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Quantification of Uncertainty for Estimation, Simulation, and Optimization (QUESO)

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Abstract

QUESO is a collection of algorithms and C++ classes aimed for research in uncertainty quantification, including the solution of statistical inverse and statistical forward problems, the validation of mathematical models under uncertainty and the prediction of quantities of interest from such models along with the quantification of their uncertainties.

QUESO is designed for flexibility, portability, easiness of use and easiness of extension. Its software design follows an object-oriented approach and its code is written on C++ and over MPI. It can run over uniprocessor or multiprocessor environments.

QUESO contains two forms of documentation: a User's Manual available in pdf format and a lower-level code documentation available in web based/html format.

This is the User's Manual. It gives an overview of the QUESO capabilities, provides procedures for software execution, and includes example studies.

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Preface

The QUESO project started in 2008 as part of the efforts of the recently established Center for Predictive Engineering and Computational Sciences (PECOS) at the Institute for Computational and Engineering Sciences (ICES) at The University of Texas at Austin.

The PECOS Center was selected by the National Nuclear Security Administration (NNSA) as one of its new five centers of excellence under the Predictive Science Academic Alliance Program (PSAAP). The goal of the PECOS Center is to advance predictive science and to develop the next generation of advanced computational methods and tools for the calculation of reliable predictions on the behavior of complex phenomena and systems (multiscale, multidisciplinary). This objective demands a systematic, comprehensive treatment of the calibration and validation of the mathematical models involved, as well as the quantification of the uncertainties inherent in such models. The advancement of predictive science is essential for the application of Computational Science to the solution of realistic problems of national interest.

The QUESO library, since its first version, has been publicly released as open source under the GNU General Public License and is available for free download world-wide. See http://www.gnu.org/licenses/gpl.html for more information on the GPL software use agreement.

The QUESO development team currently consists of Paul T. Bauman, Sai Hung Cheung, Todd A. Oliver, Ernesto E. Prudencio, Karl W. Schulz, and Rhys Ulerich.

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Referencing the QUESO Library

When referencing the QUESO library in a publication, please cite the following:

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Year = "2008-2009"}
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Chapter 1

Introduction (Incomplete)

The QUESO library is able to handle uni- and multi-processor Linux environments.

1.1 Key Statistical Concepts

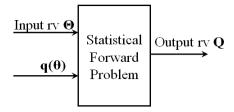


Figure 1.1.1: The representation of a statistical forward problem. Θ denotes a random variable related to parameters, θ denotes a realization of Θ and Q denotes a random variable related to quantities of interest.

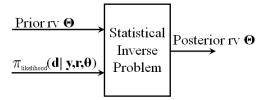


Figure 1.1.2: The representation of a statistical inverse problem. Θ denotes a random variable related to parameters, θ denotes a realization of Θ and \mathbf{r} denotes model equations, \mathbf{y} denotes some model output data and \mathbf{d} denotes experimental data.

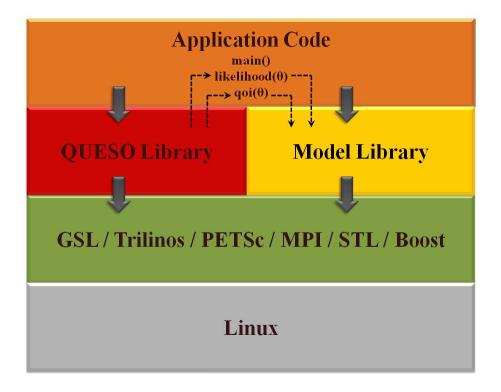


Figure 1.2.1: Overview of the software stack of a typical application that uses QUESO. The symbol $\boldsymbol{\theta}$ represents a vector of $n \geq 1$ parameters. Algorithms in the QUESO library require the supply of a likelihood routine $\pi_{\text{like}} : \mathbb{R}^n \to \mathbb{R}_+$ for statistical inverse problems and of a qoi routine $\mathbf{q} : \mathbb{R}^n \to \mathbb{R}^m$ for statistical forward problems. These routines exist at the application level and provide the necessary bridge between the statistical algorithms in QUESO, model knowledge in the model library and scenario and experimental data in the disk space. Concepts are further detailed in Chapter 1.

1.2 The Software Stack of an Application Using QUESO

- 1.2.1 A QUESO Environment
- 1.2.2 Using Other C++ Classes in the Library
- 1.2.3 Input and Output Files

Chapter 2

Installation

This chapter describes how to install QUESO, test it and use it to create your application.

2.1 Installation Steps

There are eight steps to make the QUESO Library available at your LINUX computing system. They are listed below, with examples of commands:

- 1. prepare your LINUX environment (assuming csh; some commands might be enough):
 - module load gnu
 - module load openmpi

 - setenv CC gcc
 - setenv CXX g++
 - setenv MPICC mpicc
 - setenv MPICXX mpic++
 - setenv F77 f77
 - setenv FC gfortran
- 2. install five packages:
 - GNU Scientific Library (GSL) [2], e.g GSL 1.12,
 - Boost C++ Libraries [1], e.g. Boost 1.37.0,
 - MPI Library, e.g. Open MPI [5] or MPICH [4],
 - Trilinos Library [3], e.g. Trilinos 9.0.2, and
 - High Performance Computing Toolkit (HPCT) [6], e.g. HPCT 0.25.1.

- ./configure --prefix=/home/johndoe/Installations/hpct_0_25_1 \
 --with-boost=/home/johndoe/Installations/boost_1_37_0
- make
- make install
- note: the directory '/home/johndoe/Installations/hpct_0_25_1' does not need to exist in advance, since it will be created by the command 'make install' above.
- 3. untar the QUESO tar.gz file (more comments in Section 2.2):
 - cd /home/johndoe
 - mkdir queso_download
 - cd /home/johndoe/queso_download
 - $mv < ORIGINAL_LOCATION > queso 0.41.0.tar.gz$.
 - \bullet tar -zxvf queso-0.41.0.tar
- 4. configure the QUESO building environment:
 - cd /home/johndoe/queso_download/queso-0.41.0
 - ./configure --prefix=/home/johndoe/Installations/queso_0_41_0_gnu \
 --with-trilinos=/home/johndoe/Installations/trilinos_9_0_2 \
 --with-boost=/home/johndoe/Installations/boost_1_37_0 \
 --with-gsl-prefix=/home/johndoe/Installations/gsl_1_12 \
 --with-hpct-prefix=/home/johndoe/Installations/hpct_0_25_1 \
 CXXFLAGS=''-DMPICH_IGNORE_CXX_SEEK -03 -Wall -wd383 -wd981 -wd1572''
 - if you want to see the full list of configure options, just run "./configure -help"
 - note: the directory '/home/johndoe/Installations/queso_0_41_0_gnu' does not need to exist in advance, since it will be created in step 7.
- 5. compile the QUESO source code (library, examples and tests):
 - make
- 6. check the compiled source (more comments in Section 2.3):
 - make check
- 7. install the QUESO library (more comments in Section 2.5):
 - make install
- 8. create the documentation in html format:
 - make docs
 - firefox docs/html/index.html

2.2 The Source Directory Structure

The QUESO source directory contains three main directories. They are listed below and more information about them can be obtained with the html documentation from step 8 above:

- 'libs', with five subdirectories:
 - 'libs/core/', with 'inc' and 'src' subdirectories,
 - 'libs/misc/', with 'inc' and 'src' subdirectories,
 - 'libs/basic/', with 'inc' and 'src' subdirectories,
 - 'libs/stats/', with 'inc' and 'src' subdirectories, and
 - 'libs/interface/'.
- 'examples', with four subdirectories:
 - 'examples/statisticalForwardProblem/',
 - 'examples/statisticalInverseProblem1/',
 - 'examples/validationCycle/', and
 - 'examples/validationCycle2/'.
- 'test', with four subdirectories:
 - 'test/t01_valid_cycle/',
 - 'test/t02_sip_sfp/',
 - 'test/t03_sequence/', and
 - 'text/gsl_tests'.

The executables under 'examples/validationCycle2/', 'test/t02_sip_sfp/', 'test/t03_sequence/' and 'test/gsl_tests/' have the majority of their codes in *.C files. They might then be easier to understand than the other exectuables in 'examples' and 'test/t01_valid_cycle', which have the majority of their codes in *.h files, with templated routines. It should be clear, though, that all executables might be implemented in either *.h or *.C files. It is a matter of how generic you want your application to be.

