Probit regression for ordinal data: MAR

Setting:

• For each observations, we have 3 associated variables

X1: Nomial variable with 3 possible outcomes $\{1,2,3\}$ which we will generate from Mult(1, [0.2,0.3,0.5]) X2: Nomial variable with 3 possible outcomes $\{1,2,3\}$ which we will generate from Mult(1, [0.3,0.5,0.2]) Y: Ordinal variable with 5 levels, $\{1,2,3,4,5\}$ generated using the following process

```
\epsilon_i \sim N(0,1) \ z_i = \beta^T X_i + \epsilon \text{ where } X = [X1 == 1, X1 == 2, X2 == 1, X2 == 2] \text{ i.e. we drop category } (1,1) as the baseline g(z_i) = Y_i.
```

Here $\beta = [-3, 2, 2, -4]$ and function g will be the binning function which will bin data into 5 different bins corresponding to 5 possible ordinal outcome.

- There will be data missing at random (MAR) in Y. The probability of missingness is govern by $logit(w^Tx_i 0.75)$ where w = [0.4, -0.3, -0.8, 0.3]. This results in 25% of missing data in the last feature.
- We will try to model Y conditioned on other variables (X1, and X2) using probit regression with latent variable Z with rank likelihood on parameter Z.
- We have two unknown parameters β and z_i which will be sampled from the full conditional posterior distribution using blocked gibbs sampling.

Summary on modelling process

```
\epsilon_i \sim N(0,1) \ z_i = \beta^T X_i + \epsilon \ z_i \in R(Y) \text{ where } R(Y) = \{z_i : \ z_i > z_j \text{ if } Y_i > Y_j \text{ and } z_i < z_j \text{ if } Y_i < Y_j \}
```

```
# Data generating process
set.seed(0)
n = 300
beta = c(-3, 2, 2, -4)
# noise term
epsilon = rnorm(n, mean = 0, sd = 1)
X1 = t(rmultinom(n, size = 1, prob = c(0.2, 0.3, 0.5)))
# X2
X2 = t(rmultinom(n, size = 1, prob = c(0.3, 0.5, 0.2)))
# X
X = cbind(X1[,2:3], X2[,2:3])
colnames(X) <- c('X1_cat2', 'X1_cat3', 'X2_cat2', 'X2_cat3')</pre>
# Z
Z = X%*\%beta + epsilon
# Cut-off points and Y
g = quantile(Z, probs = c(0.2, 0.4, 0.6, 0.8))
Y = rep(NA, n)
Y[Z < g[1]] = 1
Y[Z = g[1] \& Z < g[2]] = 2
```

```
Y[Z>=g[2] & Z<g[3]] = 3

Y[Z>=g[3] & Z<g[4]] = 4

Y[Z>=g[4]] = 5

Z_original = Z

Y_original = Y
```

Generate missingness in data

```
# Define parameter of logistic function
w= c(0.4, -0.3, -0.8, 0.3)

# Calculate probability of missingness of features 3
prob = apply(t(w*t(X)), MARGIN = 1, FUN = sum)-0.75
prob = 1/(exp(-prob)+1)

# Indicator for X3miss
indicator = rbernoulli(n = n, p = prob)
Y[indicator] = NA
Z[indicator] = NA
```

Prior specifications:

```
\beta \sim multiN(0, n(X^TX)^{-1})
```

Blocked Gibbs Sampling here consists of two major steps

1. Sample new β from its full conditional

```
\beta \mid z, X, Y, z \in R(Y) \sim multiN(\frac{n}{n+1}(X^TX)^{-1}X^Tz, \frac{n}{n+1}(X^TX)^{-1})
```

2. for each i, using inverse cdf method, sample new z_i from its full conditional which is a truncated normal distribution:

```
z_i \mid \beta, X, Y, z_i \in R(Y) \sim N(\beta^T x_i, 1) * I\{z_i \in (a, b)\}
where a = \max(z_j \text{ for } Y_j < Y_i) \text{ b} = \min(z_j \text{ for } Y_j > Y_i)
```

For observations where the target is missing, we need not condition on $z_i \in R(Y)$ and the resulting full conditional distribution becomes unconstrained normal distribution.

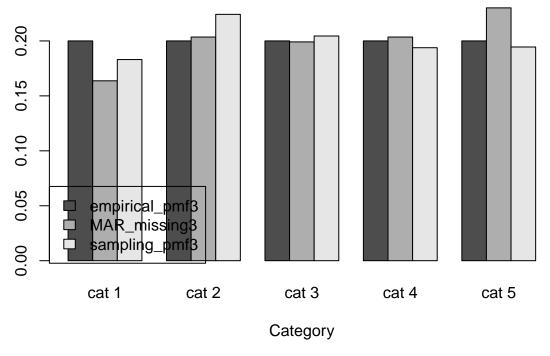
Note that in the gibbs sampling process, we force the first threshold (g1) to be at the true value in the data generating process otherwise the parameters will be unidentifiable (we can definitely fine infinite combinations of weights parameter to order the outcome according to their target Y: scaling, shifting, etc.)

