# Probit regression for ordinal data (Asymmetric): MAR

#### Setting:

• For each observations, we have 3 associated variables

X1: Nomial variable with 3 possible outcomes  $\{1,2,3\}$  which we will generate from Mult(1, [0.2,0.3,0.5]) X2: Nomial variable with 3 possible outcomes  $\{1,2,3\}$  which we will generate from Mult(1, [0.3,0.5,0.2]) Y: Ordinal variable with 5 levels,  $\{1,2,3,4,5\}$  generated using the following process

The proportion of members in each ordered category will be asymmetric. Specifically, the percent of each group will be 10%, 20%, 40%, 15%, and 15% respectively.

```
\epsilon_i \sim N(0,1) z_i = \beta^T X_i + \epsilon where X = [X1 == 2, X1 == 3, X2 == 2, X2 == 3] i.e. we drop category (1,1) as the baseline g(z_i) = Y_i.
```

Here  $\beta = [-3, 2, 2, -4]$  and function g will be the binning function which will bin data into 5 different bins corresponding to 5 possible ordinal outcome.

- There will be data missing at random (MAR) in Y. The probability of missingness is govern by  $logit(w^Tx_i 0.75)$  where w = [0.4, -0.3, -0.8, 0.3]. This results in 25% of missing data in the last feature.
- We will try to model Y conditioned on other variables (X1, and X2) using probit regression with latent variable Z with rank likelihood on parameter Z.
- We have two unknown parameters  $\beta$  and  $z_i$  which will be sampled from the full conditional posterior distribution using blocked gibbs sampling.

Summary on modelling process

```
\epsilon_i \sim N(0,1) z_i = \beta^T X_i + \epsilon z_i \in R(Y) where R(Y) = \{z_i: z_i > z_j \text{ if } Y_i > Y_j \text{ and } z_i < z_j \text{ if } Y_i < Y_j\}
```

```
# Data generating process
set.seed(0)
n = 600
beta = c(-3, 2, 2, -4)
# noise term
epsilon = rnorm(n, mean = 0, sd = 1)
# X1
X1 = t(rmultinom(n, size = 1, prob = c(0.2, 0.3, 0.5)))
X2 = t(rmultinom(n, size = 1, prob = c(0.3, 0.5, 0.2)))
# X
X = cbind(X1[,2:3], X2[,2:3])
colnames(X) <- c('X1_cat2', 'X1_cat3', 'X2_cat2', 'X2_cat3')</pre>
Z = X%*\%beta + epsilon
\# Cut-off points and Y
g = quantile(Z, probs = c(0.1, 0.3, 0.7, 0.85))
Y = rep(NA, n)
```

```
Y[Z\sq[1]] = 1

Y[Z\sq[1] & Z\sq[2]] = 2

Y[Z\sq[2] & Z\sq[3]] = 3

Y[Z\sq[3] & Z\sq[4]] = 4

Y[Z\sq[4]] = 5

Z_original = Z

Y_original = Y
```

Generate missingness in data

```
# Define parameter of logistic function
w= c(0.4, -0.3, -0.8, 0.3)

# Calculate probability of missingness of features 3
prob = apply(t(w*t(X)), MARGIN = 1, FUN = sum)-0.75
prob = 1/(exp(-prob)+1)

# Indicator for X3miss
indicator = rbernoulli(n = n, p = prob)
Y[indicator] = NA
Z[indicator] = NA
```

Prior specifications:

```
\beta \sim multiN(0, n(X^TX)^{-1})
```

Blocked Gibbs Sampling here consists of two major steps

1. Sample new  $\beta$  from its full conditional

```
\beta \mid z, X, Y, z \in R(Y) \sim multiN(\frac{n}{n+1}(X^TX)^{-1}X^Tz, \frac{n}{n+1}(X^TX)^{-1})
```

2. for each i, using inverse cdf method, sample new  $z_i$  from its full conditional which is a truncated normal distribution:

```
z_i \mid \beta, X, Y, z_i \in R(Y) \sim N(\beta^T x_i, 1) * I\{z_i \in (a, b)\}
where a = \max(z_i \text{ for } Y_i < Y_i) \text{ b} = \min(z_i \text{ for } Y_i > Y_i)
```

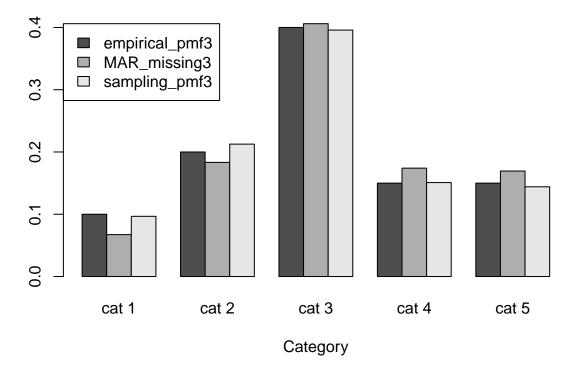
For observations where the target is missing, we need not condition on  $z_i \in R(Y)$  and the resulting full conditional distribution becomes unconstrained normal distribution.

