



Review of Machine Learning

Materials from

- Intel Deep Learning https://www.intel.com/content/www/us/en/developer/learn/course-deep-learning.html
- Introduction to Neural Networks https://www.deeplearning.ai/

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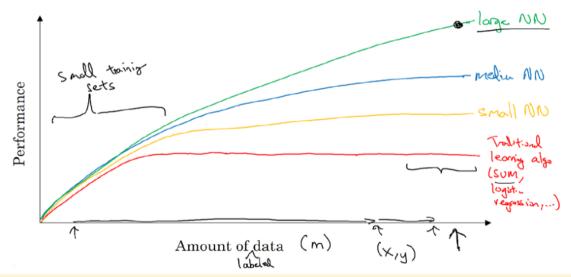
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Why is Deep Learning Taking Off?

Deep learning is taking off due to a large amount of data available through the digitization of the society, faster computation and innovation in the development of neural network algorithm.

Scale drives deep learning progress



Two things have to be considered to get to the high level of performance:

- 1. Being able to train a big enough neural network
- 2. Huge amount of labeled data

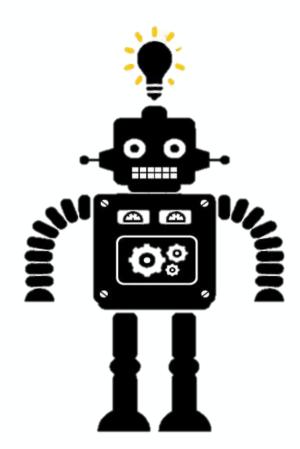
Process of Training a Neural Network

The process of training a neural network is iterative. Idea Experiment Code

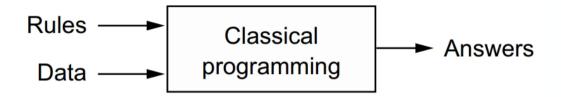
It could take a good amount of time to train a neural network, which affects your productivity. Faster computation helps to iterate and improve new algorithm.

What is Machine Learning?

Machine learning allows The model and equation computers to learn and infer from data.



Classical Programming and Machine Learning



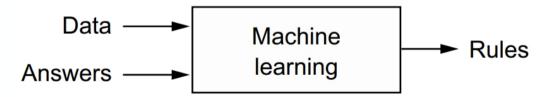
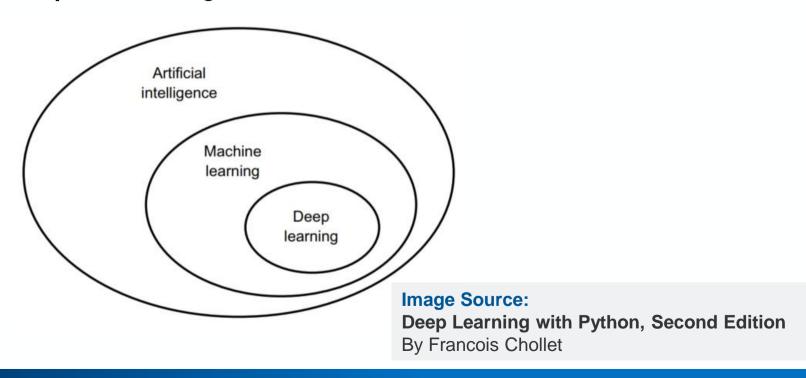


Image Source:

Deep Learning with Python, Second EditionBy Francois Chollet

Artificial Intelligence, Machine Learning, and Deep Learning



Types of Machine Learning

Supervised

Data with label (y)

data points have known outcome

Unsupervised

data points have unknown outcome

for Grouping purpose

Types of Supervised Learning

Regression

the outcome result in mumerical format, like the colories calculated from ...

outcome is continuous (numerical)

Classification

outcome is a category

Machine Learning Vocabulary

- Target: predicted category or value of the data (column to predict)
- Features: properties of the data used for prediction (non-target columns)

