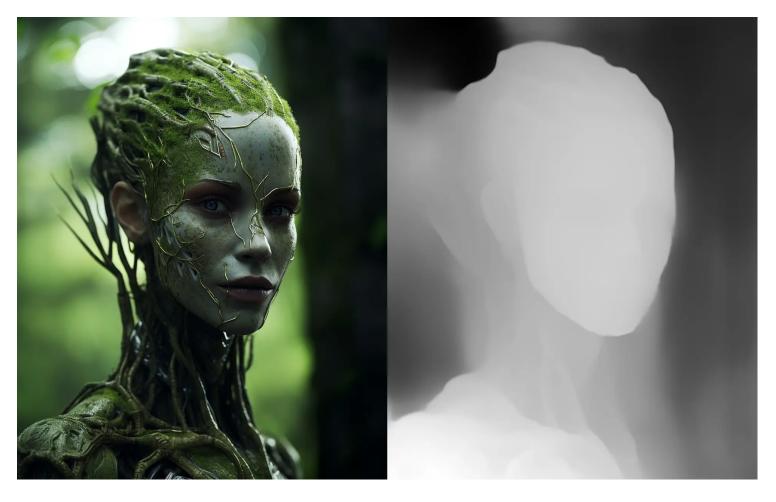
# **Table of Contents**

Manual	
Midas	 2
Getting Started	 3
Models	 5
Scripting API	
Doji.Al.Depth	 7
Midas	 8
ModelType	 11

# Midas

Midas 
☐ unlocks real-time monocular depth estimation with MiDaS models running in Unity Sentis.

To get started, please see the <u>Getting Started</u> page. The package also provides a number of samples that can be imported via the Package Manager.



# **Getting started**

This page will cover the basics of using the Midas package.

## **Basic Usage**

To start, create a new 'Midas' instance:

```
var midas = new Midas();
```

Then you can pass in a Texture2D to @Doji.Al.Depth.Midas.EstimateDepth(Texture,System.Boolean)

```
// Estimate depth from an input texture
midas.EstimateDepth(inputImage);
RenderTexture predictedDepth = midas.Result;
// ... use predictedDepth as needed
```

Finally, when you're done you should call 'Dispose()' to properly free up native memory resources.

```
midas.Dispose();
```

You can reuse the same 'Midas' instance for multiple inferences. But if you only need it once, you might want to use the 'using' statement, so you don't need to worry about disposing it:

```
using (Midas midas = new Midas()) {
   // your code
}
```

A simple example on how to use the library can also be found in the 'Basic Sample' that can be imported via the Package Manager.

# **Choosing a Model Type**

The default model is <u>midas v21 small 256</u>. You can specify the model to be used in the Midas constructor.

```
var midas = new Midas(ModelType.dpt_beit_large_384);
```

You can also change the model on an existing 'Midas' instance through the <u>ModelType</u> property. Changing the model automatically disposes of the existing model and initializes the new one.

```
midas.ModelType = ModelType.dpt_beit_large_384;
```

Note, that different models can have different output sizes, so changing the model might change the dimensions of the predicted depth map.

For more information on available models and when to use which, see the Models page.

## **Choosing a Backend**

Use the Backend property to set the desired backend for model execution (GPUCompute by default). Changing the backend automatically disposes of the existing model and initializes the new one.

```
midas.Backend = BackendType.CPU;
```

# **Normalizing Depth**

Set the NormalizeDepth property to true if you want to normalize the estimated depth values between 0 and 1. This is mainly useful for visualization.

### MiDaS Models

There are variety of different MiDaS models available. To be able to use them with Unity Sentis, the official models were converted to ONNX using this colab notebook. You'll find links to the pretrained models in ONNX format below.

#### Overview

Model Type	Size	MiDaS Version
midas_v21_small_256 <sup>™</sup>	63 MB	2.1
midas_v21_384♂	397 MB	2.1
dpt beit large 512♂	1.34 GB	3.1
dpt beit large 384♂	1.34 GB	3.1
dpt_beit_base_384♂	450 MB	3.1
dpt_swin2_large_384♂	832 MB	3.1
dpt_swin2_base_384♂	410 MB	3.1
dpt_swin2_tiny_256 <sup>™</sup>	157 MB	3.1
dpt_swin_large_384♂	854 MB	3.1
dpt_next_vit_large_384₫	267 MB	3.1
dpt levit 224♂	136 MB	3.0
dpt large 384♂	1.27 GB	3.0

### Usage

To keep the package size reasonable, only the <u>midas v21 small 256</u> model is included with the package when downloading from the Asset Store. To use other models you have to downloaded them first.

When you create an instance of the <u>Midas</u> class you can pass the <u>ModelType</u> in the constructor to choose which model to use. In the Unity Editor if you're about to use a model that is not yet present, you will automatically be prompted to allow the file download.

