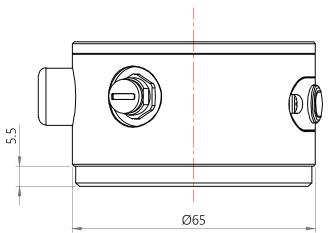
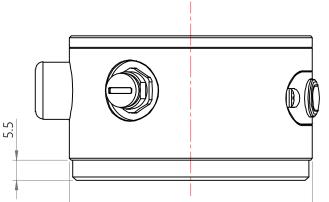


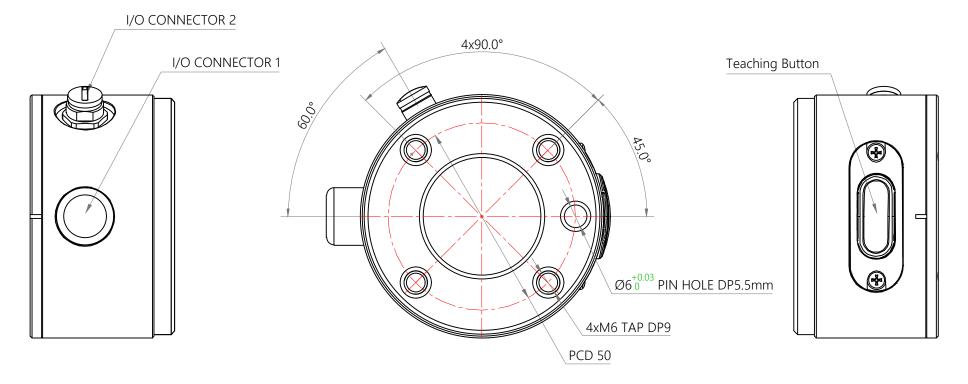
## NOTE

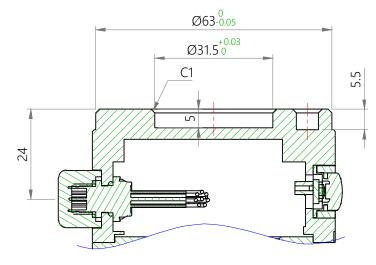
1) This drawing is an assembly drawing of RB3-730ES.

RAINBOW	PART NAME RB3-730ES			
ROBOTICS	DRAWING NO.			Rev -
THIS DRAWING MAY NOT BE REPRODUCED WITHOUT PRIOR WRITTEN APPROVAL.	SCALE 1:1	MATERIAL –	DRN. BY T.K AHN CHK'D. BY	2024.01.18
TOLERANCE UNLESS OTHERWISE SPECIFIED: XXX: ±0.2 XX: ±0.1 X: +0.1	SIZE A2	REFERENCE	APPR'D BY J.W HEO	2024.01.18
X: ±0.1 XX: ±0.05 ANGLE: ±0.5°			Page 1 of 1 CORP. ALL RIGHTS RES	ERVED.









SECTION A-A

REVISIONS					
ECN	부호	날짜	내용	수정자	승인자
-	-	2022.00.00	-	-	J.W HEO

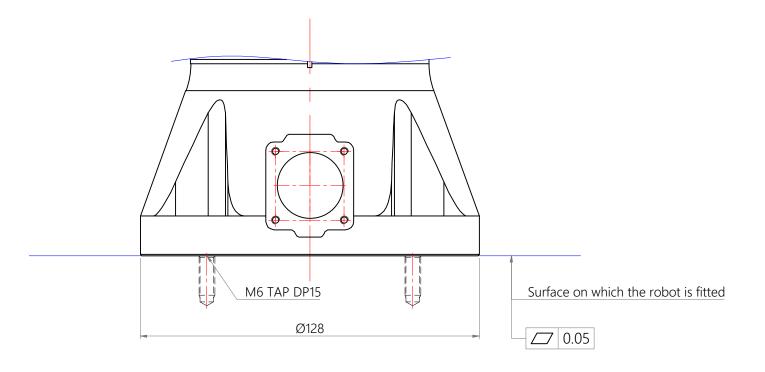
I/O Connecto	I/O Connector 2				
1) I/O Connector	- M8 female panel mount connector, 8pin - Spec : 76 6618 1111 00008-0200 - Maker : Binder				
2) Cable	- M8 male cable connector, 8pin - Spec : 77 3405 0000 50008-0200 - Maker : Binder				
3) CAP	- M8 Protecting cap - Spec : 08 2441 000 000 - Maker : Binder				