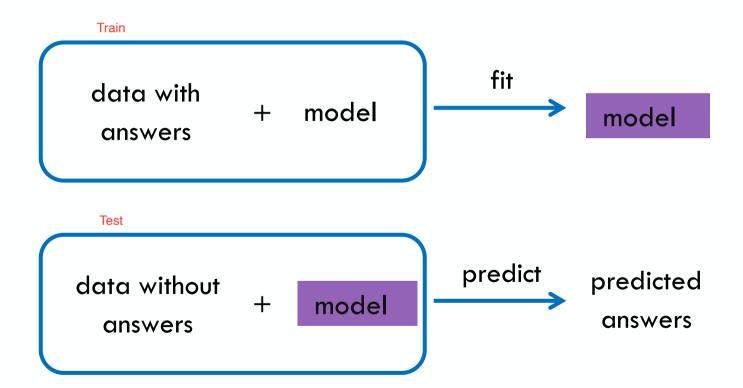
record

- Example: a single data point within the data (one row)
- Label: the target value for a single data point

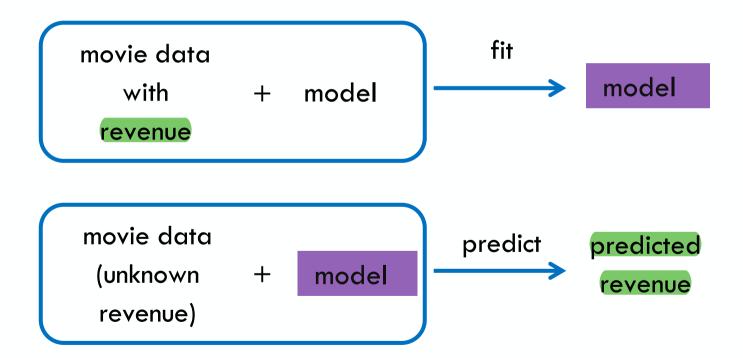
Machine Learning Vocabulary (Synonyms)

- Target: Response, Output, Dependent Variable, Labels
- Features: Predictors, Input, Independent Variables, Attributes
- **Example:** Observation, Record, Instance, Datapoint, Row
- Label: Answer, y-value, Category

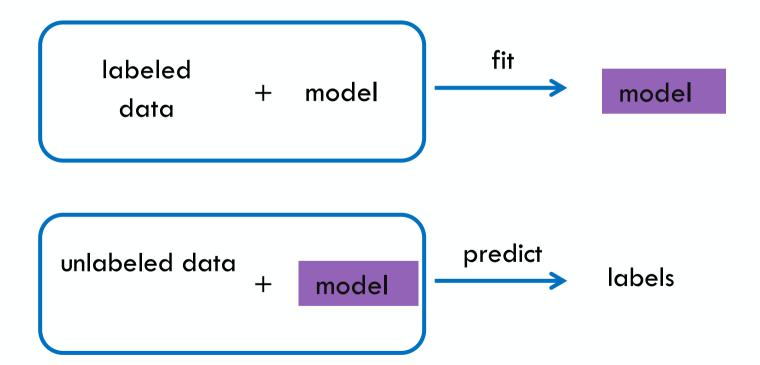
Supervised Learning Overview



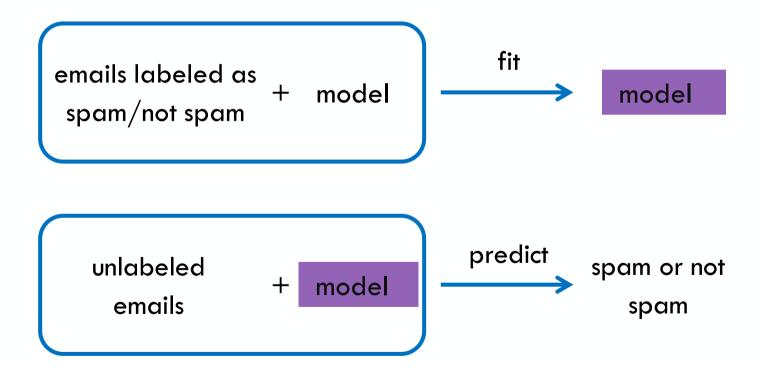
Regression: Numeric Answers



Classification: Categorical Answers



Classification: Categorical Answers



Three Types of Classification Predictions

- Hard Prediction: Predict a single category for each instance.
- Ranking Prediction: Rank the instances from most likely to least likely. (binary classification)
- Probability Prediction: Assign a probability
 distribution across the classes to each instance.