weights: 30 (20 variable)

```
## initial value 363.732968
## iter 10 value 189.015986
## iter 20 value 161.195359
## iter 30 value 160.331627
## iter 40 value 160.311527
## final value 160.311461
## converged
Y i = Y
Y_i[indicator] = predict(mod, newdata = df[is.na(df$Y),], 'class')
\#Y_i[indicator] = 3
Z_i = g1 + Y_i - 1.5
variance_beta = (n/(n+1))*solve(t(X)%*%X)
mean_beta_hat = (n/(n+1))*solve(t(X)%*%X)%*%t(X)
# Initialize the sampling matrix
S = 30000
SAMPLED_Z = matrix(nrow=S,ncol=n)
SAMPLED_Y = matrix(nrow = S, ncol = n)
BETA = matrix(nrow=S,ncol=4)
for (round in 1:S) {
  # Step 1: Sample Beta
  mean_beta = mean_beta_hat%*%Z_i
  beta_sampled = dae::rmvnorm(mean = mean_beta,
                              V = variance_beta, method = 'choleski')
  BETA[round,] <- beta_sampled</pre>
  # Step 2: Sample Z using inverse cdf appraoch
  for (i in 1:n) {
    # Get the lower and upper bound (a, b) of truncated normal
    a = max(-Inf, Z_i[Y_i < Y[i]], na.rm = TRUE)
    b = min(Z_i[Y_i>Y[i]], Inf, na.rm = TRUE)
    # Force the lowest cutoff to be at g1
    if(indicator[i] == FALSE){
      if (Y_i[i] == 1) {
        b = g1
      }else if (Y_i[i] == 2) {
        a = g1
      }
    }
    # Sample using inverse cdf
    ez = t(beta_sampled)%*%X[i,]
    u = runif(1, pnorm(a - ez), pnorm(b-ez))
    Z_i[i] = ez + qnorm(u)
    if (indicator[i] == TRUE) {
      # Impute Y for missing values
      if (Z_i[i] < g1) {</pre>
        Y_i[i] = 1
      }else if (Z_i[i] < min(Z_i[Y==3], na.rm = TRUE)) {
        Y_i[i] = 2
      else if (Z_i[i] < min(Z_i[Y==4],na.rm = TRUE)){
        Y_i[i] = 3
```

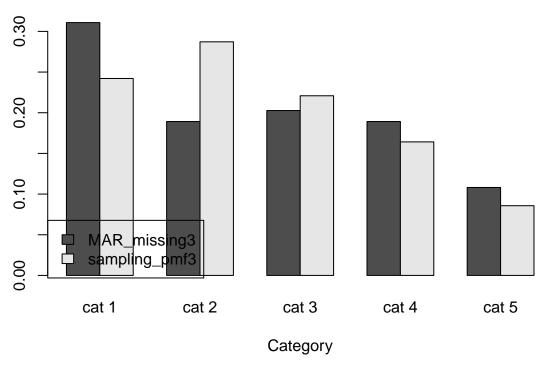
```
else if (Z_i[i] < min(Z_i[Y==5],na.rm = TRUE)){
        Y_i[i] = 4
      }else{
        Y_i[i] = 5
      }
    }
  SAMPLED_Z[round,] <- Z_i</pre>
  SAMPLED_Y[round,] <- Y_i</pre>
burnin = 5000
thining = 100
# Imputation accuracy
empirical_pmf3 = table(Y_original)/n
MAR_missing3 = table(Y[!indicator])/(n-sum(indicator))
sampling_pmf3 = table(SAMPLED_Y[seq(burnin, dim(BETA)[1], thining),])/
  sum(table(SAMPLED_Y[seq(burnin, dim(BETA)[1], thining),]))
df3 = rbind(empirical_pmf3, MAR_missing3, sampling_pmf3)
colnames(df3)<- c('cat 1', 'cat 2', 'cat 3', 'cat 4', 'cat 5')</pre>
barplot(df3, xlab = 'Category', beside = TRUE,
        legend = TRUE, args.legend=list(x='bottomleft'),
        main = 'Blocked Gibbs Sampling Assessment: Marginal Y pmf')
```

Blocked Gibbs Sampling Assessment: Marginal Y pmf



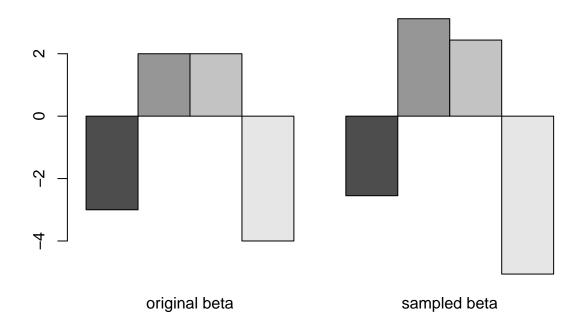
```
# Imputation accuracy
MAR_missing3 = table(Y_original[indicator])/sum(indicator)
sampling_pmf3 = table(SAMPLED_Y[seq(burnin, dim(BETA)[1], thining),indicator])/
sum(table(SAMPLED_Y[seq(burnin, dim(BETA)[1], thining), indicator]))
```