2.3 Checking the Compiled Source

Just run 'make ckeck' at the same directory where 'configure' and 'make' were run. Many printouts will appear in the screen, but towards the end of them you should see a message like:

All 2 tests passed

The 2 tests mentioned in this message are the ones under 'test/t01_valid_cycle' and 'test/t02_sip_sfp'. These tests are used as part of the periodic QUESO regression tests. The code for 't02_sip_sfp' is mentioned in Subsection 2.4.3 and is explained in more detail in Chapter 4.

2.4 Running the Executables Provided with QUESO

This section assumes that you have successfully executed steps 1 through 6 above. The codes listed in this section have explanations inside themselves, and some of them print messages during execution to make it clearer what is going on.

2.4.1 Executable at 'examples/statisticalInverseProblem1/'

Just run the following commands:

- cd /home/johndoe/queso_download/queso-0.41.0/
- $\bullet \ \ cd\ examples/statisticalInverseProblem1/tests/test_2009_02_03/$
- rm outputData/*
- ../../src/exStatisticalInverseProblem1_gsl sip.inp [this will take some seconds]
- matlab
- [inside matlab] sip_plot
- [press the left button of the mouse at a picture displayed by 'sip_plot.m', in order to display the next picture]
- ullet [inside matlab] exit
- ls -l outputData/*.png

2.4.2 Executable at 'examples/statisticalForwardProblem/'

Just run the following commands:

- cd /home/johndoe/queso_download/queso-0.41.0/
- cd examples/statisticalForwardProblem1/tests/test_2009_02_11/
- rm outputData/*
- ../../src/exStatisticalForwardProblem1_gsl sfp.inp [this will take some seconds]
- matlab
- [inside matlab] sfp_plot
- [press the left button of the mouse at a picture displayed by 'sfp_plot.m', in order to display the next picture]
- [inside matlab] exit
- ls -l outputData/*.png

2.4.3 Executable at 'test/t02_sip_sfp/sip_sfp/'

Just run the following commands:

- cd /home/johndoe/queso_download/queso-0.41.0/
- $cd test/t02_sip_sfp/sip_sfp/$
- rm outputData/*
- ./SipSfpExample_gsl example.inp [this will take some seconds]
- matlab
- [inside matlab] example_plots
- [press the left button of the mouse at a picture displayed by 'example_plots.m', in order to display the next picture]
- [inside matlab] exit
- ls -l outputData/*.png

2.5 The Installed Directory Structure

This section assumes you have successfully executed steps 1 through 7 above. The QUESO installed directory contains three main directories:

- 'lib',
- 'include', and
- 'examples', with two subdirectories:
 - 'examples/basic/',
 - 'examples/advanced/'.

2.6 Create your Application with the installed QUESO

Prepare your environment by running

-I\$(HPCT_DIR)/include \

```
setenv LD_LIBRARY_PATH \$LD_LIBRARY_PATH:
       /home/johndoe/Installations/queso_0_41_0_gnu/lib
An example Makefile is given below:
# BEGIN OF MAKEFILE
QUESO_DIR = /home/johndoe/Installations/queso_0_41_0_gnu/
TRILINOS_DIR = /home/johndoe/Installations/trilinos_9_0_2/
BOOST_DIR = /home/johndoe/Installations/boost_1_37_0/
GSL_DIR = /home/johndoe/Installations/gsl_1_12/
HPCT_DIR = /home/johndoe/Installations/hpct_0_25_1/
include $(TRILINOS_DIR)/include/Makefile.export.epetra
INC_PATHS = \
-I. \
-I$(QUESO_DIR)/include \
-I$(MPI_DIR)/include \
-I$(BOOST_DIR)/include/boost_1_37_0 \
-I$(GSL_DIR)/include \
```

```
$(EPETRA_INCLUDES)
LIBS = \
-L$(QUESO_DIR)/lib \
-lqueso \
-L$(MPI_DIR)/lib \
-L$(TRILINOS_DIR)/lib \
-L$(BOOST_DIR)/lib \
-lboost_program_options \
-L$(GSL_DIR)/lib \
-lgsl \
-L$(HPCT_DIR)/lib \
-lhpct \
$(EPETRA_LIBS)
CXX = mpic++
CXXFLAGS += -03 -Wall -c
default: all
.SUFFIXES: .o .C
all: ex_gsl
clean:
rm -f *~
rm - f *.o
rm -f example
ex_gsl: example_main.o example_likelihood.o example_qoi.o example_compute.o
$(CXX) example_main.o \
       example_likelihood.o \
       example_qoi.o \
       example_compute.o \
       -o example_gsl $(LIBS)
%.o: %.C
$(CXX) $(INC_PATHS) $(CXXFLAGS) $<</pre>
# END OF MAKEFILE
```

More documentation is provided in Chapter 4.

Chapter 3

C++ Classes in the Library (Incomplete)

3.1 Core Classes

There are four core classes:

- environment and environment options (Figures 3.1.1 and 3.1.2, pages 12 and 13),
- vector (Figure 3.1.3, page 14),
- matrix (Figure 3.1.4, page 15).

3.1.1 Environment (and Options)



Figure 3.1.1: The class diagram for the environment class.

ugBaseEnvironmentOptionsClass +m_numSubEnvironments: unsigned int = 1 +m_subDisplayFileName: std::string = "." +m_subDisplayAllowAll: bool = false +m_subDisplayAllowSet: std::set<unsigned int> +m_displayVerbosity: unsigned int = 2 +m_syncVerbosity: unsigned int = 0 $+m_seed: int = 0$ -m_env: const uqBaseEnvironmentClass& -m_prefix: std::string -m optionsDesc: po::options description* +scanOptionsValues(): void +print(std::ofstream& os): void -defineMyOptions(optionsDesc:po::options_description&): void -getMyOptionsValues(optionsDesc:po::options_description&): void

Figure 3.1.2: The environment options class.

Option	Default	Description
Name	Value	
⟨PREFIX⟩env_help		
⟨PREFIX⟩env_numSubEnvironments		
⟨PREFIX⟩env_subDisplayFileName		
⟨PREFIX⟩env_subDisplayAllowAll		
⟨PREFIX⟩env_subDisplayAllowedSet		
⟨PREFIX⟩env_displayVerbosity		
⟨PREFIX⟩env_syncVerbosity		
(PREFIX)env_seed		

Table 3.1.1: Input file options for a QUESO environment.

3.1.2 Vector

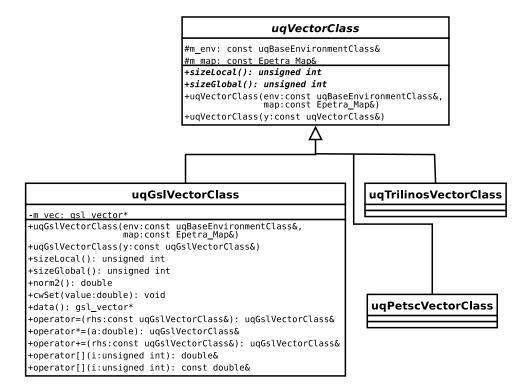


Figure 3.1.3: The class diagram for the vector class.

3.1. CORE CLASSES

3.1.3 Matrix

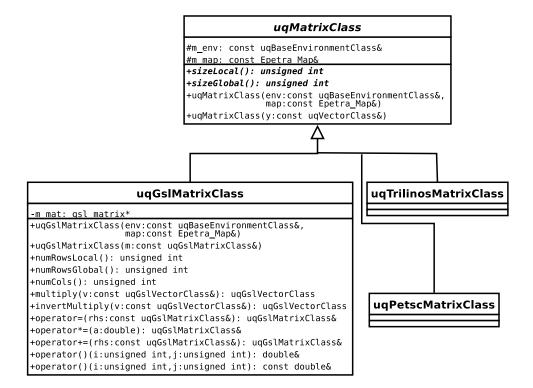


Figure 3.1.4: The class diagram for the matrix class.

3.2 Miscellaneous Classes and Routines

3.3 Templated Basic Classes

The classes in this group are:

- Vector sets, subsets and spaces (see Figure 3.3.1),
- Scalar function (see Figure 3.3.2),
- Vector function (see Figure 3.3.3),
- Scalar sequence (see Figure 3.3.4), and
- Vector sequence (see Figure 3.3.5).

These classes constitute the core entities necessary for the formal mathematical definition and description of other entities, such as random variables, Bayesian solutions of inverse problems, sampling algorithms and chains.

