### CS 170 Homework 3

Due 2025/3/1, at 10:00 pm (grace period until 11:59pm)

# 1 Study Group

List the names and SIDs of the members in your study group. If you have no collaborators, you must explicitly write "none".

Solution: I worked on this homework with the following collaborators:

• none, which is only me, Sillycheese

# 2 Depth First Search

- (a) (4 points) In each of the following cases, PreVisit and PostVisit have been defined for you. After execution, the array A[v] will hold a value for each vertex v. Describe in words what A[v] represents.
  - i. Describe in words what A[v] represents.

**Solution:** this is the lognest path form root of subtrees to leaf.

ii. Describe in words what A[v] represents.

Solution: this is maximum degree.

- (b) (6 points) In each of the following cases, write down pseudocode for PreVisit and PostVisit routines to perform the computation needed.
  - i. For each vertex v, compute the maximum weight of an edge along the path from root r to vertex v and store it in array A[v].

#### **Solution:**

```
\begin{aligned} & \mathbf{procedure} \ \operatorname{PreVisit}(u, \ v) \\ & A[v] \leftarrow \max(A[u], \ w(u, \ v)) \\ & \mathbf{procedure} \ \operatorname{PostVisit}(u, \ v) \\ & \operatorname{return} \end{aligned}
```

ii. For each vertex v, compute the maximum weight of any edge in the subtree rooted at vertex v and store it in array A[v].

#### **Solution:**

```
\begin{array}{l} \textbf{procedure} \ \mathrm{PreVisit}(u, \, v) \\ \mathrm{return} \end{array}
```

```
procedure PostVisit(u, v)

A[u] \leftarrow \max(A[u], A[v], w(u, v))
```

iii. For each vertex v, compute the maximum pre-order number of any of its children and store it in array A[v]. If v has no children, then A[v] should be 0.

## **Solution:**

```
\label{eq:procedure} \begin{split} & \mathbf{procedure} \ \operatorname{PreVisit}(u, \, v) \\ & t \leftarrow t \! + \! 1 \\ & A[u] \leftarrow t \end{split} \begin{aligned} & \mathbf{procedure} \ \operatorname{PostVisit}(u, \, v) \\ & t \leftarrow t \! + \! 1 \end{aligned}
```

## 3 Biconnected Components

(a) Suppose that |V | 2. Can you always find a vertex v V that is not critical? What about an edge that is not critical?

**Solution:** DFS,and find that leaf

if all Vs are critical

(b) Give a linear time algorithm to find all the critical edges of G.

**Solution:** PreVisit, and maintain a low value. if pre(v) < low(n), then u-v is critical.

(c) Modify your algorithm above to find all the critical vertices of G.

Solution: DFS

# 4 Topological Sort Proofs

**Solution:** SKIP!all is because of my Ph.D Exam coming:(

## 5 Distant Descendants

(a) Write an O(|V|) algorithm that computes the total size of the subtree (number of descendants plus 1 for the vertex itself) of each vertex v in an array s[v]. Give a brief justification that your algorithm is correct and runs in O(|V|) time. Do not just cite an algorithm from class; reproduce anything you use in your solution.

**Solution:** To find the size of subtree. we need to DFS(v), and maintain s[u]=s[u]+s[v] recursively.

(b) Write an O(|V|) algorithm that computes the K-th level ancestor of each vertex v (null if the depth of v is less than K) in an array a[v]. Give a brief justification that your algorithm is correct and runs in O(|V|) time. Make sure your algorithm runs in O(|V|) time and not O(K|V|) time.

**Solution:** say a array called a to note the members of ancestors.

```
if len(a) > K,then return a[len(a)-1-k] else return null then recursively loop. for (u,v) in G a.push_back(v) DFS(v) a.pop_back(v) clean the path for the next search. remember to set a visited array to optimize it!
```

(c) Write an O(|V|) algorithm to compute d[v] for each vertex v using s[v] and a[v]. Give a brief justification that your algorithm is correct and runs in O(|V|) time.

```
Solution: if a[v] exists d[a[v]]=s[v]+d[a[v]] loop and loop
```