Linear Algebra

GA DAT2 Misrab M. Faizullah-Khan We use the notation a_{ij} (or A_{ij}, A_{i,j}, etc) to denote the entry of A in the ith row and jth column:

$$A = \left[egin{array}{cccc} a_{11} & a_{12} & \cdots & a_{1n} \ a_{21} & a_{22} & \cdots & a_{2n} \ dots & dots & \ddots & dots \ a_{m1} & a_{m2} & \cdots & a_{mn} \end{array}
ight].$$

We denote the jth column of A by a_j or A_{:,j}:

$$A = \left[\begin{array}{cccc} | & | & & | \\ a_1 & a_2 & \cdots & a_n \\ | & | & & | \end{array} \right].$$

We denote the ith row of A by a_i^T or A_{i,:}

$$A = \left[egin{array}{cccc} - & a_1^T & - \ - & a_2^T & - \ & dots \ - & a_m^T & - \ \end{array}
ight].$$

Matrix Multiplication Review

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \times \begin{bmatrix} 2 & 0 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} 4 & 4 \\ 10 & 8 \end{bmatrix}$$
$$\begin{bmatrix} 2 & 0 \\ 1 & 2 \end{bmatrix} \times \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} = \begin{bmatrix} 2 & 4 \\ 7 & 10 \end{bmatrix}$$

Column combination

$$y = Ax = \begin{bmatrix} \begin{vmatrix} & & & & & \\ a_1 & a_2 & \cdots & a_n \\ & & & \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} a_1 \\ x_2 \end{bmatrix} x_1 + \begin{bmatrix} a_2 \\ a_2 \end{bmatrix} x_2 + \ldots + \begin{bmatrix} a_n \\ a_n \end{bmatrix} x_n$$

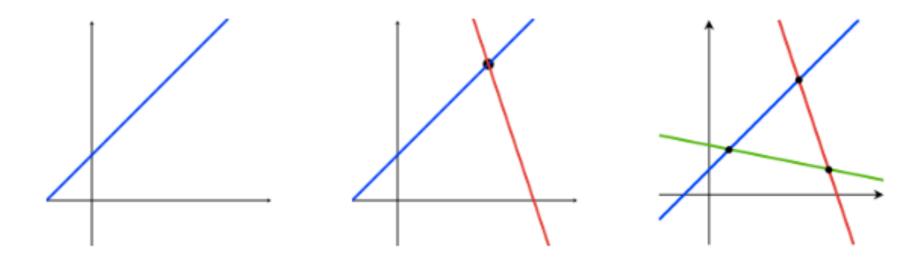
Row combination

Simultaneous System

convert the following into matrix notation

$$2x + 2y = 1$$
$$4x + 5y = 3$$

Simultaneous System



Simultaneous System - Underdetermined (n < d) "more variables than equations"

$$2x + 2y + 4z = 1$$

 $4x + 5y + 3z = 3$

Simultaneous System - Underdetermined (n < d)

$$2x + 2y + 4z = 1 (1)$$

 $4x + 5y + 3z = 3 (2)$

(2)-
$$2^*(1)$$
: $y = 1 + 5z$

sub into (2):

$$4x + 5 + 25z + 3z = 3$$

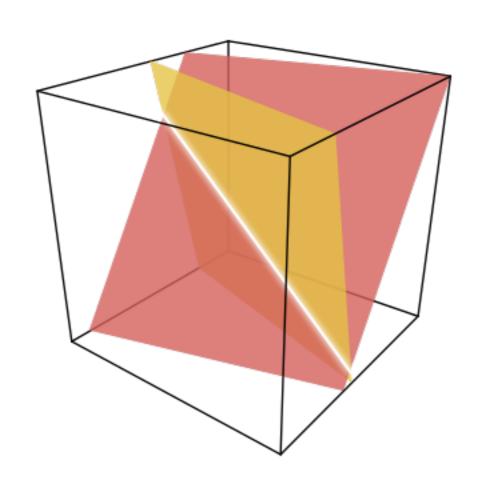
=> $x = (-2 - 28z) / 4$

"free variable"