3.3.1 Vector Subset and Vector Space

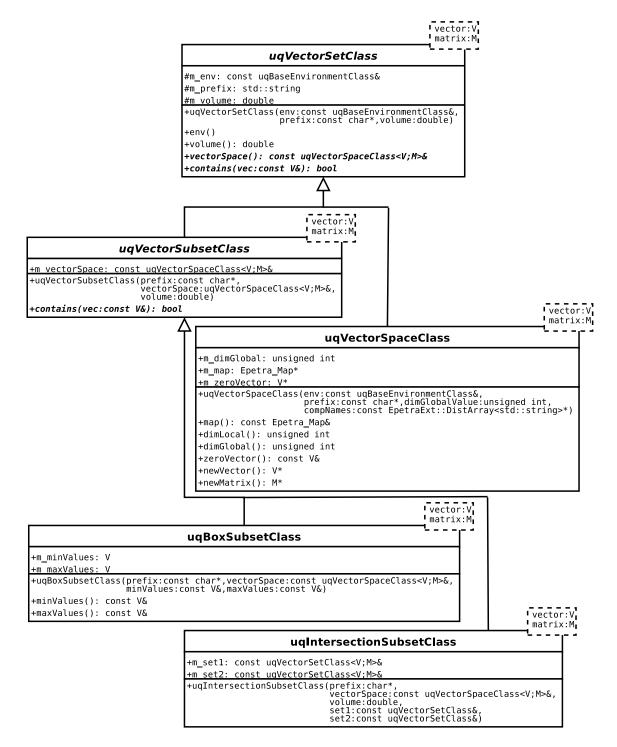


Figure 3.3.1: The class diagram for vector set, vector subset and vector space classes.

3.3.2 Scalar Function

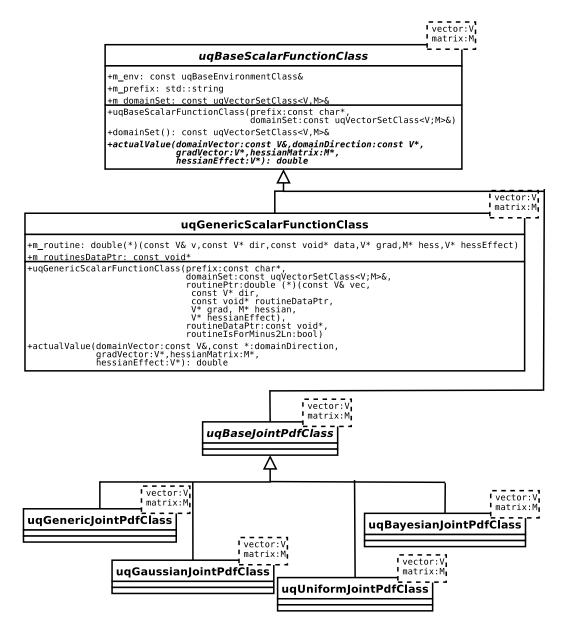


Figure 3.3.2: The class diagram for the scalar function class.

3.3.3 Vector Function

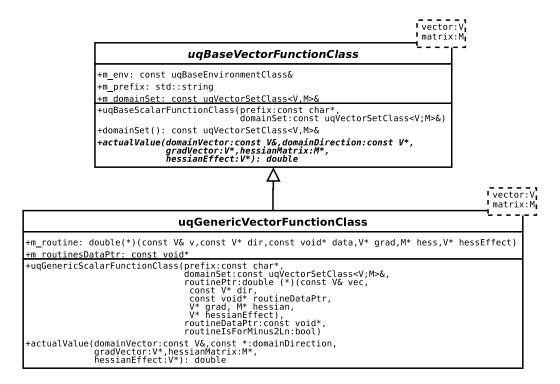


Figure 3.3.3: The class diagram for the vector function class.

3.3.4 Scalar Sequence

```
scalar:T
             uqScalarSequenceClass
+m_env: const uqBaseEnvironmentClass&
+m seq: std::vector<T>
+subSequenceSize(): unsigned int
+subSort(): void
+unifiedSort(): void
+subMean(): T
+unifiedMean(): T
+subSampleVariance(): void
+unifiedSampleVariance(): void
+subMinMax(): void
+unifiedMinMax(): void
+subHistogram(): void
+unifiedHistogram(): void
+subGaussianKDE(): void
+unifiedGaussianKDE(): void
+operator[](posId:unsigned int): const T&
+operator[](posId:unsigned int): T&
```

Figure 3.3.4: The class diagram for the scalar sequence class.

3.3.5 Vector Sequence

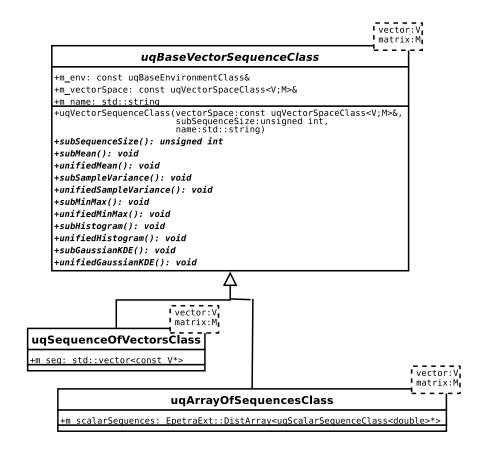


Figure 3.3.5: The class diagram for the vector sequence class.

3.4 Templated Statistical Classes

- Vector random variable
- Statistical inverse problem (and options)
- Metropolis-Hastings solver (and options)
- Statistical forward problem (and options)
- Monte Carlo solver (and options)
- Sequence statistical options

For QUESO, a statistical inverse problem has two input entities, a prior random variable and a likelihood routine, and one output entity, the posterior random variable, as shown in Figure 1.1.2.

Similarly, a statistical forward problem for QUESO has two input entities, a input random variable and a qoi routine, and one output entity, the output random variable, as shown in Figure 1.1.1.

3.4.1 Vector Random Variable

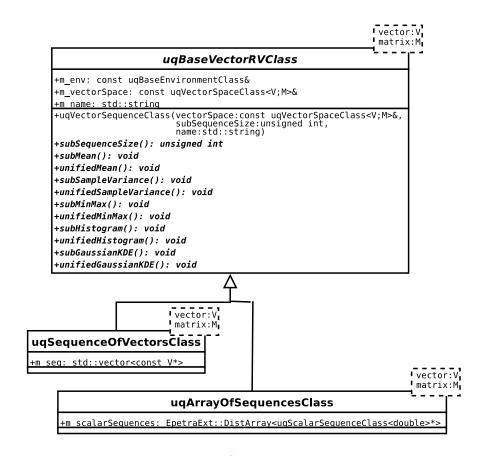


Figure 3.4.1: The class diagram for the vector random variable class.

3.4.2 Statistical Inverse Problem (and Options)

```
param vector:P_V
param matrix:P_M
                            uqStatisticalInverseProblemClass
-m_env: const uqBaseEnvironmentClass&
-m_options: uqStatisticalInverseProblemOptionsClass*
-m_priorRv: const uqBaseVectorRVClass<P_V,P_M>&
-m_likelihoodFunction: const uqBaseScalarFunctionClass <P_V,P_M>&
-m postRv: uqGenericVectorRVClass<P V,P M>&
-m_solutionDomain: uqVectorSetClass<P_V,P_M>*
-m_solutionPdf: uqBaseJointPdfClass<P_V,P_M>*
-m_solutionRealizer: uqBaseVectorRealizerClass<P_V,P_M>*
-m_mcSeqGenerator: uqMarkovChainSGClass<P_V,P_M>*
-m chain: ugBaseVectorSequenceClass<P V,P M>*
+computeSolutionFlag(): bool
+solveWithBayesMarkovChain(initialValues:const P_V&,
const P_M* proposalCovMatrix): void
+priorRv(): const uqBaseVectorRVClass <P_V;P_M>&
+postRv(): const uqGenericVectorRVClass<P_V;P_M>&
```

Figure 3.4.2: The statistical inverse problem class. It implements the representation in Figure 1.1.2.

uqBaseStatisticalInverseProblemOptionsClass				
<pre>#m_computeSolution: bool = 1</pre>				
<pre>#m_dataOutputFileName: std::string = "."</pre>				
<pre>#m_dataOutputAllowSet: std::set<unsigned int=""> = empty</unsigned></pre>				
-m_env: const uqBaseEnvironmentClass&				
-m_prefix: std::string				
-m optionsDesc: po::options description*				
<pre>+uqStatisticalInverseProblemOptionsClass(env:const uqBaseEnvironmentClass&,</pre>				
+scanOptionsValues(): void				
+print(std::ostream& os): void				
-defineMyOptions(optionsDesc:po::options description&): void				
-getMyOptionsValues(optionsDesc:po::options_description&): void				

Figure 3.4.3: The statistical inverse problem options class.