Note that in the gibbs sampling process, we force the first threshold (g1) to be at the true value in the data generating process otherwise the parameters will be unidentifiable (we can definitely fine infinite combinations of weights parameter to order the outcome according to their target Y: scaling, shifting, etc.)

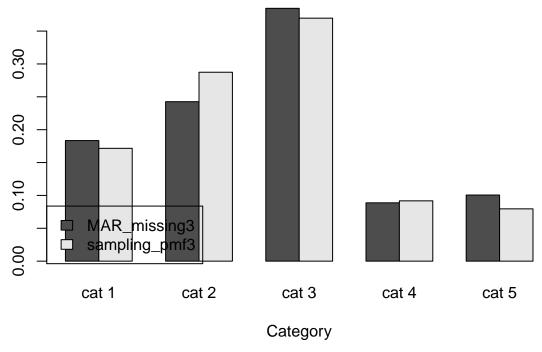
```
## # weights: 30 (20 variable)
## initial value 693.667740
## iter 10 value 388.320469
## iter 20 value 306.713265
## iter 30 value 303.025802
## iter 40 value 302.895636
## final value 302.895211
## converged
Y i = Y
Y_i[indicator] = predict(mod, newdata = df[is.na(df$Y),], 'class')
\#Y_i[indicator] = 3
Z_i = g1 + Y_i - 1.5
variance_beta = (n/(n+1))*solve(t(X)%*%X)
mean_beta_hat = (n/(n+1))*solve(t(X)%*%X)%*%t(X)
# Initialize the sampling matrix
S = 30000
SAMPLED_Z = matrix(nrow=S,ncol=n)
SAMPLED_Y = matrix(nrow = S, ncol = n)
BETA = matrix(nrow=S,ncol=4)
for (round in 1:S) {
  # Step 1: Sample Beta
  mean beta = mean beta hat "* "Z i
  beta_sampled = dae::rmvnorm(mean = mean_beta,
                              V = variance_beta, method = 'choleski')
  BETA[round,] <- beta_sampled</pre>
  # Step 2: Sample Z using inverse cdf appraoch
  for (i in 1:n) {
    # Get the lower and upper bound (a, b) of truncated normal
    a = max(-Inf, Z_i[Y_i < Y[i]], na.rm = TRUE)
    b = min(Z_i[Y_i>Y[i]], Inf, na.rm = TRUE)
    # Force the lowest cutoff to be at g1
    if(indicator[i] == FALSE){
      if (Y_i[i] == 1) {
        b = g1
      }else if (Y_i[i] == 2) {
        a = g1
      }
    }
    # Sample using inverse cdf
    ez = t(beta_sampled)%*%X[i,]
    u = runif(1, pnorm(a - ez), pnorm(b-ez))
    Z_i[i] = ez + qnorm(u)
    if (indicator[i] == TRUE) {
      # Impute Y for missing values
      Y_i[i] = -1
      if (Z_i[i] < g1) {</pre>
        Y_i[i] = 1
      }else if (Z_i[i] < min(Z_i[Y_i==3],na.rm = TRUE)) {
```

```
Y_i[i] = 2
      }else if (Z_i[i] < min(Z_i[Y_i==4], na.rm = TRUE)){
        Y_i[i] = 3
      }else if (Z_i[i] < min(Z_i[Y_i==5],na.rm = TRUE)){
        Y_i[i] = 4
      }else{
        Y_i[i] = 5
    }
  SAMPLED_Z[round,] <- Z_i</pre>
  SAMPLED_Y[round,] <- Y_i</pre>
burnin = 5000
thining = 100
# Imputation accuracy
empirical_pmf3 = table(Y_original)/n
MAR_missing3 = table(Y[!indicator])/(n-sum(indicator))
sampling_pmf3 = table(SAMPLED_Y[seq(burnin, dim(BETA)[1], thining),])/
  sum(table(SAMPLED_Y[seq(burnin, dim(BETA)[1], thining),]))
df3 = rbind(empirical_pmf3, MAR_missing3, sampling_pmf3)
colnames(df3)<- c('cat 1', 'cat 2', 'cat 3', 'cat 4', 'cat 5')</pre>
barplot(df3, xlab = 'Category', beside = TRUE,
        legend = TRUE, args.legend=list(x='topleft'),
        main = 'Blocked Gibbs Sampling Assessment: Marginal Y pmf')
```

