

Problem 1 Score: _____. The multiplication table for the group $D_3 = \{E, D, F, A, B, C\}$ is given by

	E	D	F	A	B	C
E	E	D	F	A	B	C
D	D	F	E	B	C	A
F	F	E	D	C	A	B
A	A	C	B	E	F	D
B	B	A	C	D	E	F
C	C	B	A	F	D	E

(a) Determine the dimensions of all the inequivalent irreducible representations of D_3 .

(b) Find the character table for D_3 .

Solution: (a) The inverse of each element in D_3 are

$$E^{-1} = E, \quad D^{-1} = F, \quad F^{-1} = D, \quad (1)$$

$$A^{-1} = A, \quad B^{-1} = B, \quad C^{-1} = C. \quad (2)$$

Constructing a class from D : For $X = E, D, F$,

$$XDX^{-1} = D. \quad (3)$$

For $X = A, B, C$,

$$XDX^{-1} = F. \quad (4)$$

The class of D_3 constructed from D is $\{D, F\}$.

Using the similar method, we construct all the three classes of D_3 :

$$\mathcal{C}_1 = \{E\}, \quad \mathcal{C}_2 = \{D, F\}, \quad \mathcal{C}_3 = \{A, B, C\}.$$

The number of inequivalent irreducible representations of D_3 is equal to the number of classes of G , so D_3 has three inequivalent irreducible representations. Suppose the dimensions of the three inequivalent irreducible representations $\Gamma^1, \Gamma^2, \Gamma^3$ are d_1, d_2, d_3 , respectively. The order of D_3 is $g = 6$. The sum of the squares of the dimensions of the inequivalent irreducible representations of D_3 is equal to the order of D_3 :

$$d_1^2 + d_2^2 + d_3^2 = 6. \quad (5)$$

Solving the above equation, we get

$$d_1 = 1, \quad d_2 = 1, \quad d_3 = 2. \quad (6)$$

(b) Since the character of identity in a representation is equal to the dimension of the representation, we have

$$\chi^1(\mathcal{C}_1) = \chi^2(\mathcal{C}_1) = 1, \quad \chi^3(\mathcal{C}_1) = 2. \quad (7)$$

Since $A^2 = B^2 = C^2 = E$, we have

$$\chi^p(\mathcal{C}_3) = \pm 1, \quad p = 1, 2. \quad (8)$$

Since $AB = F$ and $AC = D$, we have

$$\chi^p(\mathcal{C}_2) = \chi^p(\mathcal{C}_3)^2 = 1. \quad p = 1, 2. \quad (9)$$

There are two possibilities of $\chi^p(\mathcal{C}_3)$. Without loss of generality, we set Γ^1 to be the identity representation so that

$$\chi^1(\mathcal{C}_j) = 1, \quad j = 1, 2, 3. \quad (10)$$

As for Γ^2 , we have

$$\chi^2(\mathcal{C}_1) = 1, \quad \chi^2(\mathcal{C}_2) = 1, \quad \chi^2(\mathcal{C}_3) = -1. \quad (11)$$

Using the orthogonality relation for characters

$$\frac{1}{g} \sum_{T \in G} \chi^q(T)^* \chi^q(T) = \delta_{pq}, \quad (12)$$

we have

$$\chi^3(\mathcal{C}_1) + 2\chi^3(\mathcal{C}_2) + 3\chi^3(\mathcal{C}_3) = 0 \quad (13)$$

$$\chi^3(\mathcal{C}_1) + 2\chi^3(\mathcal{C}_2) - 3\chi^3(\mathcal{C}_3) = 0, \quad (14)$$

$$|\chi^3(\mathcal{C}_1)|^2 + 2|\chi^3(\mathcal{C}_2)|^2 + 3|\chi^3(\mathcal{C}_3)|^2 = 6. \quad (15)$$

Adding up the two equations (13) and (14) above, we get

$$\chi^3(\mathcal{C}_1) + 2\chi^3(\mathcal{C}_2) = 0, \quad (16)$$

so

$$\chi^3(\mathcal{C}_2) = -1. \quad (17)$$

Using the equation (15), we get

$$\chi^3(\mathcal{C}_3) = 0. \quad (18)$$

Now we have the character table for D_3 as shown in table 1.