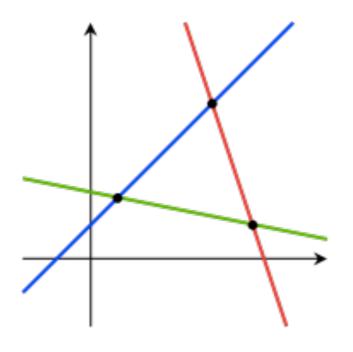
Simultaneous System - Underdetermined (n < d)

$$y = 1 + 5z$$

 $x = (-2 - 28z) / 4$

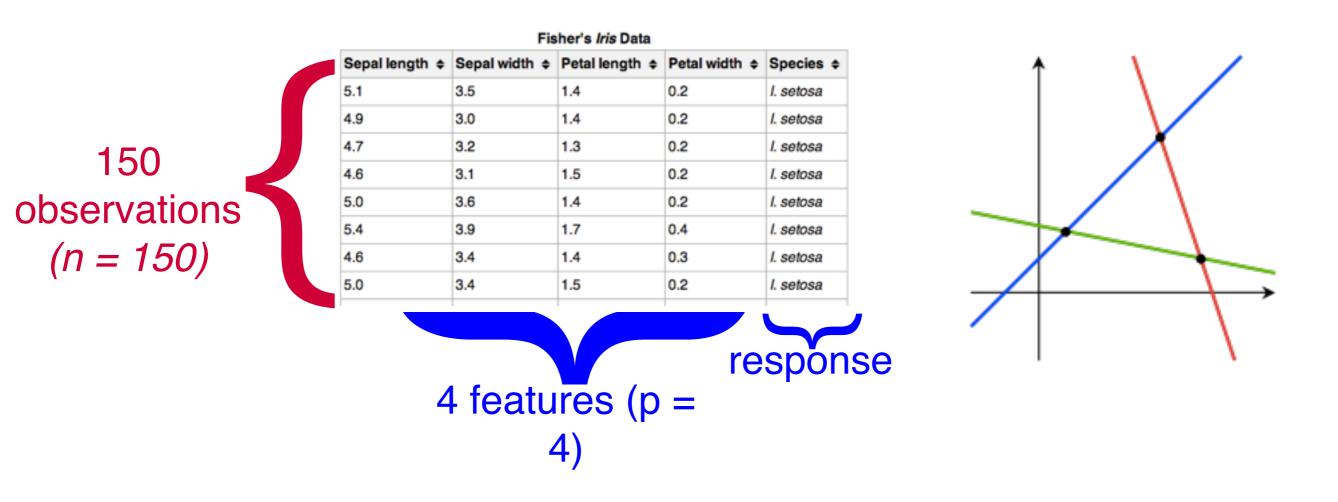


Simultaneous System - Overdetermined (n > d) "More equations (constraints) than variables"



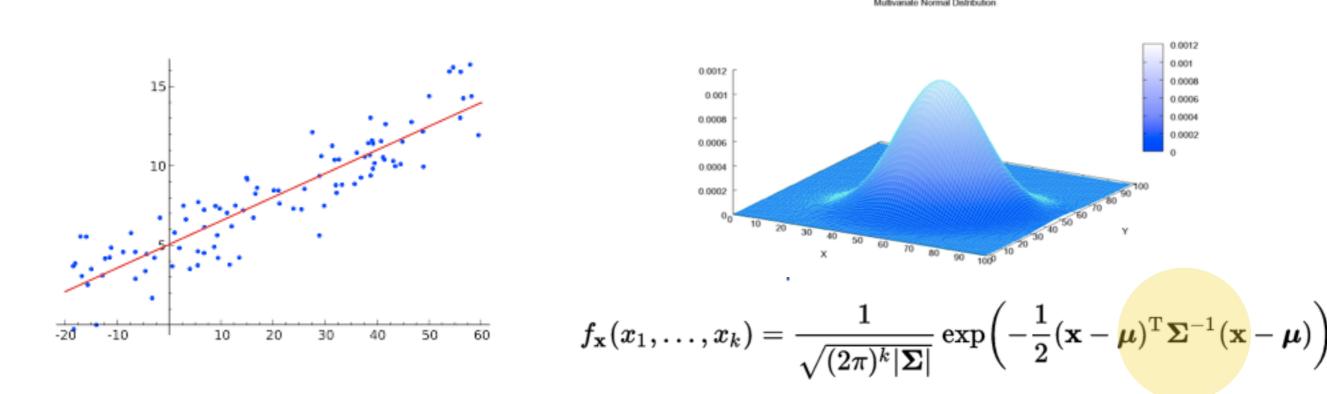
Simultaneous System - Overdetermined (n > d) "More equations (constraints) than variables"