Metrics for Classification

 Hard Prediction: Accuracy, Precision, Recall (Sensitivity), Specificity, F1 Score

Ranking Prediction: AUC (ROC), Precision-Recall
 Area Under Curve
 Curves

Probability Prediction: Log-loss (aka Cross-Entropy),
 Brier Score

Metrics for Regression

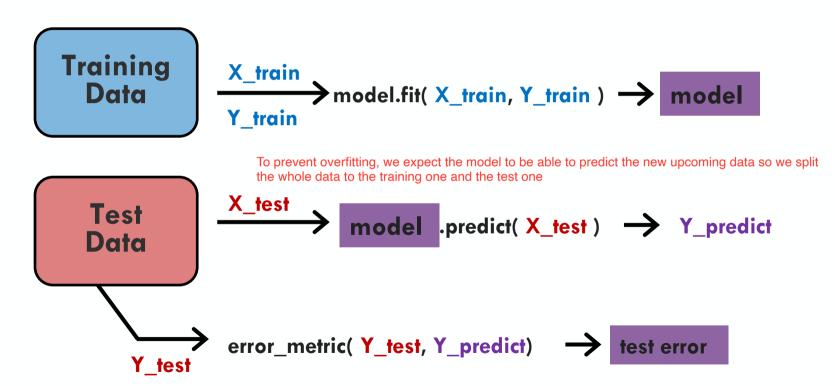
Root Mean Square Error (RMSE) ignore the negative and positive term so we use "square"

$$RMSE = \sqrt{\frac{1}{n}\sum_{i=1}^n (y_i - \hat{y}_i)^2} \quad \text{Y hat refer to the predicted value so if the prediction is correct, "y - (y hat)" should equal to 0}$$

Mean Absolute Error (MAE)