Table 1: character table for D_3			
	$\mathcal{C}_1 = \{E\}$	$\mathcal{C}_2 = \{D, F\}$	$\mathcal{C}_3 = \{A, B, C\}$
Γ^1	1	1	1
Γ^2	1	1	-1
Γ^3	2	-1	0

□

Problem 2 Score: _____. The transformation matrices in two-dimensional real space for the elements of the group $D_3 = \{E, D, F, A, B, C\}$ are given by

$$\begin{aligned} R(E) &= \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, & R(D) &= \frac{1}{2} \begin{pmatrix} -1 & \sqrt{3} \\ \sqrt{3} & -1 \end{pmatrix}, & R(F) &= \frac{1}{2} \begin{pmatrix} -1 & \sqrt{3} \\ -\sqrt{3} & -1 \end{pmatrix}, \\ R(A) &= \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, & R(B) &= \frac{1}{2} \begin{pmatrix} -1 & \sqrt{3} \\ \sqrt{3} & -1 \end{pmatrix}, & R(C) &= \frac{1}{2} \begin{pmatrix} -1 & \sqrt{3} \\ -\sqrt{3} & 1 \end{pmatrix}. \end{aligned}$$

The basis function of a carrier space for D_3 are given by $\psi_1(\vec{\rho}) = x^2 F(\rho)$, $\psi_2(\vec{\rho}) = xy F(\rho)$, and $\psi_3(\vec{\rho}) = y^2 F(\rho)$, where $F(\rho)$, a function of $\rho = \sqrt{x^2 + y^2}$, ensures that the basis function as normalizable. Using

$$Q(T)\psi_n(\vec{\rho}) = \psi_n(R(T)^{-1}\vec{\rho}) = \sum_{m=1}^3 \Gamma(T)_{mn} \psi_m(\vec{\rho}), \quad n = 1, 2, 3,$$

find the representation matrix $\Gamma(F)$ of the element F of D_3 . Here $Q(T)$ is the scalar transformation operator and $\vec{\rho}$ is the position vector of a point in two-dimensional real space.

Solution: The inverse of $R(F)$ is equal to its transpose

$$R(F)^{-1} = R(F)^T = \frac{1}{2} \begin{pmatrix} -1 & -\sqrt{3} \\ \sqrt{3} & -1 \end{pmatrix}. \quad (19)$$

Making $R(F)^{-1}$ operate on $\vec{\rho}$, we get

$$R(F)^{-1}\vec{\rho} = \frac{1}{2} \begin{pmatrix} -1 & -\sqrt{3} \\ \sqrt{3} & -1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \frac{1}{2} \begin{pmatrix} -x - \sqrt{3}y \\ \sqrt{3}x - y \end{pmatrix} \quad (20)$$

Making $Q(F)$ operating on $\psi_n(\vec{\rho})$, we get

$$Q(F)\psi_1(\vec{\rho}) = \psi_1(R(F)^{-1}\vec{\rho}) = \frac{1}{4}(x^2 + 2\sqrt{3}xy + 3y^2)F(\rho) = \frac{1}{4}\psi_1(\vec{\rho}) + \frac{\sqrt{3}}{2}\psi_2(\vec{\rho}) + \frac{3}{4}\psi_3(\vec{\rho}), \quad (21)$$

$$Q(F)\psi_2(\vec{\rho}) = \psi_2(R(F)^{-1}\vec{\rho}) = \frac{1}{4}(-\sqrt{3}x^2 - 2xy + \sqrt{3}y^2)F(\rho) = -\frac{\sqrt{3}}{4}\psi_1(\vec{\rho}) - \frac{1}{2}\psi_2(\vec{\rho}) + \frac{\sqrt{3}}{4}\psi_3(\vec{\rho}), \quad (22)$$

$$Q(F)\psi_3(\vec{\rho}) = \psi_3(R(F)^{-1}\vec{\rho}) = \frac{1}{4}(3x^2 - 2\sqrt{3}xy + y^2)F(\rho) = \frac{3}{4}\psi_1(\vec{\rho}) - \frac{\sqrt{3}}{2}\psi_2(\vec{\rho}) + \frac{1}{4}\psi_3(\vec{\rho}). \quad (23)$$