Option	Default	Description
Name	Value	
⟨PREFIX⟩ip_help		
⟨PREFIX⟩ip_computeSolution		
⟨PREFIX⟩ip_dataOutputFileName		
⟨PREFIX⟩ip_dataOutputAllowedSet		

Table 3.4.1: Input file options for a QUESO statistical inverse problem.

3.4.3 Metropolis-Hastings Solver (and Options)

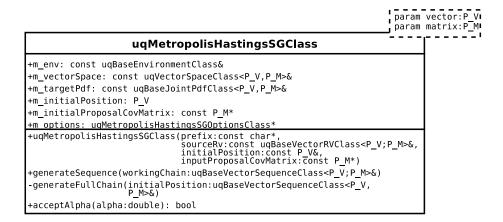


Figure 3.4.4: The Metropolis-Hastings sequence generator class.

```
uqMetropolisHastingsSGOptionsClass
+m_dataOutputFileName: std::string = "."
+m dataOutputAllowedSet: std::set<unsigned int> = empty
+m_rawChainSize: unsigned int = 100
+m_rawChainDisplayPeriod: unsigned int = 500
+m_rawChainDataOutputFileName: std::string
+m_rawChainDataOutputAllowedSet: std::set<unsigned int> = empty
+m_rawChainComputeStats: bool = false
+m rawChainStatisticalOptions: uqChainStatisticalOptionsClass* = NULL
+m_filteredChainGenerate: bool = false
+m_filteredChainDiscardedPortion: double = 0
+m filteredChainLag: unsigned int = 2
+m_filteredChainDataOutputFileName: std::string = "."
+m_filteredChainComputeStats: bool = false
+m_filteredChainStatisticalOptions: m_chainStatisticalOptionsClass* = NULL
+m_drMaxNumExtraStages: unsigned int
+m_drScalesForCovMatrices: std::vector<double>
+m_amInitialNonAdaptInterval: unsigned int
+m_amAdaptInterval: unsigned int
+m amEta: double
+m_amEpsilon: double
-m env: const ugBaseEnvironmentClass&
-m_prefix: std::string
-m optionsDesc: po::options description*
+scanOptionsValues(): void
+print(std::ofstream& os): void
-defineMyOptions(optionsDesc:po::options_description&): void
-getMyOptionsValues(optionsDesc:po::options_description&): void
```

Figure 3.4.5: The Metropolis-Hastings sequence generator options class.

Option	Default	Description
Name	Value	
⟨PREFIX⟩mh_help		
⟨PREFIX⟩mh_dataOutputFileName		
⟨PREFIX⟩mh_dataOutputAllowedSet		
⟨PREFIX⟩mh_rawChain_dataInputFileName		
⟨PREFIX⟩mh_rawChain_size		
⟨PREFIX⟩mh_rawChain_generateExtra		
⟨PREFIX⟩mh_rawChain_displayPeriod		
⟨PREFIX⟩mh_rawChain_measureRunTimes		
⟨PREFIX⟩mh_rawChain_dataOutputFileName		
⟨PREFIX⟩mh_rawChain_dataOutputAllowedSet		
⟨PREFIX⟩mh_rawChain_computeStats		
⟨PREFIX⟩mh_filteredChain_generate		
⟨PREFIX⟩mh_filteredChain_discardedPortion		
⟨PREFIX⟩mh_filteredChain_lag		
⟨PREFIX⟩mh_filteredChain_dataOutputFileName		
⟨PREFIX⟩mh_filteredChain_dataOutputAllowedSet		
⟨PREFIX⟩mh_filteredChain_computeStats		
⟨PREFIX⟩mh_displayCandidates		
⟨PREFIX⟩mh_putOutOfBoundsInChain		
⟨PREFIX⟩mh_tk_useLocalHessian		
⟨PREFIX⟩mh_tk_useNewtonComponent		
(PREFIX)mh_dr_maxNumExtraStages		
⟨PREFIX⟩mh_dr_scalesForExtraStages		
(PREFIX)mh_am_initialNonAdaptInterval		
⟨PREFIX⟩mh_am_adaptInterval		
⟨PREFIX⟩mh_am_eta		
⟨PREFIX⟩mh_am_epsilon		

Table 3.4.2: Input file options for a QUESO Metropolis-Hastings solver.

param vector:P V

3.4.4 Statistical Forward Problem (and Options)

```
param matrix:P_M
                                                                                    qoi vector:0 V
                                                                                    qoi matrix:Q M
                         uqStatisticalForwardProblemClass
-m env: const uqBaseEnvironmentClass&
-m_options: uqStatisticalForwardProblemOptionsClass*
-m paramRv: const uqBaseVectorRVClass<P V,P M>&
-m_qoiFunction: const uqBaseVectorFunctionClass <P_V,P_M,Q_V,Q_M>&
-m_qoiRv: uqGenericVectorRVClass<Q_V,Q_M>&
-m_solutionDomain: uqVectorSetClass<P_V,P_M>*
-m_solutionPdf: uqBaseJointPdfClass<P_V,P_M>*
-m_solutionRealizer: uqBaseVectorRealizerClass<P_V,P M>*
-m_mcSeqGenerator: uqMarkovChainSGClass<P_V,P_M>*
-m_chain: ugBaseVectorSequenceClass<P V,P M>*
+computeSolutionFlag(): bool
+solveWithBayesMarkovChain(initialValues:const P_V&,
const P_M* proposalCovMatrix): void
+priorRv(): const uqBaseVectorRVClass <P_V;P_M>&
+postRv(): const uqGenericVectorRVClass<P_V;P_M>&
```

Figure 3.4.6: The statistical forward problem class. It implements the representation in Figure 1.1.1.

Figure 3.4.7: The statistical forward problem options class.

Option	Default	Description
Name	Value	
⟨PREFIX⟩fp_help		
⟨PREFIX⟩fp_computeSolution		
⟨PREFIX⟩fp_computeCovariances		
⟨PREFIX⟩fp_computeCorrelations		
⟨PREFIX⟩fp_dataOutputFileName		
$\langle PREFIX \rangle$ fp_dataOutputAllowedSet		

Table 3.4.3: Input file options for a QUESO statistical forward problem.

3.4.5 Monte Carlo Solver (and Options)

Figure 3.4.8: The Monte Carlo sequence generator class.

```
uqMonteCarloSGOptionsClass
+m_dataOutputFileName: std::string = "."
+m dataOutputAllowedSet: std::set<unsigned int> = empty
+m_rawChainSize: unsigned int = 100
+m_rawChainDisplayPeriod: unsigned int = 500
+m_rawChainDataOutputFileName: std::string
+m_rawChainDataOutputAllowedSet: std::set<unsigned int> = empty
+m_rawChainComputeStats: bool = false
+m rawChainStatisticalOptions: uqChainStatisticalOptionsClass* = NULL
+m_filteredChainGenerate: bool = false
+m_filteredChainDiscardedPortion: double = 0
+m filteredChainLag: unsigned int = 2
+m_filteredChainDataOutputFileName: std::string = "."
+m_filteredChainComputeStats: bool = false
+m_filteredChainStatisticalOptions: m_chainStatisticalOptionsClass* = NULL
+m_drMaxNumExtraStages: unsigned int
+m_drScalesForCovMatrices: std::vector<double>
+m_amInitialNonAdaptInterval: unsigned int
+m_amAdaptInterval: unsigned int
+m amEta: double
+m_amEpsilon: double
-m env: const ugBaseEnvironmentClass&
-m_prefix: std::string
-m optionsDesc: po::options description*
+scanOptionsValues(): void
+print(std::ofstream& os): void
-defineMyOptions(optionsDesc:po::options_description&): void
-getMyOptionsValues(optionsDesc:po::options_description&): void
```

Figure 3.4.9: The Monte Carlo sequence generator options class.