Usually the case!! No solution?



Finding Inverse

Who cares?



least squares

multivariate normal

Finding Inverse

https://www.khanacademy.org/math/algebra-home/alg-matrices/alg-determinants-and-inverses-of-large-matrices/v/inverting-matrices-part-3

Finding Pseudo-Inverse

'best fit' (least squares) when no solution

If the linear system

$$Ax = b$$

has any solutions, they are all given by

$$x = A^+b + [I - A^+A]w$$

LU Decomposition

If A is a **square** matrix

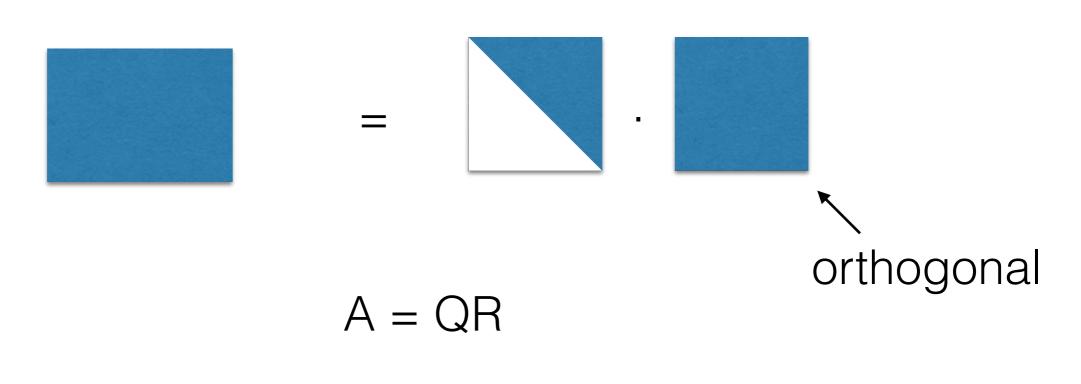
$$\begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} = \begin{bmatrix} l_{11} & 0 & 0 \\ l_{21} & l_{22} & 0 \\ l_{31} & l_{32} & l_{33} \end{bmatrix} \begin{bmatrix} u_{11} & u_{12} & u_{13} \\ 0 & u_{22} & u_{23} \\ 0 & 0 & u_{33} \end{bmatrix}$$

$$A = LU$$

QR Decomposition

Used in many efficient methods

If A is a (real) **square** matrix



QQ.T = IR upper triangular SVDecomposition

Norms

$$||x||_2 = \sqrt{\sum_{i=1}^n x_i^2}.$$

$$||x||_1 = \sum_{i=1}^n |x_i|$$

$$||x||_{\infty} = \max_i |x_i|.$$

$$||x||_p = \left(\sum_{i=1}^n |x_i|^p\right)^{1/p}.$$

Who wants to draw?

Inverses

$$A^{-1}A = I = AA^{-1}$$
.

- $(A^{-1})^{-1} = A$
- $(AB)^{-1} = B^{-1}A^{-1}$
- $(A^{-1})^T = (A^T)^{-1}$. For this reason this matrix is often denoted A^{-T} .