Fundamentos de los Sistemas Operativos (FSO)

Departamento de Informática de Sistemas y Computadoras (DISCA) *Universitat Politècnica de València*

Part 2: Process management

Seminar 6

Synchronization: POSIX Semaphores





• Goals:

To get use to deal with critical section problems

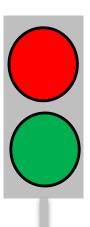
Synchronization: POSIX Semaphores

- To know the synchronization mechanisms offered
 by the OS
- To use semaphores and mutexes to solve critical section synchronization

Bibliography

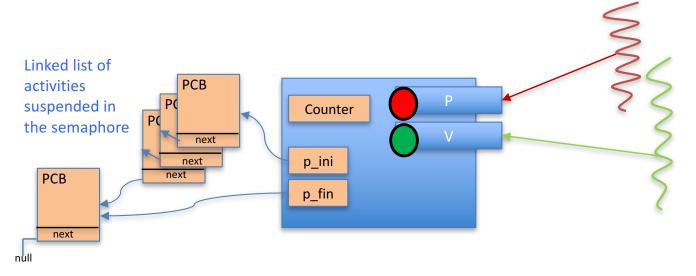
- Silberschatz 8th Ed, chapter 6
- Robbins, chapters 13, 14

- OS level solutions
- POSIX semaphores
- POSIX mutexes
- Exercises



OS level solutionsSemaphore

- Can be seen as an integer that admits an increment by 1 and a decrement by 1 operations performed by an activity (process or thread)
 - The decrement operation can suspend the activity
 - The increment operation can awake another activity previously suspended
- It is a synchronization object offered by the OS to user activities
 - It is declared as type "semaphore" specifying its initial value
 - The increment (V) and the decrement (P) operations are implemented as system calls



Initialization, P and V specification

Declaration and initialization

Semaphore S(N);

OS level solutions

- It declares a semaphore "S" with "N" as initial value
- "N" has to be greater or equal to zero
- Decrement

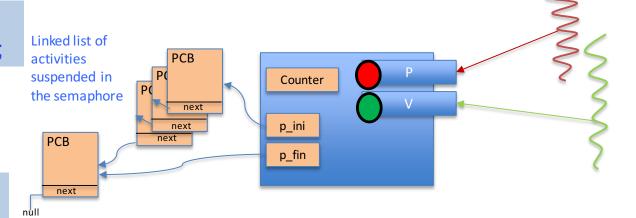
```
P(S);
```

```
S = S - 1;
if S < 0 then suspend(S);
```

Increment

```
V(S);
```

```
S = S + 1;
if S <= 0 then awake(S);
```



Notes:

- P and V are guaranteed to be atomic by the OS
- suspend(S) suspends the calling activity in a queue associated to S
- awake(S) extracts an activity from the S queue and awakes it (it goes to the scheduler ready queue)

Solving the critical section problem

We define as a global variable the semaphore "mutex", <u>initialized to 1</u>

Semaphore mutex(1);

OS level solutions

Code for N threads/processes

```
void *thread_i(void *p) {
    while(1) {
        P(mutex);

        /* Critical section */

        V(mutex);

        /* Remaining section */
    }
}
```

It complies with:

- Mutual exclusion
- Progress
- Limited waiting, if the semaphore queue is scheduled with FCFS policy

- Another synchronization use of semaphores:
 Establishing an execution order
 - We want "thread1" to execute function "F1" before "thread2" executes function "F2"
 - We define a shared semaphore between "thread1" and "thread2" named "sync", initialized to 0

Semaphore sync(0);

```
void *thread1(void *p)
{
    ...
    P(sync);
    V(sync);
}
```

- Another synchronization use of semaphores: Limiting the number of activities that can pass through a certain point in the code simultaneously
 - We have a function executed by many threads
 - We want a maximum of 5 threads call function "F" located in a certain place inside the function
 - We define a shared semaphore "max_5", initialized to 5

```
Semaphore max_5(5);
```

```
pthread_t th1, th2, th3, th4, th5;
pthread_attr_t attr;

pthread_attr_init(&attr);
pthread_create(&th1, &attr, thread_i NULL);
pthread_create(&th2, &attr, thread_i NULL);
pthread_create(&th3, &attr, thread_i NULL);
pthread_create(&th4, &attr, thread_i NULL);
.....
```

```
void *thread_i(void *p) {

...
P(max_5);
F;
V(max_5);
...
}
```