Option	Default	Description
Name	Value	
⟨PREFIX⟩mc_help		
⟨PREFIX⟩mc_dataOutputFileName		
⟨PREFIX⟩mc_dataOutputAllowedSet		
⟨PREFIX⟩mc_pseq_dataOutputFileName		
⟨PREFIX⟩mc_pseq_dataOutputAllowedSet		
⟨PREFIX⟩mc_pseq_computeStats		
⟨PREFIX⟩mc_qseq_dataInputFileName		
⟨PREFIX⟩mc_qseq_size		
⟨PREFIX⟩mc_qseq_displayPeriod		
⟨PREFIX⟩mc_qseq_measureRunTimes		
$\langle PREFIX \rangle mc_qseq_dataOutputFileName$		
$\langle PREFIX \rangle$ mc_qseq_dataOutputAllowedSet		
⟨PREFIX⟩mc_qseq_computeStats		

Table 3.4.4: Input file options for a QUESO Monte Carlo solver.

3.4.6 Options for Statistical Analysis of Sequences

```
uqSequenceStatisticalOptionsClass
+m_numSubEnvironments: unsigned int = 1
+m subDisplayFileName: std::string = "."
+m_subDisplayAllowAll: bool = false
+m_subDisplayAllowSet: std::set<unsigned int>
+m_displayVerbosity: unsigned int = 2
+m_syncVerbosity: unsigned int = 0
+m_seed: int = 0
-m_env: const uqBaseEnvironmentClass&
-m_prefix: std::string
-m optionsDesc: po::options description*
+scanOptionsValues(): void
+print(std::ofstream& os): void
-defineMyOptions(optionsDesc:po::options_description&): void
```

Figure 3.4.10: The sequence statistical options class.

Option	Default	Description
Name	Value	
(PREFIX)stats_help		
(PREFIX)stats_initialDiscardedPortions		
(PREFIX)stats_bmm_run		
⟨PREFIX⟩stats_bmm_lengths		
⟨PREFIX⟩stats_bmm_display		
(PREFIX)stats_bmm_write		
⟨PREFIX⟩stats_fft_compute		
⟨PREFIX⟩stats_fft_paramId		
⟨PREFIX⟩stats_fft_size		
⟨PREFIX⟩stats_fft_testInversion		
(PREFIX)stats_fft_write		
⟨PREFIX⟩stats_psd_compute		
(PREFIX)stats_psd_numBlocks		
(PREFIX)stats_psd_hopSizeRatio		
(PREFIX)stats_psd_paramId		
⟨PREFIX⟩stats_psd_write		
(PREFIX)stats_psdAtZero_compute		
(PREFIX)stats_psdAtZero_numBlocks		
\(\rangle \text{PREFIX} \) stats_psdAtZero_hopSizeRatio		
(PREFIX)stats_psdAtZero_display		
(PREFIX)stats_psdAtZero_write		
(PREFIX)stats_geweke_compute		
(PREFIX)stats_geweke_naRatio		
(PREFIX)stats_geweke_nbRatio		
(PREFIX)stats_geweke_display		
(PREFIX)stats_geweke_write		
\(\rangle \text{PREFIX} \) stats_autoCorr_computeViaDef		
(PREFIX)stats_autoCorr_computeViaFft		
(PREFIX)stats_autoCorr_secondLag		
(PREFIX)stats_autoCorr_lagSpacing		
(PREFIX)stats_autoCorr_numLags		
(PREFIX)stats_autoCorr_display		
(PREFIX)stats_autoCorr_write		
\(\frac{\text{PREFIX}}{\text{stats_meanStacc_compute}}\)		
\(\rangle \text{PREFIX} \rangle \text{stats_hist_compute}\)		
(PREFIX)stats_hist_numInternalBins		
\(\rmathred{PREFIX}\rangle\stats_cdf\rmathred{Stacc_compute}\)		
⟨PREFIX⟩stats_cdfStacc_numEvalPositions		
(PREFIX)stats_kde_compute		
(PREFIX)stats_kde_numEvalPositions		
⟨PREFIX⟩stats_covMatrix_compute		
(PREFIX)stats_corrMatrix_compute		

Table 2.4.5: Input file entions for a the statistical analysis of sequences

3.5 Interface Classes

Chapter 4

An Application Example (Out of Date)

In this chapter we show how to use QUESO in order to develop an application that solves an example statistical inverse problem and an example statistical forward problem, where the solution of the former serves as input to the later. Section 4.1 gives the mathematical formulation of both example problems. Section 4.2 shows the codes that translate the mathematical language into C++ using the QUESO classes and algorithms. Section 4.3 shows how to compile the code. Section 4.4 shows an example input file for QUESO classes and algorithms. Section 4.5 shows how to run the code. Finally, Section 4.6 shows how to plot figures using output data generated by the application.

4.1 Examples of Statistical Problems

4.1.1 Statistical Inverse Problem

In this example we have

$$\pi_{\text{prior}}(\boldsymbol{\theta}) \varpropto 1$$

and

$$\pi_{\text{like}}(\boldsymbol{\theta}) \propto e^{-\frac{1}{2}\left\{(\boldsymbol{\theta}-\boldsymbol{\mu})^T[\mathbf{C}^{-1}](\boldsymbol{\theta}-\boldsymbol{\mu})\right\}},$$

where

$$oldsymbol{ heta} = \left(egin{array}{c} heta_1 \ heta_2 \end{array}
ight) \in \mathbb{R}^2,$$

$$\mu = \begin{pmatrix} -1 \\ 2 \end{pmatrix}$$

and

(4.1.2)
$$\mathbf{C} = \begin{bmatrix} 4 & 0 \\ 0 & 1 \end{bmatrix}.$$

The posterior pdf is then given by

(4.1.3)
$$\pi_{\text{post}}(\boldsymbol{\theta}) \propto e^{-\frac{1}{2}\left\{(\boldsymbol{\theta}-\boldsymbol{\mu})^T[\mathbf{C}^{-1}](\boldsymbol{\theta}-\boldsymbol{\mu})\right\}}.$$

It is clear that for such problem it is possible to analytically compute the exact posterior pdf as

$$\pi_{\text{post}}(\boldsymbol{\theta}) = \frac{1}{4\pi} e^{-\frac{1}{2} \left\{ (\boldsymbol{\theta} - \boldsymbol{\mu})^T [\mathbf{C}^{-1}] (\boldsymbol{\theta} - \boldsymbol{\mu}) \right\}}$$
$$= \frac{1}{4\pi} e^{-\frac{1}{8} (\theta_1 + 1)^2 - \frac{1}{2} (\theta_2 - 2)^2},$$

and to sample it through the formula

$$\boldsymbol{\mu} + \mathbf{C}^{1/2} \mathcal{N}(0, I),$$

where $\mathcal{N}(0,I)$ designates a Gaussian joint pdf of zero mean and unit covariance matrix and

$$\mathbf{C}^{1/2} = \left[\begin{array}{cc} 2 & 0 \\ 0 & 1 \end{array} \right].$$

Nonetheless, we will use QUESO to sample the posterior (4.1.3) with a Markov chain algorithm available in QUESO, and then check the marginal results for θ_1 and θ_2 against the analytical formulas

$$\pi_{\text{post}}(\theta_1) = \frac{1}{2\sqrt{2\pi}} e^{-\frac{1}{8}(\theta_1 + 1)^2},$$

$$\pi_{\text{post}}(\theta_1) = \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}(\theta_2 - 2)^2}.$$

4.1.2 Statistical Forward Problem

Once the solution Θ_{post} of the statistical inverse problem is obtained, it is used for a statistical forward problem with a qoi function

$$\mathbf{q}: \mathbb{R}^2 \to \mathbb{R}.$$

In this example the Also, we have the very simple situation

(4.1.4)
$$\mathbf{q}(\boldsymbol{\theta}) = \theta_1 + \theta_2, \quad \forall \boldsymbol{\theta} \in \mathbb{R}^2.$$

Since the solution \mathbf{Q} of this statistical forward problem is the sum of two rvs $\mathbf{\Theta}_1$ and $\mathbf{\Theta}_2$, and since these two rvs are independent Gaussian rvs by assumption, we should have

(4.1.5)
$$E[\mathbf{Q}] = E[\mathbf{\Theta}_1] + E[\mathbf{\Theta}_2] = -1 + 2 = 1$$

and

(4.1.6)
$$V[\mathbf{Q}] = V[\mathbf{\Theta}_1] + V[\mathbf{\Theta}_2] = 4 + 1 = 5$$

where "E" and "V" indicate expectation and variance respectively.