$$MAE = \frac{1}{n} \sum_{i=1}^{n} |y_i - \hat{y}_i|$$

Fitting Training and Test Data

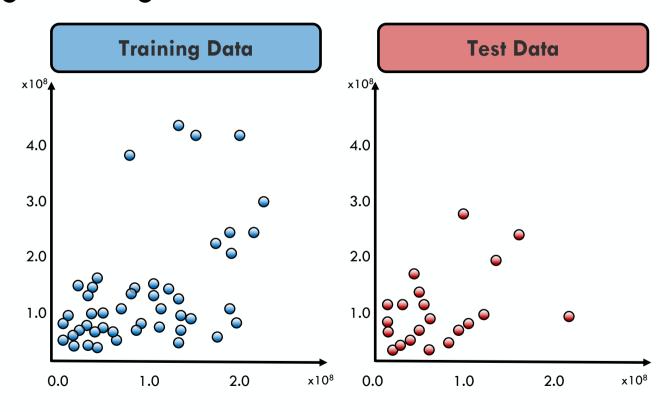


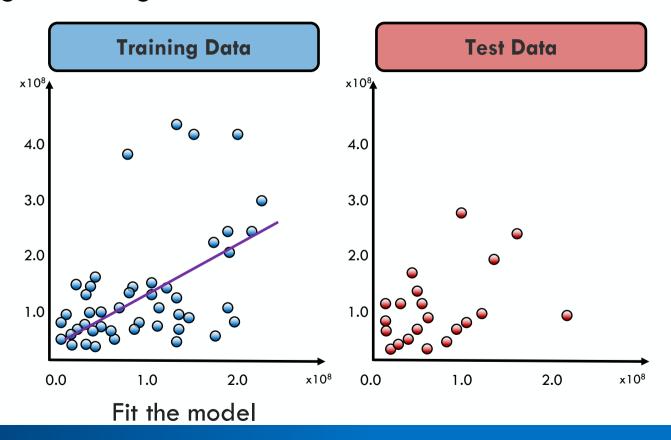
Training Data fit the model

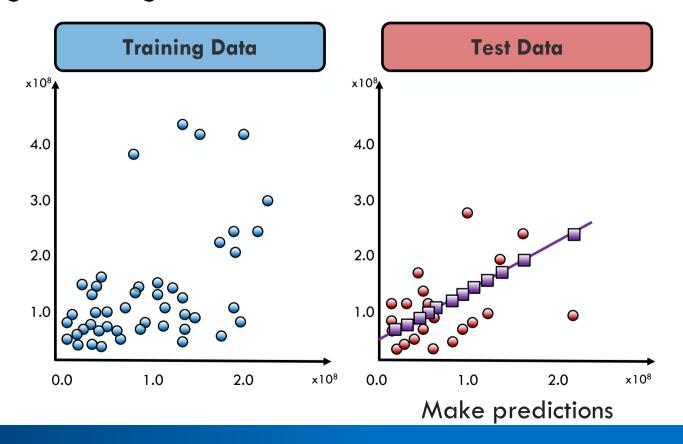
Test Data

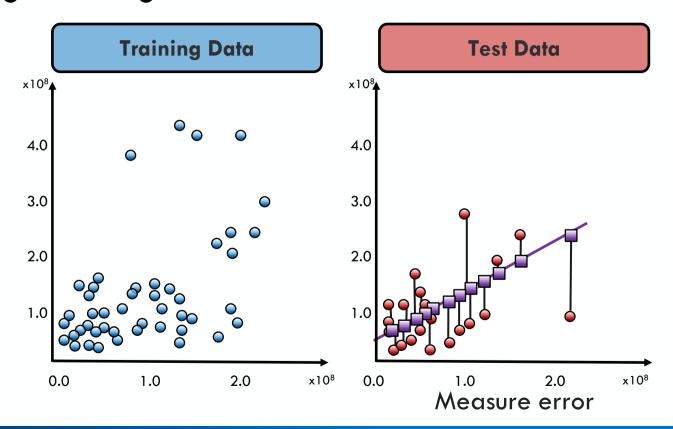
measure performance

- predict label with model
- compare with actual value
- measure error

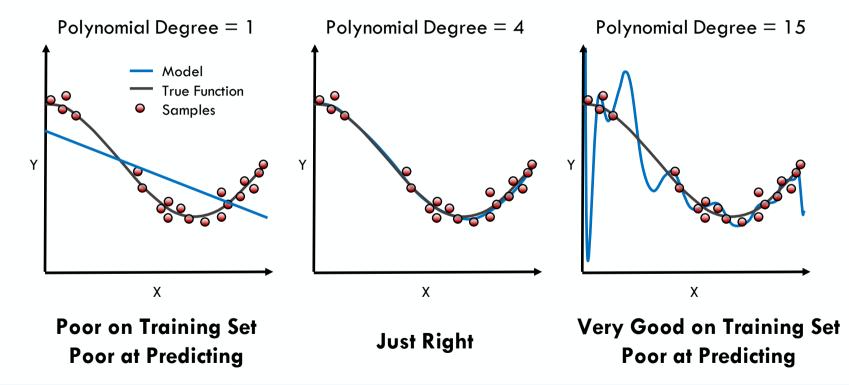




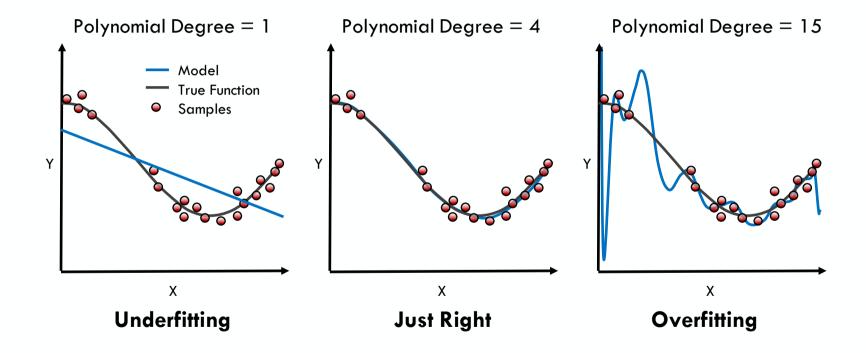




How Well Does the Model Generalize?