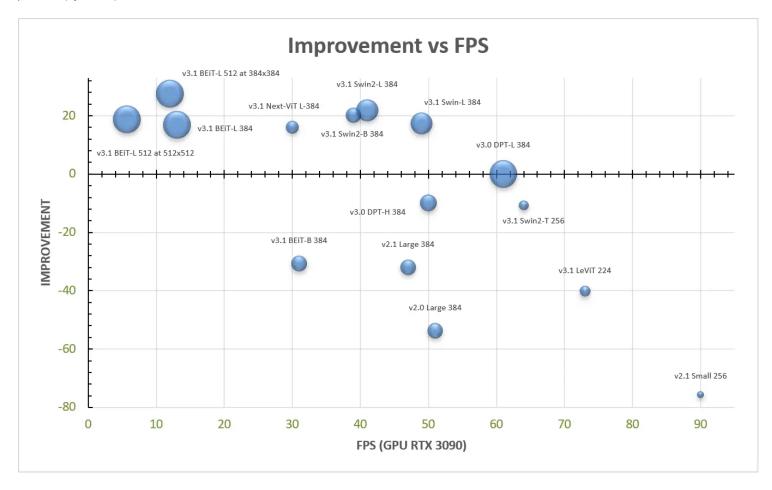
Otherwise you can always manually download the ONNX models from the links above and place them inside the Resources/ONNX folder.

#### Which Model To Use

You should choose the appropriate model type based on your requirements, considering factors such as accuracy, model size and performance.

The available models usually have a tradeoff between memory & performance and the accuracy/quality of the depth estimation.

The <u>official MiDaS documentation</u> does a fairly good job of showcasing the different capabilities, so I'll just copy the performance overview here:



Generally, if you have a hard realtime requirement, e.g. when you want to do depth estimation at runtime or on mobile devices, you may want to use smaller models like midas\_v21\_small\_256 or dpt\_swin2\_tiny\_256. If you need best quality (editor tools) or depth estimation needs to happen just once, you might be able to use models like dpt\_swin2\_large\_384 or dpt\_beit\_large\_384. Keep in mind the larger memory requirements for these model though.

# Namespace Doji.Al.Depth

## Classes

#### **Midas**

A class that allows to run Midas models to do monocular depth estimation.

#### **Enums**

#### <u>ModelType</u>

All the supported MiDaS models.

### Class Midas

Namespace: <u>Doji.Al.Depth</u>
Assembly: Doji.Midas.dll

A class that allows to run Midas models to do monocular depth estimation.

```
public class Midas : IDisposable
```

#### Inheritance

<u>object</u> 

✓ Midas

#### **Implements**

#### **Inherited Members**

#### **Constructors**

#### Midas(ModelType)

Initializes a new instance of MiDaS.

```
public Midas(ModelType modelType = ModelType.midas_v21_small_256)
```

#### **Parameters**

modelType

## **Properties**

#### **Backend**

Which Unity.Sentis.BackendType to run the model with.

```
public BackendType Backend { get; set; }
```

#### Property Value

BackendType

### ModelType

Which of the MiDaS models to run.

```
public ModelType ModelType { get; set; }
```

#### Property Value

**ModelType** 

### NormalizeDepth

Whether to normalize the estimated depth.

```
public bool NormalizeDepth { get; set; }
```

#### Property Value

bool₫

#### Remarks

MiDaS predicts depth values as inverse relative depth. (small values for far away objects, large values for near objects) If NormalizeDepth is enabled, these values are mapped to the (0, 1) range, which is mostly useful for visualization.

#### Result

A RenderTexture that contains the estimated depth.

```
public RenderTexture Result { get; set; }
```

#### Property Value

RenderTexture

#### **Methods**

# Dispose()

```
public void Dispose()
```

## EstimateDepth(Texture, bool)

```
public void EstimateDepth(Texture input, bool autoResize = true)
```

#### Parameters

input Texture

autoResize <u>bool</u>♂

# **Enum ModelType**

```
Namespace: <u>Doji.Al.Depth</u>
Assembly: Doji.Midas.dll
```

All the supported MiDaS models.

```
public enum ModelType
```

#### **Fields**

```
Unknown = -1
midas_v21_small_256 = 0
  63 MB MiDaS v2.1 model.
midas_v21_384 = 1
  397 MB MiDaS v2.1 model.
dpt_beit_large_512 = 2
  1.34 GB MiDaS v3.1 model with a beitl16_512 backbone.
dpt_beit_large_384 = 3
  1.34 GB MiDaS v3.1 model with a beitl16_384 backbone.
dpt_beit_base_384 = 4
  450 MB MiDaS v3.1 model with a beitb16_384 backbone.
dpt_swin2_large_384 = 5
  832 MB MiDaS v3.1 model with a swin2l24_384 backbone.
dpt_swin2_base_384 = 6
  410 MiDaS v3.1 model with a swin2b24_384 backbone.
dpt_swin2_tiny_256 = 7
  157 MiDaS v3.1 model with a swin2t16_256 backbone.
```

854 MB MiDaS v3.1 model with a swinl12\_384 backbone.

267 MB MiDaS v3.1 model with a next\_vit\_large\_6m backbone.

$$dpt_levit_224 = 10$$

136 MB MiDaS v3.0 model with a levit\_384 backbone.

$$dpt_large_384 = 11$$

1.27 GB MiDaS v3.0 model with a vitl16\_384 backbone.