

A Appendix

Supplemental proof for “Beyond Word Embeddings: Representations for Multi-modal Data”. by Luis Armona, José González-Brenes, and Ralph Edezath.

A.1 Proof to Theorem 1

Theorem 1. *The gradient for learning embeddings with self-supervised Feat2Vec is a convex combination of the gradient from n supervised Factorization Machines learned with implicit sampling, one for each feature group in the data.*

Proof. Let \mathbf{X} denote the training data with positive labels, $|\mathbf{X}|$ the number of observations in the data, and $S_{\kappa_i}^+$ denote the positively labeled records in \mathbf{X} whose corresponding negative samples resample feature group i . For convenience, suppress the inclusion of learned parameters θ in the notation in this section while understanding the feature extraction functions $\vec{\phi}$ implicitly include these parameters. We can express the loss function $L(\cdot)$, the binary cross-entropy of the data given the self-supervised Feat2Vec model, as follows:

$$\begin{aligned}
L(\mathbf{X}|\vec{\phi}) &= -\frac{1}{|\mathbf{X}|} \sum_{\vec{x}^+ \in \mathbf{X}} \left(\log(\tilde{p}(y=1|\vec{\phi}, \vec{x}^+)) + \sum_{\vec{x}^- \sim \mathcal{Q}(\cdot|\vec{x}^+)}^k \log(\tilde{p}(y=0|\vec{\phi}, \vec{x}^-)) \right) \\
&= -\frac{1}{|\mathbf{X}|} \sum_{\vec{x}^+ \in \mathbf{X}} \left(\log(\tilde{p}(y=1|\vec{\phi}, \vec{x}^+, \vec{x}^+ \in S_{\kappa_i}^+)p(\vec{x}^+ \in S_{\kappa_i}^+)) \right. \\
&\quad \left. + \sum_{\vec{x}^- \sim \mathcal{Q}(\cdot|\vec{x}^+)}^k \log(\tilde{p}(y=0|\vec{\phi}, \vec{x}^-, \vec{x}^+ \in S_{\kappa_i}^+)p(\vec{x}^+ \in S_{\kappa_i}^+)) \right) \\
&= -\frac{1}{|\mathbf{X}|} \sum_{i=1}^n \sum_{\vec{x}^+ \in S_{\kappa_i}^+} \left(\log\left(\frac{e^{s(\vec{x}^+, \vec{\phi})}p(\vec{x}^+ \in S_{\kappa_i}^+)}{e^{s(\vec{x}^+, \vec{\phi})} + P_{\mathcal{Q}}(\vec{x}^+|\vec{x}^+, \vec{x}^+ \in S_{\kappa_i}^+)}\right) \right. \\
&\quad \left. + \sum_{\vec{x}^- \sim \mathcal{Q}(\cdot|\vec{x}^+, \vec{x}^+ \in S_{\kappa_i}^+)}^k \log\left(\frac{P_{\mathcal{Q}}(\vec{x}^-|\vec{x}^+, \vec{x}^+ \in S_{\kappa_i}^+)p(\vec{x}^+ \in S_{\kappa_i}^+)}{e^{s(\vec{x}^-, \vec{\phi})} + P_{\mathcal{Q}}(\vec{x}^-|\vec{x}^+, \vec{x}^+ \in S_{\kappa_i}^+)}\right) \right)
\end{aligned}$$

Note now that $P_Q(\vec{x}|\vec{x}^+, \vec{x}^+ \in S_{\kappa_i}^+)$ is simply the probability of the record's feature value \vec{x}_f under the second step noise distribution $Q_2(X_f, \alpha_2)$: $P_Q(\vec{x}|\vec{x}^+, \vec{x}^+ \in S_{\kappa_i}^+) = P_{Q_2}(\vec{x}_{\kappa_i})$