Blocked Gibbs Sampling Assessment: Missing Y pmf

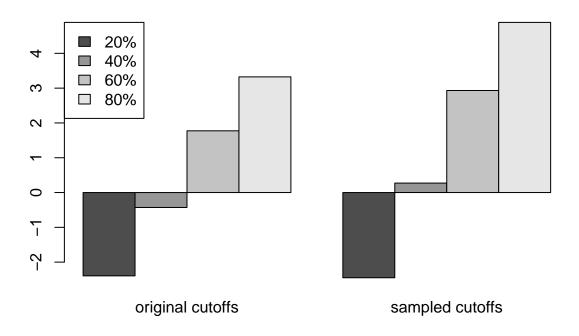


```
# Imputation accuracy
true_label = Y_original[indicator]
sampled_label = SAMPLED_Y[seq(burnin, dim(BETA)[1], thining),indicator]
mean(t(sampled_label) == true_label)
## [1] 0.5574997
# Check posterior expectation of beta
sampling_beta = apply(BETA[seq(burnin, dim(BETA)[1], thining),], MARGIN = 2, mean)
df_beta= cbind(beta, sampling_beta)
colnames(df beta)<- c('original beta', 'sampled beta')</pre>
barplot(df beta, beside = TRUE,
        legend = TRUE, main = 'Blocked Gibbs Sampling Assessment: Beta')
# Check cut off points
g1 = apply(SAMPLED_Z[, Y == 1], MARGIN = 1, max, na.rm = TRUE)
g2 = apply(SAMPLED_Z[, Y == 2], MARGIN = 1, max, na.rm = TRUE)
g3 = apply(SAMPLED_Z[, Y == 3], MARGIN = 1, max, na.rm = TRUE)
g4 = apply(SAMPLED_Z[, Y == 4], MARGIN = 1, max, na.rm = TRUE)
df g= cbind(g, c(mean(g1[seq(burnin, dim(BETA)[1], thining)]),
                 mean(g2[seq(burnin, dim(BETA)[1], thining)]),
                 mean(g3[seq(burnin, dim(BETA)[1], thining)]),
```

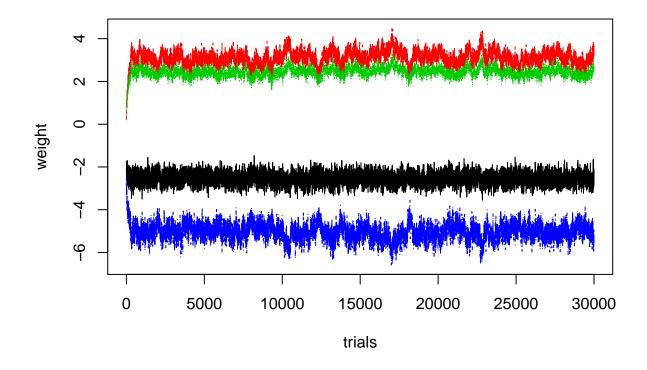
Blocked Gibbs Sampling Assessment: Beta



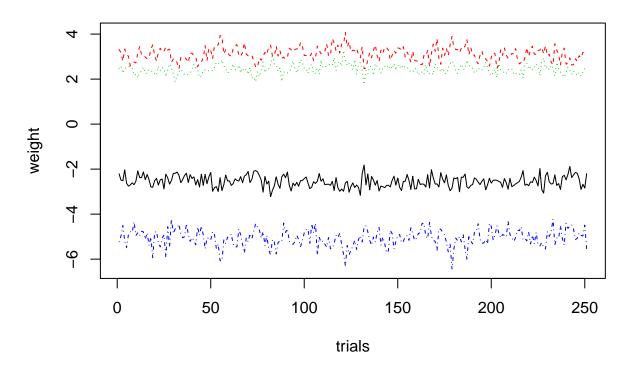
Blocked Gibbs Sampling Assessment: Cutoffs



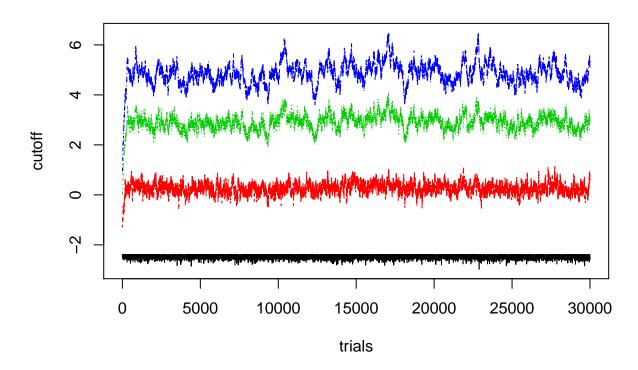
Checking stability of sampled Beta



Checking stability of sampled Beta: thining



Checking stability of sampled Cutoffs



Checking stability of sampled Cutoffs: thining