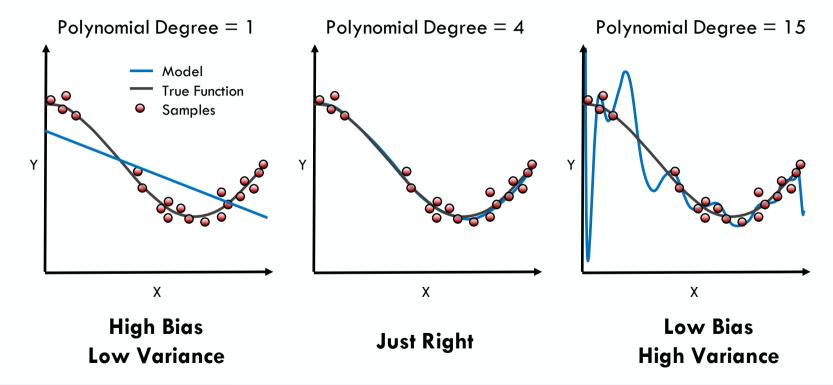
Underfitting vs Overfitting



Bias - Variance Tradeoff

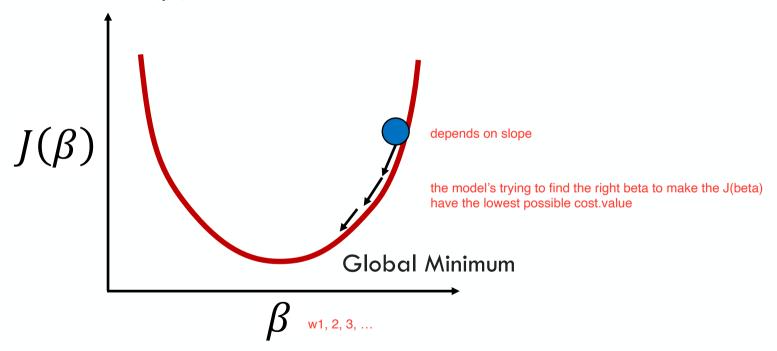
Bias: inablitity of the model to learn from the data Variance: the different in fits between data sets

Low bias: learning well with the training data High variance refers to the high difference of fitting between the data sets (more than 2 sets)



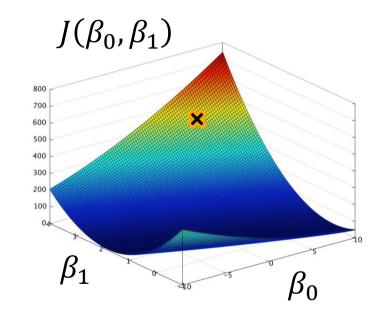
Gradient Descent

Start with a cost function $J(\beta)$:



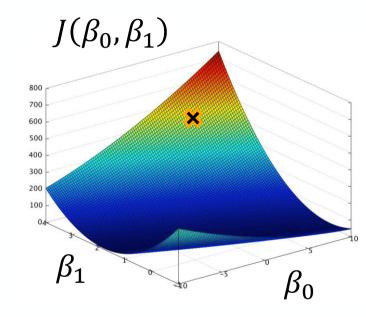
Then gradually move towards the minimum.

- Now imagine there are two parameters (β_0,β_1)
- This is a more complicated surface on which the minimum must be found
- How can we do this without knowing what $J(\beta_0,\beta_1)$ looks like?



 The gradient is a vector whose coordinates consist of the partial derivatives of the parameters

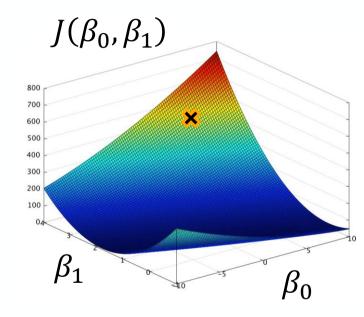
$$\nabla J(\beta_0, \dots, \beta_n) = \langle \frac{\partial J}{\partial \beta_0}, \dots, \frac{\partial J}{\partial \beta_n} \rangle$$



• Compute the gradient, $\nabla J(\beta_0, \beta_1)$, which points in the direction of the biggest increase!

Gradient (Slope)

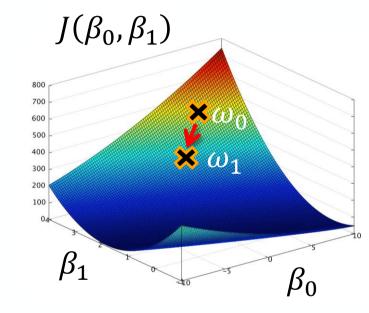
• $-\nabla J(\beta_0, \beta_1)$ (negative gradient) points to the biggest decrease at that point!



