_1 \cos(\sqrt{(2k+1)}t + \phi_1)$$

Problem 1.9

In [1]:

```
from matplotlib import pyplot as plt
import numpy as np
%matplotlib inline
```

```
In [2]:
         def springs(k, a, phi, t):
             x_0 = (np.cos(t + phi[0]) * a[0] - np.cos(np.sqrt(2*k+1)*t + phi[1]) * a[0]
             x_1 = (np.cos(t + phi[0]) * a[0] + np.cos(np.sqrt(2*k+1)*t + phi[1]) * a[1]
             return np.vstack((x_0,x_1))
In [3]:
         t = np.linspace(0, 50, 1000)
         a = (1,3)
         phi = (0, np.pi/3)
In [4]:
         plt.figure(figsize=(10,6))
         points = springs(k,a,phi,t)
         x_0 = points[0]
         x_1 = points[1]
         plt.plot(t,x_0,label = "x_0(t)")
         plt.plot(t,x_1,label = "x_1(t)")
         plt.legend(bbox_to_anchor=(1.15,1), loc="upper right")
         plt.xlabel('Time t / s')
         plt.ylabel('Displacement / m')
         plt.show()
                                                                                       x_0(t)
                                                                                       x_1(t)
           2
           1
        Displacement / m
           0
          -1
```

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20

30

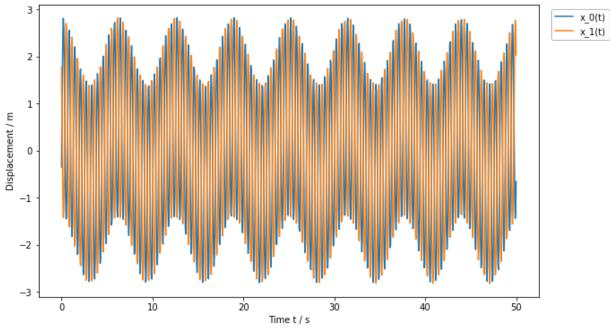
Time t / s

40

50

ó

10



Part 2: Probability

Problem 2.1

$$egin{aligned} p(k,n|h) &= inom{n}{k} h^k (1-h)^{n-k} \ &p(0,n|h) &= inom{n}{0} (1-h)^n = (1-h)^n \ &p(n,n|h) &= inom{n}{n} (h)^n = (h)^n \end{aligned}$$

Problem 2.2

Let $p_h(x)$ represent the probability density function of h.

Since h is uniformly distributed from 0 to 1.

 $p_h(x)=1$, for $x\in [0,1]$ and 0 elsewhere.

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$$egin{aligned} p(0,n) &= \int_0^1 p(0,n|h) p_h dh = \int_0^1 (1-h)^n dh = rac{1}{n+1} \ & \ p(n,n) = \int_0^1 p(n,n|h) p_h dh = \int_0^1 h^n dh = rac{1}{n+1} \end{aligned}$$

Problem 2.3

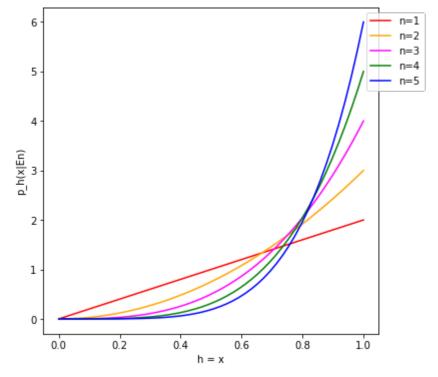
```
Using Bayes' Theorem: p_h(x|E_n)=rac{p_h(E_n|x)p_h(x)}{p_h(E_n)}=rac{x^n}{rac{1}{n+1}}=x^n(n+1)
```

```
In [6]:
    x = np.linspace(0,1,50)

    ret = []
    for n in range(1,6):
        ret.append((n+1)*x**n)

plt.figure(figsize = (6,6))
    plt.plot(x, ret[0], color='red', label='n=1')
    plt.plot(x, ret[1], color='orange', label='n=2')
    plt.plot(x, ret[2], color='magenta', label='n=3')
    plt.plot(x, ret[3], color='green', label='n=4')
    plt.plot(x, ret[4], color='blue', label='n=5')
    plt.legend(bbox_to_anchor=(1.15,1), loc="upper right")
    plt.xlabel('h = x')
    plt.ylabel('p_h(x|En)')

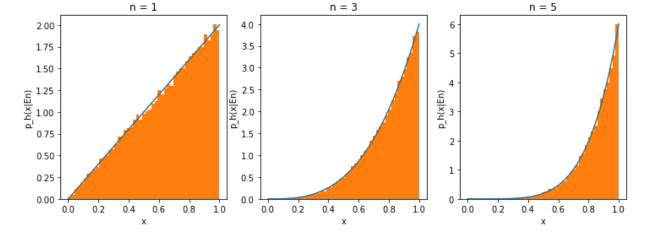
plt.show()
```



Problem 2.4

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```
In [7]:
    def sample(n, m=100000):
        rng = np.random.default_rng()
        h = rng.uniform(0,1,100000)
        b = rng.binomial(n, h)
        ret = []
        for i in range(len(b)):
            if b[i] == n:
                 ret.append(h[i])
        return ret
```



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