4.2 Application Code

The program example given in this paper is compatible with version 0.41.0 of QUESO [?]. The source code for the example is composed of 7 files:

- example_main.C (Figure 4.2.1),
- example_likelihood.h and example_likelihood.C (Figures 4.2.2 and 4.2.3),
- example_qoi.h and example_qoi.C (Figures 4.2.4 and 4.2.5), and
- example_compute.h and example_compute.C (Figures 4.2.6, 4.2.7 and 4.2.8).

```
#include <example_compute.h>
int main(int argc, char* argv[])
  // Initialize environment
  MPI_Init(&argc,&argv);
  UQ_FATAL_TEST_MACRO(argc != 2,
                      UQ_UNAVAILABLE_RANK,
                       "main()",
                      "input file must be specified in command line
                       as argv[1], just after executable argv[0]");
  uqFullEnvironmentClass* env =
    new uqFullEnvironmentClass(MPI_COMM_WORLD, argv[1], "");
  // Compute
  compute(*env);
  // Finalize environment
  delete env;
 MPI_Finalize();
  return 0;
}
```

Figure 4.2.1: The example_main.C file.

```
#ifndef __EX_LIKELIHOOD_H__
#define __EX_LIKELIHOOD_H__
#include <uqGslMatrix.h>
struct
likelihoodRoutine_DataType
  const uqGslVectorClass* meanVector;
  const uqGslMatrixClass* covMatrix;
};
double likelihoodRoutine(
  const uqGslVectorClass& paramValues,
  const uqGslVectorClass* paramDirection,
  const void*
                          functionDataPtr,
  uqGslVectorClass*
                          gradVector,
  uqGslMatrixClass*
                          hessianMatrix,
  uqGslVectorClass*
                          hessianEffect);
#endif
```

Figure 4.2.2: The example_likelihood.h file

```
#include <example_likelihood.h>
double likelihoodRoutine(
  const ugGslVectorClass& paramValues,
  const uqGslVectorClass* paramDirection,
  const void*
                          functionDataPtr,
  uqGslVectorClass*
                          gradVector,
 uqGslMatrixClass*
                          hessianMatrix,
  uqGslVectorClass*
                          hessianEffect)
{
 // Just checking: the user, at the application level, expects
 // vector 'paramValues' to have size 2.
 UQ_FATAL_TEST_MACRO(paramValues.sizeGlobal() != 2,
                      UQ_UNAVAILABLE_RANK,
                      "likelihoodRoutine()",
                      "paramValues vector does not have size 2");
 // This code exemplifies multiple Metropolis-Hastings solvers, each calling
 // this likelihood routine.
  //
 // In this simple example, only node 0 in each subenvironment does the job
 // even though there might be more than one node per subenvironment.
 // In a more realistic situation, if the user is asking for multiple nodes per
 // subenvironment, then the model code in the goi and likelihood routines
 // might really demand more than one node.
 //
 // Here we use 'env.subRank()' only. A realistic application might want to use
 // 'env.subComm()' or 'env.subComm().Comm()'
  double result = 0.;
  const uqBaseEnvironmentClass& env = paramValues.env();
  if (env.subRank() == 0) {
    const uqGslVectorClass& meanVector =
      *((likelihoodRoutine_DataType *) functionDataPtr)->meanVector;
    const uqGslMatrixClass& covMatrix =
      *((likelihoodRoutine_DataType *) functionDataPtr)->covMatrix;
   uqGslVectorClass diffVec(paramValues - meanVector);
   result = scalarProduct(diffVec, covMatrix.invertMultiply(diffVec));
  }
  else {
   // Do nothing;
 return -.5*result;
}
```

Figure 4.2.3: The example_likelihood.C file

```
#ifndef __EX_QOI_H__
#define __EX_QOI_H__
#include <uqGslMatrix.h>
#include <EpetraExt_DistArray.h>
struct
qoiRoutine_DataType
  double coef1;
  double coef2;
};
void
qoiRoutine(
  const uqGslVectorClass&
                                                  paramValues,
  const uqGslVectorClass*
                                                  paramDirection,
  const void*
                                                  functionDataPtr,
        uqGslVectorClass&
                                                  qoiValues,
        EpetraExt::DistArray<uqGslVectorClass*>* gradVectors,
        EpetraExt::DistArray<uqGslMatrixClass*>* hessianMatrices,
        EpetraExt::DistArray<uqGslVectorClass*>* hessianEffects);
#endif
```

Figure 4.2.4: The example_qoi.h file

```
#include <example_qoi.h>
void qoiRoutine(
  const ugGslVectorClass&
                                                  paramValues,
  const uqGslVectorClass*
                                                  paramDirection,
  const void*
                                                  functionDataPtr,
        uqGslVectorClass&
                                                  qoiValues,
        EpetraExt::DistArray<uqGslVectorClass*>* gradVectors,
        EpetraExt::DistArray<uqGslMatrixClass*>* hessianMatrices,
        EpetraExt::DistArray<uqGslVectorClass*>* hessianEffects)
{
 // Just checking: the user, at the application level, expects
 // vector 'paramValues' to have size 2 and
  // vector 'qoiValues' to have size 1.
 UQ_FATAL_TEST_MACRO(paramValues.sizeGlobal() != 2,
                      UQ_UNAVAILABLE_RANK,
                      "qoiRoutine()",
                      "paramValues vector does not have size 2");
 UQ_FATAL_TEST_MACRO(qoiValues.sizeGlobal() != 1,
                      UQ_UNAVAILABLE_RANK,
                      "qoiRoutine()",
                      "qoiValues vector does not have size 1");
 // This code exemplifies multiple Monte Carlo solvers, each calling this
 // qoi routine.
 //
 // In this simple example, only node 0 in each subenvironment does the job
 // even though there might be more than one node per subenvironment.
 // In a more realistic situation, if the user is asking for multiple nodes per
 // subenvironment, then the model code in the qoi and likelihood routines
 // might really demand more than one node.
 // Here we use 'env.subRank()' only. A realistic application might want to use
  // 'env.subComm()' or 'env.subComm().Comm()'
  const uqBaseEnvironmentClass& env = paramValues.env();
  if (env.subRank() == 0) {
   double coef1 = ((qoiRoutine_DataType *) functionDataPtr)->coef1;
    double coef2 = ((qoiRoutine_DataType *) functionDataPtr)->coef2;
    qoiValues[0] = (coef1*paramValues[0] + coef2*paramValues[1]);
  }
  else {
    qoiValues[0] = 0.;
 return;
}
```

Figure 4.2.5: The example_qoi.C file

```
#ifndef __EX_COMPUTE_H__
#define __EX_COMPUTE_H__
#include <uqEnvironment.h>

void compute(const uqFullEnvironmentClass& env);
#endif
```

Figure 4.2.6: The example_compute.h file

```
#include <example_compute.h>
#include <example_likelihood.h>
#include <example_qoi.h>
#include <ugGslMatrix.h>
#include <uqStatisticalInverseProblem.h>
#include <ugStatisticalForwardProblem.h>
void compute(const uqFullEnvironmentClass& env) {
  // Step 1 of 9: Instantiate the parameter space
  uqVectorSpaceClass<uqGslVectorClass,uqGslMatrixClass>
   paramSpace(env, "param_", 2, NULL);
  // Step 2 of 9: Instantiate the parameter domain
  uqGslVectorClass paramMins(paramSpace.zeroVector());
  paramMins.cwSet(-INFINITY);
  uqGslVectorClass paramMaxs(paramSpace.zeroVector());
 paramMaxs.cwSet( INFINITY);
  uqBoxSubsetClass<uqGslVectorClass,uqGslMatrixClass>
    paramDomain("param_",paramSpace,paramMins,paramMaxs);
  // Step 3 of 9: Instantiate the likelihood function object
  uqGslVectorClass meanVector(paramSpace.zeroVector());
 meanVector[0] = -1;
 meanVector[1] = 2;
  uqGslMatrixClass covMatrix(paramSpace.zeroVector());
  covMatrix(0,0) = 4.; covMatrix(0,1) = 0.;
  covMatrix(1,0) = 0.; covMatrix(1,1) = 1.;
  likelihoodRoutine_DataType likelihoodRoutine_Data;
  likelihoodRoutine_Data.meanVector = &meanVector;
  likelihoodRoutine_Data.covMatrix = &covMatrix;
  uqGenericScalarFunctionClass<uqGslVectorClass,uqGslMatrixClass>
    likelihoodFunctionObj("like_",
                          paramDomain,
                          likelihoodRoutine,
                          (void *) &likelihoodRoutine_Data,
                          true); // routine computes [ln(function)]
  // Step 4 of 9: Instantiate the inverse problem
  uqUniformVectorRVClass<uqGslVectorClass,uqGslMatrixClass>
   priorRv("prior_", paramDomain);
  uqGenericVectorRVClass<uqGslVectorClass,uqGslMatrixClass>
    postRv("post_", paramSpace);
  uqStatisticalInverseProblemClass<uqGslVectorClass,uqGslMatrixClass>
    ip("", priorRv, likelihoodFunctionObj, postRv);
```

Figure 4.2.7: Initial part of example_compute.C file: the first 4 of the 5 steps to deal with the statistical inverse problem.