Basically a semaphore is a "resource counter"

OS level solutions

- When an activity tries to use a resource, it decrements the counter (P operation) and if there are not available resources then the activity is suspended
- When an activity finishes using a resource then it increments the counter (*V* operation). If there is any suspended activity waiting for the resource, then the *V* operation awakes it.
- If the counter is greater than 0 then its value indicates the number of available resources
 if S >0 then |S|= number of available resources
- When its value is less than cero its absolute value indicates the number of suspended activities in the semaphore queue

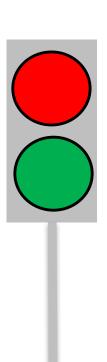
if S <0 then |S|= number of suspended processes

When the counter is cero both of the former sentences are true

if S =0 then → there are no suspended processes there are no available resources

- With semaphores the OS manages suspended activity queues, waiting for available resources
- Activity synchronization is one of the essential mechanisms that an OS has to provide

- OS level solutions
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- POSIX mutexes
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POSIX.1b introduced the semaphore type sem t

```
#include <semaphore.h>
sem_t sem;
```

POSIX semaphores

- A semaphore can be used by all the threads inside a process and also can be shared between processes.
 - After a fork() call semaphores in the parent can be inherited by the child depending on "pshared" paramete value in "sem_init".
- POSIX.1b semaphore operations are:

```
- int sem_init(sem_t *sem, int pshared, unsigned int
  value);
- int sem_destroy(sem_t *sem);
- int sem_wait(sem_t *sem);
- int sem_trywait(sem_t *sem);
- int sem_post(sem_t *sem);
- int sem_post(sem_t *sem);
- int sem_getvalue(sem_t *sem, int *sval);
Operation
V(sem)
```

Producer/Consumer version 1

POSIX semaphores

We define a semaphore "mutex" initialized to 1 → sem_init(&mutex,0,1);

```
void *func prod(void *p) {
  int item;
  while(1) {
    item = produce();
    sem wait(& mutex);
    while (counter == N)
      /*empty loop*/;
    buffer[input] = item;
    input = (input + 1) % N;
    counter = counter + 1;
    sem post(&mutex);
```

```
void *func cons(void *p) {
  int item;
  while(1) {
    sem wait(&mutex);
    while (counter == 0)
      /*empty loop*/;
    item = buffer[output];
    output = (output + 1) % N;
    counter = counter - 1;
    sem post(&mutex);
    consume (item);
```

 If the producer enters the critical section being the buffer full it will get into the while loop forever, the same happens with the consumer when the buffer is empty

Producer/Consumer version 2

POSIX semaphores

```
#include <semaphore.h>
sem_t mutex, items, vacants;
```

```
void *func prod(void *p) {
  int item;
  while(1) {
    item = produce();
    sem wait(&vacants);
    sem wait(&mutex);
    buffer[input] = item;
    input = (input + 1) % N;
    counter = counter + 1;
    sem post(&mutex);
    sem post(&items);
```

```
void *func cons(void *p) {
  int item;
  while(1) {
    sem wait (&items);
    sem_wait(&mutex);
    item = buffer[output];
    output = (output + 1) % N;
    counter = counter - 1;
    sem post(&mutex);
    sem post(&vacants);
    consume(item);
```

```
sem_init(&mutex, 0, 1);
sem_init(&vacants, 0, N); // indicates the initial number of buffer vacants
sem_init(&items, 0, 0); // indicates the initial number of buffer items
...
```

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Mutex

- POSIX.1c defines the mutex object for thread synchronization
 - It can be seen as semaphores that can only be initialized to 1
 - It is used only to guaranty mutual exclusion
 - It works as a latch -> two operations: lock and unlock
 - A mutex has at every moment:
 - State: Open or closed
 - Owner: It is a thread that has executed a successful lock peration on it

Mutex operation:

POSIX mutexes

- A mutex is created opened and without owner
- When a thread calls to lock
 - If the mutex was open (without owner), the calling thread closes it and becomes its owner
 - If the mutex was closed, the calling thread is suspended
- When an owner thread calls to unlock
 - The mutex gets open
 - If there were suspended threads on it, one of them is awaked, then the mutex gets closed an the awoken thread is the new owner