Using

$$Q(T)\psi_n(\vec{\rho}) = \psi_n(R(T)^{-1}\vec{\rho}) = \sum_{m=1}^3 \Gamma(T)_{mn}\psi_m(\vec{\rho}), \quad n = 1, 2, 3, \quad (24)$$

we find the representation matrix $\Gamma(F)$ of the element F of D_3 :

$$\Gamma(F) = \begin{pmatrix} \frac{1}{4} & \frac{\sqrt{3}}{2} & \frac{3}{4} \\ -\frac{\sqrt{3}}{4} & -\frac{1}{2} & \frac{\sqrt{3}}{4} \\ \frac{3}{4} & -\frac{\sqrt{3}}{2} & \frac{1}{4} \end{pmatrix}. \quad (25)$$

□

Problem 3 Score: _____. Using the information given in the previous problem, find the representation matrix $\Gamma(B)$ of the element B of D_3 .

Solution: The inverse of $R(B)$ is its transpose

$$R(T)^{-1} = R(T)^T = \frac{1}{2} \begin{pmatrix} -1 & \sqrt{3} \\ \sqrt{3} & 1 \end{pmatrix}. \quad (26)$$

Making $R(B)^{-1}$ operate on $\vec{\rho}$, we get

$$R(F)^{-1}\vec{\rho} = \frac{1}{2} \begin{pmatrix} -1 & \sqrt{3} \\ \sqrt{3} & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \frac{1}{2} \begin{pmatrix} -x + \sqrt{3}y \\ \sqrt{3}x + y \end{pmatrix}. \quad (27)$$

Making $Q(B)$ operating on $\psi_n(\vec{\rho})$, we get

$$Q(B)\psi_1(\vec{\rho}) = \psi_1(R(B)^{-1}\vec{\rho}) = \frac{1}{4}(x^2 - 2\sqrt{3}xy + 3y^2)F(\rho) = \frac{1}{4}\psi_1(\vec{\rho}) - \frac{\sqrt{3}}{2}\psi_2(\vec{\rho}) + \frac{3}{4}\psi_3(\vec{\rho}), \quad (28)$$

$$Q(F)\psi_2(\vec{\rho}) = \psi_2(R(F)^{-1}\vec{\rho}) = \frac{1}{4}(-\sqrt{3}x^2 + 2xy + \sqrt{3}y^2)F(\rho) = -\frac{\sqrt{3}}{4}\psi_1(\vec{\rho}) + \frac{1}{2}\psi_2(\vec{\rho}) + \frac{\sqrt{3}}{4}\psi_3(\vec{\rho}), \quad (29)$$

$$Q(F)\psi_3(\vec{\rho}) = \psi_3(R(F)^{-1}\vec{\rho}) = \frac{1}{4}(3x^2 + 2\sqrt{3}xy + y^2)F(\rho) = \frac{3}{4}\psi_1(\vec{\rho}) + \frac{\sqrt{3}}{2}\psi_2(\vec{\rho}) + \frac{1}{4}\psi_3(\vec{\rho}). \quad (30)$$