}

```
// Step 5 of 9: Solve the inverse problem
uqGslVectorClass paramInitials(paramSpace.zeroVector());
paramInitials[0] = 0.1;
paramInitials[1] = -1.4;
uqGslMatrixClass proposalCovMatrix(paramSpace.zeroVector());
proposalCovMatrix(0,0) = 8.; proposalCovMatrix(0,1) = 4.;
proposalCovMatrix(1,0) = 4.; proposalCovMatrix(1,1) = 16.;
ip.solveWithBayesMetropolisHastings(paramInitials, &proposalCovMatrix);
// Step 6 of 9: Instantiate the goi space
uqVectorSpaceClass<uqGslVectorClass,uqGslMatrixClass>
  qoiSpace(env, "qoi_", 1, NULL);
// Step 7 of 9: Instantiate the qoi function object
qoiRoutine_DataType qoiRoutine_Data;
goiRoutine_Data.coef1 = 1.;
qoiRoutine_Data.coef2 = 1.;
uqGenericVectorFunctionClass<uqGslVectorClass,uqGslMatrixClass,
                             uqGslVectorClass,uqGslMatrixClass>
  qoiFunctionObj("qoi_",
                 paramDomain,
                 qoiSpace,
                 qoiRoutine,
                 (void *) &qoiRoutine_Data);
// Step 8 of 9: Instantiate the forward problem
uqGenericVectorRVClass<uqGslVectorClass,uqGslMatrixClass>
  qoiRv("qoi_", qoiSpace);
uqStatisticalForwardProblemClass<uqGslVectorClass,uqGslMatrixClass,
                                 uqGslVectorClass,uqGslMatrixClass>
  fp("", postRv, qoiFunctionObj, qoiRv);
// Step 9 of 9: Solve the forward problem
fp.solveWithMonteCarlo();
return;
```

Figure 4.2.8: Final part of example_compute.C file: the final step of the 5 steps to deal with the statistical inverse problem and the 4 steps to deal with the statistical forward problem.

4.3 Application Compilation

The makefile is given in Figure 4.3.1.

```
QUESO_DIR = /basepath/Installations/queso_0_41_0_gnu/
TRILINOS_DIR = /basepath/Installations/Trilinos_8_0_7/
BOOST_DIR = /basepath/Installations/Boost_1_35_0/
HPCT_DIR = /org/centers/pecos/LIBRARIES/hpct/0.25.1/
include $(TRILINOS_DIR)/include/Makefile.export.epetra
INC_PATHS = \setminus
        -I. \
        -I$(QUESO_DIR)/include \
        -I$(MPI_DIR)/include \
        -I$(BOOST_DIR)/include/boost-1_35 \
        -I$(GSL_DIR)/include \
        -I$(HPCT_DIR)/include \
        $(EPETRA_INCLUDES)
LIBS = \
        -L$(QUESO_DIR)/lib -lqueso \
        -L$(MPI_DIR)/lib \
        -L$(TRILINOS_DIR)/lib \
        -L$(BOOST_DIR)/lib -lboost_program_options \
        -L$(GSL_DIR)/lib -lgsl \
        -L$(HPCT_DIR)/lib -lhpct \
        $(EPETRA_LIBS)
CXX = mpicxx
CXXFLAGS += -03 -Wall -c
default: all
.SUFFIXES: .o .C
all:
        ex_gsl
clean:
        rm -f *~
        rm -f *.o
        rm -f example
ex_gsl: example_main.o example_likelihood.o example_qoi.o example_compute.o
        $(CXX) example_main.o example_likelihood.o example_qoi.o example_compute.o \
               -o example_gsl $(LIBS)
%.o: %.C
        $(CXX) $(INC_PATHS) $(CXXFLAGS) $<</pre>
```

Figure 4.3.1: Makefile for the program in Figures 4.2.1-4.2.8.

4.4 Application Input File

The options input file is given in Figures 4.4.1, 4.4.2 and 4.4.3.

```
# UQ Environment
#env_help
                = anything
env_numSubEnvironments
               = 1
env_subDisplayFileName
               = outputData/display
env_subDisplayAllowAll
env_subDisplayAllowedSet = 0
env_displayVerbosity
env_syncVerbosity
                = 0
                = 0
env_seed
# Statistical inverse problem (ip)
#ip_help
                = anything
ip_computeSolution
                = 1
ip_dataOutputFileName
                = outputData/sipOutput
ip_dataOutputAllowedSet = 0
# Statistical forward problem (fp)
fp_help
                = anything
fp_computeSolution
                = 1
fp_computeCovariances
fp_computeCorrelations = 1
fp_dataOutputFileName
                = outputData/sfpOutput
fp_dataOutputAllowedSet = 0 1
```

Figure 4.4.1: Some options in the input file for program in Figures 4.2.1-4.2.8.

```
# 'ip_': information for Metropolis-Hastings algorithm
ip_mh_dataOutputFileName
                        = outputData/sipOutput
ip_mh_dataOutputAllowedSet = 0 1
ip_mh_rawChain_size
                                  = 32768
ip_mh_rawChain_dataOutputFileName
                                  = outputData/ip_raw_chain
ip_mh_rawChain_dataOutputAllowedSet = 0 1
ip_mh_rawChain_computeStats
ip_mh_dr_maxNumExtraStages
ip_mh_dr_listOfScalesForExtraStages = 5.
ip_mh_am_initialNonAdaptInterval
                                  = 0
                                  = 100
ip_mh_am_adaptInterval
                                  = 1.92
ip_mh_am_eta
                                  = 1.e-5
ip_mh_am_epsilon
                                       = 1
ip_mh_filteredChain_generate
ip_mh_filteredChain_discardedPortion
                                       = 0.
ip_mh_filteredChain_lag
                                       = 16
ip_mh_filteredChain_dataOutputFileName
                                       = outputData/ip_filt_chain
ip_mh_filteredChain_dataOutputAllowedSet = 0 1
                                       = 1
ip_mh_filteredChain_computeStats
ip_mh_rawChain_stats_autoCorr_computeViaFft
                                             = 1
ip_mh_rawChain_stats_autoCorr_secondLag
                                             = 2
ip_mh_rawChain_stats_autoCorr_lagSpacing
ip_mh_rawChain_stats_autoCorr_numLags
                                             = 10
ip_mh_rawChain_stats_autoCorr_display
                                             = 1
ip_mh_rawChain_stats_autoCorr_write
                                             = 1
ip_mh_filteredChain_stats_autoCorr_computeViaFft
                                                  = 1
ip_mh_filteredChain_stats_autoCorr_secondLag
                                                  = 2
ip_mh_filteredChain_stats_autoCorr_lagSpacing
                                                  = 2
ip_mh_filteredChain_stats_autoCorr_numLags
                                                 = 10
ip_mh_filteredChain_stats_autoCorr_display
                                                 = 1
ip_mh_filteredChain_stats_autoCorr_write
                                                 = 1
ip_mh_filteredChain_stats_hist_compute
                                                 = 1
ip_mh_filteredChain_stats_hist_numInternalBins
                                                 = 250
ip_mh_filteredChain_stats_kde_compute
                                                 = 1
ip_mh_filteredChain_stats_kde_numEvalPositions
                                                 = 250
ip_mh_filteredChain_stats_covMatrix_compute
                                                 = 1
ip_mh_filteredChain_stats_corrMatrix_compute
                                                 = 1
```