Mutex operation

A mutex is created opened and without owner



When a thread calls to lock and

the calling thread

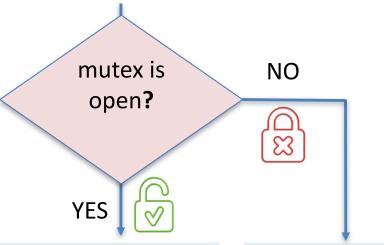
closes it and

becomes its owner



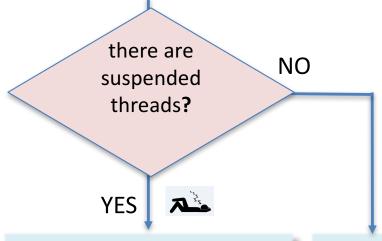
when the **owner** thread calls to **unlock** and ...





the calling thread is **suspended**





one of them is awaked, then the mutex gets closed an the awoken thread is the **new owner**





The mutex gets opened



POSIX calls for mutexes

- Creation and destruction
 - pthread_mutex_init
 - pthread_mutex_destroy
- Attribute initialization
 - pthread_mutexattr_init
 - pthread_mutexattr_destroy
 - Changing/Checking attribute values
- Lock and unlock
 pthread_mutex_lock
 pthread_mutex_trylock
 pthread_mutex_unlock
 Equivalent to P(sem)
 Equivalent to V(sem)

- Example: concurrent access to a shared variable by two threads
 - Main function code:

POSIX mutexes

```
pthread mutex t m = PTHREAD MUTEX INITIALIZER;
int V = 100;
// Threads code (next slide)
int main ( ) {
  pthread attr t attributes;
  pthread attr init(&attributes);
  pthread create(&thread1, &attributes, func thread1, NULL);
  pthread create (&thread2, &attributes, func thread2, NULL);
  pthread join(thread1, NULL);
  pthread join(thread2, NULL);
```

- Example (cont)
 - Thread functions:

```
void *func_thread1(void *p) {
  int c;

for(c=0; c<1000; c++) {
    pthread_mutex_lock(&m);

    V = V + 1;

    pthread_mutex_unlock(&m);
}

pthread_exit(0);
}</pre>
```

```
void *func_thread2(void *p) {
  int c;

for(c=0; c<1000; c++) {
    pthread_mutex_lock(&m);

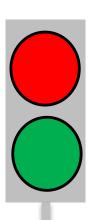
    V = V - 1;

    pthread_mutex_unlock(&m);
}

pthread_exit(0);
}</pre>
```

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Exercises

• Exercise S06.1 What possible values will take x as a result of the concurrent execution of the following threads?

```
#include <semaphore.h>
#include <pthread.h>
#include <stdlib.h>
#include <stdio.h>
sem t s1, s2, s3;
int x;
```



```
void *func thread1(void *a)
                              int main()
                                 pthread t h1, h2;
 sem wait(&s1);
                                 x = 1;
 sem wait(&s2);
                                 sem_init(&s1,0,1); /*Inicializa a 1*/
 x=x+1;
                                 sem init(\&s2,0,1); /*Inicializa a 1*/
 sem post(&s3);
 sem post(&s1);
                                 sem init(\&s3,0,0); /*Inicializa a 0*/
 sem post(&s2);
                                 pthread create(&h1,NULL,func thread1,NULL);
void *func thread2(void *b)
                                 pthread create (&h2, NULL, func thread2, NULL);
                                 pthread join(h1, NULL);
 sem wait(&s2);
                                 pthread join(h2, NULL);
 sem wait(&s1);
 sem wait(&s3);
 x=10*x;
 sem post(&s2);
 sem post(&s1);
```

Exercise S06.2 What possible values will take shared variables **x** and **y** at the end of the following concurrent threads. The initial values are: x=1, y=4, S1=1, S2=0 y S3=1.

Thread B	Thread C
P(S1);	P(S1);
P(S3);	P(S3);
x=x+1;	x = y + 2;
y = 8 + x;	y = x * 4;
V(S2);	V(S3);
V(S3);	V(S1);
	P(S1); P(S3); x = x + 1; y = 8 + x; V(S2);