• Then use the gradient (∇) and the cost function to calculate the next point (ω_1) from the current one (ω_0) :

$$\omega_{1} = \omega_{0} - \alpha \nabla \frac{1}{2} \sum_{i=1}^{m} \left(\left(\beta_{0} + \beta_{1} x_{obs}^{(i)} \right) - y_{obs}^{(i)} \right)^{2}$$

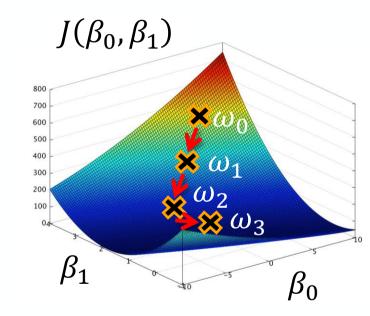
• The learning rate (α) is a tunable parameter that determines step size



 Each point can be iteratively calculated from the previous one

$$\omega_{2} = \omega_{1} - \alpha \nabla \frac{1}{2} \sum_{i=1}^{m} \left(\left(\beta_{0} + \beta_{1} x_{obs}^{(i)} \right) - y_{obs}^{(i)} \right)^{2}$$

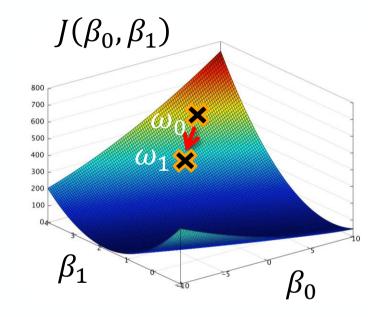
$$\omega_{3} = \omega_{2} - \alpha \nabla \frac{1}{2} \sum_{i=1}^{m} \left(\left(\beta_{0} + \beta_{1} x_{obs}^{(i)} \right) - y_{obs}^{(i)} \right)^{2}$$



 Use a single data point to determine the gradient and cost function instead of all the data

Full Batch
$$\omega_1 = \omega_0 - \alpha \nabla \frac{1}{2} \sum_{i=1}^m \left(\left(\beta_0 + \beta_1 x_{obs}^{(i)} \right) - y_{obs}^{(i)} \right)^2$$

$$\omega_1 = \omega_0 - \alpha \nabla \frac{1}{2} \left(\left(\beta_0 + \beta_1 x_{obs}^{(0)} \right) - y_{obs}^{(0)} \right)^2$$



Stochastic Gradient Descent

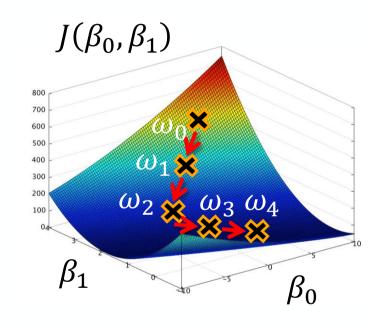
 Use a single data point to determine the gradient and cost function instead of all the data

$$\omega_1 = \omega_0 - \alpha \nabla \frac{1}{2} \left(\left(\beta_0 + \beta_1 x_{obs}^{(0)} \right) - y_{obs}^{(0)} \right)^2$$

• • •

$$\omega_4 = \omega_3 - \alpha \nabla \frac{1}{2} \left(\left(\beta_0 + \beta_1 x_{obs}^{(3)} \right) - y_{obs}^{(3)} \right)^2$$

 Path is less direct due to noise in single data point—"stochastic"



Mini Batch Gradient Descent

Something like 100 from 1,000

• Perform an update for every n training examples

$$\omega_{1} = \omega_{0} - \alpha \nabla \frac{1}{2} \sum_{i=1}^{n} \left(\left(\beta_{0} + \beta_{1} x_{obs}^{(i)} \right) - y_{obs}^{(i)} \right)^{2}$$

Best of both worlds:

- Reduced memory relative to "vanilla" gradient descent
- Less noisy than stochastic gradient descent