$$\begin{aligned}
&= -\frac{1}{|\mathbf{X}|} \sum_{i=1}^n \sum_{\vec{x}^+ \in S_{\kappa_i}^+} \left(\log \left(\frac{e^{s(\vec{x}^+, \vec{\phi})} p(\vec{x}^+ \in S_{\kappa_i}^+)}{e^{s(\vec{x}^+, \vec{\phi})} + P_{Q_2}(\vec{x}_{\kappa_i}^+)} \right) + \sum_{\vec{x}^- \sim Q(\cdot|\vec{x}^+, i \in S_{\kappa_i}^+)}^k \log \left(\frac{P_{Q_2}(\vec{x}_{\kappa_i}^-) p(\vec{x}^+ \in S_{\kappa_i}^+)}{e^{s(\vec{x}^-, \vec{\phi})} + P_{Q_2}(\vec{x}_{\kappa_i}^-)} \right) \right) \\
&= -\frac{1}{|\mathbf{X}|} \sum_{i=1}^n \sum_{\vec{x}^+ \in S_{\kappa_i}^+} \left(\log \left(\frac{e^{s(\vec{x}^+, \vec{\phi})}}{e^{s(\vec{x}^+, \vec{\phi})} + P_{Q_2}(\vec{x}_{\kappa_i}^+)} \right) + \log(p(\vec{x}^+ \in S_{\kappa_i}^+)^{k+1}) \right. \\
&\quad \left. + \sum_{\vec{x}^- \sim Q(\cdot|\vec{x}^+, i \in S_{\kappa_i}^+)}^k \log \left(\frac{P_{Q_2}(\vec{x}_{\kappa_i}^-)}{e^{s(\vec{x}^-, \vec{\phi})} + P_{Q_2}(\vec{x}_{\kappa_i}^-)} \right) \right)
\end{aligned}$$

We now drop the term containing the probability of assignment to a feature group $p(\vec{x}^+ \in S_{\kappa_i}^+)$ since it is outside of the learned model parameters $\vec{\phi}$ and fixed in advance:

$$\begin{aligned}
&\propto \frac{1}{|\mathbf{X}|} \sum_{i=1}^n \sum_{\vec{x}^+ \in S_{\kappa_i}^+} \left(\log \left(\frac{e^{s(\vec{x}^+, \vec{\phi})}}{e^{s(\vec{x}^+, \vec{\phi})} + P_{Q_2}(\vec{x}_{\kappa_i}^+)} \right) + \sum_{\vec{x}^- \sim Q(\cdot|\vec{x}^+, i \in S_{\kappa_i}^+)}^k \log \left(\frac{P_{Q_2}(\vec{x}_{\kappa_i}^-)}{e^{s(\vec{x}^-, \vec{\phi})} + P_{Q_2}(\vec{x}_{\kappa_i}^-)} \right) \right) \\
&\xrightarrow{|\mathbf{X}| \rightarrow \infty} \sum_{i=1}^n p(\vec{x}^+ \in S_{\kappa_i}^+) E \left[\log \left(\frac{e^{s(\vec{x}^+, \vec{\phi})}}{e^{s(\vec{x}^+, \vec{\phi})} + P_{Q_2}(\vec{x}_{\kappa_i}^+)} \right) + \sum_{\vec{x}^- \sim Q(\cdot|\vec{x}^+, i \in S_{\kappa_i}^+)}^k \log \left(\frac{P_{Q_2}(\vec{x}_{\kappa_i}^-)}{e^{s(\vec{x}^-, \vec{\phi})} + P_{Q_2}(\vec{x}_{\kappa_i}^-)} \right) \right] \\
&= - \sum_{i=1}^n p(\vec{x}^+ \in S_{\kappa_i}^+) E \left[L(\vec{x}|\vec{\phi}, \text{target} = \kappa_i) \right]
\end{aligned}$$

Thus, the loss function is just a convex combination of the loss functions of the targeted classifiers for each of the p features, and by extension so is the gradient since:

$$\frac{\partial}{\partial \phi} \sum_{i=1}^n p(\vec{x}^+ \in S_{\kappa_i}^+) E \left[L(\vec{x}|\vec{\phi}, \text{target} = i) \right] = \sum_{i=1}^n p(\vec{x}^+ \in S_{\kappa_i}^+) \frac{\partial}{\partial \phi} E \left[L(\vec{x}|\vec{\phi}, \text{target} = i) \right]$$

Thus the algorithm will, at each step, learn a convex combination of the gradient for a targeted classifier on feature f , with weights proportional to the feature group sampling probabilities in step 1 of the sampling algorithm. Note that if feature groups are not singletons, the gradient from unsupervised Feat2Vec will analogously be a convex combination of n gradients learned from supervised learning tasks on each of the n feature groups. \square