### **Blocked Gibbs Sampling Assessment: Marginal Y pmf**

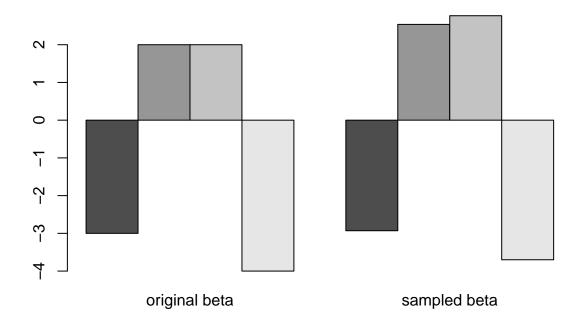


#### **Blocked Gibbs Sampling Assessment: Missing Y pmf**

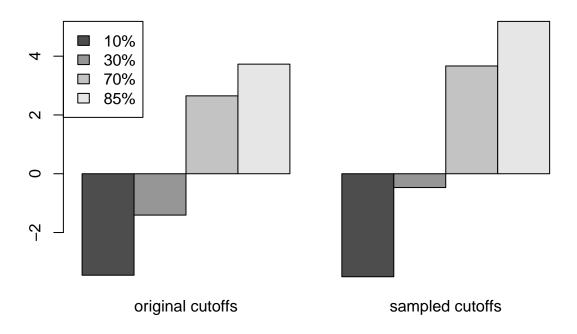


```
# Imputation accuracy
true_label = Y_original[indicator]
sampled_label = SAMPLED_Y[seq(burnin, dim(BETA)[1], thining),indicator]
mean(t(sampled_label) == true_label)
## [1] 0.5908909
# Check posterior expectation of beta
sampling_beta = apply(BETA[seq(burnin, dim(BETA)[1], thining),], MARGIN = 2, mean)
df_beta= cbind(beta, sampling_beta)
colnames(df_beta)<- c('original beta', 'sampled beta')</pre>
barplot(df_beta, beside = TRUE,
        legend = TRUE, main = 'Blocked Gibbs Sampling Assessment: Beta')
# Check cut off points
g1 = apply(SAMPLED_Z[, Y == 1], MARGIN = 1, max, na.rm = TRUE)
g2 = apply(SAMPLED_Z[, Y == 2], MARGIN = 1, max, na.rm = TRUE)
g3 = apply(SAMPLED_Z[, Y == 3], MARGIN = 1, max, na.rm = TRUE)
g4 = apply(SAMPLED_Z[, Y == 4], MARGIN = 1, max, na.rm = TRUE)
```

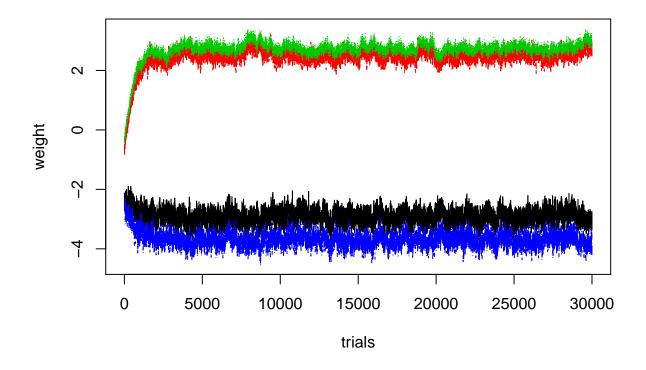
#### **Blocked Gibbs Sampling Assessment: Beta**



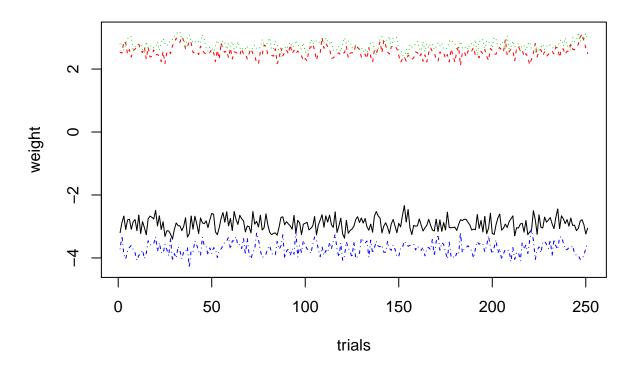
## **Blocked Gibbs Sampling Assessment: Cutoffs**



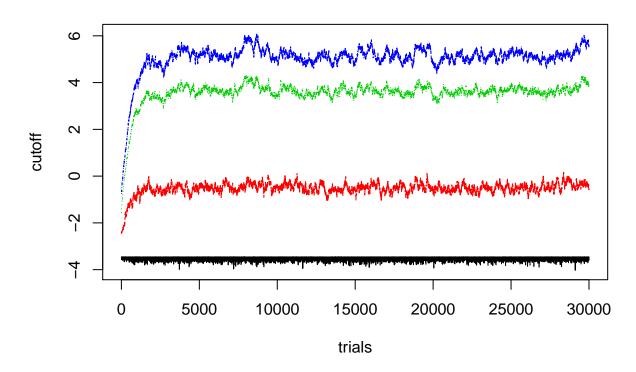
## **Checking stability of sampled Beta**



# **Checking stability of sampled Beta: thining**



## **Checking stability of sampled Cutoffs**



# **Checking stability of sampled Cutoffs: thining**