Figure 4.4.2: Options for the Markov chain algorithm for solving the statistical inverse problem.

```
# 'fp_': information for Monte Carlo algorithm
fp_mc_help
                         = anything
fp_mc_dataOutputFileName
                         = outputData/sfpOutput
fp_mc_dataOutputAllowedSet = 0 1
fp_mc_pseq_dataOutputFileName
                             = outputData/fp_p_seq
fp_mc_pseq_dataOutputAllowedSet = 0 1
fp_mc_pseq_computeStats
#fp_mc_pseq_stats_help
                                         = anything
fp_mc_pseq_stats_initialDiscardedPortions = 0.
fp_mc_pseq_stats_hist_compute
                                        = 1
fp_mc_pseq_stats_hist_numInternalBins
                                        = 250
fp_mc_pseq_stats_kde_compute
                                        = 1
                                        = 250
fp_mc_pseq_stats_kde_numEvalPositions
fp_mc_pseq_stats_covMatrix_compute
                                        = 1
fp_mc_pseq_stats_corrMatrix_compute
                                        = 1
fp_mc_qseq_size
                              = 1048576
fp_mc_qseq_displayPeriod
                              = 20000
fp_mc_qseq_measureRunTimes
                             = 1
fp_mc_qseq_dataOutputFileName = outputData/fp_q_seq
fp_mc_qseq_dataOutputAllowedSet = 0 1
fp_mc_qseq_computeStats
                              = 1
#fp_mc_qseq_stats_help
                                         = anything
fp_mc_qseq_stats_initialDiscardedPortions = 0.
fp_mc_qseq_stats_autoCorr_computeViaFft
                                        = 1
                                        = 2
fp_mc_qseq_stats_autoCorr_secondLag
fp_mc_qseq_stats_autoCorr_lagSpacing
                                        = 1
fp_mc_qseq_stats_autoCorr_numLags
                                        = 15
fp_mc_qseq_stats_autoCorr_display
                                        = 1
fp_mc_qseq_stats_autoCorr_write
                                        = 1
fp_mc_qseq_stats_hist_compute
                                        = 1
fp_mc_qseq_stats_hist_numInternalBins
                                        = 250
fp_mc_qseq_stats_kde_compute
                                        = 1
fp_mc_qseq_stats_kde_numEvalPositions
                                        = 250
fp_mc_qseq_stats_covMatrix_compute
                                        = 1
fp_mc_qseq_stats_corrMatrix_compute
                                        = 1
```

Figure 4.4.3: Options for the Monte Carlo algorithm for solving the statistical forward problem.

4.5 Application Run

Once the code is compiled, one just needs to run "example_gsl example.inp".

4.6 Application Results and Some Plots

The files generated will be in subdirectory "outputData", as specified by the options input file. Figures 4.6.1 and 4.6.2 show the contents of "test/t02_sip_sfp/sip_sfp/example_plots.m".

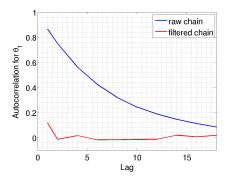
```
cd outputData
sipOutput_subO
sfpOutput_subO
plot(ip_mh_rawChain_corrViaFftLags_sub0,ip_mh_rawChain_corrViaFftInitPos0_sub0(1,:),'-b','l:
hold
plot(ip_mh_filtChain_corrViaFftLags_sub0,ip_mh_filtChain_corrViaFftInitPos0_sub0(1,:),'-r',
ylabel('Autocorrelation for \theta_1', 'fontsize', 20);
xlabel('Lag', 'fontsize', 20);
a = axis;
axis([a(1) a(2) -0.1 1]);
grid minor;
set(gca, 'fontsize', 20);
legend('raw chain',...
       'filtered chain',...
       'location', 'northeast');
print -dpng paper_plot1.png
waitforbuttonpress;
clf;
plot(ip_mh_rawChain_corrViaFftLags_sub0,ip_mh_rawChain_corrViaFftInitPos0_sub0(2,:),'-b','1:
hold
plot(ip_mh_filtChain_corrViaFftLags_sub0,ip_mh_filtChain_corrViaFftInitPos0_sub0(2,:),'-r',
ylabel('Autocorrelation for \theta_2', 'fontsize', 20);
xlabel('Lag', 'fontsize', 20);
a = axis;
axis([a(1) a(2) -0.1 1]);
grid minor;
set(gca,'fontsize',20);
legend('raw chain',...
       'filtered chain',...
       'location', 'northeast');
print -dpng paper_plot2.png
waitforbuttonpress;
clf;
```

Figure 4.6.1: Matlab program file for plotting: part 1 of 2

```
plot(ip_mh_filtChain_unifGkdePosits_sub0(1,:),ip_mh_filtChain_unifGkdeValues_sub0(1,:)
hold
x = ip_mh_filtChain_unifGkdePosits_sub0(1,:);
plot(x,(exp(-(x+1).*(x+1)/8))/2/sqrt(2*pi),'--r','linewidth',2);
ylabel('Posterior marginal pdf', 'fontsize', 20);
xlabel('\theta_1','fontsize',20);
grid minor;
set(gca,'fontsize',20);
legend('QUESO',...
       'Analytic',...
       'location','northwest');
print -dpng paper_plot3.png
waitforbuttonpress;
clf;
plot(ip_mh_filtChain_unifGkdePosits_sub0(2,:),ip_mh_filtChain_unifGkdeValues_sub0(2,:)
hold
x = ip_mh_filtChain_unifGkdePosits_sub0(2,:);
plot(x,(exp(-(x-2).*(x-2)/2))/sqrt(2*pi),'--r','linewidth',2);
ylabel('Posterior marginal pdf', 'fontsize', 20);
xlabel('\theta_2', 'fontsize', 20);
%title('Fig 4, Pdfs for \theta_2', 'fontsize', 20);
grid minor;
set(gca,'fontsize',20);
legend('QUESO',...
       'Analytic',...
       'location', 'northwest');
print -dpng paper_plot4.png
waitforbuttonpress;
clf;
plot(fp_mc_QoiSeq_unifGkdePosits_sub0(1,:),fp_mc_QoiSeq_unifGkdeValues_sub0(1,:),'-b';
ylabel('Pdf','fontsize',20);
xlabel('QoI = \theta_1 + \theta_2', 'fontsize', 20);
a = axis;
axis([-9 11 a(3) a(4)]);
grid minor;
set(gca, 'fontsize', 20);
print -dpng paper_plot5.png
```

Figure 4.6.2: Matlab program file for plotting: part 2 of 2

4.6.1 Results for the Statistical Inverse Problem



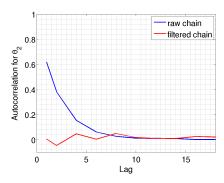
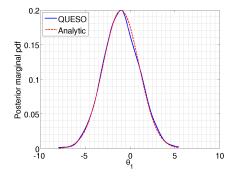


Figure 4.6.3: Autocorrelation plots obtained with QUESO for the statistical inverse problem. The user might want to see the results with a Markov chain with more positions than "just" 32,768. One might set "ip_mh_rawChain_size = 1,048,576" in the options input file, for instance.



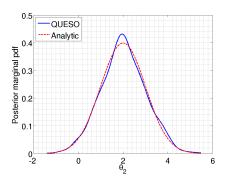


Figure 4.6.4: KDE plots obtained with QUESO for the statistical inverse problem. The user might want to see the results with a Markov chain with more positions than "just" 32,768. One might set "ip_mh_rawChain_size = 1,048,576" in the options input file, for instance.

4.6.2 Results for the Statistical Forward Problem

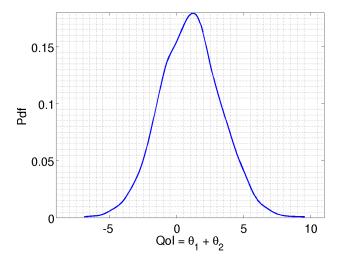


Figure 4.6.5: KDE plot obtained with QUESO for the statistical forward problem. The user might want to see the results with a Markov chain with more positions than "just" 32,768. One might set "ip_mh_rawChain_size = 1,048,576" in the options input file, for instance.

Appendix A

Free Software Needs Free Documentation

The following article was written by Richard Stallman, founder of the GNU Project.

The biggest deficiency in the free software community today is not in the software—it is the lack of good free documentation that we can include with the free software. Many of our most important programs do not come with free reference manuals and free introductory texts. Documentation is an essential part of any software package; when an important free software package does not come with a free manual and a free tutorial, that is a major gap. We have many such gaps today.

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Appendix B

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