Using

$$Q(T)\psi_n(\vec{\rho}) = \psi_n(R(T)^{-1}\vec{\rho}) = \sum_{m=1}^3 \Gamma(T)_{mn}\psi_m(\vec{\rho}), \quad n = 1, 2, 3, \quad (31)$$

we find the representation matrix $\Gamma(F)$ of the element F of D_3 :

$$\Gamma(F) = \begin{pmatrix} \frac{1}{4} & -\frac{\sqrt{3}}{2} & \frac{3}{4} \\ -\frac{\sqrt{3}}{4} & \frac{1}{2} & \frac{\sqrt{3}}{4} \\ \frac{3}{4} & \frac{\sqrt{3}}{2} & \frac{1}{4} \end{pmatrix}. \quad (32)$$

□

Problem 4 Score: _____. Show that, if the projection operators P_{mn}^p and P_{jk}^q belong to two unitary irreducible representations Γ^p and Γ^q of G that are not equivalent if $p \neq q$ (but are identical if $p = q$), then $P_{mn}^p P_{jk}^q = \delta_{pq} \delta_{nj} P_{mk}^q$.

Solution: Using the definition of the projection operators

$$P_{mn}^p = \frac{d_p}{g} \sum_{T \in G} \Gamma^p(T)_{mn}^* Q(T), \quad (33)$$

$$P_{jk}^q = \frac{d_q}{g} \sum_{T' \in G} \Gamma^q(T')_{jk}^* Q(T'), \quad (34)$$

we have

$$P_{mn}^p P_{jk}^q = \frac{d_p d_q}{g^2} \sum_{T, T' \in G} \Gamma^p(T)_{mn}^* \Gamma^q(T')_{jk}^* Q(T) Q(T'). \quad (35)$$

Since

$$Q(T)Q(T') = Q(TT'), \quad (36)$$

we have

$$P_{mn}^p P_{jk}^q = \frac{d_p d_q}{g^2} \sum_{T, T' \in G} \Gamma^p(T)_{mn}^* \Gamma^q(T')_{jk} Q(TT'). \quad (37)$$

Setting $T'' = TT' \in G$ and replacing T' with $T' = T^{-1}T''$, we get

$$P_{mn}^p P_{jk}^q = \frac{d_p d_q}{g^2} \sum_{T, T'' \in G} \Gamma^p(T)_{mn}^* \Gamma^q(T^{-1}T'')_{jk} Q(T''). \quad (38)$$

Since Γ^p and Γ^q are two unitary representations,

$$\Gamma^q(T^{-1}T'')^* = [\Gamma^q(T^{-1})\Gamma^q(T'')]^* = [\Gamma^q(T)^{-1}\Gamma^q(T'')]^* = [\Gamma^q(T)^\dagger \Gamma^q(T'')]^* = \Gamma^q(T)^T \Gamma^q(T'')^*, \quad (39)$$

we have

$$P_{mn}^p P_{jk}^q = \frac{d_p d_q}{g^2} \sum_{T, T'' \in G} \sum_l \Gamma^p(T)_{mn}^* \Gamma^q(T)_{lj} \Gamma^q(T'')_{lk} Q(T''). \quad (40)$$

Using the orthogonality relation for unitary irreducible representations

$$\frac{1}{g} \sum_{T \in G} \Gamma^p(T)_{mn}^* \Gamma^q(T)_{lj} = \frac{1}{d_p} \delta_{pq} \delta_{ml} \delta_{nj}, \quad (41)$$

we get

$$P_{mn}^p P_{jk}^q = \frac{d_q}{g} \delta_{pq} \delta_{nj} \sum_{T'' \in G} \sum_l \delta_{ml} \Gamma^q(T'')_{lk} Q(T'') = \frac{d_q}{g} \delta_{pq} \delta_{nj} \sum_{T'' \in G} \Gamma^q(T'')_{mk} Q(T'') = \delta_{pq} \delta_{nj} P_{mk}^q. \quad (42)$$

□

Problem 5 Score: _____. Choosing $\phi(\vec{r}) = (xy + yz)e^{-r}$, construct the basis function for two-dimensional irreducible representation Γ^5 of the crystallographic point group D_4 .