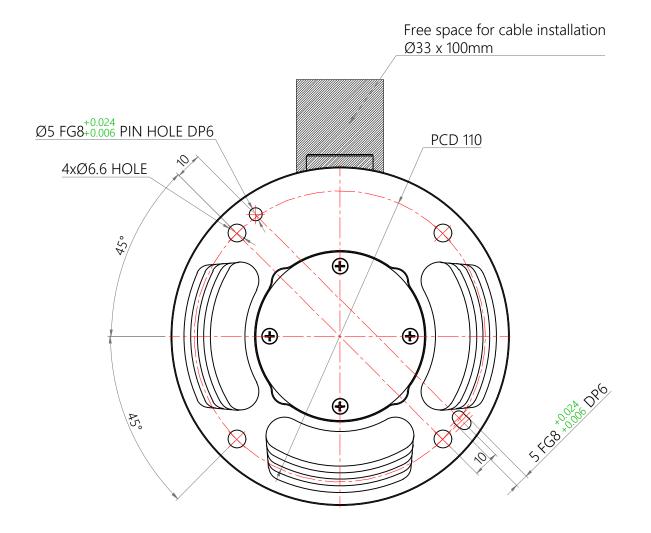
I/O Connector 1				
1) I/O Connector	- M8 male panel mount connector, 8pin - Spec : 76 6319 1111 00008-0200 - Maker : Binder			
2) Cable	- M8 female cable connector - Spec : 77 3406 0000 50008-0200 - Maker : Binder			
3) CAP	- M8 knurling cap - Maker : Rainbow-Robotics			

NOTE					
1) This drawing is a "Tool flange set-up" drawing.					
2) Mechanical interfaces: ISO 9409-1-50-4-M6					

rainbow robotics	PART NAME  DRAWING NO.	Tool flange set u	p_RB3-730E	S
THIS DRAWING MAY NOT BE REPRODUCED WITHOUT PRIOR	SCALE	- MATERIAL	DRN. BY	2024.01.18
WRITTEN APPROVAL.  TOLERANCE UNLESS	1:1	-	CHK'D. BY	-
OTHERWISE SPECIFIED:  XXX: ±0.2  XX: ±0.1  X: ±0.1	A3	REFERENCE _	J.W HEO	2024.01.18
X.X: ±0.05 ANGLE: ±0.5° 단위:MM		DPYRIGHT (C) RAINBOW ROBOTICS	1 of 1	ERVED.

REVISIONS					
ECN	부호	날짜	내용	수정자	승인자
-	-	2022.00.00	-	-	J.W HEO





## NOTE

1) This drawing is a "Base set-up" drawing.

RAINBOW	Base set-up_RB3-730ES			
ROBOTICS	DRAWING NO.	-		Rev –
THIS DRAWING MAY NOT BE REPRODUCED WITHOUT PRIOR WRITTEN APPROVAL.	SCALE 1:1	MATERIAL –	T.K AHN CHK'D. BY	2024.01.18
TOLERANCE UNLESS OTHERWISE SPECIFIED: XXX: ±0.2 XX: ±0.1 X: ±0.1 XX: ±0.05 ANGLE: ±0.5°	A2	REFERENCE _	J.W HEO Page 1 of 1	2024.01.18
단위 : MM	CC	L DPYRIGHT (C) RAINBOW ROBOTICS (	L Corp. All rights res	ERVED.