Solution: The transformation matrices of D_4 are

$$R(E) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \quad R(C_{2x}) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{pmatrix}, \quad R(C_{2y}) = \begin{pmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix}, \quad R(C_{2z}) = \begin{pmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \quad (43)$$

$$R(C_{4z}) = \begin{pmatrix} 0 & 0 & -1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix}, \quad R(C_{4y}^{-1}) = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ -1 & 0 & 0 \end{pmatrix}, \quad R(C_{2c}) = \begin{pmatrix} 0 & 0 & 1 \\ 0 & -1 & 0 \\ 1 & 0 & 0 \end{pmatrix}, \quad R(C_{2d}) = \begin{pmatrix} 0 & 0 & -1 \\ 0 & -1 & 0 \\ -1 & 0 & 0 \end{pmatrix}. \quad (44)$$

The inverses of these transformation operators are their transposes respectively

$$R(E)^{-1} = R(E)^T = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \quad R(C_{2x})^{-1} = R(C_{2x})^T = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{pmatrix}, \quad (45)$$

$$R(C_{2y})^{-1} = R(C_{2y})^T = \begin{pmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix}, \quad R(C_{2z})^{-1} = R(C_{2z})^T = \begin{pmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \quad (46)$$

$$R(C_{4y})^{-1} = R(C_{4y})^T = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ -1 & 0 & 0 \end{pmatrix}, \quad R(C_{4y}^{-1})^{-1} = R(C_{4y}^{-1})^T = \begin{pmatrix} 0 & 0 & -1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix}, \quad (47)$$

$$R(C_{2c})^{-1} = R(C_{2c})^T = \begin{pmatrix} 0 & 0 & 1 \\ 0 & -1 & 0 \\ 1 & 0 & 0 \end{pmatrix}, \quad R(C_{2d})^{-1} = R(C_{2d})^T = \begin{pmatrix} 0 & 0 & -1 \\ 0 & -1 & 0 \\ -1 & 0 & 0 \end{pmatrix}. \quad (48)$$

Making the inverse of transformation operators operate on \vec{r} , we get

$$R(E)^{-1} \vec{r} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}, \quad (49)$$

$$R(C_{2x})^{-1}\vec{r} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} x \\ -y \\ -z \end{pmatrix}, \quad (50)$$

$$R(C_{2y})^{-1}\vec{r} = \begin{pmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -x \\ y \\ -z \end{pmatrix}, \quad (51)$$

$$R(C_{2z})^{-1}\vec{r} = \begin{pmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -x \\ -y \\ z \end{pmatrix}, \quad (52)$$

$$R(C_{4y})^{-1}\vec{r} = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ -1 & 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} z \\ y \\ -x \end{pmatrix}, \quad (53)$$

$$R(C_{4y}^{-1})^{-1}\vec{r} = \begin{pmatrix} 0 & 0 & -1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -z \\ y \\ x \end{pmatrix}, \quad (54)$$

$$R(C_{2c})^{-1}\vec{r} = \begin{pmatrix} 0 & 0 & 1 \\ 0 & -1 & 0 \\ 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} z \\ -y \\ x \end{pmatrix}, \quad (55)$$

$$R(C_{2d})^{-1}\vec{r} = \begin{pmatrix} 0 & 0 & -1 \\ 0 & -1 & 0 \\ -1 & 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -z \\ -y \\ -x \end{pmatrix}. \quad (56)$$

Making the scalar transformation operators operate on $\phi(\vec{r})$, we get

$$Q(E)\phi(\vec{r}) = \phi(R(E)^{-1}\vec{r}) = (xy + yz)e^{-r}, \quad (57)$$

$$Q(R_{2x})\phi(\vec{r}) = \phi(R(C_{2x})^{-1}\vec{r}) = (-xy + yz)e^{-r}, \quad (58)$$

$$Q(R_{2y})\phi(\vec{r}) = \phi(R(C_{2y})^{-1}\vec{r}) = (-xy - yz)e^{-r}, \quad (59)$$

$$Q(R_{2z})\phi(\vec{r}) = \phi(R(C_{2z})^{-1}\vec{r}) = (xy - yz)e^{-r}, \quad (60)$$

$$Q(R_{4y})\phi(\vec{r}) = \phi(R(C_{4y})^{-1}\vec{r}) = (-xy + yz)e^{-r}, \quad (61)$$

$$Q(R_{4y}^{-1})\phi(\vec{r}) = \phi(R(C_{4y}^{-1})^{-1}\vec{r}) = (xy - yz)e^{-r}, \quad (62)$$

$$Q(R_{2c})\phi(\vec{r}) = \phi(R(C_{2c})^{-1}\vec{r}) = (-xy - yz)e^{-r}, \quad (63)$$

$$Q(R_{2d})\phi(\vec{r}) = \phi(R(C_{2d})^{-1}\vec{r}) = (xy + yz)e^{-r}. \quad (64)$$

The two-dimensional irreducible representation Γ^5 of D_4 is

$$\Gamma^5(E) = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \quad \Gamma^5(C_{2x}) = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \quad \Gamma^5(C_{2y}) = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}, \quad \Gamma^5(C_{2z}) = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}, \quad (65)$$

$$\Gamma^5(C_{4y}) = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}, \quad \Gamma^5(C_{4y}^{-1}) = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}, \quad \Gamma^5(C_{2c}) = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad \Gamma^5(C_{2d}) = \begin{pmatrix} 0 & -1 \\ -1 & 0 \end{pmatrix}. \quad (66)$$

Using

$$P_{mn}^p(\vec{r}) = \frac{d_p}{g} \sum_{T \in D_4} \Gamma^p(T)_{mn} Q(T)\phi(\vec{r}), \quad (67)$$

we have

$$P_{11}^5\phi(\vec{r}) = \frac{1}{4}[(xy + yz) + (-xy + yz) - (-xy - yz) - (xy - yz)]e^{-r} = yze^{-r}, \quad (68)$$

$$P_{22}^5\phi(\vec{r}) = \frac{1}{4}[(xy + yz) - (-xy + yz) - (-xy - yz) + (xy - yz)]e^{-r} = xye^{-r}. \quad (69)$$

We calculate the coefficients

$$\begin{aligned} (c_1^5)^2 &= (P_{11}^5\phi(\vec{r}), P_{11}^5\phi(\vec{r}))^{1/2} = \iiint_{-\infty}^{+\infty} dx dy dz y^2 z^2 e^{-2r} \\ &= \int_0^{2\pi} d\varphi \int_0^\pi \sin\theta d\theta \int_0^{+\infty} r^2 dr (r \sin\theta \sin\varphi)^2 (r \cos\theta)^2 e^{-2r} = \frac{3}{2}\pi, \end{aligned} \quad (70)$$

$$c_2^5 = (P_{11}^5(\vec{r}), P_{22}^5\phi(\vec{r})) = \iiint_{-\infty}^{+\infty} dx dy dz x^2 y^2 e^{-2r} = (c_1^5)^2 = \frac{3}{2}\pi. \quad (71)$$

Without loss of generality, we set $c_1^5 = (\frac{3}{2}\pi)^{1/2}$. The basis functions for Γ^5 of D_4 are

$$\psi_1^5(\vec{r}) = \frac{P_{11}^p\phi(\vec{r})}{c_1^5} = \left(\frac{2}{3\pi}\right)^{1/2} yze^{-r}, \quad (72)$$

$$\psi_2^5(\vec{r}) = P_{21}^5\psi_1^5(\vec{r}) = \frac{2}{8} \sum_{T \in G} \Gamma^5(T)_{21}^* Q(T)\psi(\vec{r}) = \frac{1}{4} \left(\frac{2}{3\pi}\right)^{1/2} [(-xy) - xy + (-xy) - xy]e^{-1} = -\left(\frac{2}{3\pi}\right)^{1/2} xye^{-r}. \quad (73)$$

□